

7.1-1)

Given:

- Theorem 7.1

$$\langle u_i, u_j \rangle = \delta_{i-j}$$

(1)

Find:

Show (1) is true

Solution:

$$u_i = \frac{Av_i}{\sqrt{\lambda_i}}$$

where  $\lambda_i$  is an eigenvalue of  $A$   
 $v_i$  is an eigenvector of  $A$ 

$$\langle u_i, u_j \rangle = \delta_{i-j} \quad \text{where } \delta \text{ is the Kronecker delta.}$$

$$\text{Let } \langle a, b \rangle = b^H a$$

$$\Rightarrow \langle u_i, u_j \rangle = \frac{v_j^H A A v_i}{\sqrt{\lambda_i} \sqrt{\lambda_j}} = \frac{v_j^H A^H \lambda_i v_i}{\sqrt{\lambda_i} \sqrt{\lambda_j}}$$

$$\text{We know } Av = \lambda v \Rightarrow v^H A^H = \lambda v^H$$

$$\Rightarrow \frac{\lambda_i \lambda_j v_j^H v_i}{\sqrt{\lambda_i} \sqrt{\lambda_j}} \quad \text{and we know } v_i \perp v_j \text{ if } i \neq j$$

$$\Rightarrow \langle u_i, u_j \rangle = \delta_{i-j} //$$

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7.1-2)

Given:

- Matrix 2 norm and Frobenius norm

Find:

$$\|A\|_F^2 = \sum_{i=1}^p \sigma_i^2$$

$$\|A\|_2 = \sigma_1$$

one true.

Solution:

$$A = U \Sigma V^H$$

U is unitary

V is unitary

$$\Sigma = \text{diag}(\sigma_1, \sigma_2, \dots, \sigma_p)$$

$$\|A\|_F = \left( \sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2 \right)^{1/2} ; \|A\|_F^2 = \text{tr}(AA^H)$$

$$\|A\|_2 = \sqrt{\rho(A^H A)} \quad \text{and if } A \text{ is Hermitian } \|A\|_2 = \rho(A)$$

Because U and V are unitary, they drop out of the norm leaving

$$\|A\|_F^2 = \text{tr}(AA^H) = \sum_{i=1}^p \sigma_i^2 //$$



$\Sigma = \Sigma^H$  because it is diagonal thus

$$\|A\|_2 = \rho(A) \quad \text{where} \quad \rho(A) = \max_i |\lambda_i|$$

Since  $\Sigma$  has  $\sigma_i$  in descending order

$$\|A\|_2 = \rho(\Sigma) = \sigma_1 //$$





7.2-3) Given:

$$R(A) = \text{span}(U_1)$$

$$N(A) = \text{span}(U_2)$$

$$R(A^H) = \text{span}(V_1)$$

$$N(A^H) = \text{span}(V_2)$$

(1)

Find:

Show that the SVD can be used to determine the Fundamental Subspaces in (1)

Solution: Note the end for definition of  $U_1, U_2, V_1, V_2$ .

Let  $A = U \Sigma V^H$  be the SVD of  $A$ .

$$\begin{aligned} R(A) &= b : b = U \Sigma V^H x \\ &= U \Sigma y \\ &= U_1 y = \text{span}\{U_1\} // \end{aligned}$$

$$R(A^H) = V \Sigma^H U^H x = V \Sigma y = V_1 y = \text{span}(V_1) //$$

$$\begin{aligned} N(A) &= U \Sigma V^H x = 0 \\ &= U_2 x = \text{span}(U_2) // \end{aligned}$$

$$N(A^H) = V \Sigma^H U^H x = U_2 x = \text{span}(U_2) //$$



Note

$$U \Sigma V^H = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \begin{bmatrix} \Sigma_1 & \\ & \Sigma_2 \end{bmatrix} \begin{bmatrix} v_1 & v_2 \end{bmatrix}$$

$$\Sigma_2 = 0$$





7.3-5) Given:

The LS solution to  $\|Ax - b\|_2^2$  is

$$E_{\min}^2 = \|U_0^H b\|_2^2 \quad (1)$$

Find:

- Show (1)

- Interpret (1) in terms of the four fundamental subspaces.

Solution:

$$\begin{aligned} \|Ax - b\|_2^2 &= \|U \Sigma V^H \cdot b\|_2^2 \\ &= \|U(\Sigma V^H - U^H b)\|_2^2 \\ &= \|\Sigma \underline{v} - \hat{b}\|_2^2 \end{aligned}$$

Where  $\underline{v} = V^H x$  and  $\hat{b} = U^H b$ 

$$\Rightarrow \min \|\Sigma \underline{v} - \hat{b}\|_2^2 = \left\| \begin{bmatrix} \Sigma_1 \underline{v}_1 = \hat{b}_1 \\ \Sigma_2 \underline{v}_2 = \hat{b}_2 \end{bmatrix} \right\|_2^2$$

$$\Rightarrow \|\underline{v} = \Sigma^+ \hat{b}\|_2^2 = \|\Sigma^+ U^H b\|_2^2$$

$$= \Sigma_1^+ \|U^H b\|_2^2 = \Sigma_1^+ \left\| \begin{bmatrix} u_1 & u_2 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \right\|_2^2$$

 $\Sigma_2$  is 0, but to get the minimum norm we want



$V_2$  to be 0. This means that, in terms of the fundamental subspaces, no "data" is lost because  $V_2$  is 0.





7.5-7) Given:

$$\|A-B\|_2^2 \stackrel{(1)}{\geq} \|A z\|_2^2 = \sum_{i=1}^{k+1} \sigma_i^2 (v_i^H z)^2 \stackrel{(2)}{\geq} \sigma_{k+1}^2 \quad (1)$$

Find:

- Show the inequalities in (1) are correct.
- Show the conditions for achieving the lower bound are correct.

Solution:

(1)

$$\|A-B\|_2 \geq \|(A-B)z\|_2 = \|Az\|_2$$

where  $z \in \text{span}\{v_1, v_2, \dots, v_{k+1}\}$

(2)

$$\begin{aligned} \|Az\|_2^2 &= \sum_{i=1}^{k+1} \sigma_i^2 (v_i^H z)^2 \geq \sigma_{k+1}^2 \sum_{i=1}^{k+1} (v_i^H z)^2 \\ &= \sigma_{k+1}^2 \end{aligned}$$

b) Let  $B = \sum_{i=1}^k \sigma_i u_i v_i^H$  and  $z = v_{k+1}$

$$A = U \Sigma V^H = \sum_{i=1}^r \sigma_i u_i v_i^H$$

$$\|A-B\| = \left\| \sum_{i=1}^r \sigma_i u_i v_i^H - \sum_{i=1}^k \sigma_i u_i v_i^H \right\|$$

$$= \left\| \sum_{i=k+1}^r \sigma_i u_i v_i^H \right\|$$



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$$\left\| \sum_{i=k}^r (\sigma_i u_i v_i) z_i \right\| \quad \text{where } z = v_{k+1}$$

$$\Rightarrow \left\| \sum_{i=k}^r (\sigma_i u_i v_i) v_{k+1} \right\| = 0 //$$





7.7-12) Given:

P is on the plane  $\perp$  normal vector  $n \in \mathbb{R}^{n+1}$ 

$$P = \{r \in \mathbb{R}^{n+1} : r^T n = 0\}$$

$$\text{Let } n = \begin{bmatrix} x \\ -1 \end{bmatrix} \text{ and } p = \begin{bmatrix} a \\ b \end{bmatrix} \in \mathbb{R}^{n+1}$$

Find:

Show the shortest squared distance from P to P is

$$\frac{(x^T a - b)^2}{x^T x + 1}$$

Solution:

$$[A + E \mid b + r] \begin{bmatrix} x \\ -1 \end{bmatrix} = 0$$

$$\underbrace{([A \mid b])}_{C} + \underbrace{[E \mid r]}_{D} \begin{bmatrix} x \\ -1 \end{bmatrix} = 0$$

$$\Sigma = R(D) = \text{span}(V_{k+1}, V_{k+2}, \dots, V_{n+1})$$



$$\min_x \frac{\| [A|b] \begin{bmatrix} x \\ -1 \end{bmatrix} \|^2}{\| \begin{bmatrix} x \\ -1 \end{bmatrix} \|^2} = \min_x \sum_i \frac{|a_i^H x - b_i|^2}{x^H x + 1}$$

$$= \min_x \sum_i \frac{(a_i^H x - b_i)^2}{x^H x + 1} = \min_x \sum_i \frac{(x^H a_i - b)^2}{x^T x + 1}$$

Because  $n \in \mathbb{R}^{n+1}$

$$= \min_x \sum_i \frac{(x^T a_i - b)^2}{x^T x + 1} \quad \text{since } p = [a|b] \text{ is a single point}$$

$$= \min_x \frac{(x^T a - b)^2}{x^T x + 1}$$

noting that  $x^T a = b$  we want  
an  $x$  that minimizes the square  
distance with  $b$ .





7.7-13) Given:

$\bar{V} = [V_k, V_{k+1}, \dots, V_{n+1}] \in \mathbb{R}^{(m+1)(n-k+2)}$ , In TLS  
we sought an element  $y \in R(\bar{V})$  such that  $x = \bar{I}y$   
of minimum norm where

$$\bar{I} = \begin{bmatrix} I_m \\ 0 \end{bmatrix}$$

picks out the first  $m$  elements of  $y$ , and  $y_{m+1} = -1$ .

Find:

Formulate the problem of minimum-norm  $x$  as a  
constrained optimization problem, and determine the  
solution.

Solution:

$$\max \| \bar{I}y \|^2 \quad \text{s.t.} \quad y_{m+1} = -1$$

$$\bar{I} = \sum_{i=1}^m \sigma_i u_i v_i^H \quad m = \text{rank}(I_m)$$

$$v_{m+1} \perp v_i \quad i = 1, 2, \dots, m$$

$$\Rightarrow y = -v_{m+1} \quad \text{recall } y_{m+1} = -1 \quad \therefore$$

$$y = -\frac{v_{m+1}}{\|v_{m+1}\|}$$



7.9-15) Given:

$$A = \begin{bmatrix} 4.85 & -2.47 & 0.55 & -4.32 \\ 0.81 & -3.46 & -0.25 & 2.97 \end{bmatrix}$$

$$B = \begin{bmatrix} 4.51 & -2.19 & 6.59 & -4.72 \\ 1.95 & -3.64 & -0.131 & 2.29 \end{bmatrix}$$

A and B are rotations of each other

Find

The amount of rotation between the data sets.

Solution:

maximize  $\text{tr}(Q^H B^H A)$   $Q$  is unitary

The maximizing  $Q$  can be found by means of SVD of  $B^H A$ .

Theorem: If

$$B^H A = U \Sigma V^H$$

then the maximizing  $Q$  for the orthogonal Procrustes problem is

See P715.m

$$Q = UV^T$$

$$A - BQ = \begin{bmatrix} -0.029 & 0.293 & 0.0281 & -0.313 \\ 0.453 & 0.266 & -0.047 & 0.360 \end{bmatrix} //$$



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7.10-17)

Given:

$$A = B + jC \quad B \text{ and } C \text{ are real}$$

Find

Determine a means of finding the SVD of  $A$  in terms of the SVD of

$$\begin{bmatrix} B & -C \\ C & B \end{bmatrix}$$

Solution:

$$U^H A V = \begin{bmatrix} B \\ 0 \end{bmatrix} + j \begin{bmatrix} C \\ 0 \end{bmatrix}$$

Where we attempt to get the diagonals to be eigenvalues of  $A$ . Much like in the book.

$$\begin{bmatrix} B & 0 \\ 0 & B \end{bmatrix}$$

But because  $C$  is complex it will have positive and negative eigenvalue pairs resulting in

$$\begin{bmatrix} 0 & -C \\ C & 0 \end{bmatrix}$$

Thus by adding them we get

$$\begin{bmatrix} B & -C \\ C & B \end{bmatrix}$$

