Robot active follow FSM

No Wall

States and transitions:

- No Wall → Straight
- Straight → (Front) → Turn Rnd
- Straight → No Wall (self loop)
- Straight → (Side/Front) → Turn opposite
- Turn Rnd → <θ (Small Angle)
- Turn Rnd → (Side/Front) → Turn opposite
- Turn Rnd → No Wall → Straight
- Turn opposite → Side/Front (self loop)
- Turn opposite → (Side) → Follow
- Follow → (Front) → Turn Rnd
- Straight → (Side) → Follow
- Follow → No Wall
- Follow — Along wall