$\mathcal{N} = 4$ SYM Loop Notes

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1 loop review Let's consider a general 1-loop amplitude \mathcal{A}_n^1 with n external momenta p_i^{μ} (i=1,...,n)

$$\mathcal{A}_n^1 = \mathcal{A}_n^1(p_1, ..., p_n) \tag{1}$$

where the n external momenta have the constraints

$$p_i^{\mu} p_{\mu,i} = p_i^2 = 0 \tag{2}$$

$$\sum_{i} p_i^{\mu} = 0 \tag{3}$$

 $\forall i=1,...,n$ Namely, (2) is the "on-shell" condition and (3) is the "conservation of momentum" relation. We can trivially satisfy (3) by introducing dual coordinates (region variables) x_i^{μ} with (i=1,...,n) such that

$$p_i^{\mu} = x_i^{\mu} - x_{i-1}^{\mu} = x_{i,i-1}^{\mu} \tag{4}$$

with $p_1 = x_1 - x_n$. Let's now consider a d-dim Euclidean CFT (defined therefore on \mathbb{R}^d) with conformal group SO(d+1,1) acting non-linearly on \mathbb{R}^d (clearly $\mathbb{R} \ni x^{\mu}$). To linearise the action of the conformal group on \mathbb{R}^d (Dirac) we consider the linear action of SO(d+1,1) on the embedding space $\mathbb{R}^{d+1,1}$ by the embedding of x_i^{μ} to $\mathbb{R}^{d+1,1}$

$$x_i^{\mu} \to X_i^A = (X^+, X^-, x_i^{\mu}) \in \mathbb{R}^{d+1,1}$$
 (5)

with inner product

$$X \cdot X = \eta_{AB} X^A X^B = -X^+ X^- + \eta_{\mu\nu} X^{\mu} X^{\nu} \tag{6}$$

with $\eta_{+-} = \eta_{-+} = -\frac{1}{2}$ and $\eta_{\mu\mu} = 1$

For d=4, the embedding space is $\mathbb{R}^{5,1}$ so X^A , $A=(1,...,dim(\mathbb{R}^{5,1}))=(1,...,6)$, where $X^+=X^0+X^5$ and $X^-=X^0-X^5$. The condition $X\cdot X=X^2=0$ defines an SO(5,1) invariant subspace of 5d, the null-cone, or light-cone. Then, we obtain \mathbb{R}^4 by projectivising the light-cone, that is, by quotienting the light-cone by rescaling $X\sim\lambda X$ with $\mathbb{R}\ni\lambda$. Because projectivising respects Lorentz rotations of the embedding space $\mathbb{R}^{5,1}$, the projective null-cone naturally inherits an action of $SO(5,1)\simeq SO(4,2)$ on the original \mathbb{R}^4 spacetime.

By gauge-fixing the rescaling we can identify the original Eucledian spacetime \mathbb{R}^d with

the projective light-cone. The gauge-fixing condition $X^+=1$ gives light-cone (projective subspace) vectors of the form

$$X = (X^+, X^-, X^\mu) = (1, x^2, x^\mu) \tag{7}$$

 $(x^2 = x^{\mu}x_{\mu})$ In this gauge choice we can see that (not confusing the component of y with its squared length)

$$X \cdot Y = \begin{pmatrix} 1 \\ x^2 \\ x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}^T \begin{pmatrix} 0 & -\frac{1}{2} & 0 & 0 & 0 & 0 \\ -\frac{1}{2} & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ y^2 \\ y^1 \\ y^2 \\ y^3 \\ y^4 \end{pmatrix} = -\frac{1}{2}x^2 - \frac{1}{2}y^2 + x_{\mu}y^{\mu}$$
(8)

Trivially, we see that

$$X \cdot X = X^2 = -\frac{1}{2}x^2 - \frac{1}{2}x^2 + x_\mu x^\mu = -x^2 + x^2 = 0 \tag{9}$$

Moreover, for dual vectors x^{μ} , y^{μ} we can map their squared difference to the projective light-cone, giving

$$(x-y)^2 \to (X-Y)^2 = (X)^2 + (Y)^2 - 2X \cdot Y = -2X \cdot Y = x^2 + y^2 - 2x_\mu y^\mu = (x-y)^2$$
(10)

It is therefore convenient to introduce the product on the projective space

$$(X_i, X_j) = -2X_i \cdot X_j = (x_i - x_j)^2 \tag{11}$$

Thus, we can express products of momenta as products of null vectors, that is vectos that are on the light-cone. For example, taking 4-momentum p_1^{μ}

$$p_2^2 = 0 \mapsto x_{21}^2 = (x_2 - x_1)^2 = 0 \mapsto (X_2, X_1) = 0$$
 (12)

Due to the on-shell constraint, we obtain the relations

$$(X_i, X_{i+1}) = (X_i, X_{i-1}) = 0 (13)$$

Similarly, for a variable momentum l we can assign a dual variable x_0 as $l = x_0 - x_4$ (to ensure momentum conservation). To the dual representation of the loop momentum we then assign then a coordinate on the light-cone as previously. Thus, we map the products as

$$l^2 \mapsto x_{04}^2 \mapsto (X_0, X_4)$$
 (14)

Generally,

$$l_i^2 \mapsto (x_0 - x_i)^2 = x_{0i}^2 \mapsto (X_0, X_i)$$
(15)

Given this embedding, we can express Feynman-integrals on the projective null-cone. The 1-loop n-point integral has the structure

$$I_n = \int \frac{d^4 l P(l)}{D_1 D_2 \cdots D_n} \tag{16}$$

with propagators $D_1, ..., D_n$, which for on shell external momenta exhibits conformal symmetry. Thus, due to the embedding formalism we can use a manifestly conformal representation of the 1-loop integral with a conformal integral defined on the embedding space.

n=4 (box) 1-loop scalar integral The amplitude has the structure

$$\mathcal{A}_4^1 = \mathcal{A}_4^1(p_1, p_2, p_3, p_4) \tag{17}$$

and arises at the first quantum correction of the 4-point boson interaction (with Mandelstam variables s, u).

$$I_4 = \int d^4 l f(l) = \int \frac{sud^4 l}{l^2 (l - p_1)^2 (l - p_1 - p_2)^2 (l + p_4)^2}$$
(18)

By transforming to dual coordinates, we obtain an integral in the x_0 variable (the transformation is linear so has unit Jacobian)

$$\int d^4l \mapsto \int d^4x_0 \tag{19}$$

$$\Rightarrow I_4 = \int \frac{d^4 x_0 x_{13}^2 x_{24}^2}{x_{01}^2 x_{02}^2 x_{03}^2 x_{04}^2}$$
 (20)

Under the dilation transformation

$$x_i^{\mu} \to \lambda x_i^{\mu}$$
 (21)

(with $\lambda \in \mathbb{R}$)

$$\frac{(\lambda^4 d^4 x_0)(\lambda x_1 - \lambda x_3)^2 (\lambda x_2 - \lambda x_4)^2}{(\lambda x_0 - \lambda x_1)^2 (\lambda x_0 - \lambda x_2)^2 (\lambda x_0 - \lambda x_3)^2 (\lambda x_0 - \lambda x_4)^2} = \frac{\lambda^8 d^4 x_0 x_{13}^2 x_{24}^2}{\lambda^8 x_{01}^2 x_{02}^2 x_{03}^2 x_{04}^2} = \frac{d^4 x_0 x_{13}^2 x_{24}^2}{x_{01}^2 x_{02}^2 x_{03}^2 x_{04}^2}$$
(22)

the integrand is invariant. Also, it is invariant under inversion transformation

$$x_i^{\mu} \to \frac{x_i^{\mu}}{x_i^{\mu} x_{\mu i}} = \frac{x_i^{\mu}}{x_i^2}$$
 (23)

$$\frac{\frac{d^4x_0}{x_0^8} \left(\frac{x_1}{x_1^2} - \frac{x_3}{x_3^2}\right)^2 \left(\frac{x_2}{x_2^2} - \frac{x_4}{x_4^2}\right)^2}{\left(\frac{x_0}{x_0^2} - \frac{x_1}{x_1^2}\right)^2 \left(\frac{x_0}{x_0^2} - \frac{x_2}{x_2^2}\right)^2 \left(\frac{x_0}{x_0^2} - \frac{x_3}{x_3^2}\right)^2 \left(\frac{x_0}{x_0^2} - \frac{x_4}{x_4^2}\right)^2} = \frac{\frac{d^4x_0}{x_0^8} \frac{x_{13}^2 x_{24}^2}{x_0^2 x_{13}^2 x_{24}^2 x_{34}^2}}{\frac{x_{11}^2 x_{12}^2 x_{23}^2 x_{24}^2}{x_0^8 x_{12}^2 x_{23}^2 x_{23}^2 x_{44}^2}} = \frac{d^4x_0 x_{13}^2 x_{24}^2}{x_0^2 x_{13}^2 x_{24}^2}$$
(24)

So, the integrand in the dual coordinate representation exhibits conformal invariance. We can therefore use the embedding formalism to embed the integral on the light cone. The conformal integral measure $(X_0^2 = 0)$ becomes

$$\int d^4 l f(l) \mapsto \int d^4 x_0 f(x_0) \mapsto \int \frac{d^6 X_0 \delta(X_0^2)}{Vol(GL(1))} f(X_0)$$
 (25)

Consequently, the 4-pt box scalar integral after embedding on the projective light cone takes the form

$$I_{4} = \int d^{4}lf(l) = \int \frac{d^{4}x_{0}x_{13}^{2}x_{24}^{2}}{x_{01}^{2}x_{02}^{2}x_{03}^{2}x_{04}^{2}} = \int \frac{d^{6}X_{0}\delta(X_{0}^{2})}{Vol(GL(1))} \frac{(X_{1}, X_{3})(X_{2}, X_{4})}{(X_{1}, X_{0})(X_{2}, X_{0})(X_{3}, X_{0})(X_{4}, X_{0})}$$
(26)

So the integral has the structure

$$I_4 = \int \frac{d^6 X_0 \delta(X_0^2)}{Vol(GL(1))} f(X_0)$$
 (27)

Clearly, the integral is invariant under dilation $X_0 \to \lambda X_0$

$$\int \frac{\lambda^6 d^6 X_0 \delta(\lambda X_0^2)}{Vol(GL(1))} f(\lambda X_0) = \int \frac{d^6 X_0 \delta(X_0^2)}{Vol(GL(1))} \frac{\lambda^4}{\lambda^4(X_1, X_0)(X_2, X_0)(X_3, X_0)(X_4, X_0)}$$
(28)

$$\implies \int \frac{\lambda^6 d^6 X_0 \delta(\lambda X_0^2)}{Vol(GL(1))} f(\lambda X_0) = \int \frac{d^6 X_0 \delta(X_0^2)}{Vol(GL(1))} f(X_0) \tag{29}$$

So by embedding the integral on the projective light-cone, we have made the conformal invariance manifest. In other words, we have found a more natural representation that explicitly exhibits the conformal symmetry of the loop integral considered. For planar theories, we can decompose n > 4 loop integrals to a basis of the 4-point integrals discussed in this section. Moreover we can also define an anti-symmetric product on the projective light-cone with

$$\langle X_i X_j X_k X_l X_m X_p \rangle = \varepsilon^{ABCDFG} X_{iA} X_{jB} X_{kC} X_{lD} X_{mF} X_{pG}$$
 (30)

where ϵ^{ABCDFG} is the totally anti-symmetric tensor. This will be used in the next section, for the reduction of the n=5 (and above) 1-loop case.

n=5 (pentagonal) 1-loop integral Let's consider a general 5-point 1-loop amplitude. By transforming to dual coordinates with variable x_0 and general dual vector w we obtain the representation

$$I_5 = \int \frac{d^4 x_0 (x_0 - w)^2}{x_{10}^2 x_{20}^2 x_{30}^2 x_{40}^2 x_{50}^2}$$
(31)

Similarly as before, we can embed to the projective light-cone. Since we are in 6d we can hence write an arbitrary $\mathbb{R}^{5,1} \ni W$ as

$$W = c_1 X_1 + c_2 X_2 + c_3 X_3 + c_4 X_4 + c_5 X_5 + rR = c_i X_i + rR$$
(32)

with $(X_i, R) = 0$ and (R, R) = 1. Then

$$I_{5} = \int \frac{d^{4}x_{0}(x_{0} - w)^{2}}{x_{10}^{2}x_{20}^{2}x_{30}^{2}x_{40}^{2}x_{50}^{2}} \mapsto \mathcal{I}_{5} = \int \frac{d^{6}X_{0}(X_{0}, W)}{Vol(GL(1))(X_{1}, X_{0})(X_{2}, X_{0})(X_{3}, X_{0})(X_{4}, X_{0})(X_{5}, X_{0})}$$
(33)

So

$$\mathcal{I}_{5} = \int \frac{d^{6}X_{0}}{Vol(GL(1))} \frac{c_{i}(X_{0}, X_{i}) + r(X_{0}, R)}{(X_{1}, X_{0})(X_{2}, X_{0})(X_{3}, X_{0})(X_{4}, X_{0})(X_{5}, X_{0})}$$
(34)

The coefficients of the base expansion can be expressed using the anti-symmetric product. For example, we can get c_1 as

$$W = c_1 X_1 + c_2 X_2 + c_3 X_3 + c_4 X_4 + c_5 X_5 + rR$$
(35)

$$\langle WX_2X_3X_4X_5R\rangle = \langle (c_1X_1 + c_2X_2 + c_3X_3 + c_4X_4 + c_5X_5 + rR)X_2X_3X_4X_5\rangle \tag{36}$$

$$\langle WX_2X_3X_4X_5R\rangle = \langle c_1X_1X_2X_3X_4X_5R\rangle \implies c_1 = \frac{\langle WX_2X_3X_4X_5R\rangle}{\langle X_1X_2X_3X_4X_5R\rangle}$$
(37)

Similarly, for c_2

$$\langle WX_1X_3X_4X_5R\rangle = \langle c_2X_2X_1X_3X_4X_5R\rangle \implies c_2 = \frac{\langle WX_1X_3X_4X_5R\rangle}{\langle X_2X_1X_3X_4X_5R\rangle}$$
(38)

Let's consider the c_1 term further with the definition of the anti-symmetric product

$$c_1 = \frac{\langle WX_2X_3X_4X_5R \rangle}{\langle X_1X_2X_3X_4X_5R \rangle} = \frac{\langle WX_2X_3X_4X_5R \rangle \langle X_1X_2X_3X_4X_5R \rangle}{\langle X_1X_2X_3X_4X_5R \rangle \langle X_1X_2X_3X_4X_5R \rangle} =$$
(39)

$$= \frac{\varepsilon^{ABCDFG} W_A X_{2B} X_{3C} X_{4D} X_{5F} R_G \varepsilon_{PQRSTV} X_{1P} X_{2Q} X_{3R} X_{4S} X_{5T} R_V}{\varepsilon^{HJKLMN} X_{1H} X_{2J} X_{3K} X_{4L} X_{5M} R_N \varepsilon_{PQRSTV} X_{1P} X_{2Q} X_{3R} X_{4S} X_{5T} R_V}$$
(40)

Using the product identity for the 6d Levi-Civita tensors

$$\varepsilon^{ABCDFG} \varepsilon_{PQRSTV} = \delta_{PQRSTV}^{ABCDFG} = \begin{vmatrix} \delta_{P}^{A} & \delta_{Q}^{A} & \delta_{R}^{A} & \delta_{S}^{A} & \delta_{T}^{A} & \delta_{V}^{A} \\ \delta_{P}^{B} & \delta_{Q}^{B} & \delta_{R}^{B} & \delta_{S}^{B} & \delta_{T}^{B} & \delta_{V}^{B} \\ \delta_{P}^{C} & \delta_{Q}^{C} & \delta_{R}^{C} & \delta_{S}^{C} & \delta_{T}^{C} & \delta_{V}^{C} \\ \delta_{P}^{D} & \delta_{Q}^{D} & \delta_{R}^{D} & \delta_{S}^{D} & \delta_{T}^{D} & \delta_{V}^{D} \\ \delta_{P}^{F} & \delta_{Q}^{F} & \delta_{R}^{F} & \delta_{S}^{F} & \delta_{T}^{F} & \delta_{V}^{F} \\ \delta_{P}^{G} & \delta_{Q}^{C} & \delta_{R}^{C} & \delta_{S}^{C} & \delta_{T}^{C} & \delta_{V}^{C} \end{vmatrix}$$

$$(41)$$

(42)