目录

- 1. Heaps
- 2. Heap Implementations
- 3. Operation on heaps
 - 1. Get the maximum element
 - 2. Insert an element
 - 1. fixUp
 - 2. Example
 - 3. Delete the maximum element
 - 1. fixDown
 - 2. Example
 - 4. Animation of heap insertion/deletion
- 4. Comparing heaps with 'normal' arrays
- 5. Converting an arbitrary array into a heap

Heaps

The segment of memory that can be used by a C programmer is referred to as the heap

- more accurately, it is called *heap memory*
- a programmer can request heap memory by using *malloc()*
 - o for example, when creating a node for a linked list
- the memory is 'returned' to the heap by using free()

That has nothing to do with the *heap data structure*.

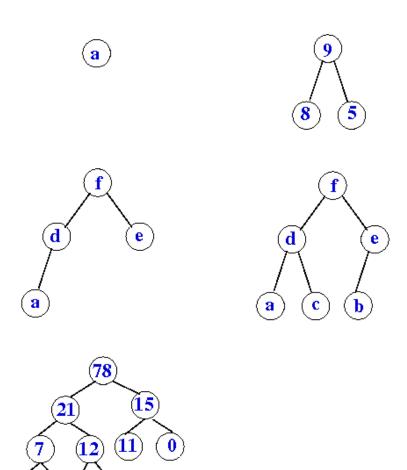
A heap data structure is a high-level, two-dimensional data structure

- it is 'higher-level' than an array, or a linked list ...
 - o in the sense that a heap data structure is built on an array, or linked list
- it is two-dimensional because it forms a tree of data
 - o a binary tree (at most 2 children per node)

A heap:

- has a root node
- the root node can have 0, 1 or 2 'child' nodes
- in turn, each child node can have 0, 1 or 2 child nodes

Examples of heaps:



Types of heaps:

• Max-heaps

- o the element with the largest key is at the root
- o the children of a node have keys smaller than the parent

• Min-heaps

- o the element with the smallest key is at the root
- o the children of a node have keys larger than the parent

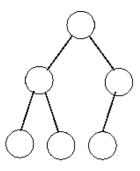
A max-heap (analogously for min-heap) satisfies 2 properties:

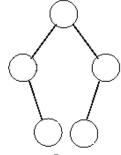
1. Heap-Order Property (sometimes called HOP)

- \circ for root node with key k
 - the nodes in each subtree has key $\leq k$
- the root of each <u>subtree</u> recursively down the tree satisfies the same property

2. Complete-Tree Property (sometimes called CTP)

- $\circ\,$ nodes in a given level are filled in from left to right with no breaks
- o every level is filled in before adding a node to the next level
 - technically should be called the *Almost-Complete Tree Property* ...
 - because 'complete' means exactly 2 children per non-leaf node





Complete tree

Incomplete tree

A heap data structure is partially ordered

- more order than 'unordered', less ordered than 'ordered'
- useful in applications that don't need fully ordered data
 - the application may want the maximum or minimum element (only)
 - sorting a whole list just to find the maximum is very inefficient
- heaps often used to implement *priority queues*, used in shortest-path algorithms

Size of a heap:

- because of the Complete-Tree Property,
 - \circ at level 0 there is 2^0 nodes (i.e. the root node)
 - o at level 1 there is either 1 or 2¹ nodes (i.e. the children of the root node)
 - o at level 2 there are between 1 and 2² nodes (i.e. 'grand-children' of the root node)
 - o at level 3 there are between 1 and 2³ nodes
 - 0 ...
 - o at level n there are between 1 and 2ⁿ nodes

If there are a total of N nodes then the maximum value of n is O(log(N))

• because approximately $2^n = N$ hence n = log(N)

This means that:

```
the maximum height of a heap of size N is O(log(N))
```

This means that:

```
the maximum path length in a heap of size N is O(log(N))
```

Heap Implementations

An array is the most efficient way of implementing a heap data structure

Ironically, a heap data structure implemented on a linked list ...

• would be using heap memory, but this is rarely done in practice

Why?

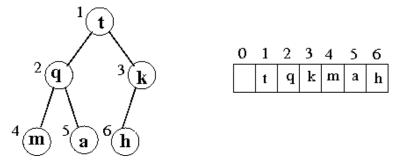
• because of the Complete Tree Property, CTP

We always place the root of the heap at index 1

• given any node at index i:

3 of 10

- o its left child is located at 2i
- o its right child is located at 2i+1
- o its parent is located at i/2 (use integer division)



- Here:
 - \circ t (i=1) has children q (2*i=2*1) and k (2*i+1=2*1+1)
 - o **q** (2) has children **m** (2*2) and **a** (2*2+1)
 - o **k** (3) has one child **h** (2*3)
 - \circ parent of \mathbf{q} (\mathbf{i} =2) is \mathbf{t} (\mathbf{i} /2=2/2)
 - \circ parent of **k** (3) is **t** (3/2)
 - \circ parent of **m** (4) is **q** (4/2)
 - \circ parent of a (5) is q (5/2)
 - o parent of **h** (6) is **k** (6/2)

Operation on heaps

Get the maximum element

The maximum element is always the root element, which is always at location 1

- a trivial, constant-time operation
 - o return element at location 1

Note, we are just 'getting' the maximum element

• we are not changing the heap in any way

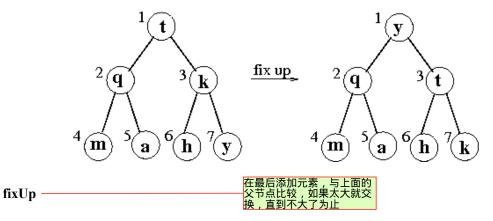
Insert an element

Inserting an element in a heap is a 2-stage process:

- 1. **put** the new element at bottom-most, rightmost position (so *Complete-Tree Property* is maintained).
 - o in other words, add it to the end of the array
- 2. fixUp (i.e. possibly swap) values along single path back to root to restore the Heap-Order Property

For example, assume we want to add the key 'y' to the heap

- 1. **put** the new key at the bottom right position (i.e. at location 7)
 - o this makes the heap incorrect why?
- 2. we do a **fix up** to re-establish order
 - 1. first swap k and y
 - 2. next swap t and y



- is also called heapify up
- means simply to move a key to its correct place upwards in the heap
- has complexity O(log(N)) because that is the height of the heap

Let us implement the heap data structure in an array called *heap[]*

- the root of the heap is at heap[1]
- assume we have a new node ...
 - o we put it at the end of the array, at index child say
 - we know the parent of the new node is at index child/2
 - o then we **fixUp** the tree order by calling the function:

```
只有当满足两个条件的时候,才会逐渐向上移动,否则直接停止就行,并不是一定要比较到最上面
```

```
切换行号显示
  1 // fix up the heap for the new element at index child
  2 void fixUp(int *heap, int child) {
        while (child>1 && heap[child/2]<heap[child]) {</pre>
                                      // if parent < child ...
  4
           int swap = heap[child];
          heap[child] = heap[child/2]; // swap them ...
  5
  6
          heap[child/2] = swap;
                                        // and then ...
  7
           child = child/2;
                                        // become the parent
  8
        }
  9
        return;
 10 }
```

Example

We'll make a heap by <u>inserting</u> the keys **m**, **t**, **h**, **q**, **a** and **k**

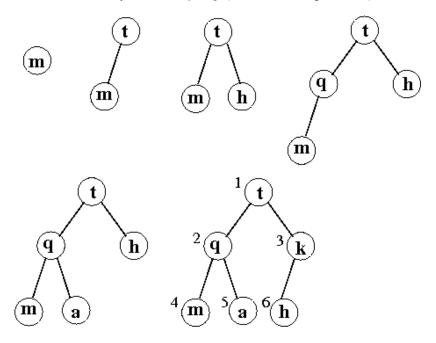
- 1. Start with an empty heap. Make the first node **m** the root node (see diagram below)
- 2. Add **t**
 - o Completeness: tree is a root node with left child
 - Heap-Order violated?
 - yes, need to *fix up* (which will swap **t** and **m**)
- 3. Add **h**
 - o Completeness: add to next available position
 - Head-Order violated?
 - no
- 4. Add **q**
 - o Completeness: add to next available position
 - o Heap-Order violated?
 - yes, need to fix up (which will swap **q** and **m**)
- 5. Add a
 - o Completeness: add to next available position

5 of 10

- Head-Order violated?
 - no

6. Add **k**

- o Completeness: add to next available position
- Head-Order violated?
 - yes, need to fix up (which will swap **k** and **h**)



Items inserted in order: m t h q a k

Delete the maximum element

This operation if often referred to as:

- delMax if it is a max-heap or
- delMin if it is a min-heap

If we were deleting a leaf node, it is 'easy' in general

• the parent node simply deletes the link to the child

Deleting the root node, which usually has children, is difficult

• what do you do with the children?

To delete the maximum element, we must delete the root node of the heap.

The function carries out 4 steps:

- 1. generally the function returns the node that is deleted
 - o so save the root node into a temporary variable
 - o put the last element in the heap into the root position (index 1)
 - which is the bottom-most, rightmost element in the heap
 - which is the last element in the array
 - \blacksquare the array is of size n, so location of last element is n
 - the heap order property (HOP) must now be broken

2. delete the last element

- o this can be done by just changing the size of the heap
- o deleting the last element means the CTP is maintained

3. fixDown from the root

o this ensures the HOP is restored

4. return the saved root node

o this was saved in the first step and is now returned

Code to implement this is quite simple:

```
切换行号显示

1 int delMaxHeap(int *heap, int len) {
2 int retval = heap[1];  // remember the root
3 heap[1] = heap[len];  // replace the root
4 fixDown(heap, 1, len-1);  // fixDown, heap now has length
'len-1'
5 return retval;
6 }
```

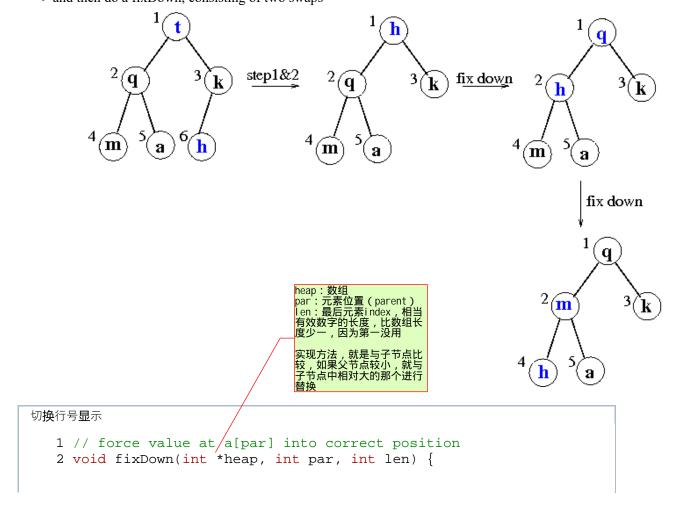
fixDown

- also called heapify down
- if a node is smaller than either of its children, swap with the largest child
 - o means simply to move a key to its correct place downwards in the heap
- has complexity O(log(N)) because that is the height of the heap

Example

When we delete the root element in the next example, we:

- over-write the root with the bottom-right element
- and then do a fixDown, consisting of two swaps



```
3
        int finished = 0;
   4
        while (2*par<=len && !finished) {// as long as you have a
child
   5
           int child = 2*par;
                                          // the first child is here
   6
           if (child<len && heap[child]<heap[child+1]) {</pre>
   7
              child++;
                                         // choose larger of two
children
   8
           if (heap[par]<heap[child]) {// compare parent with</pre>
largest child
              int swap = heap[child];
                                         // if parent<child, do a
swap
  11
              heap[child] = heap[par];
  12
              heap[par] = swap;
              par = child;
                                          // ... and become this child
  13
  14
                                          // if parent>child we are
  15
           else {
finished
  16
              finished = 1;
  17
  18
  19
        return;
  20 }
```

Why do we need to swap with the largest child in a fixDown()?

- consider the following case
 - o if we were to swap with the smallest of the children when we fixDown() then we get

```
e a c
/ \ step / \ swap / \
d c ====> d c ===> d a
/ \ 1&2 / a&c /
b a b b
```

- the resulting tree is not a heap
 - c is larger than a but it is smaller than d
- o what we should have done is swap with the largest child

```
d
                                                           d
     е
                       а
           step
                             swap
                                                swap
  d
           ====>
                     d
                             ====>
                                                ====>
                                                        h
           1&2
                             a&d
                                                a&b
b
                  b
                                     b
                                                      а
```

- because the largest child becomes the parent, it is guaranteed to not affect the other path
 - simply because the largest child by definition is larger than the other child

Animation of heap insertion/deletion

Somewhat slow 10 minute summary of insertion/deletion

Comparing heaps with 'normal' arrays

Suppose that we are interested in quickly doing operations:

- inserting elements into an array and
- deleting the maximum element (or minimum element) in an array

How does having elements in a heap (array) compare with having them in 'normal' arrays?

- a. If the array is unordered:
 - \circ we can insert items to the array in O(1) time (just add it to the end of the array)
 - o to get the maximum item, we must do a linear search: this is O(n)
- b. If the array is ordered:
 - we can insert items to the array in **O(n)** time if we use linear search (need to find the place to insert the item)
 - (or O(log(n)) time if we use binary search)
 - \circ to get the maximum item, we just return the last item: O(1) time
- c. If the array has heap-order:
 - o we can insert items in $O(\log(n))$ time
 - we can get the maximum item in $O(\log(n))$ time

So both operations are fast with heaps.

With ordered and unordered arrays, then you will suffer O(n) performance (which is very slow) in one of the operations (assuming you do not use binary search)

Converting an arbitrary array into a heap

If you already have an array of data, you can convert that into a max-heap (or min-heap) *in-place*, using 2 methods:

- 1. use fixUp() or
- 2. use fixDown()

All that these functions do is rearrange the data so that the elements satisfy HOP.

Example: consider the character array *heap[] = "roses"*

• represented as a heap we get

which clearly is not a heap. There are 2 methods to make it a heap.

- Method 1: use **fixUp()**
 - o we build the heap by inserting them one at a time
 - i.e. we fixUp from 1 to n

- the array contains ssreo, which satisfies the HOP
- actually, fixUp() of location 1 does nothing because ... why?
- so we could have done fixUp() from just 2 to n
- Method 2: use **fixDown()**
 - we consider each character in reverse order, and 'insert' into a heap using fixDown()
 - i.e. we fixDown() from n to 1

r r s

- the elements in the array *srseo* satisfy HOP
- actually, fixDown() from n up to n/2+1 does nothing because ... why?
- so we could have done **fixDown()** from just n/2 to 1

Notice that the heap arrays are different, but both are correct.

Do not get the direction wrong!

- fixUp() from n to 1 does not work!!
 - o example:

- which is not a heap!
- what went wrong?
 - the functions *fixUp()* and *fixDown()* assume that we have heap order before elements are added
 - fixUp() of element 4 did nothing but it is on a path that fails HOP

Heaps (2019-07-09 09:09:34由AlbertNymeyer编辑)