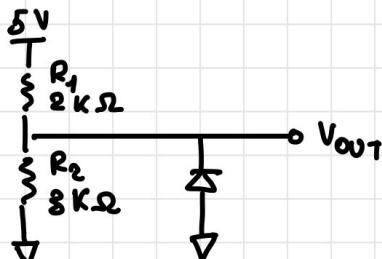
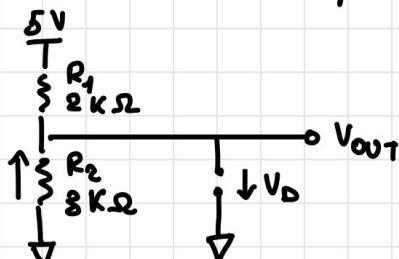


30/09/21
ESEMPIO 1



$$V_{OUT} = ?$$

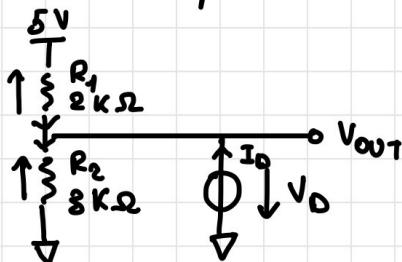
Supponiamo diodo spento e verifichiamo:



$$V_D = -V_{R_2} = -5 \cdot \frac{8\text{k}\Omega}{5\text{k}\Omega} = -8\text{V}$$

$$V_{OUT} = -V_D = 8\text{V}$$

Se avessimo ipotizzato diodo ACCESO avremmo ottenuto:



$$I_D > 0 ?$$

$$V_{R_2} = -V_D = -0,7\text{V}$$

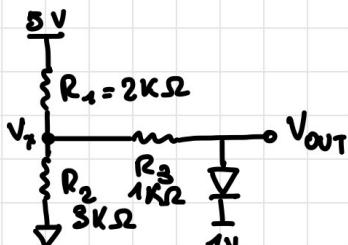
$$I_{R_2} = -0,7\text{V}/3\text{k}\Omega = -0,23\text{mA}$$

$$V_{R_1} = 5\text{V} - V_{R_2} = 5,7\text{V}$$

$$I_{R_1} = 5,7\text{V}/2\text{k}\Omega = 2,85\text{mA}$$

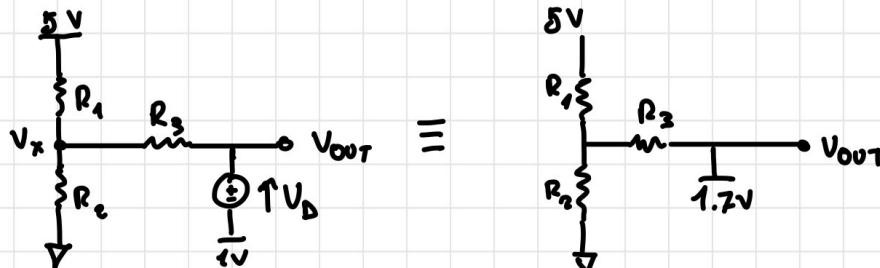
$I_D = -0,23 - 2,85 < 0$!! diodo è spento

ESEMPIO 2



$$V_{OUT} = ? \quad V_x = ?$$

Ipotizziamo diodo acceso:

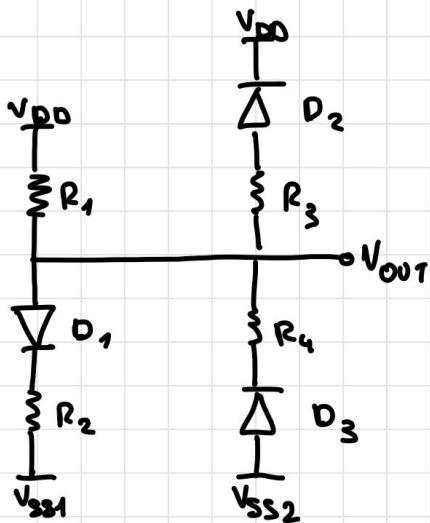


PDI... $\rightarrow I_D = \dots = 0.59 \text{ mA} \rightarrow$ diodo acceso

$$\rightarrow V_{OUT} = \dots = 1.7 \text{ V}$$

$$V_x = \dots = 2.29 \text{ V}$$

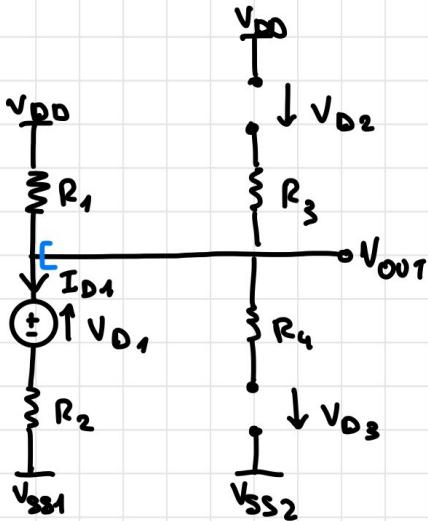
ESERCIZIO 3



$$\begin{aligned}
 V_{DD} &= 3 \text{ V} \\
 V_{SS1} &= -2 \text{ V} \\
 V_{SS2} &= -7 \text{ V} \\
 R_1 &= 1 \text{ k}\Omega \\
 R_2 &= 1.7 \text{ k}\Omega \\
 R_3 &= 4.3 \text{ k}\Omega \\
 R_4 &= 5 \text{ k}\Omega
 \end{aligned}$$

$$V_{OUT} = ?$$

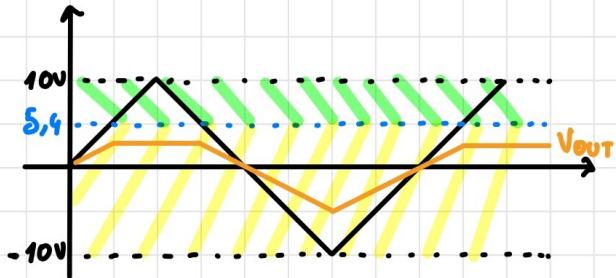
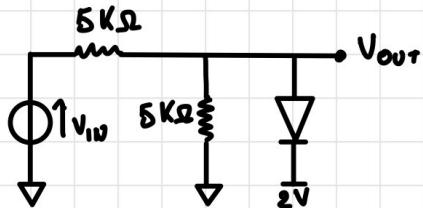
Ipotizziamo
 D1: acceso $\rightarrow I_{D1} > 0$?
 D2: spento $\rightarrow V_{D2} > 0$?
 D3: spento $\rightarrow V_{D3} > 0$?



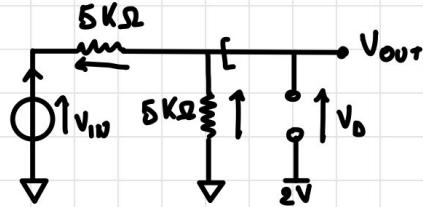
$$\begin{aligned}
 V_{OUT1} &= V_{SS1} + V_{R2} + 0.7V \\
 V_{R2} &= I_D R_2 \\
 V_{R2} + 0.7V + V_{R2} &= 5V \\
 \hookrightarrow V_{R2} + V_{R2} &= 4.7V \\
 \hookrightarrow I_{D1} = 4.7V / (R_1 + R_2) &= 1.59 \text{ mA} \\
 \Rightarrow V_{OUT1} &= \dots = 1.4V
 \end{aligned}$$

$$\begin{aligned}
 V_{D2} &= V_{OUT1} - V_{DD} = \dots = -1.6V \\
 V_{D2} &= V_{SS2} - V_{OUT1} = \dots = -8.4V
 \end{aligned}$$

05/10/2021
ESERCIZIO 1



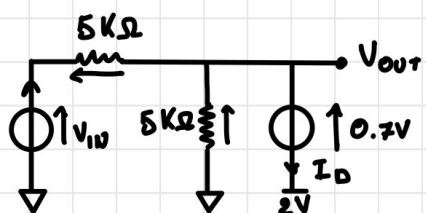
Ipotesi di diodo spento:



$$\begin{aligned}
 V_{OUT1} &= V_{IN}/2 \\
 V_D &= V_{OUT} - 2V = V_{IN}/2 - 2V \\
 V_{IN} &< (0.7V + 2V) \cdot 2 = 5.4
 \end{aligned}$$

$$I_D = 0, \quad I_{R_1} = I_{R_2} = V_{IN}/10\text{k}\Omega$$

Se consideriamo il diodo acceso:



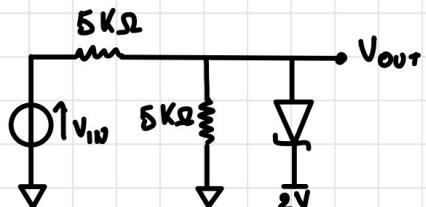
$$V_{R_2} = 2,7 \text{ V} \quad I_{R_2} = R_2 I_{R_2} = 0.54 \text{ mA}$$

$$V_{OUT} = 2,7 \text{ V}$$

$$I_{R_1} = V_{IN} - V_{R_2} / 5 \text{ k}\Omega = V_{IN} - 2,7 / 5 \text{ k}\Omega$$

$$I_D = I_{R_1} - I_{R_2} = \dots = V_{IN} / 5 \text{ k}\Omega - 0.54 \text{ mA}$$

Scriviamo al diodo un diodo zener con $V_{BD} = -2 \text{ V}$
e ricordiamoci i parametri

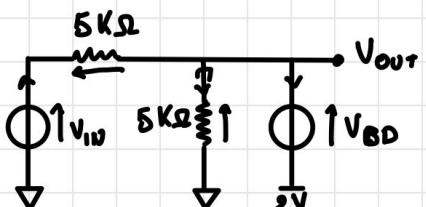


$$\dots$$

$$0 \text{ V} < V_{IN} < 5,4 \text{ V}$$

$$\downarrow$$

breakdown



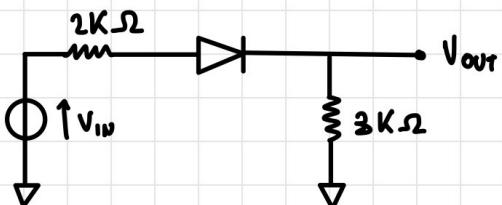
$$V_{OUT} = V_{BD} + 2 \text{ V} = 0 \text{ V}$$

$$I_{R_2} = 0 \text{ A}$$

$$I_{R_1} = V_{IN} / 5 \text{ k}\Omega$$

$$I_{D1} = I_{R_1}$$

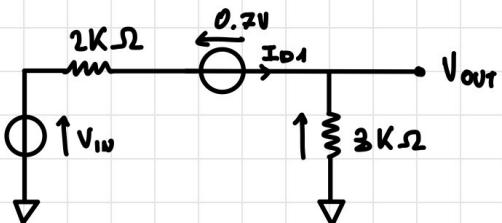
ESERCIZIO 2



$$V_{IN} = 5 \text{ V} \cdot \sin(2\pi f t)$$

$$f = 1 \text{ kHz}$$

Scriviamo diodo acceso:

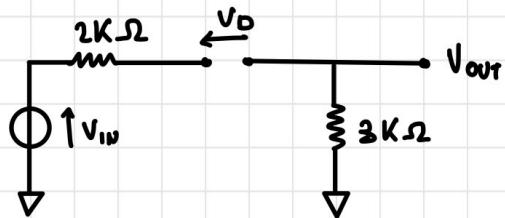


$$I_{D1} = (V_{IN} - 0.7 \text{ V}) / 5 \text{ k}\Omega$$

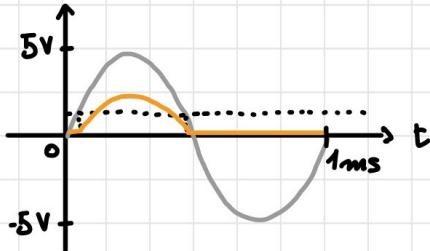
$$I_{D1} > 0 \rightarrow \frac{V_{IN}}{5 \text{ k}\Omega} > \frac{0.7 \text{ V}}{5 \text{ k}\Omega}$$

$$V_{OUT} = \dots = 0.6 V_{IN} - 0.42 \text{ V}$$

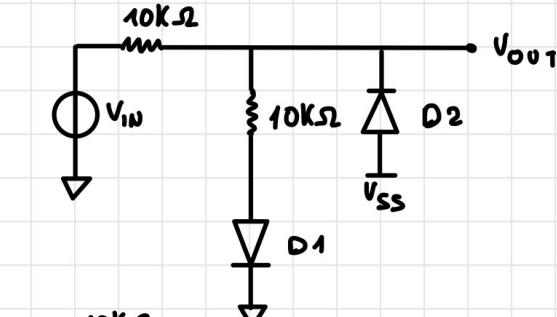
Se il diodo è spento:



$$V_{OUT} = 0 \text{ V}$$



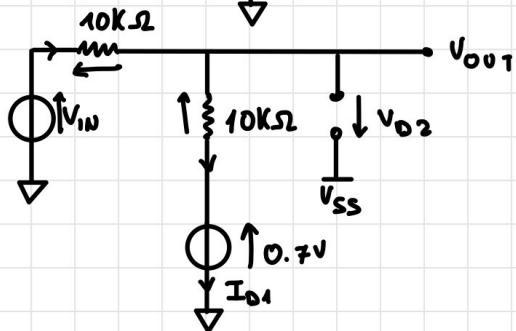
ESERCIZIO 3



$$V_{IN} = 5 \text{ V} \sin(2\pi 1 \text{ kHz} t)$$

$$V_{SS} = -2 \text{ V}$$

IPOTESI: D2 spento
D1 acceso



$$I_{D1} = \frac{V_{IN} - 0.7 \text{ V}}{20 \text{ k}\Omega}$$

$$\hookrightarrow V_{IN} > 0.7 \text{ V per } D_1 \text{ acceso}$$

$$V_{D2} = -2 \text{ V} - V_{OUT}$$

$$= -2 \text{ V} - 0.7 \text{ V} - I_{D1} R_2$$

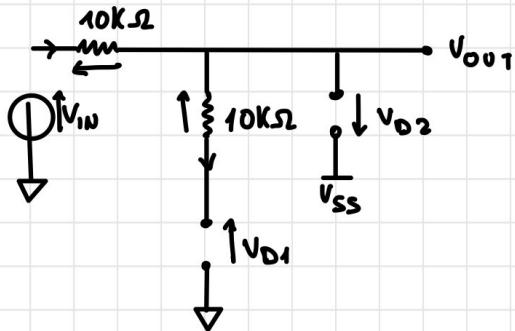
$$= -2.7 \text{ V} - \frac{V_{IN} - 0.7 \text{ V}}{2} / 2$$

$$= -2.35 \text{ V} - \frac{V_{IN}}{2}$$

$$\hookrightarrow V_{IN} > 6.05 \text{ V } \forall V_{IN}$$

$$\Rightarrow V_{IN} > 0.7 \text{ V} \Rightarrow \begin{cases} D_1 \text{ acceso} \\ D_2 \text{ spento} \end{cases} \rightarrow V_{OUT} = 0.35 \text{ V} + \frac{V_{IN}}{2}$$

Se D1 è spento, anche D2 rimarrà spento:

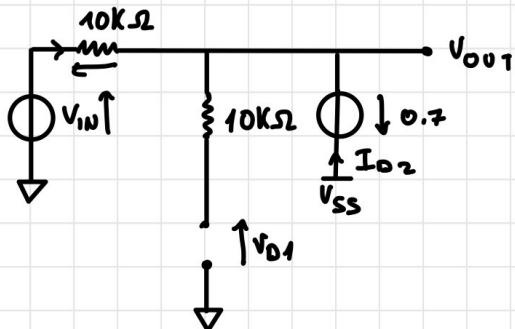


$$V_{D2} = -V_{D1} + V_{SS} = -V_{IN} - 2V$$

$$V_{D1} = V_{IN}$$

$$\begin{cases} V_{IN} < 0.7V \rightarrow V_{OUT} = V_{IN} \\ V_{IN} > -2.7V \end{cases}$$

Per $V_{IN} < -2.7V$ il diodo 2 si accende:

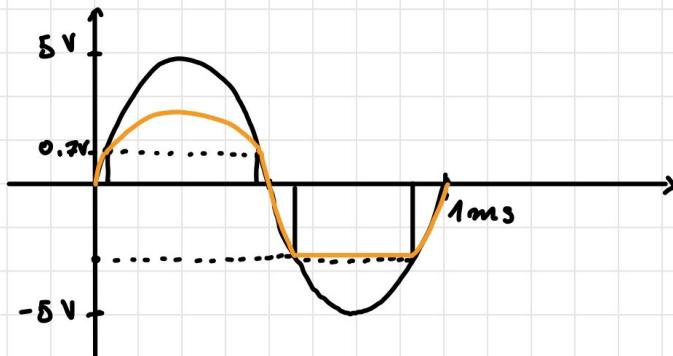


$$V_{OUT} = -2.7V$$

$$I_{D2} = -I_{R_2} = \frac{V_{IN} + 2.7V}{10k\Omega}$$

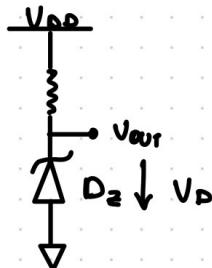
$$\hookrightarrow I_{D2} > 0A \checkmark$$

$$V_{D1} = -2.7V < 0.7V \checkmark$$



12/10/21

ESERCIZIO 1



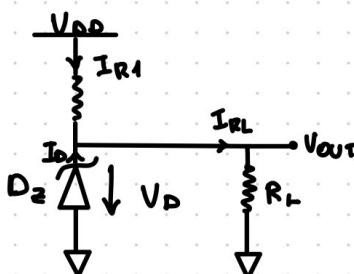
$$V_{DD} = 10V$$

$$R_L = 1K\Omega$$

$$V_{BD} = -5.1V$$

Hip: D_z è spento $V_D = 0 - V_{out} = 0 - V_{DD} = -10V < V_{BD}$
 \Rightarrow non è spento!
 \Rightarrow siamo in BD

$$V_{DDT} = -V_{BD} = 5.1V$$

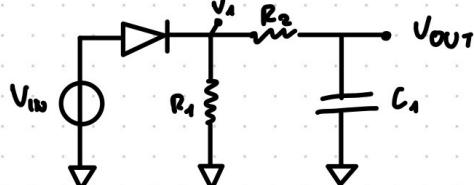


Affinché D_z sia ancora in breakdown
 $I_D < 0$.

$$I_D = I_{RL} - I_{R1} = \frac{5.1}{R_L} - \frac{10V - 5.1V}{1K\Omega} < 0$$

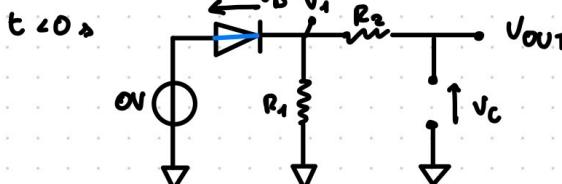
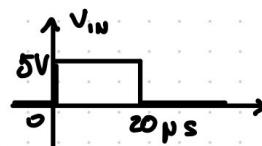
$$\Rightarrow R_L > 1.04 K\Omega$$

ESERCIZIO 2



$$R_1 = R_2 = 10 K\Omega$$

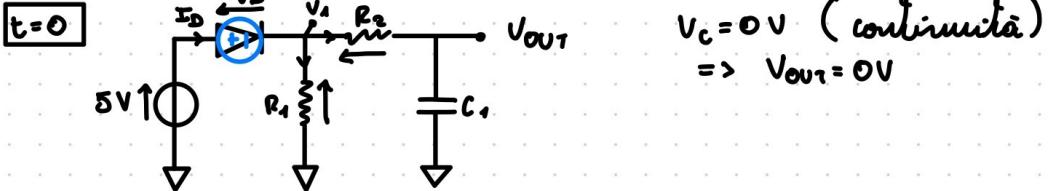
$$C_1 = 1000 pF$$



Hip: diodo spento $\rightarrow V_D = 0V \checkmark$

$$V_{outT} = 0V, V_1 = 0V$$

$$V_C = 0V, i_C = 0V$$



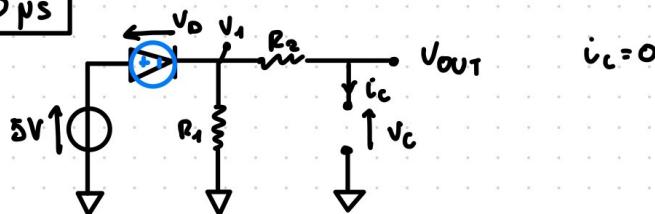
Hp: diodo acceso

$$V_1 = V_{IN} - V_D = 4,3 \text{ V}$$

$$i_C = i_{Z2} = \frac{6,8 \text{ V}}{10K\Omega} = 0,68 \text{ mA}$$

$$i_D = i_{Z1} + i_{Z2} = 0,86 \text{ mA}$$

t = 20 μs



Hp: diodo acceso

$$i_D = i_{Z1} = \frac{V_1}{R_1} = \frac{5 \text{ V} - 0,7 \text{ V}}{R_1} = 0,43 \text{ mA} > 0 \quad \checkmark$$

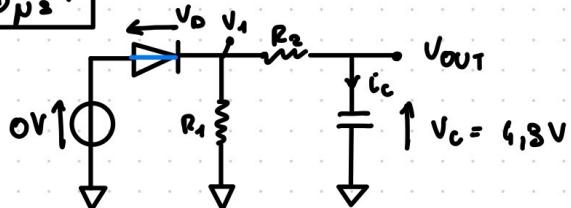
$$V_1 = i_D \cdot 10K\Omega = 4,3 \text{ V}$$

$$V_{OUT} = V_1 = V_C = 4,3 \text{ V}$$

$t = C \cdot R_{eq} = 1000 \text{ nS} = 1 \mu\text{s} \rightarrow 5t < 20 \mu\text{s} \Rightarrow$ circuito è ancora in funzione!

→ spunto diodo e gen.

t = 20 μs +



Hp: diodo spento: $V_D = -V_1 = -V_{OUT} \frac{R_1}{R_1+R_2} = \dots = -2,15 \text{ V} < 0,7 \text{ V} \quad \checkmark$

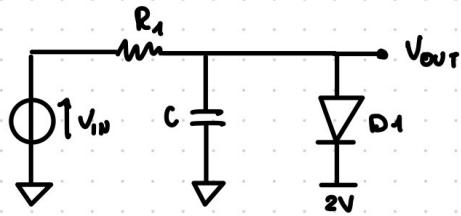
$$i_C = -\frac{2,15}{10K\Omega} = 0,215 \text{ mA}$$

$t = 20 \mu\text{s}$ uguale a $t < 0 \mu\text{s}$

$$t = C \cdot (R_1 + R_2) = 2 \mu\text{s}$$

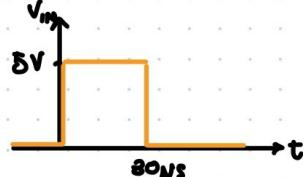
14/10/21

ESERCIZIO 1

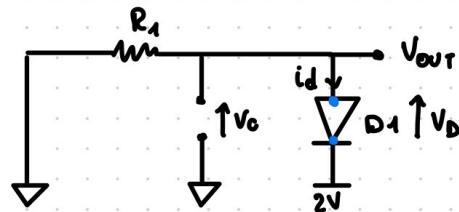


$$R_1 = 7 \text{ k}\Omega$$

$$C_1 = 2 \text{ nF}$$



$t < 0$



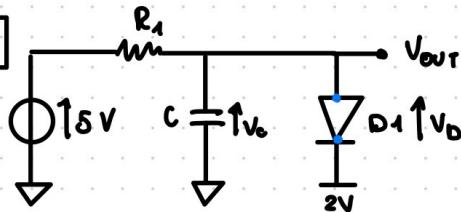
$$V_D < 0.7V ?$$

$$V_D = V_{OUT} - 2V = -2V < 0.7V \quad \checkmark$$

↓

$$V_{OUT} = 0V = V_C$$

$t = 0^+$



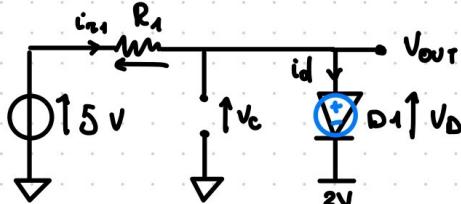
$$V_{OUT} = V_C = 0V$$

Diodo nella stessa situaz.
di $t < 0$

$$\tau = R_1 \cdot C = 14 \mu s \quad \text{con diodo spento!}$$

$t = 80\text{ ns}^-$

Supponendo regime:

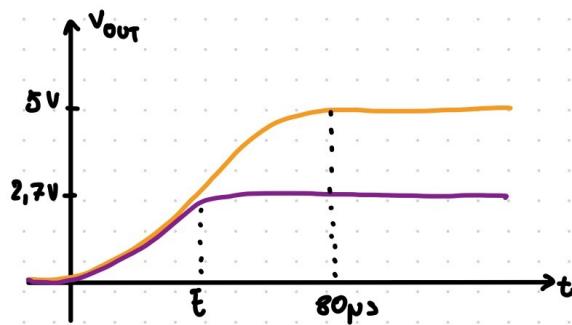


$$i_D > 0 ?$$

$$i_D = i_{C2} = \frac{5V - V_{OUT}}{R_1} = \frac{5V - 2V + 0.7V}{7\text{ k}\Omega} \\ = 0.33 \text{ mA} \quad \checkmark$$

$$V_{OUT} = V_C = 2.7V$$

V_{OUT} tende ai 5V, come visto dall'analisi a regime fornendo al diodo spunto. Quindi il diodo si accenderà pur
 $V_B = V_{OUT} - 2V \geq 0.7V \rightarrow V_{OUT} \geq 2.7V$.



$$V_{OUT} = 5V - 5V e^{-t/14\mu s}$$

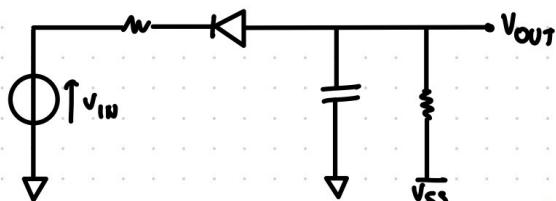
$$V_{OUT}(\bar{t}) = 5V - 5V e^{-\bar{t}/14\mu s} = 2.7V$$

$$\rightarrow \dots \rightarrow \bar{t} = \tau \cdot \ln(5V/2.7V)$$

$$= 10.87 \mu s$$

$$t = 80 \mu s^+ : \quad V_{OUT} = V_C = 2.7 V$$

ESERCIZIO 2

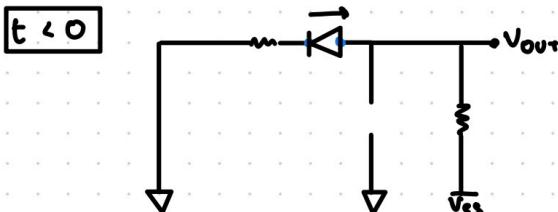


$$V_{ss} = 1V$$

$$R_1 = 7K\Omega$$

$$R_2 = 2K\Omega$$

$$C = 70 nF$$

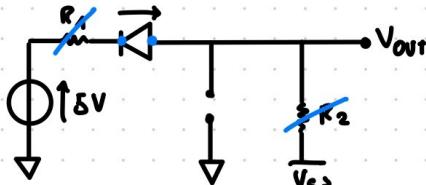


$$V_D = -1V < 0.7V \checkmark$$

$$V_{OUT} = V_C = -1V$$

$$t = 0^+ \quad V_{OUT} = V_C = -1V$$

$t = T^-$ Ipoteremo regime:

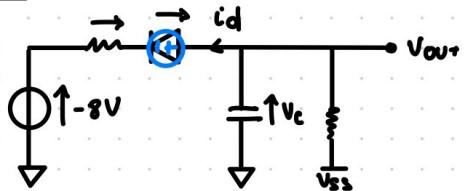


$$V_D < 0.7V ?$$

$$V_D = -1V - 5V = -6V \checkmark$$

$$V_{OUT} = -1V = V_C$$

$$t = T^+ \quad V_{OUT} = -1V = V_0$$

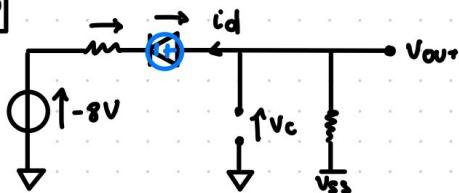


$$I_D > 0 ?$$

$$V_{R1} = -1V - V_{IN} - 0.7 = 6.3V$$

$$I_{R1} = I_D = \dots = 0.3mA \quad \checkmark$$

$$t = +\infty$$



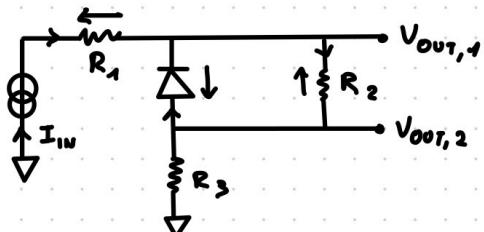
$$I_D > 0$$

$$I_D = \frac{(-8V + 0.7V + 1V)}{R_1 + R_2} = 0.7mA$$

$$V_{OUT} = -1V + V_{R2} = \dots = -2.4V$$

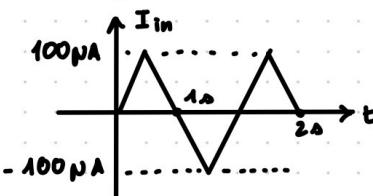
$$\tau = C \cdot \left(\frac{R_1 R_2}{R_1 + R_2} \right) = \dots = 108.83 \mu s$$

ESERCIZIO 3



$$R_1 = 50k\Omega \quad R_2 = 20\Omega$$

$$R_3 = 50k\Omega$$



1. Supponiamo D1 acceso: $I_D > 0$?

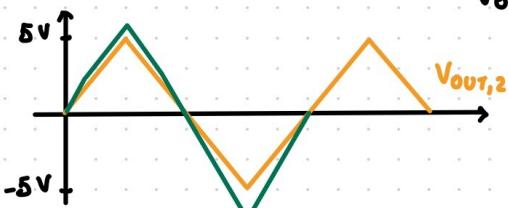
$$I_{R2} = I_{IN} - I_D = \frac{V_{IN}}{R_2} = \frac{0.2V}{20k\Omega} = 35\mu A$$

$$I_D = I_{IN} - 35\mu A > 0$$

$$\rightarrow I_{IN} > 35\mu A$$

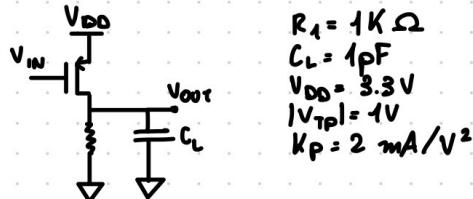
2. Nel caso di D1 acceso: $V_{OUT1,2} = I_{IN} \cdot R_3 = I_{IN} \cdot 50k\Omega$
 $V_{OUT1,1} = V_{OUT1,2} + 0.7V$

Nel caso di D1 spento: $V_{OUT1,2} = I_{IN} \cdot R_2 = I_{IN} \cdot 50k\Omega$
 $V_{OUT1,1} = V_{OUT1,2} + I_{IN} \cdot R_2 = I_{IN} (R_2 + R_3)$
 $= I_{IN} \cdot 70k\Omega$



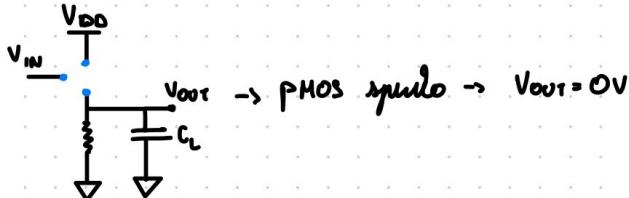
21/10/21

ESERCIZIO 1

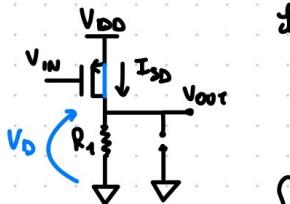


$$\begin{aligned}R_1 &= 1 \text{ k}\Omega \\C_L &= 1 \text{ pF} \\V_{DD} &= 3.3 \text{ V} \\|V_{TP}| &= 1 \text{ V} \\K_P &= 2 \text{ mA/V}^2\end{aligned}$$

$$V_{IN} = 3.3 \text{ V}$$



$$V_{IN} = 0 \text{ V}$$



Sappiamo phos saturato:

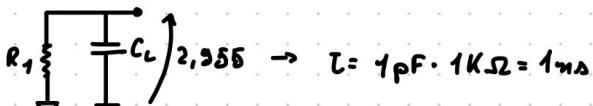
$$\begin{aligned}I_{SD} &= |K_P| (V_{SG} - |V_{TP}|)^2 = \dots = 10.58 \mu\text{A} \\V_{OUT} &= R_1 \cdot I_{SD} = 10.58 \text{ V} \times \rightarrow \text{uscita impossibile!} \\&\rightarrow \text{HDS omicrona}\end{aligned}$$

$$\begin{cases} I_{SD} = 2 |K_P| [(V_{SG} - |V_{TP}|) \cdot V_{SD} - \frac{V_{SD}^2}{2}] \\ I_{SD} = V_D / R_1 \end{cases}$$

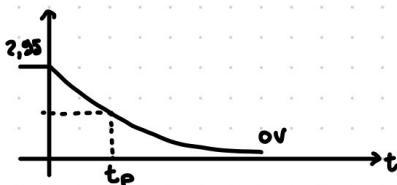
$$\begin{aligned}\rightarrow V_D / 1 \text{ k}\Omega &= 2 \cdot 2 \text{ mA/V}^2 \cdot [2.3 \text{ V} \cdot (3.3 - V_D) - (3.3 - V_D)^2 / 2] \\ \rightarrow \dots \rightarrow V_D &= \underbrace{-1.455 \text{ V}}_{2.955 \text{ V}} \times \text{VOUT non può essere negativa}\end{aligned}$$

$$\Rightarrow V_{OUT} = V_D = 2.955 \quad V_{SD} = 0.345 \text{ V} < V_{SG} - |V_{TP}| = 2.3 \text{ V} \quad \checkmark$$

Per $\underset{t=0}{\text{square wave}}$, calcoliamo il tempo di commutazione:



$$\begin{aligned}V_{OUT} &= 2.95 \cdot e^{-t/\tau} \\&\rightarrow 1.48 = 2.95 e^{-t_p/t} \Rightarrow t_p = \dots = 0.63 \text{ ms}\end{aligned}$$



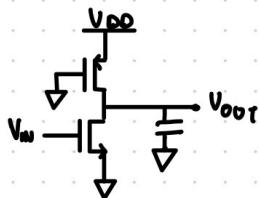
La polarizzazione statica sarà:

$$\begin{array}{l} V_{IN} = 3,3 \text{ V} \\ V_{IN} = 0 \text{ V} \end{array}$$

$$I_{SO} = 0 \rightarrow P = 0 \text{ W}$$

$$I_{SD} = 2,35 \text{ A} \rightarrow P = V_{DD} \cdot I_{SD} = 3,735 \text{ mW}$$

ESERCIZIO 2



$$|K_P| = \frac{1}{2} N_p C_{ox} \frac{W}{L} = 200 \text{ nA/V}^2$$

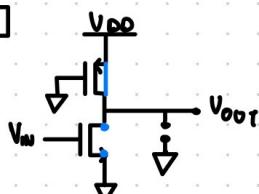
$$K_n = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} = 50 \text{ nA/V}^2$$

$$V_{TN} = |V_{TP}| = 1 \text{ V}$$

$$V_{DD} = 5 \text{ V}$$

$$C_L = 1 \text{ pF}$$

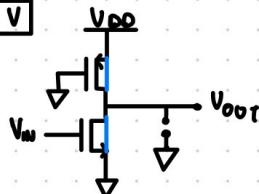
$$V_{IN} = 0$$



$V_{SG,P} = 5 \text{ V} > |V_{TP}| \rightarrow \text{PMOS acceso}$
 $V_{GS,N} = 0 \text{ V} < V_{TN} \rightarrow \text{NMOS spento}$

poiché PMOS vede 2 CA, la $V_{SD,P} = 0$ e quindi
 $V_{OUT} = V_{DD} = 5 \text{ V}$

$$V_{IN} = 5 \text{ V}$$

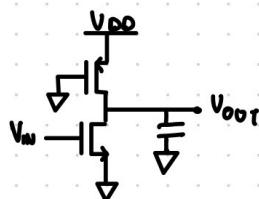


$V_{SG,P} = 5 \text{ V} > |V_{TP}| \rightarrow \text{PMOS acceso}$
 $V_{GS,N} = 5 \text{ V} > V_{TN} \rightarrow \text{NMOS acceso}$

$V_{OUT} = 0 \text{ V}$ poiché è la tensione ai capi di un CC

26/10/21

ESERCIZIO 1



$$|K_P| = \frac{1}{2} N_p C_{ox} \frac{W}{L} = 200 \text{ nA/V}^2$$

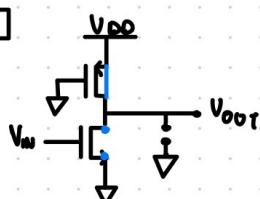
$$K_n = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} = 50 \text{ nA/V}^2$$

$$V_{TN} = |V_{TP}| = 1 \text{ V}$$

$$V_{DD} = 5 \text{ V}$$

$$C_L = 1 \text{ pF}$$

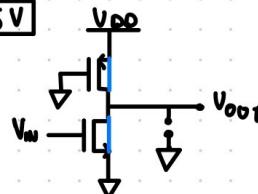
$$V_{IN} = 0$$



$V_{SG,P} = 5 \text{ V} > |V_{TP}| \rightarrow \text{PMOS acceso}$
 $V_{GS,N} = 0 \text{ V} < V_{TN} \rightarrow \text{NMOS spento}$

poiché PMOS vede 2 CA, la $V_{SD,P} = 0$ e quindi
 $V_{OUT} = V_{DD} = 5 \text{ V}$

$V_{IN} = 5V$



$V_{GS,P} = 5V > |V_{TP}| \rightarrow PMOS acceso$
 $V_{GS,N} = 5V > V_{TN} \rightarrow NMOS acceso$

$V_{OUT} = 0V$ poiché è la tensione ai capi di un CC

Dimensionare w/L del NMOS affinché con $V_{IN} = 5V$ si abbia $V_{OUT} = 0,5V$.

$$V_{IN} = 5V \rightarrow \begin{cases} V_{GSN} = 5V \\ V_{SDP} = 0V \end{cases} \rightarrow V_{GSN} = 5V > V_{TN} = 1V$$

$$V_{OUT} = 0,5V \rightarrow V_{DSN} = 0,5 < V_{GSN} - V_{TN} = 4V \rightarrow \text{OHMICO}$$

$$\rightarrow V_{SDP} = 4,5 > V_{SGP} - |V_{TP}| = 4V \rightarrow \text{SATURAZ.}$$

$$I_{SDP} = |K_P| (V_{SGP} - |V_{TP}|)^2 = \dots = 3,2 \text{ mA}$$

$$I_{DSN} = I_{SDP} = 2 K_N [(V_{GSN} - V_{TN}) V_{DSN} - \frac{V_{DD}^2}{2}]$$

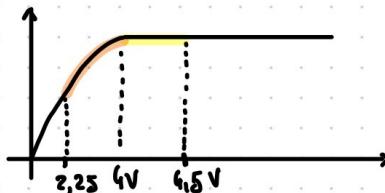
$$\rightarrow K_N = \dots = 853,33 \text{ } \mu\text{A/V}^2$$

$$\Rightarrow w/L = K_N/K'_N = \dots = 17$$

Nel caso in cui V_{IN} varia istantaneamente da 5V a 0V, calcolare il tempo di propagazione.

$$V_{OUT}(V_{IN} = 5V) = 0,5V$$

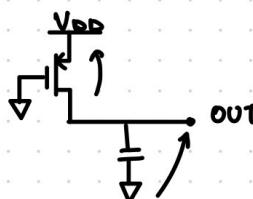
$$V_{OUT}(V_{IN} = 0V) = 5V$$



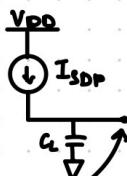
T_p è il tempo da $V_{OUT} = 0,5V$ a $V_{OUT} = 2,75V$.

$$V_{SDP}(0,5V) = 4,5V$$

$$V_{SDP}(2,75V) = 2,25V$$

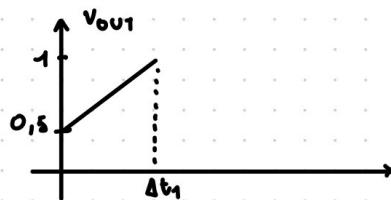


1) SATURAZIONE

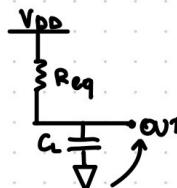


$$I_C = C \cdot \frac{dV_O}{dt} \rightarrow I_{SDP} = C \frac{dV_O}{dt} \rightarrow \text{curr. costante}$$

$$\rightarrow \Delta t_1 = C \Delta V_{OUT} / I_{SDP} = \dots = 1,56 \text{ ns}$$

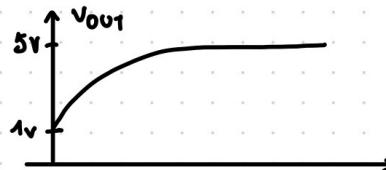


2) OHMICO



$$R_{eq} = \dots = 1,25 \text{ k}\Omega$$

$$\tau = C_L R_{eq} = 12,5 \text{ ns} \rightarrow V_{OUT} = 4 \text{ V} (1 - e^{-t/\tau}) + 1 \text{ V}$$



$$\rightarrow 5 \text{ V} - 4 \text{ V} e^{-\Delta t_2/\tau} = 2,75 \text{ V} \rightarrow \dots \rightarrow \Delta t_2 = \dots = 7,15 \text{ ns}$$

$$\Rightarrow t_p = \dots = 8,75 \text{ ns}$$

Calcolare la potenza statica dissipata.

$$V_{IN} = 0 \text{ V} \rightarrow P = 0 \text{ W}$$

$$V_{IN} = 5 \text{ V} \rightarrow P = V_{DD} \cdot I_{SDP} = 16 \text{ mW}$$

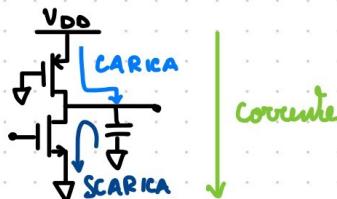
Calcolare la potenza dinamica data un'onda quadra con periodo 1 ns e duty-cycle 50%.

$$V_{IN} : \begin{cases} 5 \text{ V} \\ 0 \text{ V} \end{cases}$$

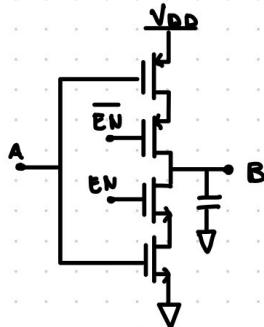
$$V_{OUT} : \begin{cases} 0,5 \text{ V} \\ 5 \text{ V} \end{cases}$$

$$E = \Delta Q \cdot V_{DD} = C_L \Delta V_{OUT} \cdot V_{DD}$$

$$\hookrightarrow P = \frac{E}{T} = \dots = 225 \text{ nW}$$



ESERCIZIO 2



$$K_P = 380 \text{ nA/V}^2$$

$$K_N = 580 \text{ nA/V}^2$$

$$V_{TN} = |V_{TPI}| = 1V$$

$$V_{DD} = 5V$$

$$C_L = 4pF$$

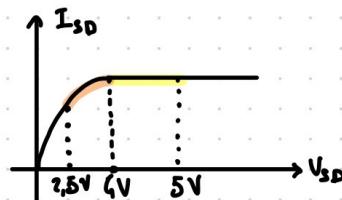
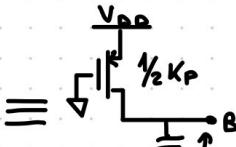
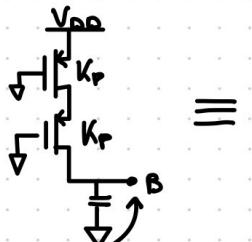
A	EN	B
0	0	H _Z
0	1	A
1	0	H _Z
1	1	A

Calcolare il tempo di propagazione con $A=0$ e $EN=0 \rightarrow 1$

$$A=0; EN=0 \rightarrow B=H_Z$$

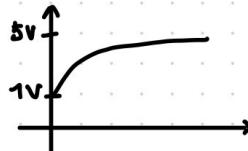
$$A=0; EN=1 \rightarrow B=1$$

(non ci serve nulla da calcolare nemmeno)



1) SATURAZIONE: $\Delta t_1 = C_L \Delta V_{out} / I_{SDP} = 1,31 \text{ ns}$
 $I_{SDP} = 1 K_{eq} (V_{SG} - V_{TPI})^2 = 3,04 \text{ mA}$

2) OHMICO: $R_{eq} = \frac{4V}{3,04 \text{ mA}} = 1,31 \text{ k}\Omega$
 $\tau = C_L \cdot R_{eq} = 5,24 \text{ ns}$



$$V_{OU1} = 5V - 4Ve^{-\frac{t}{\tau}} \Rightarrow \dots \Rightarrow \Delta t_2 = \dots = 2,46 \text{ ns}$$

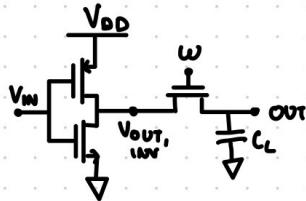
$$\Rightarrow t_p = 3,77 \text{ ns}$$

Calcolare la potenza dinamica quando $EN=1$ e A è un'onda quadra con frequenza 400 KHz

→ come un'invertir: $E = C_L \Delta V_{out} V_{DD} = C_L V_{DD}^2$
 $P = E \cdot f = C_L V_{DD}^2 f = 40 \mu W$

28/10/21

ESERCIZIO 1



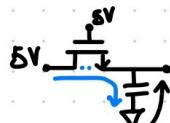
$$K_N = |K_P| = 1 \text{ mA/V}^2$$

$$V_{TN} = |V_{TP}| = 1 \text{ V}$$

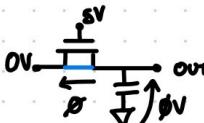
$$V_{DD} = 5 \text{ V}$$

$$C_L = 1 \text{ pF}$$

$$\begin{cases} W=1 \\ V_{IN}=0 \end{cases} \rightarrow \begin{cases} V_{OUT, INV} = 5 \text{ V} \\ V_{OUT} = 5 \text{ V} - V_{TN} = 4 \text{ V} \end{cases}$$



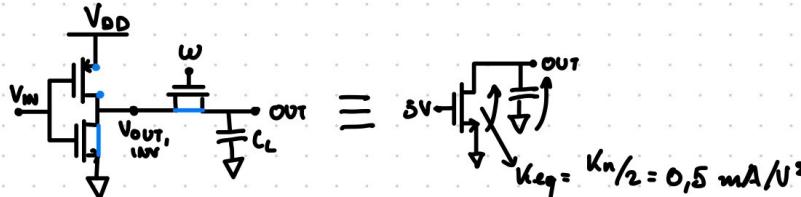
$$\begin{cases} W=1 \\ V_{IN}=1 \end{cases} \rightarrow \begin{cases} V_{OUT, INV} = 0 \\ V_{OUT} = 0 \end{cases}$$



Calcolare il tempo di propagazione con $W=1$ e $V_{IN}=0 \rightarrow 1$

$V_{OUT} = 4 \text{ V} \rightarrow 0 \text{ V}$ attraverso il condensatore

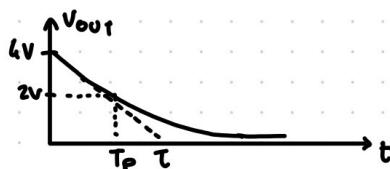
Con $V_{IN}=1$, $W=1$:



$V_{DS} = V_{OUT} \in [0; 4 \text{ V}] \Rightarrow$ tutto in regione ohmica

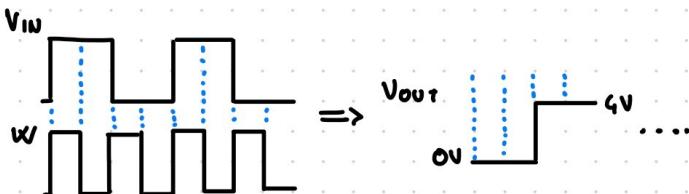
$$R_{EQ} = \frac{V_{GSN} - V_{TN}}{I_{DS,SAT}} = \frac{4 \text{ V}}{0,5 \frac{\text{mA}}{\text{V}^2} \cdot 4 \text{ V}} = 0,5 \text{ k}\Omega$$

$$\Rightarrow T = C_L \cdot R_{EQ} = 0,5 \text{ ns}$$



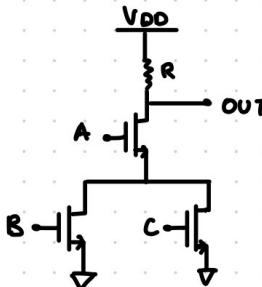
$$V_{OUT} = 4 \text{ V} e^{-t/T_p} \Rightarrow \dots \Rightarrow T_p = 0,34 \text{ ns}$$

Calcolare la potenza dinamica dissipata con V_{IN} e W anch'essere quadri con frequenza $f_V = 1 \text{ MHz}$ e $f_W = 2 \text{ MHz}$ rispettivamente con duty cycle di 50%.



$$E = C_L \cdot \Delta V \cdot V_{DD} = 1 \text{ pF} \cdot 4 \text{ V} \cdot 5 \text{ V} = 20 \text{ pJ} \Rightarrow W = E \cdot f = 20 \text{ pJ} \cdot 1 \text{ MHz} = 20 \mu \text{W}$$

ESERCIZIO 2



$$\begin{aligned} K_N &= 1 \text{ mA/V}^2 \\ V_{TN} &= 1 \text{ V} \\ V_{DD} &= 5 \text{ V} \\ R &= 5 \text{ k}\Omega \end{aligned}$$

Determinare la funzione logica:

A	B	C	OUT
0	0	0	1
0	0	1	1
0	1	0	1
0	1	1	1
1	0	0	1
1	0	1	0
1	1	0	0
1	1	1	0

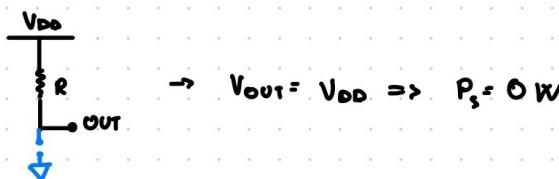
PARALLELO

$$\overline{\text{OUT}} = \underbrace{A \wedge (B+C)}_{\text{SERIE}} \rightarrow \text{estratto dalla PDN}$$

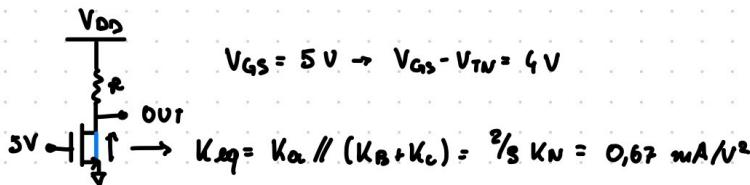
$$\hookrightarrow \text{OUT} = (A \cdot \overline{(B+C)})$$

Calcolare V_{OUT} e la potenza statica quando $A=B=C=1$ e $A=B=C=0$.

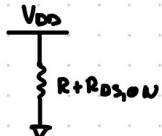
$$A \cdot B \cdot C = 0 :$$



$$A=B=C=1 :$$



Ipotizzeremo regime ohmico:



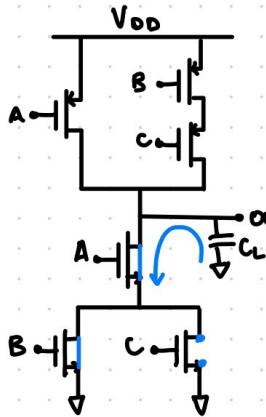
$$R_{DS,ON} = \frac{1}{2} K_N (V_{GS} - V_T) = 0,15 \text{ k}\Omega$$

$$V_{OUT} = V_{DD} \frac{R_{DS,ON}}{R + R_{DS,ON}} = 0,18 \text{ V}$$

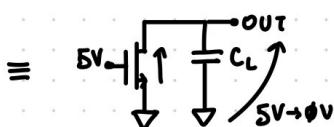
$$V_{DD} = V_{OUT} < V_{GS} - V_{TN} \Rightarrow \text{ipotesi verificata}$$

$$P_S = V_{DD} \cdot I_{DS} = V_{DD} \cdot \frac{V_{DD}}{R + R_{DS,ON}} = \dots = 4,82 \text{ mW}$$

Costruire la PUN a partire dalla PDN. Usando la PUN trovata, calcolare il tempo di propagazione di $A \bar{B} C = 000 \rightarrow 110$ considerando $C_L = 10 \text{ pF}$



$$\begin{aligned} A \bar{B} C = 000 &\rightarrow V_{OUT} = V_{DD} \\ A \bar{B} C = 110 &\rightarrow V_{OUT} = 0 \text{ V} \end{aligned}$$



$$\begin{aligned} K_{eq} &= K_A / K_B = K_N / 2 = 0,5 \text{ mA/V}^2 \\ V_{GS} - V_T &= 4 \text{ V} \\ \hookrightarrow V_{DS} &= V_{OUT} \in [0; 5 \text{ V}] \rightarrow \text{ristretto} \end{aligned}$$

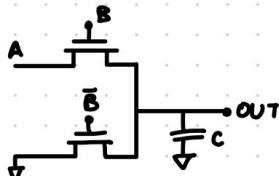
$$\Delta t_1 = \frac{C_L \cdot \Delta V_{OUT}}{I_{DSAT}} = \frac{10 \text{ pF} \cdot 1 \text{ V}}{0,5 \text{ mA/V}^2 \cdot (4 \text{ V})^2} = 1,25 \text{ ns}$$

$$R_{eq} = \frac{V_{GS} - V_{TN}}{I_{DSAT}} = \frac{4 \text{ V}}{0,5 \text{ mA/V}^2 \cdot (4 \text{ V})^2} = 0,5 \text{ k}\Omega \rightarrow T = C_L \cdot R_{eq} = 5 \text{ ns}$$

$$\hookrightarrow V_{OUT} = 4 \text{ V} e^{-\Delta t_2 / T} = 2,5 \text{ V} \Rightarrow \dots \Rightarrow \Delta t_2 = 2,35 \text{ ns}$$

$$\Rightarrow T_P = 3,60 \text{ ns}$$

ESERCIZIO 3



$$\begin{aligned} K_N &= 200 \text{ mA/V}^2 \\ V_{TN} &= 1 \text{ V} \\ V_{DD} &= 3,3 \text{ V} \\ C &= 0,2 \text{ pF} \end{aligned}$$

Determinare la tabella di verità della porta logica specificando i valori di V_{OUT} .

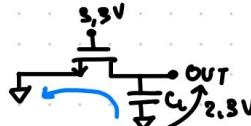
A	B	OUT	V _{DD}
0	0	0	0V
0	1	0	0V
1	0	0	0V
1	1	1	2,3V

$$OUT = AB$$

Calcolare il tempo di propagazione in corso di $AB = 11 \rightarrow 10$.

$$AB = 11 \rightarrow V_{OUT} = 2,3V \Rightarrow$$

$$AB = 10 \rightarrow V_{OUT} = 0V$$



$$V_{GS} = 3,3V \Rightarrow V_{GS} - V_T = 2,3V ; V_{DS} \in [2,3V, 0V] \Rightarrow \text{sempre ohmico}$$

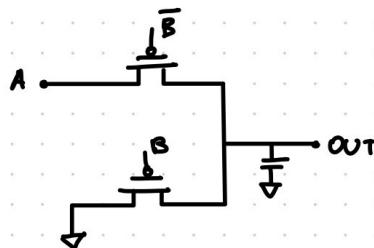
$$\hookrightarrow R_{DS,ON} = V_{GS} - V_T / I_{D,SAI} = \dots = 2,17 k\Omega$$

$$T = C_L \cdot R_{DS,ON} = 0,434 \text{ ns}$$

$$\Rightarrow V_{OUT} = 2,3V \cdot e^{-t_p/T} = 1,15 \Rightarrow t_p = 0,3 \text{ ns}$$

02/11/21

ESERCIZIO 1



$$|K_P| = 200 \text{ mA/V}^2$$

$$|V_{TP}| \approx 1V$$

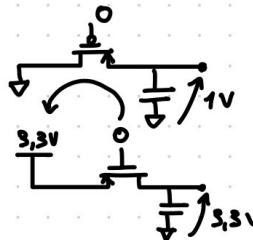
$$V_{DD} = 3,3V$$

$$C = 0,2 \text{ pF}$$

$$A, B \in \{0V; 3,3V\}$$

A	B	OUT
0	0	1V
0	1	1V
1	0	1V
1	1	3,3V

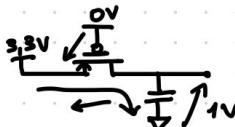
\rightarrow AND



Calcolare il tempo di propagazione con $AB = 01 \rightarrow 11$.

$$AB = 01 \Rightarrow V_{OUT} = 1V$$

$$AB = 11 \Rightarrow V_{OUT} = 3,3V$$



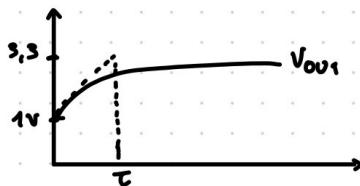
$$V_{SG} = 3,3V \Rightarrow V_{SG} - |V_{TP}| = 2,3V$$

$$V_{SD} = 3,3V - V_{OUT}$$

$\hookrightarrow V_{SD} \in [1,15V; 2,8V] \Rightarrow$ sempre ohmico

$$R_{eq} = \frac{V_{SD} - |V_{TP}|}{|K_P| (V_{SG} - |V_{TP}|)} = \frac{1}{200mA/V^2 \cdot 2,3V} = 2,174k\Omega$$

$$\Rightarrow \tau = R \cdot C = 0,434\text{ ms}$$



$$V_{OUT} = 2,3V (1 - e^{-t/\tau}) + 1V$$

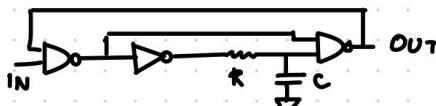
$$= 3,3V - 2,3V e^{-t/\tau}$$

$$\Rightarrow \Delta t = \dots = 0,3\text{ ms}$$

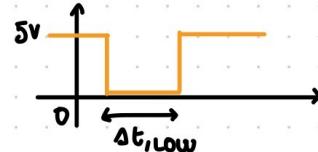
Con A=1 e B un'onda quadra con $T=2\mu s$ e $D=50\%$, calcolare la potenza dinamica.

$$P = \frac{C \cdot \Delta V \cdot V_{DD}}{T} = \frac{0,2 \cdot 2,3 \cdot 3,3V}{2\mu s} =$$

ESERCIZIO 2



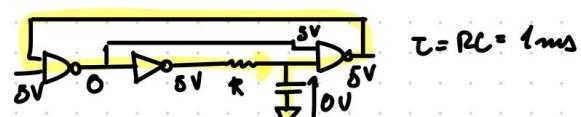
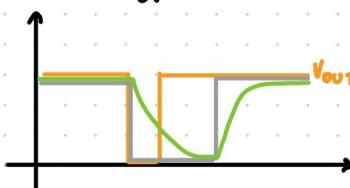
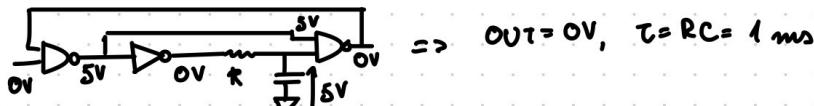
$$R = 100k\Omega \quad C = 10\text{ nF}$$



$$V_{OUT} = ? \text{ con } \Delta t_{LOW} = 1\text{ ms}$$

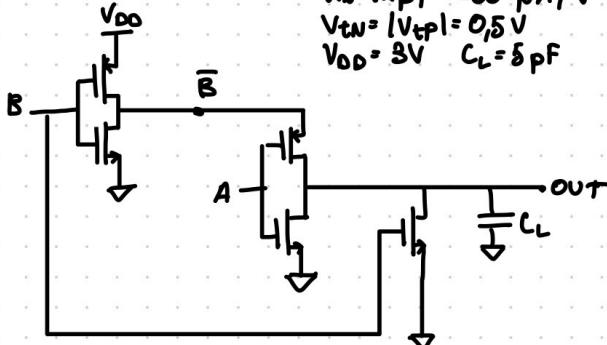
$\hookrightarrow V_{IN} = 5V \dots OUT = 5V, V_C = 5V$

$\hookrightarrow V_{IN} = 5V \rightarrow 0V$



4/11/21

ESERCIZIO 1



$$B=0 \rightarrow V_{OUT} = \bar{A}$$

$$B=1 \rightarrow V_{OUT} = 0$$

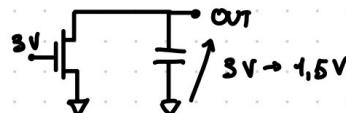
↓		
A	B	
0	0	1
0	1	0
1	0	0
1	1	

\rightarrow NOR

Calcolare il tempo di propagazione della transizione $AB = 00 \rightarrow 11$

$$AB = 00 \rightarrow 11$$

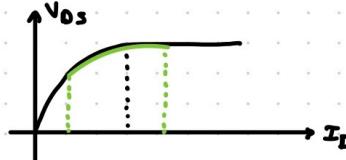
$$3V \rightarrow 0V$$



$$K_{eq} = K_4 + K_5 = 2K_N = 400 \mu A/V^2$$

$$V_{GS} - V_T = 2,5 V$$

$$V_{DS} \in [2,5 V; 3]$$

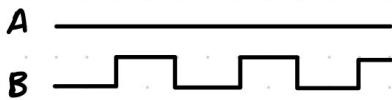


$$1) t_1 = \frac{C \Delta V_{DS}}{I_{D,SAT}} = \dots = 1 \text{ ns}$$

$$2) \tau = C \cdot R_{eq} = C \cdot \frac{1}{K_{eq} (V_{GS} - V_{TN})} = 5 \text{ ns} \rightarrow \dots \rightarrow t_2 = \tau \ln \frac{2,5}{1,5} = 2,55 \text{ ns}$$

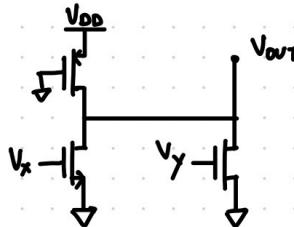
$$\Rightarrow t_p = 3,55 \text{ ns}$$

Calcolare la potenza dinamica dissipata con $A=0$ e B un'onda quadrata con duty cycle 50% e $f = 1 \text{ MHz}$



$$\begin{aligned}
 P &= C_L \cdot \Delta V_{OUT} \cdot V_{DD} \cdot f = 5 \text{ pF} \cdot 3 \text{ V} \cdot 3 \text{ V} \cdot 1 \text{ MHz} \\
 &= 45 \text{ } \mu \text{W}
 \end{aligned}$$

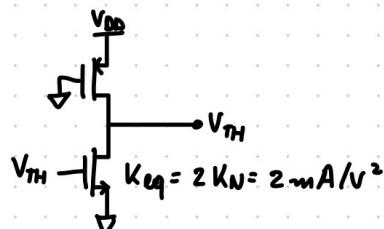
ESERCIZIO 2



$$\begin{aligned} K_N &= 1 \text{ mA/V}^2 \\ |K_P| &= 50 \text{ nA/V}^2 \\ V_{TP} &= 1,2 \text{ V} \\ V_{TN} &= 0,7 \text{ V} \\ V_{DD} &= 3,33 \text{ V} \end{aligned}$$

Calcolare la soglia di commutazione.

$$OUT = V_x = V_y = V_{TH}$$



$$\text{NMOS} \quad \begin{cases} V_{GS} - V_{TN} = V_{TH} - 0,7 \text{ V} \\ V_{DS} = V_{TH} \end{cases} \rightarrow \text{renzu saturato}$$

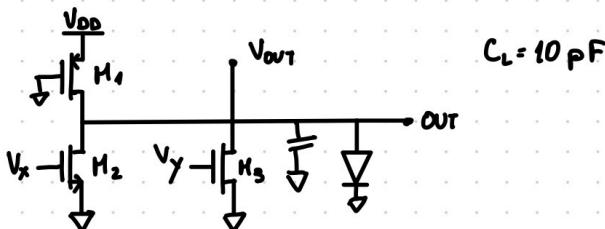
$$\text{PMOS} \quad \begin{cases} V_{SG} - |V_{TP}| = 3,3 \text{ V} - 1,2 \text{ V} = 2,1 \text{ V} \\ V_{SD} = 3,3 \text{ V} - V_{TH} \end{cases}$$

Ipotizzeremo PMOS in saturazione e NMOS in saturazione

$$I_{SD, SAT, P} = I_{SD, SAT, N} \Rightarrow I_{D, SAT, P} = |K_P| (V_{SG} - |V_{TP}|)^2 = 220,5 \text{ mA}$$

$$I_{D, SAT, N} = K_{EQ} (V_{GS} - V_{TH})^2 = 2 \text{ mA/V}^2 (V_{TH} - 0,7)^2$$

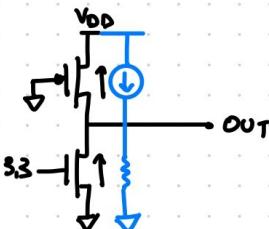
$$\Rightarrow V_{TH} = \sqrt{\frac{220,5 \text{ mA}}{2 \text{ mA}}} + 0,7 = 1,08 \text{ V} \quad \leftarrow \cdot V_{TH} > V_{TN} \quad \checkmark \quad \cdot V_{SD, P} \sim 2,27 \text{ V} > 2,1 \quad \checkmark$$



Calcolare Vout con $V_x = V_y = 3,3 \text{ V} \rightarrow 0 \text{ V}$

$$t=0^-:$$

Ipotizzeremo diodo spento:



Ipotizziamo il PMOS saturato e lo NMOS offerto

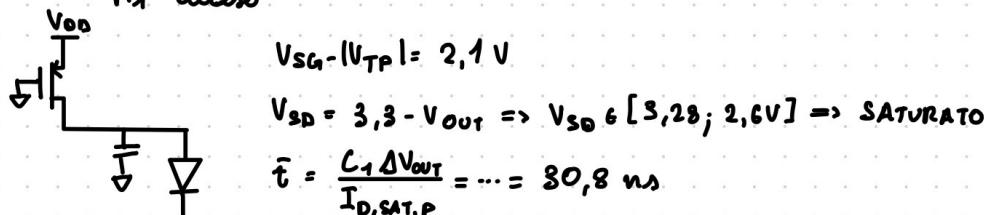
$$I_{D,SAT,P} = \dots = 220,5 \text{ mA}$$

$$R_{DS,ON} = \frac{1}{2} K_{eq} (V_{GS} - V_{TN}) = 96 \Omega$$

$$V_{OUT} = 220,5 \mu\text{A} \cdot 96 \Omega = 20 \text{ mV}$$

- $V_D = V_{OUT} < 0,7 \text{ V}$ ✓
- $V_{SD,P} = 3,3 \text{ V} - 20 \text{ mV} \sim 3,28 \text{ V} > V_{SG} - |V_{TP}|$ ✓
- $V_{DS} = V_{OUT} < V_{GS} - V_{TN}$ ✓

$t \geq 0$: M_2 e M_3 spenti $\rightarrow V_{OUT} \sim 20 \text{ mV} \rightarrow 3,3 \text{ V}$
 M_1 acceso



Calcolare la potenza stativa con $V_x = 0 \text{ V}$ e V_y un'onda quadra con $f = 100 \text{ kHz}$ e duty cycle 50% sia con diodo/capacità collegati che scollegati

C e D scollegati: $V_x V_y = 00 \rightarrow 01$
 $3,3 \text{ V} \rightarrow 40 \text{ mV}$

\downarrow
 M_2 spento e M_1/M_3 accesi

$$\Rightarrow V_{OUT} = I_{D,SAT,P} \cdot R_{DS,ON} = 40 \text{ mV}$$

$$P_{statica}(00) = 0 \text{ W}$$

$$P_{statica}(01) = V_{DD} \cdot I_{D,SAT,P} = 727,65 \text{ nW}$$

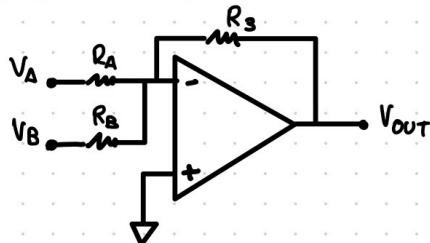
$$P_{statica_media} = 727,65/2 = 363,825 \text{ nW}$$

$$C e D \text{ connessi: } V_x = V_y = 0V \rightarrow 0V \\ 0,7V \rightarrow 40mV$$

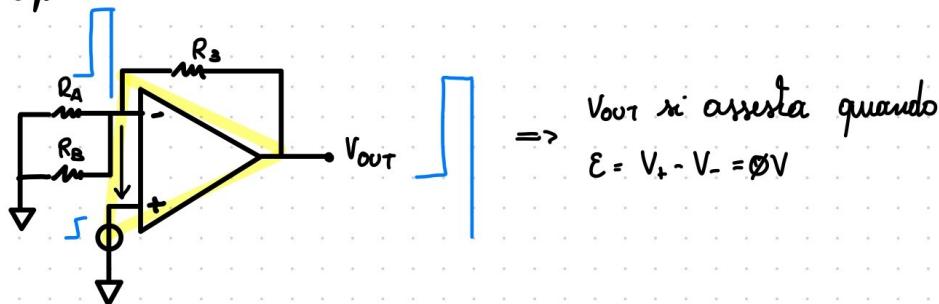
$$P_{\text{statica}}(00) = 727,65 \mu W \rightarrow P_{\text{statica_media}} = 727,65 \mu W \\ P_{\text{statica}}(01) = 727,65 \mu W$$

11/11/21

ESERCIZIO 1

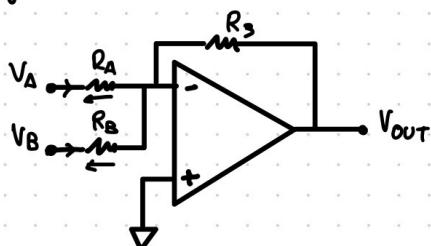


Che tipo di retroazione otteniamo?



V_{out} si arresta quando
 $E = V_+ - V_- = 0V$

Determinare la tensione di uscita V_{out} in funzione dei due ingressi V_A e V_B e della somma



$E = 0$ perché OPAMP works $\Rightarrow V^+ = V^-$

$$i_A = V_A / R_A$$

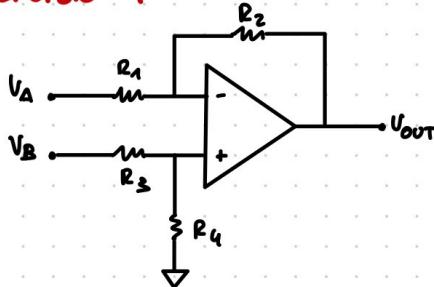
$$i_B = V_B / R_B \Rightarrow i_B = i_A + i_B$$

$$\Rightarrow V_{\text{out}} = -R_3 i_B = R_3 \left(-\frac{V_A}{R_A} - \frac{V_B}{R_B} \right) = R_3 \frac{-R_B V_A - R_A V_B}{R_A R_B}$$

Se $R_A = R_B$ otteniamo che $V_{\text{out}} = (V_A + V_B) \left(-\frac{R_3}{R} \right)$

12/11/21

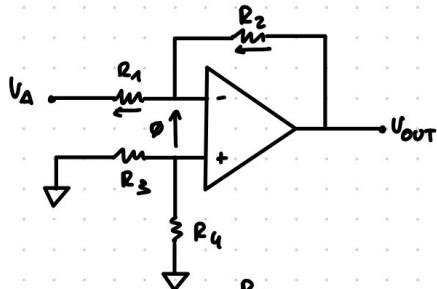
ESERCIZIO 1



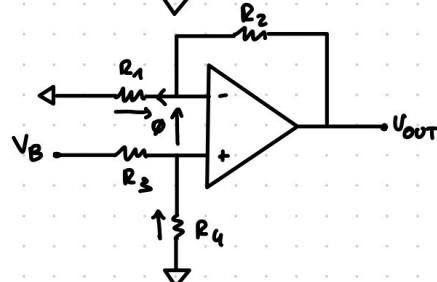
Hp: OPAMP ideal

Determinare V_{OUT} in funzione di V_A e di V_B

Applichiamo la sovrapposizione degli effetti:



$$\text{Var } I_{V_A} = -V_{R2} = -R_2 \cdot (V_{R4}/R_4) = \\ = -\frac{R_2}{R_4} V_A$$

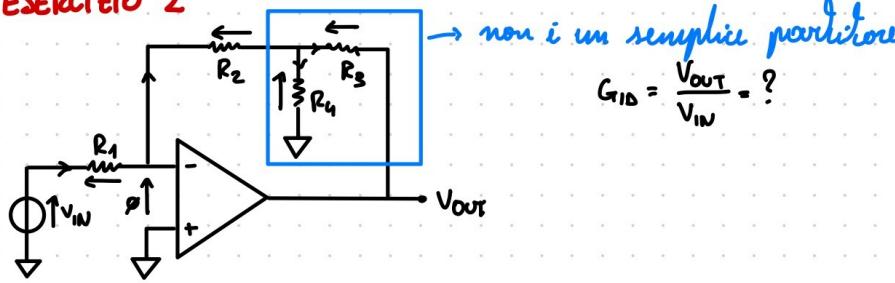


$$V^- = V^+ = V_B \frac{R_4}{R_3 + R_4} = V_{R1} \\ V_{R2} = V_B \frac{R_4}{R_3 + R_4} \frac{R_2}{R_1} \\ \Rightarrow V_{OUT} = V_B \frac{R_4}{R_4 + R_3} \left(1 + \frac{R_2}{R_1} \right)$$

$$\Rightarrow V_{OUT} = -V_A \frac{R_2}{R_1} + V_B \frac{R_4}{R_3 + R_4} \left(1 + \frac{R_2}{R_1} \right)$$

Per leggere V_{OUT} a $V_B - V_A$ basta porre $\frac{R_2}{R_1} = \frac{R_4}{R_4 + R_3} \left(1 + \frac{R_2}{R_1} \right)$

ESERCIZIO 2



$$G_{ID} = \frac{V_{OUT}}{V_{IN}} = ?$$

$$i_{R1} = \frac{V_{IN}}{R_1}$$

$$V_{R2} = \frac{V_{IN}}{R_1} R_2$$

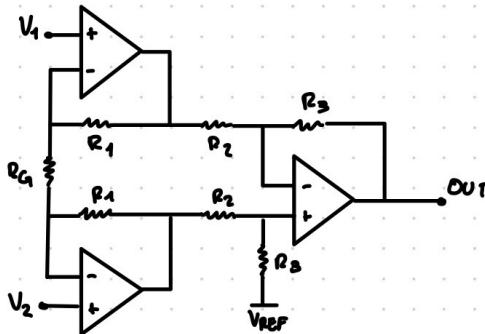
$$V_{R4} = -V_{R2}$$

$$i_{R4} = V_{R4}/R_4 = -\frac{V_{IN}}{R_1} \frac{R_2}{R_4}$$

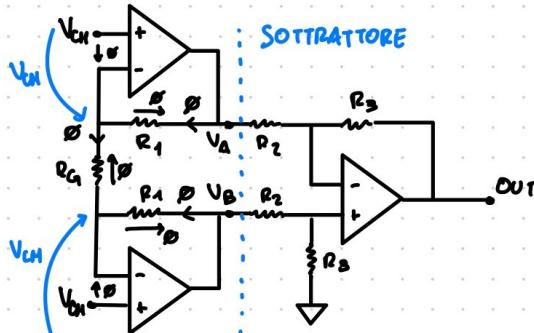
$$i_{R3} = i_{R2} - i_{R4} = \dots = \frac{V_{IN}}{R_1} + \frac{V_{IN}}{R_1} \frac{R_2}{R_4} \Rightarrow V_{OUT} = V_x - V_{R3} = -V_{IN} \frac{R_2}{R_1} - V_{IN} \left(1 + \frac{R_2}{R_4} \right) R_3 \\ = -\frac{V_{IN}}{R_1} \left(R_2 + R_3 + \frac{R_2 R_3}{R_4} \right)$$

15/11/21

ESERCIZIO 1 INSTRUMENTATION AMPLIFIER



Imponendo $V_{REF}=0V$ e $V_1=V_2=V_{CH}$, determinare il guadagno totale.

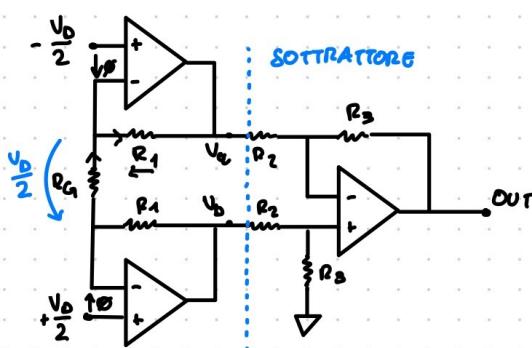


$$V_{OUT} = (V_B - V_A) \frac{R_3}{R_2}$$

$$V_A = V_B = V_{CH} \Rightarrow V_{OUT} = 0$$

$$G_{ID} = 0$$

Considerando $V_{REF} = 0V$ e $V_1 = -\frac{V_D}{2}$, $V_2 = +\frac{V_D}{2}$ determinare il guadagno ideale $G_{ID} = \frac{V_{OUT}}{V_D}$



$$i_{R_G} = \frac{V_D}{R_G}$$

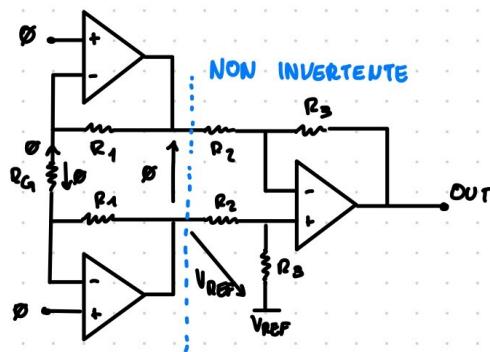
$$V_A = -\frac{V_D}{2} - \left(\frac{V_D}{R_G} R_1 \right)$$

$$V_b = \frac{V_D}{2} + \frac{V_D}{R_G} R_1$$

$$\Rightarrow V_{OUT} = (V_b - V_a) \frac{R_3}{R_2} = \dots = V_d \left(1 + \frac{2R_1}{R_G} \right) \frac{R_3}{R_2}$$

$$\Rightarrow G_{ID} = \left(1 + \frac{2R_1}{R_G} \right) \frac{R_3}{R_2}$$

Considerando $V_1 = V_2 = 0V$, determinare il guadagno $G_{ID} = \frac{V_{OUT}}{V_{REF}}$

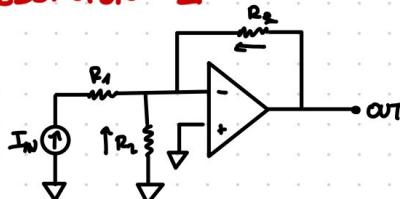


$$V^+ = V_{REF} \frac{R_2}{R_2 + R_3} = V^-$$

$$\begin{aligned} V_{OUT} &= V^- \left(1 + \frac{R_3}{R_2} \right) = V_{REF} \frac{R_2}{R_2 + R_3} \left(1 + \frac{R_3}{R_2} \right) \\ &= V_{REF} \left(\frac{R_2}{R_2 + R_3} + \frac{R_3}{R_2 + R_3} \right) = V_{REF} \end{aligned}$$

$$\Rightarrow G_{ID} = 1$$

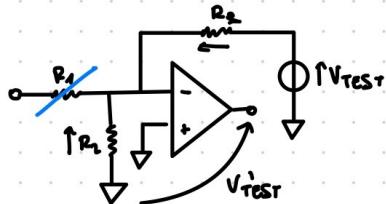
ESERCIZIO 2



Calcolare il trasformatore ideale $T_{ID} = \frac{V_{OUT}}{I_{IN}}$

$$V_{OUT} = -R_2 - V_{R_3} = -R_3 I_{IN} \Rightarrow T_{ID} = -R_3$$

Calcolare il guadagno d'anello:

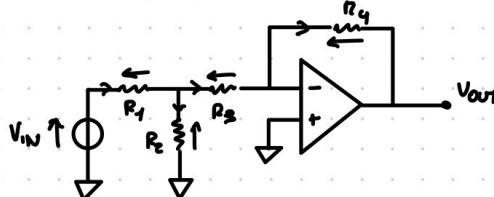


$$V^- = V_{TEST} \frac{R_2}{R_2 + R_3}$$

$$V'_{TEST} = -V^- A_d = -V_{TEST} \frac{R_2}{R_2 + R_3} A_d$$

$$\Rightarrow G_{LOOP} = -\frac{R_2}{R_2 + R_3} A_d$$

ESERCIZIO 3



$$R_1 = R_2 = R_3 = 1 \text{ k}\Omega \quad A_d = 10^5$$

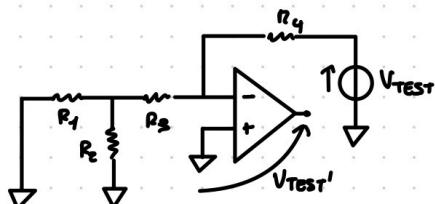
$$R_4 = 12 \text{ k}\Omega$$

Calcolare il G_{REALE} .

$$V_{OUT} = -V_{IN} \frac{R_2 // R_3}{R_2 // R_3 + R_1} - V_{IN} \frac{(R_2 // R_3) R_4}{(R_2 // R_3 + R_1) R_3}$$

$$= -V_{IN} \frac{R_2 // R_3}{R_2 // R_3 + R_1} \left(1 + \frac{R_4}{R_3} \right)$$

$$\Rightarrow G_{ID} = -\frac{R_2 // R_3}{R_2 // R_3 + R_1} \left(1 + \frac{R_4}{R_3} \right) = \dots = -4$$



$$V_{TEST}' = -A_d V^-$$

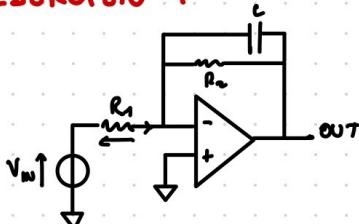
$$= -A_d \left(V_{TEST} \frac{R_1 // R_2 + R_3}{R_1 // R_1 + R_2 + R_3 + R_4} \right)$$

$$\Rightarrow G_{loop} = -A_d \frac{R_1 // R_2 + R_3}{R_1 // R_1 + R_2 + R_3 + R_4} = -11111$$

$$\Rightarrow G_{REALE} = -4 / 1 + 1 / -11111 = -3,8896$$

16/11/21

ESERCIZIO 1



$$R_1 = 5 \text{ k}\Omega$$

$$R_2 = 100 \text{ k}\Omega$$

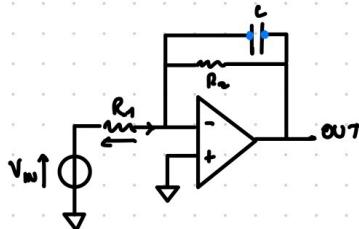
$$C = 1.6 \text{ nF}$$

$$A_0 = 4000$$

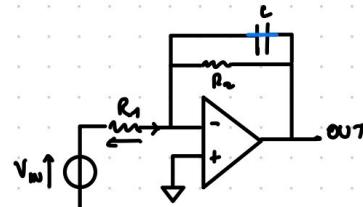
$$GBWP = 320 \text{ KHz}$$

Calcolare i $G_{ID}(s)$ e i relativi diagrammi di modulo e fase

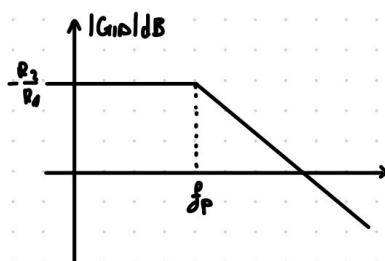
$$V^+ = V^- = 0V \Rightarrow V_{R1} = V_{IN} \quad i_{c_1} = \frac{V_{IN}}{R_1}$$



$$\text{per } s \rightarrow 0 \quad G_{ID}(s) = -\frac{R_2}{R_1}$$



$$\text{per } s \rightarrow +\infty \quad G_{ID}(s) = 0$$



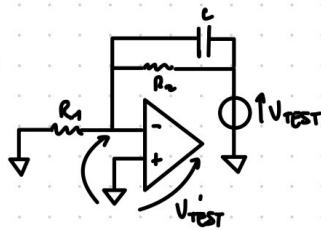
$$V_{out}(s) = -\frac{V_{IN}}{R_1} \left(\frac{1}{sC} \cdot R_2 \right)$$

$$\Rightarrow G_{ID}(s) = -\frac{R_2}{R_1} \frac{1}{1+sCR_2}$$

$$\Rightarrow f_P = \frac{1}{2\pi CR_2} = 1\text{ KHz}$$

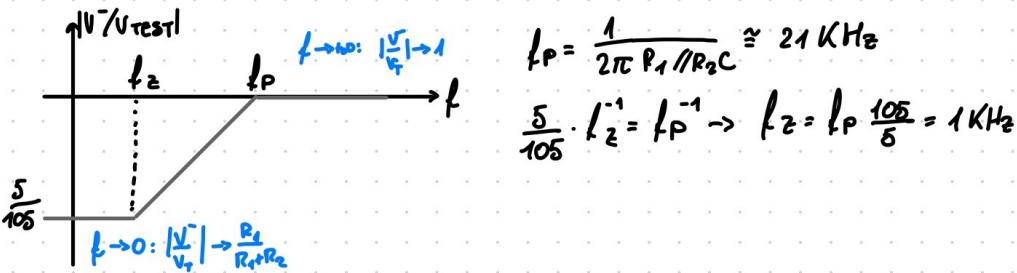
Calcolare l'G_{REAL} e fare il diagramma di Bode.

l'G_{REAL}:



$$G_{loop}(s) = \frac{V^-}{V_{TEST}} \cdot \underbrace{\frac{V_{TEST}}{V^-}}_{-A_d(s)}$$

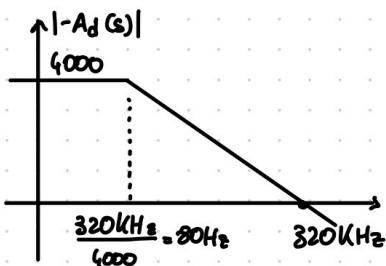
$$\begin{aligned} \frac{V^-}{V_{TEST}} &= \frac{R_1}{R_1 + R_2 // \frac{1}{sC}} = \frac{R_1}{R_1 + \frac{R_2 \frac{1}{sC}}{R_2 + \frac{1}{sC}}} = \frac{R_1 (R_2 + \frac{1}{sC})}{R_1 R_2 + \frac{R_1}{sC} + \frac{R_2}{sC}} = \frac{R_1 R_2 + \frac{R_1}{sC}}{R_1 R_2 + \frac{R_1 + R_2}{sC}} \\ &= \frac{R_1 R_2 sC + R_1}{R_1 R_2 sC + R_1 + R_2} = \frac{R_1}{R_1 + R_2} \cdot \frac{1 + R_2 sC}{1 + \frac{R_1}{R_2} sC} \end{aligned}$$



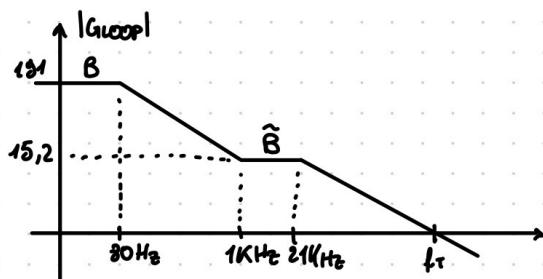
$$f_P = \frac{1}{2\pi R_1 // R_2 C} \cong 21\text{ KHz}$$

$$\frac{5}{105} \cdot f_Z^{-1} = f_P^{-1} \rightarrow f_Z = f_P \frac{105}{5} = 1\text{ KHz}$$

$$f \rightarrow 0: |V^-| \rightarrow \frac{R_1}{R_1 + R_2}$$



$$\Rightarrow G_{LOOP} = - \frac{P_1}{P_1 + P_2} \cdot \frac{1 + R_2 s C}{1 + P_1 / R_2 s C} \cdot \frac{4000}{1 + s T_0}$$



$$B = \frac{4000 \cdot 5}{105} \approx 191$$

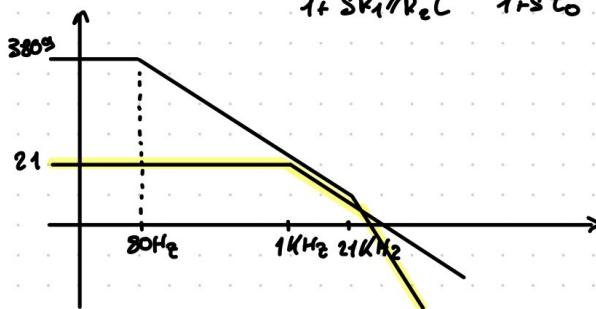
$$\tilde{B} = \frac{191 \cdot 80 \text{ Hz}}{1 \text{ KHz}} = 15,2$$

$$f_T = 21 \text{ KHz} \cdot 15,2 \approx 318 \text{ KHz}$$

$|G_{OPEN}|:$

$$G_{OPEN} = 191 \cdot \frac{\frac{1}{1 + s R_2 / R_e C}}{1 + s R_2 / R_e C} \cdot \frac{1}{1 + s T_0} \cdot 21 \cdot \frac{\frac{1}{1 + s R_2 C}}{1 + s R_2 C}$$

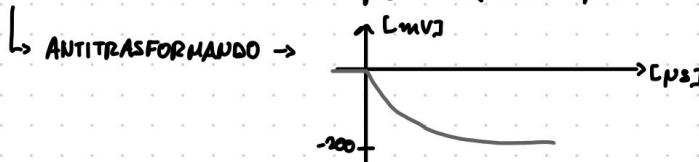
$$= 3809 \cdot \frac{1}{1 + s R_1 / R_e C} \cdot \frac{1}{1 + s T_0}$$



Dato un gradino di tensione $0V \rightarrow 1mV$, traciamo il grafico di V_{out} .

$$G_D(s) = - \left(\frac{R_2}{R_1} \right) \frac{1}{1 + s C P_2} = -20 \cdot \frac{1}{1 + s \cdot 160 \mu s} = \frac{V_{out}(s)}{V_{in}(s)}$$

$$\Rightarrow V_{out} = \frac{10 \text{ mV}}{s} \cdot \frac{-20}{1 + s \cdot 160 \mu s} = \frac{-200 \text{ mV}}{s(1 + s \cdot 160 \mu s)}$$

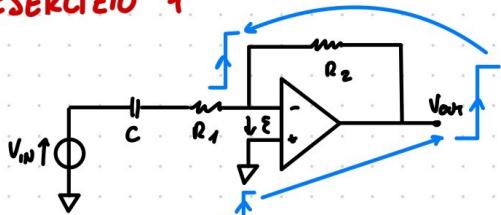


Valutare la stabilità del circuito

$$\phi_m = 180^\circ - \arctg\left(\frac{f_T}{f_0}\right) - \arctg\left(\frac{f_T}{f_P}\right) + \arctg\left(\frac{f_T}{f_Z}\right) = 180^\circ - 90^\circ - 90^\circ + 90^\circ \\ = 90^\circ > 45^\circ \quad \checkmark$$

18/11/21

ESERCIZIO 1



$$R_1 = 1 \text{ k}\Omega \\ R_2 = 10 \text{ k}\Omega \\ C = 10 \text{ nF} \\ A_D = 10^4 \\ f_0 = 100 \text{ Hz} \\ GBWP = 1 \text{ MHz}$$

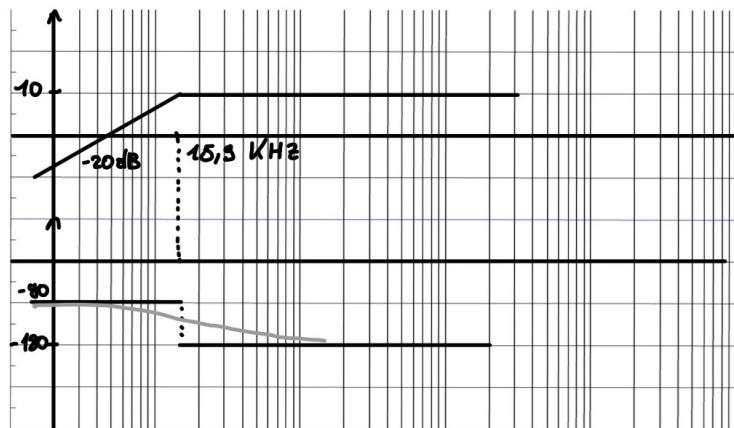
Calcolare G_{1D} e disegnare il diagramma di Bode.

Poiché se abbiamo V^+ il circuito reagisce alla tensione V^- per rendere $V^+ = V^-$ si mantieni $\epsilon = 0 \Rightarrow$ retroazione negativa.

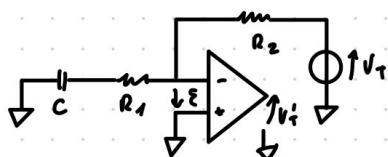
$$I_{IN}(s) = \frac{V_{IN}}{\frac{1}{sC} + R_1} \quad V_{OUT}(s) = -I_{IN} R_2 \Rightarrow G_{1D} = \frac{V_{OUT}}{V_{IN}} = -\frac{R_2}{\frac{1}{sC} + R_1} \\ = \frac{-3CR_2}{1 + sCR_1}$$

$$@ f=0 \Rightarrow G_{1D}=0 \quad (s=0) \quad f_P = \frac{1}{2\pi CR_1} = 15,3 \text{ kHz}$$

$$@ f=\infty \Rightarrow G_{1D} = -\frac{R_2}{R_1} = -10 \quad f_Z = 0$$



Determinare G_{loop} e rappresenta il diagramma di Bode del modulo.



$$G_{\text{loop}}(s) = T_p(s)(-A(s))$$

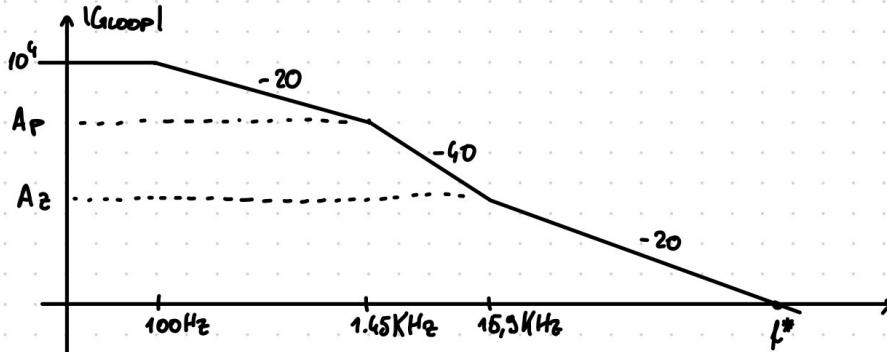
$$T_p(s) = \frac{V^-}{V_T} = \frac{\frac{1}{sC} + R_1}{\frac{1}{sC} + R_1 + R_2} = \frac{1 + sC R_1}{1 + sC(R_1 + R_2)}$$

$$\textcircled{1} f=0 \rightarrow T_p(s)=1$$

$$\textcircled{2} f \rightarrow \infty \rightarrow T_p(s) = \frac{R_1}{R_1 + R_2} = \frac{1}{11}$$

$$f_p = \dots = 1,45 \text{ KHz}$$

$$f_z = 15,9 \text{ KHz}$$



$$10^4 f_0 = A_p f_p \rightarrow A_p = \dots = 683,6$$

$$A_p f_p^2 = A_z f_z^2 \rightarrow A_z = \dots = 5,7 \quad \Rightarrow \quad f^* = A_z f_z = 90,65 \text{ KHz}$$

Stabilire la stabilità del circuito:

$$\phi_m = 180 - \arctg\left(\frac{f^*}{f_0}\right) - \arctg\left(\frac{f^*}{f_p}\right) + \arctg\left(\frac{f^*}{f_z}\right) = 0^\circ + 80^\circ = 80^\circ \quad \checkmark$$

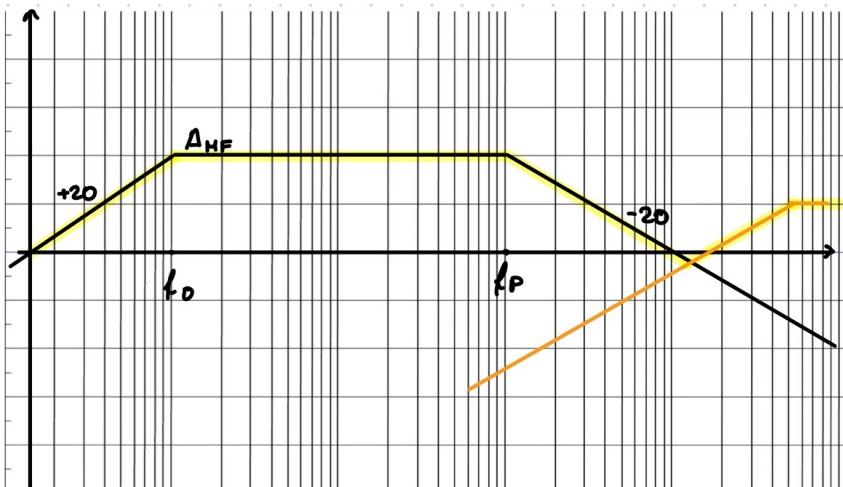
Calcolare G_{REALE} e disegnare il diagramma del modulo.

$$G_{\text{REALE}} = \frac{G_{\text{ID}}}{1 - \frac{1}{G_{\text{loop}}}} \quad \begin{cases} |G_{\text{loop}}| \gg 1 \rightarrow G_{\text{REALE}} \approx G_{\text{ID}} \\ |G_{\text{loop}}| \ll 1 \rightarrow G_{\text{OPEN}} = -G_{\text{loop}} G_{\text{ID}} \end{cases}$$

$$\begin{aligned} \rightarrow G_{\text{OPEN}} &= - \left(\frac{-A_0}{1+sT_0} \right) \left(\frac{1+sCR_2}{1+sC(R_1+R_2)} \right) \left(\frac{-sCR_2}{1+sCR_1} \right) \\ &= - \frac{A_0 sCR_2}{(1+sT_0)(1+sC(R_1+R_2))} \end{aligned}$$

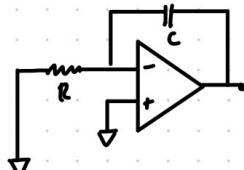
$$A_H = \frac{A_0}{1+sT_0} \frac{sCR_2}{1+sC(R_1+R_2)} = 100$$

↳ dopo zero ↳ prima del polo



22/11/21

ESERCIZIO 1 INTEGRATORE IDEALE

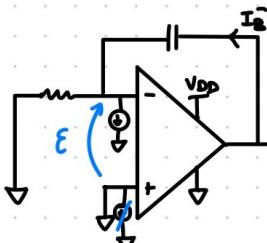


$$\frac{V_{\text{OUT}}(s)}{V_{\text{IN}}(s)} = \frac{1/sC}{R} = -\frac{1}{sRC}$$

$$\Rightarrow V_{\text{OUT}} = V_{\text{IN}} \left(-\frac{1}{sRC} \right) = -\underbrace{\frac{1}{CR} \int_0^t V_{\text{IN}}(t') dt'}_0$$

nel dominio di Laplace, moltiplicare per s
equivale ad integrare.

Calcolare l'effetto delle correnti di bias considerando l'alternante



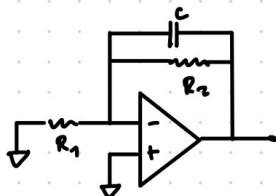
$$V_{\text{OUT}} = I_B / C \cdot t$$



Una volta che salvo, la corrente rea in R, rompendo la retroazione poiché non riesce a mantenere $E=0$.

Per limitare questo problema possiamo:

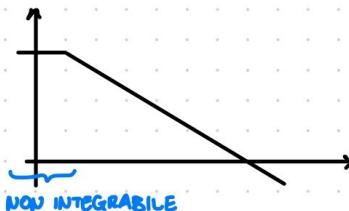
- aggiungere una resistenza in parallelo a C



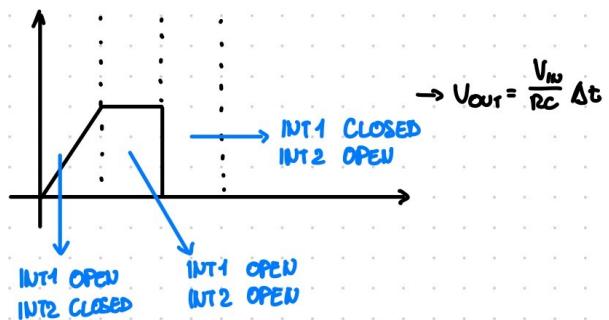
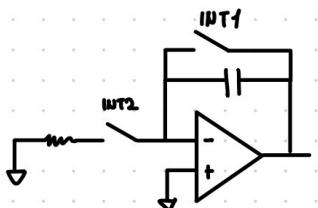
$$V_{\text{out}} / I_B = -R_2 \Rightarrow \text{corrente limitata}$$

$$\hookrightarrow G_{ID} = -\frac{R_1}{R_2} \cdot \frac{1}{1 + SCR_2}$$

integrazione reale



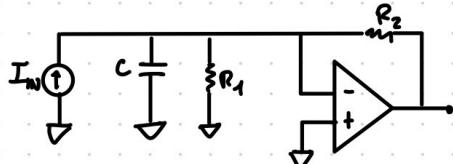
- usare degli interruttori per scaricare periodicamente la capacità



Ottiamo realizzando un convertitore tempo-ampliavita.

23/11/21

ESERCIZIO 1



$$R_1 = 500 \Omega \quad A_0 = 10^5$$

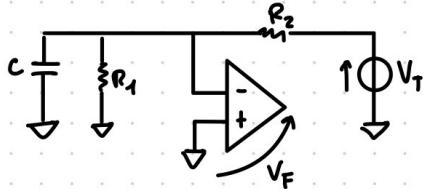
$$R_2 = 5 \text{ K}\Omega \quad G_{BW}P = 100 \text{ kHz}$$

$$C_1 = 100 \text{ pF}$$

Calcolare il trasferimento totale $T_{ID}(s) = \frac{V_{\text{out}}}{I_{\text{in}}} = \frac{V_{\text{out}}}{I_{\text{in}} R_2}$.

$$V^+ = V^- = 0V \quad V_{R2} = I_{\text{in}} R_2 \quad V_{\text{out}} = -I_{\text{in}} R_2 \Rightarrow T_{ID}(s) = -R_2 = -5 \text{ K}\Omega$$

Valutare la stabilità del circuito.

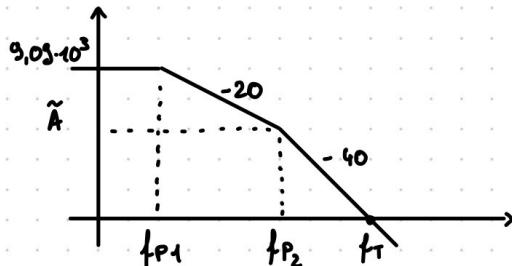


$$\begin{aligned}
 G_{\text{loop}}(s) &= \frac{V_F}{V_T} = -A(s) \frac{V^-}{V_T} = \\
 &= -A(s) \frac{\frac{1}{sC} // R_1}{\frac{1}{sC} // R_1 + R_2} \\
 &= \dots = -\frac{A_0}{1 + s\tau_0} \frac{R_1}{(R_1 + R_2)(1 + sCR_1 // R_2)}
 \end{aligned}$$

$$|G_{\text{loop}}(0)| = A_0 \left(\frac{R_1}{R_1 + R_2} \right) = \dots = 3,03 \cdot 10^3$$

$$f_{P1} = f_0 = \frac{GBWP}{A_0} = 1 \text{ kHz}$$

$$f_{P2} = \frac{1}{2\pi C R_1 // R_2} = 3,5 \text{ MHz}$$



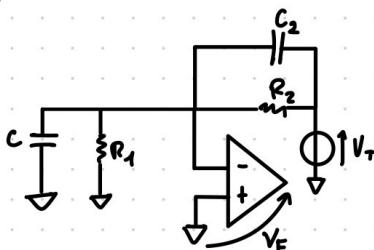
$$\tilde{A} = A_0 f_0 / f_T = 2,60$$

$$f_T = \sqrt{\tilde{A} f_{P2}^2} = 5,64 \text{ MHz}$$

$$\begin{aligned}
 \phi_m &= 180^\circ - \arctg\left(\frac{f_T}{f_{P1}}\right) - \arctg\left(\frac{f_T}{f_P}\right) \\
 &= 31,82^\circ \quad X
 \end{aligned}$$

Si collega C_2 in parallelo a R_2 . Dimensionare C_2 per avere

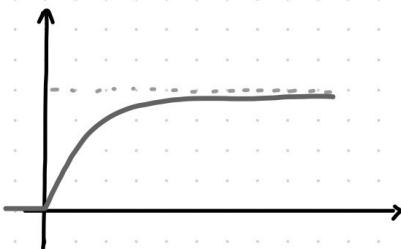
$$\phi_m = 90^\circ$$



$$\begin{aligned}
 G_{\text{loop}}(s) &= -A(s) \frac{R_1 // \frac{1}{sC}}{R_1 // \frac{1}{sC} + R_2 // \frac{1}{sC}} \\
 &= \frac{A_0}{1 + s\tau_0} \left(\frac{R_1}{R_1 + R_2} \right) \left(\frac{1 + sC_1 R_2}{1 + s(C_1 + C_2)(R_1 // R_2)} \right)
 \end{aligned}$$

$$\text{poniamo } f_{P2} = f_z \Rightarrow C_2 R_2 = (C_1 + C_2)(R_1 // R_2) \rightarrow C_2 = C_1 \frac{R_1}{R_2} = \dots = 10 \mu\text{F}$$

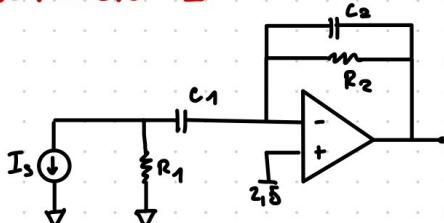
Disegnare su un grafico qualsiasi la tensione di uscita V_{out} var in risposta ad un gradino di ampiezza -1 mA .



$$T_{1D}(s) = -5 \text{ K } \Omega$$

$$\tau = C_2 R_2 = 50 \text{ ms}$$

ESERCIZIO 2



$$\begin{aligned} R_1 &= 1 \text{ M}\Omega \\ R_2 &= 10 \text{ M}\Omega \\ C_1 &= 100 \text{ nF} \\ C_2 &= 1 \text{ pF} \end{aligned}$$

$$\begin{aligned} f_0 &= 10 \text{ Hz} \\ G_{BW}P &= 1 \text{ MHz} \end{aligned}$$

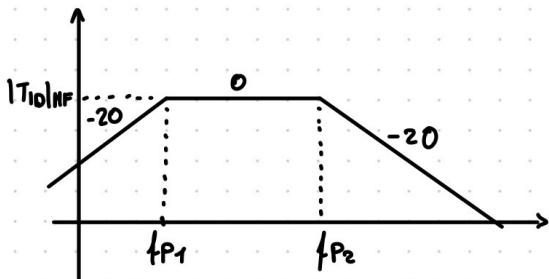
$$I_s = 100 \text{ mA} \sin(2\pi 100 \text{ kHz} t)$$

Determinare il trasferimento ideale $T_{1D}(s) = \frac{V_o}{I_s}$ e tracciare su un grafico qualato il diagramma di Bode del modulo.

sviluppiamo il polinomiale a massa:

$$V_+ = V_- = 0 \text{ V} \quad I_{IN} = I_s \frac{R_1}{R_1 + \frac{1}{sC_1}} \rightarrow V_{IN} = I_{IN} \left(R_2 \parallel \frac{1}{sC_2} \right)$$

$$\Rightarrow T_{1D}(s) = \left(\frac{sC_1 R_1}{1 + sC_1 R_1} \right) \left(\frac{R_2}{1 + sC_2 R_2} \right)$$



$$f_P1 = \frac{1}{2\pi C_1 R_1} = 1,6 \text{ Hz}$$

$$f_P2 = \frac{1}{2\pi C_2 R_2} = 15,3 \text{ kHz}$$

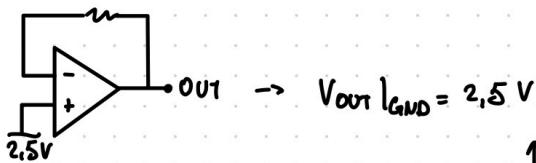
$$|T_{1D}|_{HF} = \left| \frac{sC_1 f_P1 R_2}{sC_2 f_P1 \cdot 1} \right| = R_2$$

Determinare la tensione $V_o(t)$ e rappresentarla. Calcolare il minimo slew rate per non distorcere.

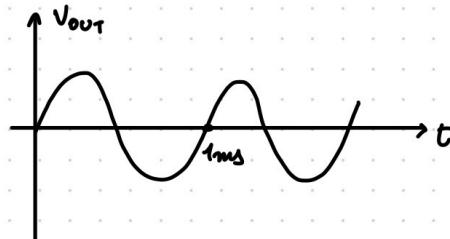
$$V_{out}|_{I_s} = 100 \text{ mA} |T_{1D}| \sin(2\pi 1 \text{ kHz} t + \Delta T_{1D}) =$$

$$= 100 \text{ mA} \cdot (10 \text{ M}\Omega) \sin(2\pi 1 \text{ kHz} t + \cancel{(90^\circ - 90^\circ - 0)})$$

$$= 1 \text{ V} \sin(2\pi 1 \text{ kHz} t)$$



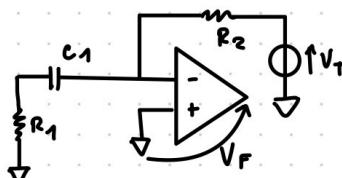
$$\Rightarrow V_{out} = 2.5 \text{ V} + 1 \text{ V} \sin(2\pi 1 \text{ kHz} t)$$



$$\frac{dV_{out}}{dt} = 1 \text{ V} \cos(2\pi 1 \text{ kHz} t) \cdot 2\pi 1 \text{ kHz}$$

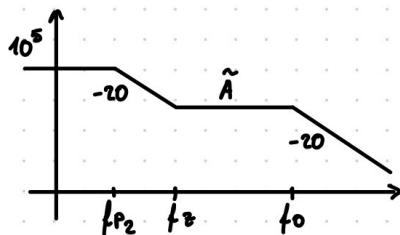
$$\Rightarrow SP_{MIN} = 1 \text{ V} \cdot 2\pi \cdot 1 \text{ kHz} = 6.28 \text{ V/mus}$$

Varicando C_2 , valutare la stabilità



$$G_{loop}(s) = -A(s) \frac{V_r}{V_f} = -A(s) \frac{\frac{1}{sC_1 + R_1}}{\frac{1}{sC_1 + R_1 + R_2}}$$

$$= -\frac{A_0}{1 + sT_0} \frac{1 + sC_1 R_1}{1 + sC_1 (R_1 + R_2)}$$



$$|G_{loop}(s)| = 10^5$$

$$f_Z = \frac{1}{2\pi C_1 R_1} = 1.6 \text{ Hz}$$

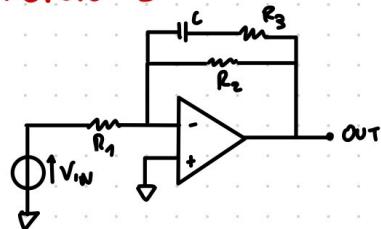
$$f_{P2} = \frac{1}{2\pi C_1 (R_1 + R_2)} = 0.14 \text{ Hz}$$

$$\hat{A} = 10 f_{P2} / f_Z = 8750$$

$$f_T = \hat{A} f_{P2} = 87.5 \text{ kHz}$$

$$\phi_H = 180^\circ - \arctg\left(\frac{f_1}{f_{P2}}\right) + \arctg\left(\frac{f_1}{f_2}\right) - \arctg\left(\frac{f_1}{f_0}\right) = \dots = 90^\circ \quad \checkmark$$

ESERCIZIO 3



$$R_1 = 10 \text{ k}\Omega$$

$$R_2 = 1 \text{ M}\Omega$$

$$R_3 = 10 \text{ k}\Omega$$

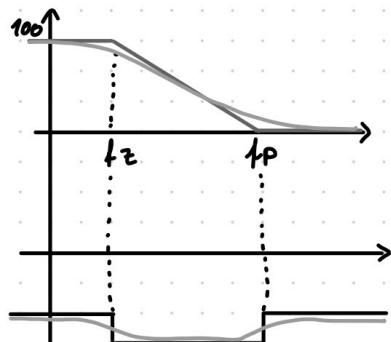
$$C = 1,6 \text{ nF}$$

Disegnare i diagrammi di Bode di modulo e fase di $G_{10}(s)$

$$V_- = V_+ = 0V \rightarrow V_{out} = -\frac{V_{in}}{V_{R_1}} (R_2) // \left(\frac{1}{sC} + R_3 \right)$$

$$\Rightarrow G_{10}(s) = -\frac{R_2}{R_1} \left(\frac{1 + sCR_3}{1 + sC(R_2 + R_3)} \right) \rightarrow G_{10}(0) = \dots = -100$$

$$G_{10}(+\infty) = \dots = -\frac{R_2 // R_3}{R_1} = -1$$



$$f_Z = \frac{1}{2\pi} C R_3 = 9,95 \text{ kHz}$$

$$f_P = \frac{1}{2\pi C (R_1 + R_2)} = 98,5 \text{ kHz}$$

Trovare l'espressione di V_{out} con

$$V_{in} = 1 \text{ mV} \sin(2\pi 5 \text{ Hz} t) + 5 \text{ mV} \sin(2\pi 100 \text{ Hz} t) + 20 \text{ mV} \sin(2\pi 1 \text{ MHz} t)$$

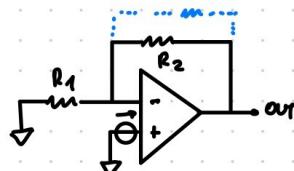
$$V_{out} = (1 \text{ mV} \cdot 100) \sin(2\pi 5 \text{ Hz} t - 180^\circ) +$$

$$(5 \text{ mV} \cdot \frac{100}{\sqrt{2}}) \sin(2\pi 100 \text{ Hz} t - 225^\circ) +$$

$$(20 \text{ mV} \cdot 1) \sin(2\pi 1 \text{ MHz} t - 180^\circ)$$

40 dB - 3 dB; i 3 dB sono dovuti all'approssimazione

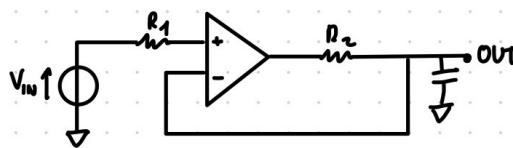
Valutare l'effetto di una tensione di offset di $\pm 100 \mu\text{V}$



$$V_{out|V_{os}} = V_{os} \left(1 + \frac{R_2}{R_1} \right) = \pm 10,1 \text{ mV}$$

25/11/21

ESERCIZIO 1

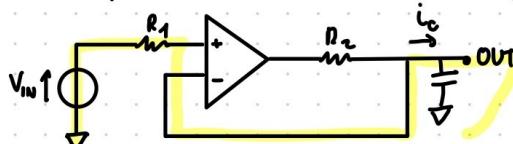


$$R_1 = 1K\Omega$$

$$R_2 = 100\Omega$$

$$C = 1\text{mF}$$

Se V_{IN} una sinusode con ampiezza 1V e frequenza fra 10 Hz e 10 KHz, qual è la I_{out} minima per non distorcere



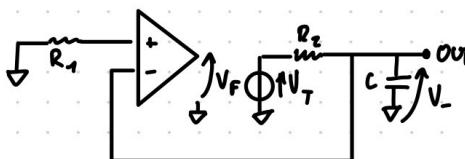
$$V_{OUT} = V_{IN}$$

$$I_{OUT, OPAMP} = i_C = C \frac{dV_C}{dt}$$

$$I_{OUT, OPAMP}|_{V_{IN}} = C \frac{dV_C}{dt}|_{MAX} = C \cdot A \cdot 2\pi f_{MAX} = 62,83 \text{ mA}$$

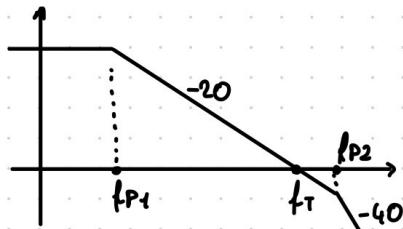
Se $GBWP = 1 \text{ MHz}$, calcolare il massimo slew rate per non distorcere.
Considerare GREALE

Loop:



$$\begin{aligned} G_{LOOP} &= \frac{V_F}{V_T} = -A(s) \frac{V_-}{V_T} \\ &= -A(s) \frac{\frac{1}{sC}}{\frac{1}{sC} + R_2} \\ \Rightarrow G_{LOOP} &= -\frac{A_0}{1+sT_0} \frac{1}{1+2sR_2} \end{aligned}$$

$$f_{P1} = f_0 \quad f_{P2} = \frac{1}{2\pi CR_2} = 1,6 \text{ MHz}$$



$$f_T = 1 \text{ MHz}$$

$\hookrightarrow |G_{LOOP}| > 1$ per $f < 1 \text{ MHz}$

$\hookrightarrow G_{REALE} = G_{ID}$ per $f < 1 \text{ MHz}$

G_{OPEN} non bisogna calcolarlo perché il circuito non supererà 10 KHz

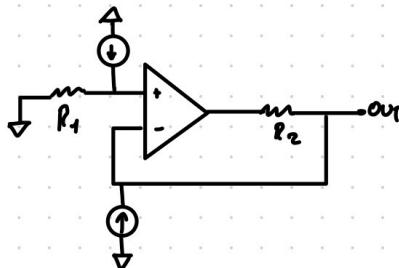
$$V_{OUT} = V_{IN}$$

$$V_{OUT,OPAMP} = V_{OUT} + V_{R2} = V_{IN} + R_2 C \frac{dV_{IN}}{dt}$$

$$\frac{dV_{OUT,OPAMP}}{dt} = \frac{dV_{IN}}{dt} + R_2 C \underbrace{\frac{d^2V_{IN}}{dt^2}}_{\text{TRASCURIAMO}} \rightarrow SR_{HIN} = \left. \frac{dV_{IN}}{dt} \right|_{MAX} = 1V \cdot 2\pi f_{MAX} = 62,8 \text{ V/ms}$$

Qual è l'effetto delle correnti di bias sul circuito?

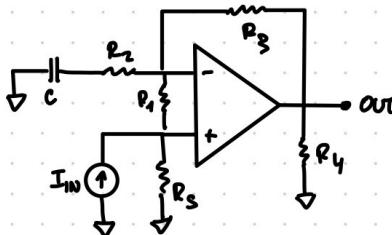
$$I_B = 3 \text{ mA} \text{ (circuito)}$$



$$\begin{aligned} V_{OUT} &= I_B R_1 = 3 \mu\text{V} \\ V_{OUT,OPAMP} &= 3 \text{ mV} \end{aligned} \quad \left. \right\} I_B^+$$

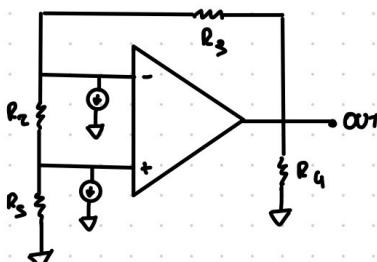
$$\begin{aligned} V_{OUT} &= 0 \text{ V} \\ V_{OUT,OPAMP} &= -I_B R_2 = -3 \text{ mV} \end{aligned} \quad \left. \right\} I_B^-$$

ESERCIZIO 2



$$\begin{aligned} R_1 &= R_S = 100 \text{ k}\Omega \\ R_2 &= 1 \text{ k}\Omega \\ R_3 &= 10 \text{ k}\Omega \\ R_4 &= 20 \text{ k}\Omega \\ C &= 1 \text{ nF} \end{aligned}$$

Determinare l'effetto delle correnti di bias subirambi $I_B = 1 \text{ nA}$

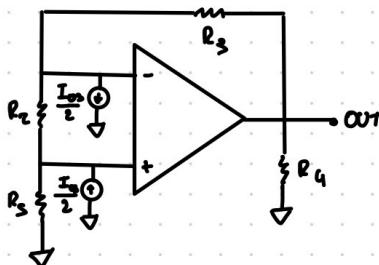


$$V_+ = -I_B R_3 = -100 \text{ mV}$$

$$V_- = V_+$$

$$V_{OUT} = V_- + V_{R2} = V_- + I_B \cdot R_3 = -90 \text{ mV}$$

Calcolare l'effetto sull'uscita della corrente di offset $I_{OS} = 100 \text{ nA}$



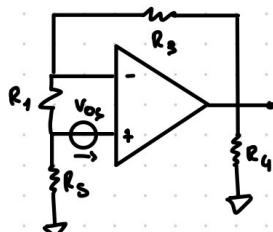
$$V_+ = \frac{I_{OS}}{2} R_3 = 50 \text{ nA} (100 \text{ k}\Omega) = 5 \text{ mV}$$

$$V_- = V_+ = 5 \text{ mV}$$

$$V_{OUT} = V_- + V_{R3} = V_- + \frac{I_{OS}}{2} R_3 = 5,5 \text{ mV}$$

$$\Rightarrow \pm 5,5 \text{ mV}$$

Calcolare l'effetto della tensione di offset $V_{OS} = \pm 1 \text{ mV}$



$$V_{R1} = V_{OS}$$

$$I_{R1} = V_{OS} / R_1$$

$$V_{RS} = I_{R1} R_S$$

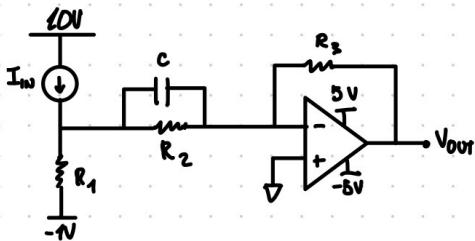
$$V_{R3} = I_{R1} R_3$$

$$V_{OUT} = V_{RS} + V_{R1} + V_{R3}$$

$$= V_{OS} \left(1 + \frac{R_S + R_3}{R_1} \right) = \pm 2,1 \text{ mV}$$

30/11/21

ESERCIZIO 1



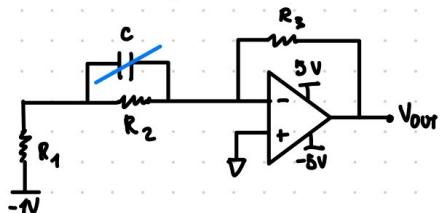
$$R_1 = 1,5 \text{ k}\Omega$$

$$R_2 = 4,5 \text{ k}\Omega$$

$$R_3 = 18 \text{ k}\Omega$$

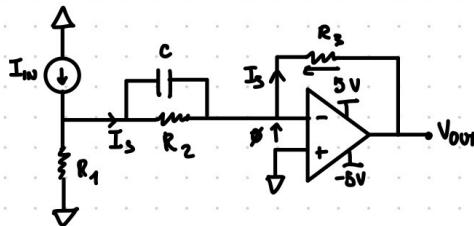
$$C = 17,5 \text{ nF}$$

Calcolare V_{OUT} quando $I_w = 0$



$$V_{OUT} = +1V \frac{R_3}{R_1 + R_2} = 3V$$

Tracciare $V_{out}(t)$ in risposta a $I_{in}(t) = 400 \mu A \sin(2\pi 80 \text{ KHz} t)$



$$I_s = I_{in} \frac{R_1}{R_1 + R_2 // sC}$$

$$V_{out} = -R_3 I_s$$

$$\Rightarrow T_{ID} = \frac{V_{out}}{I_{in}} = \dots = - \frac{R_1 R_3}{R_1 + R_2} \cdot \frac{1 + sCR_2}{1 + sCR_1 // R_2}$$

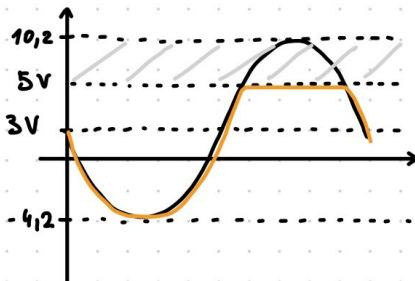
$$f_Z = \frac{1}{2\pi CR_2} = 2,02 \text{ KHz} \quad T(0) = - \frac{R_1 R_3}{R_1 + R_2} = -4,5 \text{ K}\Omega$$

$$f_P = \frac{1}{2\pi CR_1 // R_2} = 3,08 \text{ KHz} \quad T(\infty) = -R_3 = -18 \text{ K}\Omega$$

$$V_{out}|_{I_{in}} = 400 \mu A |T_{ID}| \cdot \sin(2\pi 80 \text{ KHz} t + \Delta T_{ID}) \xrightarrow{\text{+1 decade rispetto a fp}}$$

$$= 400 \mu A \cdot 18 \text{ K}\Omega \cdot \sin(2\pi 80 \text{ KHz} t - 180^\circ) = 7,2 \text{ V} \sin(2\pi 80 \text{ KHz} t - 180^\circ)$$

$$\rightarrow V_{out} = V_{out}|_{I_{in}} + V_{out}|_{-1v} + V_{out}|_{T_{ID}} = 3 \text{ V} + \dots$$

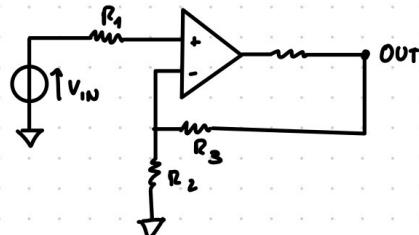


Sia un segnale con banda $[0; 100 \text{ KHz}]$ e ampiezza $[50; 250] \mu A$. Quale è lo slew rate minimo per non distorcere.

$$SR_{MIN} = \left. \frac{dV_{out}}{dt} \right|_{MAX} = A_{MAX} \cdot 2\pi f_{MAX} = 250 \mu A \cdot T_{MAX} \cdot 2\pi \cdot 100 \text{ KHz}$$

$$= 250 \mu A \cdot 18 \text{ K}\Omega \cdot 2\pi \cdot 100 \text{ KHz} = 2,83 \text{ V}/\mu s$$

ESERCIZIO 2



$$R_1 = 50 \text{ k}\Omega$$

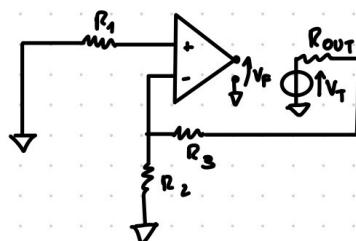
$$R_2 = 2 \text{ k}\Omega$$

$$R_3 = 18 \text{ k}\Omega$$

$$R_{\text{out}} = 1 \text{ k}\Omega$$

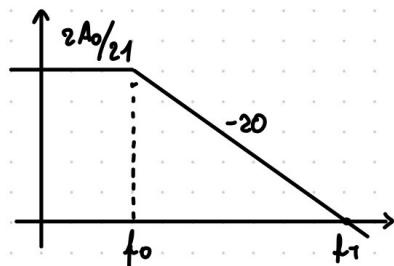
$$V_{\text{IN}}(t) = -\sqrt{2} \cdot 100 \text{ mV}$$

Considerando l'OPAMP a singolo polo con $\text{GBWP} = 42 \text{ MHz}$, quanto vale V_{OOR} ?



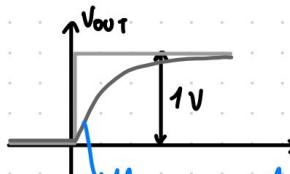
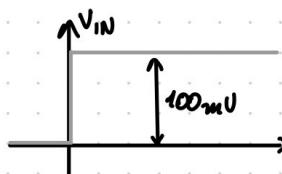
$$G_{\text{ID}} = 1 + \frac{R_3}{R_2} = 10$$

$$\begin{aligned} G_{\text{LOOP}} &= \frac{V_E}{V_T} = -A(s) \frac{V_-}{V_T} = -\frac{A_0}{1+sT_0} \frac{R_2}{R_2 + R_3 + R_{\text{out}}} \\ &= -\frac{A_0}{1+sT_0} \frac{2 \text{ k}\Omega}{21 \text{ k}\Omega} \end{aligned}$$



$$A_0 \frac{2}{21} f_0 = f_T$$

$$\frac{2}{21} \text{ GBWP} = f_T \rightarrow f_T = 4 \text{ MHz}$$



abbiamo un filtro passa basso,
può passare solo le basse frequenze

$$V_{\text{OOR}} = 1V \left(1 - e^{-t/\tau}\right) \quad \tau = \frac{1}{2\pi f_T} = 39,73 \text{ ms}$$

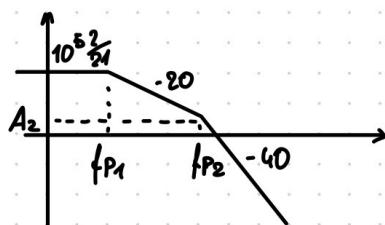
Discussire la stabilità del circuito

$$\phi_H = 180^\circ - \arctg\left(\frac{f_1}{f_0}\right) \geq 90^\circ \quad \checkmark$$

non possono dunque

Considerare un OPAMP con due poli $f_{P1} = 420 \text{ Hz}$ e $f_{P2} = 4 \text{ MHz}$ e $A_0 = 10^5$.

$$G_{\text{LOOP}} = -A(s) \frac{2}{21}$$



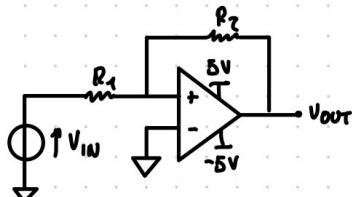
$$10^{\frac{5.2}{21}} 420 \text{ Hz} = A_2 4 \text{ MHz}$$

$$\Rightarrow A_2 \approx 1$$

$$\Rightarrow f_T \approx f_{P2} = 4 \text{ MHz}$$

$$\rightarrow \phi_H = 180^\circ - \arctg\left(\frac{f_1}{f_{P1}}\right) - \arctg\left(\frac{f_1}{f_{P2}}\right) = 45^\circ \quad \checkmark$$

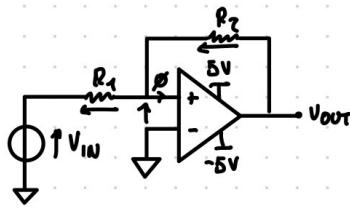
ESERCIZIO 3



$$R_1 = R_2 = 5 \text{ k}\Omega$$

Calcolare la caratteristica $V_{\text{OUT}} / V_{\text{IN}}$

La inversione è positiva: $\begin{cases} \epsilon > 0 \rightarrow V_{\text{OUT}} \rightarrow +\infty \\ \epsilon < 0 \rightarrow V_{\text{OUT}} \rightarrow -\infty \end{cases} \begin{cases} V_{\text{OUT}} \rightarrow 5 \text{ V} \\ V_{\text{OUT}} \rightarrow -5 \text{ V} \end{cases}$



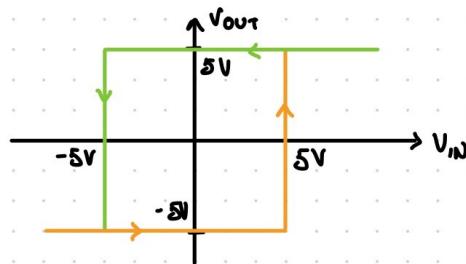
$$V_- = 0 \text{ V}$$

$$I_{R_1} = I_{R_2} = \frac{V_{\text{IN}} - V_+}{R_1} = \frac{V_+ - V_{\text{OUT}}}{R_2}$$

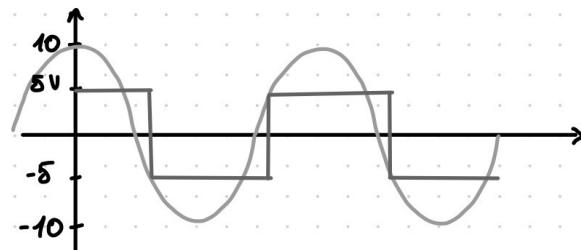
$$\rightarrow V_+ = \frac{V_{\text{IN}} + V_{\text{OUT}}}{2}$$

$$V_{\text{OUT}} = 5 \text{ V} \quad \begin{cases} V_- = 0 \text{ V} \\ V_+ = V_{\text{IN}} + 5 \text{ V} / 2 \end{cases} \rightarrow \epsilon < 0 \Rightarrow \text{commuto a } \frac{V_{\text{IN}} + 5 \text{ V}}{2} < 0 \text{ V} \rightarrow V_{\text{IN}} < -5 \text{ V}$$

$$V_{\text{OUT}} = -5 \text{ V} \quad \begin{cases} V_- = 0 \text{ V} \\ V_+ = V_{\text{IN}} - 5 \text{ V} / 2 \end{cases} \rightarrow \epsilon > 0 \Rightarrow \text{commuto a } \frac{V_{\text{IN}} - 5 \text{ V}}{2} > 0 \text{ V} \rightarrow V_{\text{IN}} > +5 \text{ V}$$



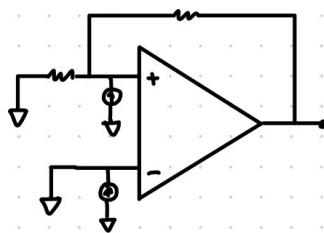
di considerare V_{IN} una sinusoidi di ampiezza 10V, valor medio ov e frequenza 1KHz, disegnare la risposta.



$$f = 1 \text{ KHz}$$

$$\text{DC} = 50\%$$

Calcolare il contributo delle correnti di bias considerando usciti con $I_B = 100 \text{ nA}$



$$V_+ = I_B \cdot R_1 / R_2 = \dots = 250 \text{ nV}$$

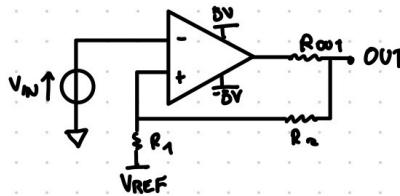
$$V_+ = \frac{V_{IN} + V_{OUT}}{2} + 250 \text{ nV}$$

$$V_{OUT} = 5V \rightarrow E < 0 \rightarrow \text{commuta a } V_{IN} < -5V - 500 \text{ nV}$$

$$V_{OUT} = -5V \rightarrow E > 0 \rightarrow \text{commuta a } V_{IN} > 5V + 500 \text{ nV}$$

2/12/21

ESERCIZIO 1



$$R_1 = R_2 = 5 \text{ k}\Omega$$

$$R_{OUT} = 100 \text{ k}\Omega$$

Supponendo $V_{REF} = 0V$, tracciare la caratteristica $V_{OUT} - V_{IN}$.

RETROAZIONE POSITIVA: $\begin{cases} \epsilon > 0 \rightarrow V_{OUT,OPAMP} = 5V \\ \epsilon < 0 \rightarrow V_{OUT,OPAMP} = -5V \end{cases}$

$$V_{OUT} = V_{OUT,OPAMP} \left(\frac{R_1 + R_2}{R_1 + R_2 + R_{OUT}} \right) = \pm 4,95V$$

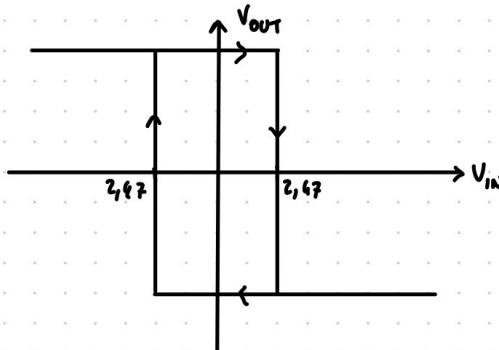
$$V_- = V_{IN} \quad V_+ = V_{OUT,OPAMP} \left(\frac{R_1}{R_1 + R_2 + R_{OUT}} \right) = \pm 2,47V$$

con $V_{OUT} = -4,95V$, per comutare dobbiamo ottenere $\epsilon > 0$

$$\Rightarrow V_+ > V_- \rightarrow V_{IN} < -2,47V$$

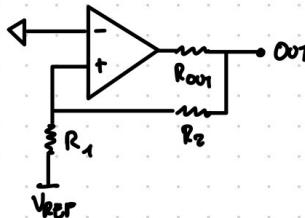
con $V_{OUT} = 4,95V$, per comutare dobbiamo ottenere $\epsilon < 0$

$$\Rightarrow V_+ < V_- \rightarrow V_{IN} > 2,47V$$



Se $V_{REF} = 2V$, ridisegnare la caratteristica.

Applichiamo PSE:

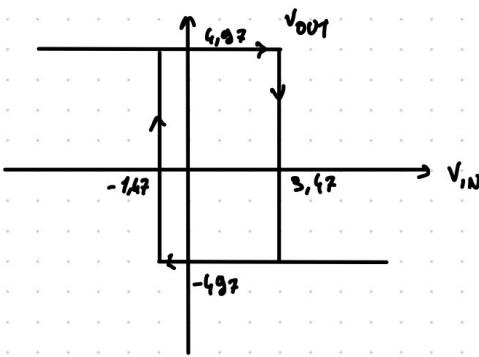


$$V_+ | V_{REF} = V_{REF} \left(\frac{R_1 + R_{OUT}}{R_1 + R_2 + R_{OUT}} \right) = 1V$$

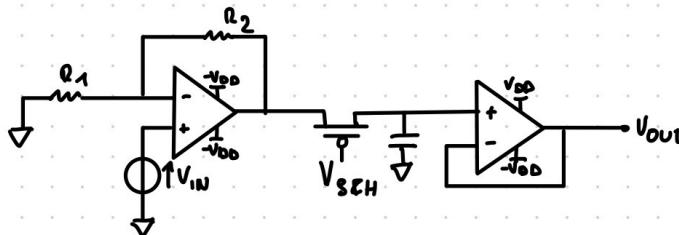
$$V_{OUT} | V_{REF} = V_{REF} \left(\frac{R_{OUT}}{R_1 + R_2 + R_{OUT}} \right) = 0,02V$$

$$\Rightarrow V_+ = \pm 2,47V + 1V = \begin{cases} 3,47V \\ -1,47V \end{cases}$$

$$V_{OUT} = \pm 4,95V + 0,02 = \begin{cases} 4,97V \\ -4,93V \end{cases}$$



ESERCIZIO 2



$$\begin{aligned}
 R_1 &= 1K\Omega \\
 V_{DD} &= 5V \\
 C &= 1\mu F \\
 V_{TP} &= -1V \\
 KpI &= 1mA/V^2 \\
 V_{IN} &\in [-100mV; +100mV]
 \end{aligned}$$

Calcolare R_2 affinché la dinamica dello stadio amplificante sia sfruttata completamente.

$$V_{OUT} \in [-5V; 5V] \quad e \quad V_{IN} \in [-100mV; +100mV]$$

$$G_{TOT} = G_1 G_2 = 1 + \left(\frac{R_2}{R_1} \right) \cdot 1 = \frac{5V}{100mV} = 50$$

$$\hookrightarrow \frac{R_2}{R_1} = 49 \rightarrow R_2 = 4.9K\Omega$$

Considerando $R_2 = 24K\Omega$, scegliere V_{SAMPLE} e V_{HOLD} che garantiscono il corretto funzionamento.

$$\begin{aligned}
 \underline{\text{SAMPLE}}: \quad \text{PMOS ON} \rightarrow V_{SG} > |V_T| \rightarrow V_S - V_G > 1V \\
 \Rightarrow V_S - V_{SAMPLE} > 1V \Rightarrow V_{SAMPLE} < V_S - 1V
 \end{aligned}$$

poiché sfruttiamo tutta dinamica, $V_{OUT} \in [-2.5V; 2.5V]$

$$\Rightarrow V_{SAMPLE} < 2.5V - 1V = -1.5V$$

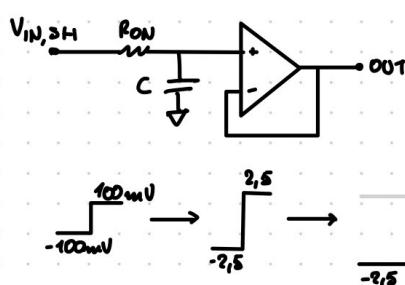
$$\begin{aligned}
 \underline{\text{HOLD}}: \quad \text{PMOS OFF} \rightarrow V_{SG} < |V_T| \rightarrow V_S - V_G < 1V \\
 \Rightarrow V_{HOLD} > V_S - 1V > 2.5V - 1V = 1.5V
 \end{aligned}$$

Determinare la tensione di comando da applicare allo S8H per avere una resistenza in ingresso di 50Ω

$$R_{SD,ON} = \frac{1}{2|K_p|(V_{SG} - V_{TPL})} < 50 \Omega \rightarrow V_{SG} > 1V + \frac{1}{2 \cdot 1mA/2 \cdot 50\Omega} = 1V$$

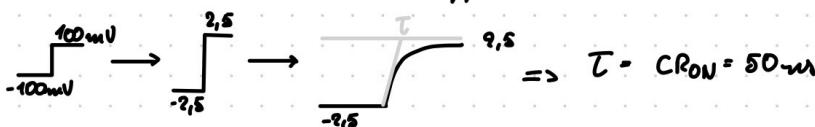
$$V_S - V_{SAHPLB} > 1V \rightarrow V_{SAMPLE} < V_S - 1V = -19,5V$$

Considerando $R_{ON} = 50 \Omega$, determinare il minimo SR del secondo OPAMP compatibile col circuito.



$$V_{IN,SH} \in [-2,5V; 2,5V]$$

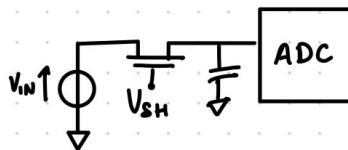
Non conosciamo la forma di V_{IN} , supponiamo il caso peggiore: gradino



$$SR_{MIN} = \frac{dV_{OUT}}{dT} \Big|_{MAX} = \frac{dV_C}{dT} \Big|_{MAX} = \frac{\Delta V_C}{T} = \frac{5V}{50ms} = 100V/\mu s$$

3/12/21

ESERCIZIO 1



$$C_H = 30nF$$

$$V_{IN} = A \sin(2\pi f_{IN} t)$$

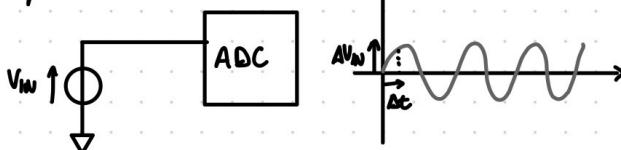
$$V_T = 1V$$

$$A \in [10mV; 100mV]$$

$$f_{IN} = 0,1\mu s$$

$$f_{IN} \in [10kHz; 100kHz]$$

Qual è il T_{CAMP} affinché si abbia $E_{MAX} = \frac{1}{2000} V_{IN}$ di errore SENZA sample & hold



$$\Delta V_N = \frac{dV_N}{dt} \Delta t = E$$

$$T_{CAMP}$$

$$\Rightarrow E = A \cos(2\pi f_{int} t) 2\pi f_{int} T_{COMP} \rightarrow E_{MAX} = A 2\pi f_{int} T_{COMP}$$

$$\rightarrow T_{COMP} \leq \frac{1}{1000 2\pi f_{int}} \xrightarrow[\text{PESSIMO}]{\text{CASO}} T_{COMP} \leq 1,6 \text{ ns}$$

Considerando $T_{HOLD} = 1 \text{ ns}$, calcolare $T_{SAMPLE, MAX}$ compatibile con il circuito

$$T_{SAMPLE} + T_{HOLD} = T_{COMP} \leq \frac{T_{IN}}{2} \Rightarrow T_{SAMPLE} \leq \frac{T_{IN}}{2} - T_{HOLD} = \frac{1}{2\pi f_{IN}} - T_{HOLD}$$

Th. Shannon $\xrightarrow[\text{PESSIMO}]{\text{CASO}}$ $T_{SAMPLE} \leq 4 \text{ ns}$

Considerare $R_{ON} = 10 \Omega$, calcolare la corrente massima in ingresso

$$\Delta V_{CH} = 200 \text{ mV}$$

$$I_{MAX} = C_H \cdot \frac{dV_{CH}}{dt} = C_H \frac{\Delta V_{CH}}{\tau} = \frac{\Delta V_{CH}}{R_{ON}} = 20 \text{ mA}$$

Determinare V_{SAMPLE} e V_{HOLD} compatibili con la dinamica del circuito

$$\text{SAMPLE} \rightarrow \text{NMOS ON} \rightarrow V_{GS} > V_T = 1V$$

$$V_G - V_S > 1V \rightarrow V_{SAMPLE} - V_{IN} > 1V \rightarrow V_{SAMPLE} > V_{IN} + V \rightarrow 1,1 \text{ V}$$

$$\text{HOLD} \rightarrow \text{NMOS OFF} \rightarrow V_{GS} < V_T = 1V$$

$$V_G - V_S < 1V \rightarrow V_{SAMPLE} - V_{IN} < 1V \rightarrow V_{SAMPLE} < V_{IN} + V \rightarrow 0,9 \text{ V}$$

Si consideri $V_{SAMPLE} = 3V$, si calcoli la K_N affinché si abbia $R_{ON} \approx 10 \Omega$

$$R_{ON} \cdot \frac{1}{2K_N(V_{GS}-V_T)} \leq 10 \Omega \Rightarrow K_N = \frac{1}{2 \cdot 10 \Omega (V_{SAMPLE} - V_{IN} - V_T)} =$$

$$= \frac{1}{2 \cdot 10 \Omega (3V - 0,1V - 1V)} = 26,3 \text{ mA/V}^2$$

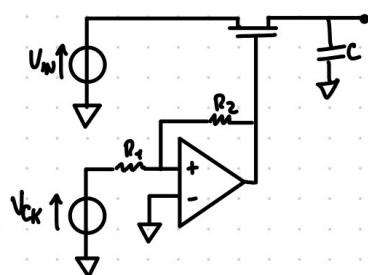
Considerando $V_{SAMPLE} = 3V$, determinare la V_{HOLD} l'errore massimo rispetto al segnale sia $E_{MAX} = \frac{1}{1000} V_{IN}$ nel passaggio tra sample e hold

$$\Delta V_{CH} = \Delta V_G \left(\frac{1/C_{SH}}{1/C_{SH} + 1/C_{PAR}} \right) = \Delta V_G \left(\frac{C_{PAR}}{C_{PAR} + C_H} \right)$$

$$\Rightarrow \Delta V_{CH} = \Delta V_G \cdot \frac{C_{PAR}}{C_{PAR} + C_H} \leq \frac{1}{1000} A \rightarrow \Delta V_G \leq 3V$$

$$\rightarrow V_{HOLD} \approx 0V$$

ESERCIZIO 2

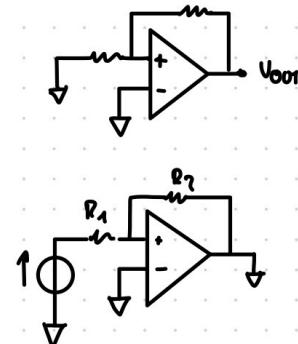


$$\begin{aligned}
 R_1 &= 10 \text{ k}\Omega \\
 R_2 &= 30 \text{ k}\Omega \\
 V_{OUT,OPAMP} &\in [-10; 10] \text{ V} \\
 V_T &= 1,4 \text{ V} \\
 K &= 5 \text{ mA/V}^2 \\
 V_{CK} &= 4 \text{ V} \cos(2\pi 1000 \text{ Hz} t)
 \end{aligned}$$

Calcolare T_{SAMPLE} e T_{HOLD}

d'OPAMP i retroevidenzio posizionando:

$$\begin{aligned}
 E > 0 & \quad V_{OUT,OPAMP} = 10 \text{ V} \\
 E < 0 & \quad V_{OUT,OPAMP} = -10 \text{ V} \\
 V_- = 0 \text{ V} &
 \end{aligned}$$



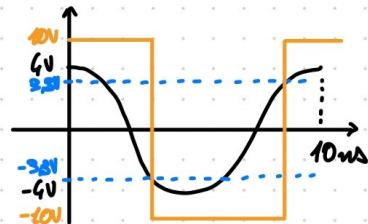
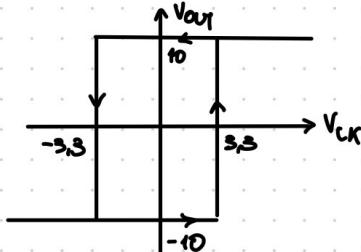
$$V^+ / V_{OUT} = V_{OUT} \frac{R_1}{R_1 + R_2}$$

$$V^+ / V_{CK} = V_{CK} \frac{R_2}{R_1 + R_2}$$

$$\begin{aligned}
 V^+ &= V_{OUT} \frac{R_1}{R_1 + R_2} + V_{CK} \frac{R_2}{R_1 + R_2} \\
 &= \pm \frac{10 \text{ V}}{4} + \frac{3}{4} V_{CK}
 \end{aligned}$$

$$\underline{V_{OUT,OPAMP} = -10 \text{ V}, E < 0} \rightarrow \text{per } V_{OUT} = +10 \text{ V} \quad \frac{10 \text{ V}}{4} + \frac{3}{4} V_{CK} > 0 \rightarrow V_{CK} > 5,3 \text{ V}$$

$$\underline{V_{OUT,OPAMP} = 10 \text{ V}, E > 0} \rightarrow \text{per } V_{OUT} = -10 \text{ V} \quad -\frac{10 \text{ V}}{4} + \frac{3}{4} V_{CK} < 0 \rightarrow V_{CK} < -5,3 \text{ V}$$



\hookrightarrow Onda quadra $DC = 50\%$, $L = T = 10 \text{ ms}$

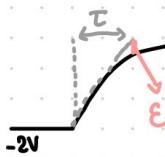
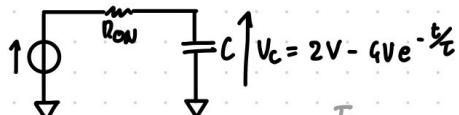
$$\hookrightarrow T_S = T_H = 5 \text{ ms}$$

Calcolare il valore massimo e minimo di V_{IN} compatibili con il S&H

$$\text{SAMPLE} \rightarrow \text{NMOS ON} \rightarrow V_{GS} > V_T \\ V_G - V_S > V_T \rightarrow V_{\text{SAMPLE}} - V_{IN} > V_T \rightarrow V_{IN} < V_{\text{SAMPLE}} - V_T \\ \rightarrow 8,6V$$

$$\text{HOLD} \rightarrow \text{NMOS OFF} \rightarrow V_{GS} < V_T \\ V_G - V_S < V_T \rightarrow V_{\text{HOLD}} - V_{IN} > V_T \rightarrow V_{IN} > V_{\text{HOLD}} - V_T \\ \rightarrow -11,4V$$

Se $V_{IN} \in [-2, 2]V$ stimare il valore massimo di C_{MAX} . Si consideri $E_{MAX} = \frac{1}{2000} V_{IN}$



$$\epsilon = 2V - (2V - 4Ve^{-\frac{\tau_s}{\tau}}) \leq \frac{1}{2000} 2V$$

$$\therefore \tau \leq \frac{\tau_s}{\ln(4V/1mV)} = R_{ON} C$$

$$R_{ON} \cdot \frac{1}{2K_N(V_{GS}-V_T)} = \frac{1}{2 \cdot 5mA/V^2(10V-2V-1V)} = 15,15 \Omega \rightarrow C \leq \frac{\tau}{R_{ON}} = 39,8 \mu F$$

Calcolare $R_{2,MIN}$ che permette al segnale del S&H di avere la forma richiesta

$$\begin{cases} V^+ = 0 \\ V^- = V_{OUT} \frac{R_1}{R_1 + R_2} + V_{CK} \frac{R_2}{R_1 + R_2} \end{cases}$$

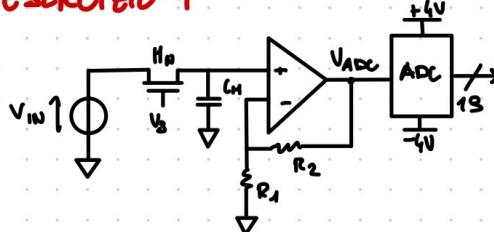
$$V^+ = V^- \rightarrow \dots \rightarrow V_{CK} = \pm 10V \left(\frac{R_1}{R_2} \right) \leq 4V$$

Dove sempre commutare prima dei 4V

$$\Rightarrow R_2 \geq 25k\Omega$$

16/12/21

ESERCIZIO 1



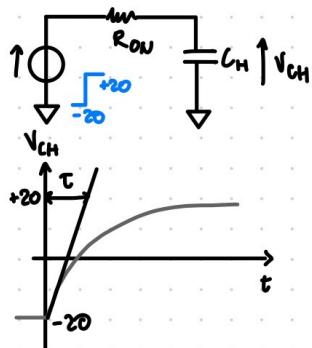
$$\begin{aligned} R_1 &= 1k\Omega \\ R_2 &= 9k\Omega \\ C_H &= 10nF \end{aligned}$$

Qual è il LSB dell'ADC visto all'ingresso dell'OPAMP

$$LSB = \frac{FSR}{2^{13}} = \frac{V_H - V_M}{2^{13}} = \frac{4V + 4V}{2^{13}} \approx 976,5 \mu V$$

$$LSB_{IN} = LSB/G = \frac{976,5 \mu V}{1 + \frac{3k\Omega}{1k\Omega}} = 97,6 \mu V$$

Supponendo $-20 \text{ mV} < V_{IN} < 20 \text{ mV}$ e $R_{ON} = 100 \Omega$, calcolare T_{SAMPLE} minimo compatibile



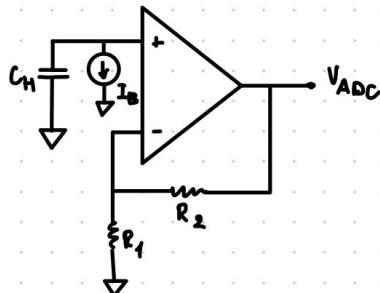
$$V_{CH} = 20 \text{ mV} - 40 \text{ mV} e^{-t/\tau}$$

$$\epsilon = 20 \text{ mV} - V_{CH}(t = T_S) =$$

$$= 40 \text{ mV} e^{-T_S/\tau} \leq LSB_{IN} = 97,6 \mu V$$

$$\Rightarrow T_S \geq \dots = 6 \mu s$$

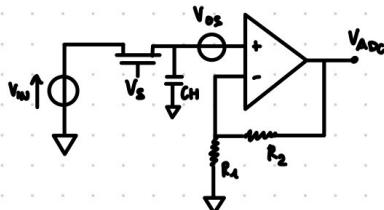
Determinare la massima T_{HAD} se l'OPAMP possiede $I_B = 2 \text{nA}$



$$\Delta V_{CH} = \frac{I_B}{V_{CH}} T_H \leq LSB_{IN}$$

$$\Rightarrow T_H \leq \dots = 488 \mu s$$

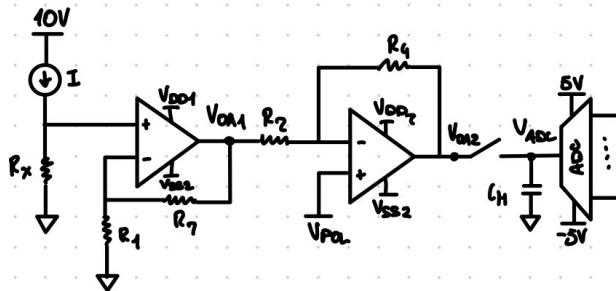
Qual è l'errore causato da una $V_{OS} = 100 \mu V$?



$$\epsilon_{V_{OS}} = V_{OS} = \pm 100 \mu V$$

$$\epsilon / V_{OS} = \frac{V_{OS}}{LSB} = \frac{100}{97,6} \approx 1 \cdot LSB$$

ESERCIZIO 2



$$\begin{aligned}
 R_1 &= 2 \text{ k}\Omega \\
 R_2 &= 49 \text{ k}\Omega \\
 R_3 &= 5 \text{ k}\Omega \\
 R_4 &= 20 \text{ k}\Omega \\
 I &= 100 \mu\text{A} \\
 V_{POL} &= 1 \text{ V}
 \end{aligned}$$

Calcolare il numero di bit dell' ADC sapendo che $\Delta R_x = 0,1 \Omega$

$$\begin{aligned}
 V_{ADC}|_I &= IR_x \left(1 + \frac{R_2}{R_1}\right) \left(-\frac{R_4}{R_3}\right) \Rightarrow V_{ADC} = \dots = 100 \mu\text{A} R_x (-100) + 5 \text{ V} \\
 V_{ADC}|_{V_{POL}} &= V_{POL} \left(1 + \frac{R_4}{R_3}\right)
 \end{aligned}$$

$$\Delta R_x \rightarrow \Delta V_{ADC} = -1 \text{ mV} \Rightarrow \text{LSB} = \frac{F_{SR}}{2^n} \leq 1 \text{ mV} \Rightarrow n \geq \log_2 10000 \approx 15,23 \rightarrow n = 16$$

Calcolare il massimo valore di R_x misurabile.

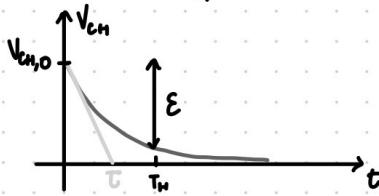
$$-5 \text{ V} \leq V_{ADC} \leq 5 \text{ V} \Rightarrow V_{ADC} = -10 \text{ mA} R_x + 5 \text{ V} \geq -5 \text{ V} \Rightarrow R_x \leq \dots = 1 \text{ k}\Omega$$

Determinare le tensioni di alimentazione degli operazionali affinché il circuito funzioni correttamente. Si considerino gli OPAMP R2R.

$$V_{OA1} = IR_x \left(1 + \frac{R_2}{R_1}\right) = 2,5 \text{ mA} \cdot R_x \rightarrow V_{OA1} \in [0; 2,5] \text{ V} \rightarrow V_{SS1} = 0 \text{ V} \\ V_{DD1} = 2,5 \text{ V}$$

$$V_{OA2} = 5 \text{ V} - 10 \text{ mA} \cdot R_x \rightarrow V_{OA2} \in [-5; +5] \text{ V} \rightarrow V_{SS2} = -5 \text{ V} \\ V_{DD2} = 5 \text{ V}$$

Sia la resistenza in ingresso dell' ADC $100 \text{ k}\Omega \leq R_{ADC} \leq 1 \text{ M}\Omega$. Quanto deve valere C_H affinché $\epsilon < 1 \text{ LSB}$ con $T_H = 10 \mu\text{s}$



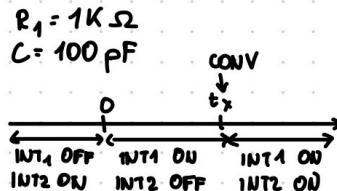
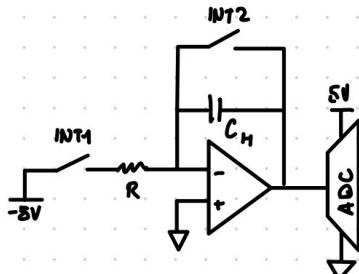
$$\text{PESSIMO: } V_{CH} = 5 \text{ V} e^{-t/\tau}$$

$$\epsilon = 5 \text{ V} - 5 \text{ V} e^{-T_H/\tau} \leq 1 \cdot \text{LSB} = \frac{F_{SR}}{2^n}$$

$$e^{-T_H/\tau} \leq 1 - 2^{-13} \rightarrow \tau \geq \frac{T_H}{\log_2(1-2^{-13})} = 81,9 \text{ ms}$$

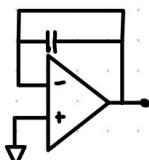
$\xrightarrow{\substack{R_{ADC} C_H \geq 81,9 \text{ ms} \\ \rightarrow C_H \geq \frac{\tau_{MIN}}{R_{ADC}} = 819 \text{ nF}}} \xrightarrow{\substack{81,9 \text{ ms} \\ \rightarrow 400 \text{ K}\Omega}}$

ESEMPIO 3



Dopotutto $t_x = 50 \text{ ms}$, calcolare $V_{out}(t)$ tra $0 \leq t \leq 60 \text{ ms}$

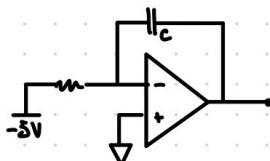
$t < 0 \text{ s}$:



$$V_{out} = 0V$$

$$V_c = 0V$$

$t \in [0; t_x] \Delta:$



$$I_C = \frac{5V}{R} = 5 \text{ mA}$$

$$= C \frac{dV_C}{dt}$$

$$\Rightarrow \frac{dV_C}{dt} = \frac{I_C}{C} = 50 \text{ V/}\mu\text{s}$$

$$\Rightarrow V_C(t) = 50 \text{ V}/\mu\text{s} \cdot t$$

$$\Rightarrow V_{out}(t) = 50 \text{ V}/\mu\text{s} \cdot t$$

$t > t_x$: V_C costante $\Rightarrow V_{out}$ costante

$$V_{out}(t_x) = 50 \text{ V}/\mu\text{s} \cdot 50 \text{ ns} = 2,5 \text{ V}$$

Calcolare il massimo t_x compatibile con la dinamica in ingresso.

$$V_{out} \leq 5 \text{ V} \rightarrow 50 \text{ V}/\mu\text{s} \cdot t_{x,\max} \leq 5 \text{ V} \rightarrow t_{x,\max} \leq 100 \text{ ns}$$

Leggere il numero di bit dell'ADC affinché la risoluzione sia 50 ps.

$$\Delta V_{ADC} = \Delta V_{out} = 50 \text{ V}/\mu\text{s} \cdot \Delta t_x = \dots = 2,5 \text{ mV}$$

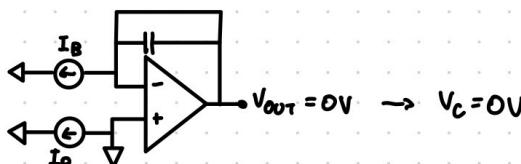
$$LSB_{ADC} \leq 2,5 \text{ mV}$$

$$\frac{FSR}{2^n} \leq 2,5 \text{ mV}$$

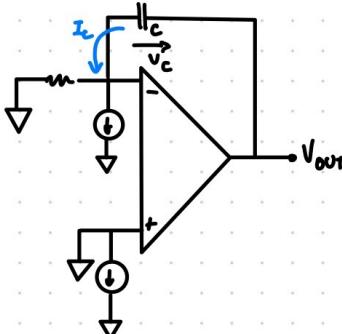
$$\frac{\delta V}{2^n} \leq 2,5 \text{ mV} \rightarrow n \geq \log_2 \left(\frac{\delta V}{2,5 \text{ mV}} \right) = 10,96 \Rightarrow n = 11$$

Calcolare l'effetto sul codice dell'ADC di una corrente di bias $I_B = 100 \mu\text{A}$ entrante con $t_x = 50 \text{ ns}$

$t < t_x$:



$t \in [0; t_x]$:



$$V_{out}|_{I_B} = \frac{I_c}{C} t = \frac{100 \mu\text{A}}{100 \text{ pF}} t = 1 \text{ V}/\mu\text{s} \cdot t$$

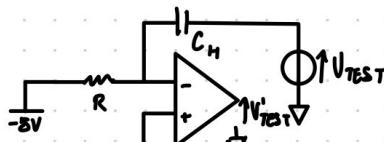
$$V_{out}(t_x)|_{I_B} = 50 \text{ mV}$$

$$LSB \cdot \frac{FSR}{2^{11}} = \frac{5 \text{ V}}{2^{11}} = 2,44 \text{ mV}$$

$$\rightarrow E = 20,5 \text{ LSB}$$

Calcolare il margine di fase con INT1 chiuso e INT2 aperto, $f_o = 10 \text{ Hz}$ e $GBWP = 100 \text{ Hz}$

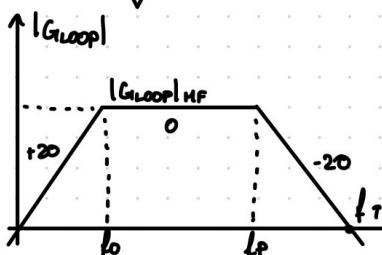
$$GBWP = 100 \text{ Hz}$$



$$G_{loop} = -A(s) \cdot \frac{V}{V_T} = -\frac{A_0}{1+sT_o} \cdot \frac{R}{R + \frac{1}{sC}}$$

$$= -\frac{A_0}{1+sT_o} \frac{sCR}{1+sCR}$$

$$|G_{loop}|_{HF} = \frac{A_0}{sT_o} \cdot \frac{sCR}{1} = A_0 \frac{f_o}{f_p} = \frac{GBWP}{f_p} \frac{f_o}{f_p}$$



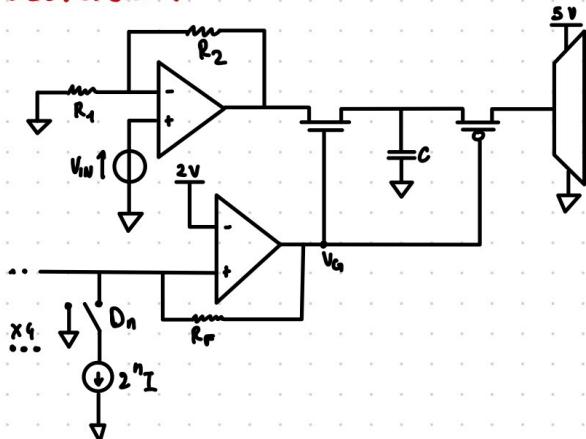
$$f_T = f_p |G_{loop}|_{HF} = GBWP = 100 \text{ MHz}$$

$$\phi = 180^\circ - \arctg\left(\frac{f_1}{f_0}\right) - \arctg\left(\frac{f_1}{f_P}\right) + \arctg\left(\frac{f_1}{f_2}\right)$$

$$= 180^\circ - 90^\circ - 90^\circ + 90^\circ = 90^\circ$$

16/12/21

ESERCIZIO 1



$$I = 250 \text{ nA}$$

$$C_{PAR} = 200 \text{ pF}$$

$$|V_T| = 1 \text{ V}$$

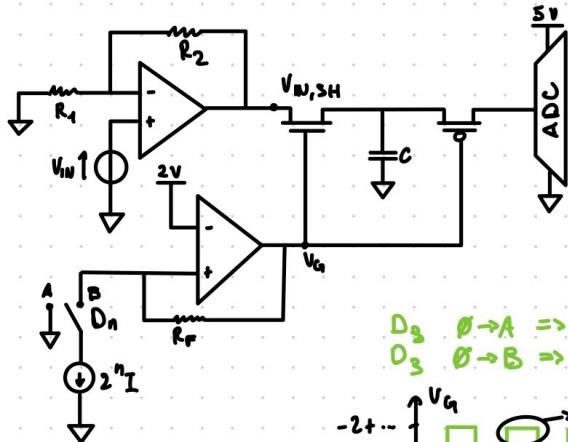
$$m_{bit} = 18$$

$$C = 5 \text{ nF}$$

$$R_1 = 1 \text{ k}\Omega$$

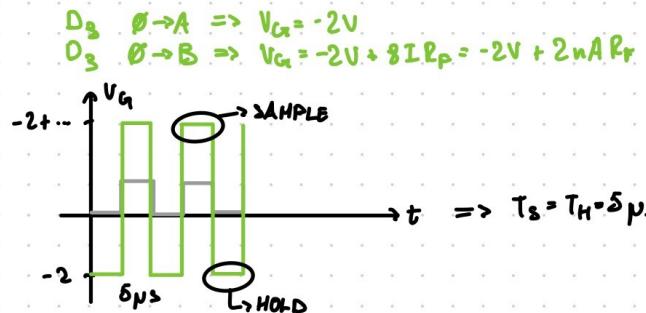
$$R_2 = 24 \text{ }\Omega$$

Si consideri $D_0 = D_1 = D_2 = \emptyset$ e D_3 che oscilla secondo un'onda quadrata di $f = 100 \text{ KHz}$ e $DC = 50\%$, calcolare la $R_{out,max}$ tale che $E < 1 \text{ LSB}$

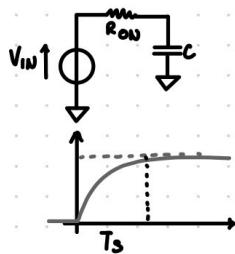


$$V_{IN,SH} = V_{IN} \left(1 + \frac{R_2}{R_1}\right) = 25 V_{IN}$$

IPOTIZZIAMO $V_{IN} = 5 \text{ V}$



$$LSB = \frac{FSR}{2^{15}} = \dots = 0,61 \text{ mV}$$

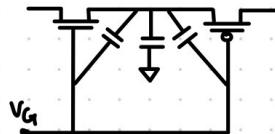


$$\begin{aligned} V_C(t) &= 5V - 5Ve^{-t/\tau} \\ \Rightarrow E &= 5V - V_C(T_s) = 5V - 5V + 5Ve^{-T_s/\tau} \\ \Rightarrow \dots &\Rightarrow \tau \leq 0,55 \text{ ms} \\ R_{ON} &\leq 110 \Omega \end{aligned}$$

Considerando $V_{G,MAX} = 8V$, quale deve essere valore R_F ?

$$V_{G,MAX} = -2V + 2mA \cdot R_F \Rightarrow R_F = 5k\Omega$$

Calcolare l'errore dovuto a charge injection. È minore di 2LSB?



$$E = \Delta V_G \frac{2C_{PAR}}{C + 2C_{PAR}} \approx \frac{2C_{PAR}}{C} \approx 0,8 \text{ mV} \approx 1,3 \text{ LSB}$$

Dimensionare K_{nmax} per avere $R_{ON} < 100 \Omega$

$$R_{ON} = \frac{1}{2K_N(V_{GS}-V_{TN})} < 100 \Omega \Rightarrow K_N > 2,5 \text{ mA/V}^2$$

$$V_{GS} = V_{Gz} - V_S = 8V - V_{IN,SH} \xrightarrow{\text{W.C.}} 8V - 5V = 3V$$

fase di sample

Considerando $A_0 = 10^5$ e $V_{IN} \in [0, 100] \text{ mV}$, calcolare l'errore statico max

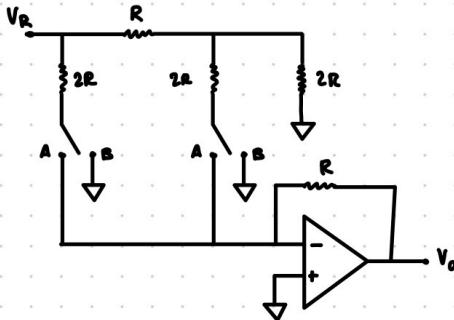
$$V_{IN,SH,1D} = V_{IN} \frac{25}{G_{IDEALE}}, \quad V_{IN,SH} = V_{IN} \cdot G_{REALE} \approx V_{IN} \cdot 25 \left(1 - 25 \cdot 10^{-5}\right)$$

$$G_{REALE} = \frac{G_{IDEALE}}{1 - \frac{1}{G_{LOOP}}} = \dots \approx 25 \left(1 - 25 \cdot 10^{-5}\right)$$

$$G_{LOOP}(0) = -A_0 \frac{V_T}{V_T} = -A_0 \frac{R_1}{R_1 + R_2} = -\frac{10^5}{25}$$

$$\Rightarrow E = V_{IN,SH} - V_{IN,SH,1D} = \dots \approx 1 \text{ LSB}$$

ESERCIZIO 2

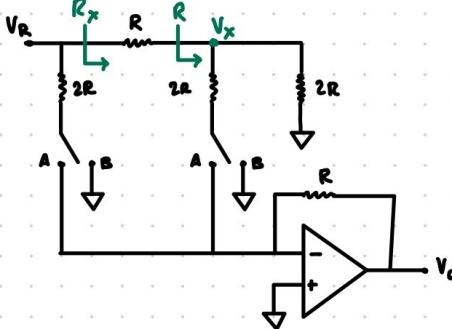


$$R = 5 \text{ k}\Omega$$

$$V_R = -10 \text{ k}\Omega$$

Quanto vale V_o ? Qual è la funzione del circuito?

$$V_+ = V_- = 0 \text{ V}$$



$$R_x = 2R$$

$$V_x = V_R/2$$

$$I_R = \left(\frac{V_R}{2R} \right) \cdot D_1 + \frac{V_R/2}{2R} \text{ DO}$$

$$V_o = -I_R R$$

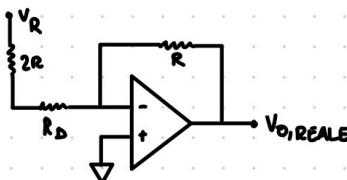
$$= -\frac{V_R}{2} \left(D_1 + D_0/2 \right)$$

Il circuito è un DAC R-2R

Supponendo che gli interruptori derivatori sono degli mos con $K = 1 \text{ mA/V}^2$, $V_{DS} = 4 \text{ V}$, quanto vale R_D ? È l'errore dato $D_0=0$, $D_1=1$?

$$R_{D,ON} = \frac{1}{2 K_N \underbrace{(V_{GS} - V_T)}_{V_{DD}}} \rightarrow R_D = 125 \Omega$$

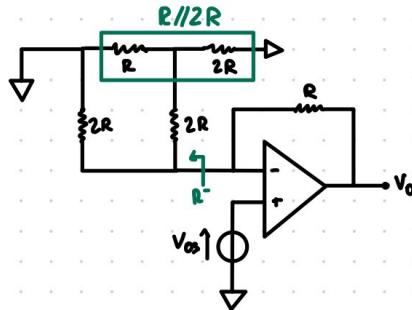
$$V_{O,IDEALE} = -\frac{V_R}{2} \left(D_0 + \frac{D_1}{2} \right) = 5 \text{ V}$$



$$V_{O,REAL} = V_R \left(-\frac{R}{2R + R_D} \right) = \dots = 4,938 \text{ V}$$

$$\Rightarrow E = V_{O,REAL} - V_{O,IDEALE} = -0,062 \text{ V}$$

Calcolare l'errore introdotto da $V_{DS} = \pm 10 \text{ mV}$ con $D_0 = D_1 = 1$.



$$V_o = V_{fb} \left(1 - \frac{R}{R_{-}} \right) = \dots = \pm 18,75 \text{ mV}$$

$$R_{-} = (R//2R + 2R)/1/2R$$

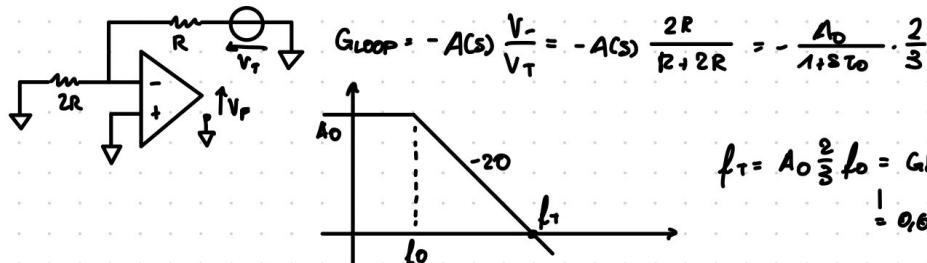
$$= 2R // \left(2R + \frac{2}{3}R \right) = 2R // \frac{8}{3}R = \frac{3}{2}R$$

Considerando $A_0 = 100 \text{ dB}$ e $\text{GBWP} = 1 \text{ MHz}$, come si comporta V_o oltrato $0 \rightarrow 0 \text{V}$?

$$D_0 = 0, D_0 = 0 \rightarrow V_o = 0 \text{V}$$

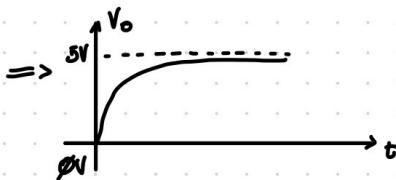
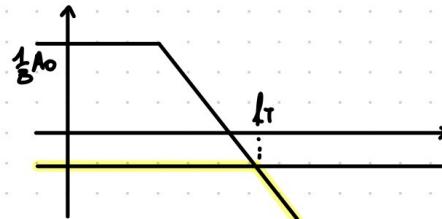
$$D_0 = 0, D_0 = 1 \rightarrow V_o = -V_o/2 = 5 \text{V}$$

$$G_{ID} = \frac{V_o}{V_R} = \frac{5\text{V}}{-10\text{V}} = -\frac{1}{2} \text{V},$$



$$G_{OPEN} = -G_{ID} \cdot G_{LOOP} = \dots = -\frac{A_0}{1+sT_0} \cdot \frac{1}{3}$$

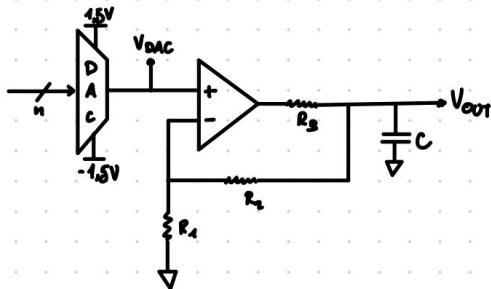
$$G_{REAL} = \begin{cases} G_{ID} & f < f_T \\ \frac{A_0}{1+sT_0} \cdot \frac{1}{3} & f > f_T \end{cases}$$



$$\tau = \frac{1}{2\pi f_T} \approx 0,24 \text{ } \mu\text{s}$$

17/12/21

ESERCIZIO 1



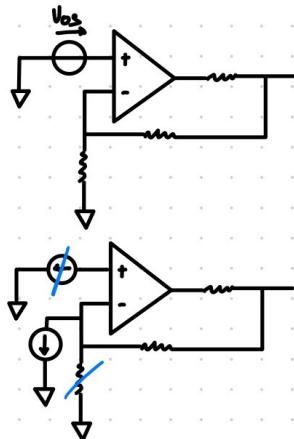
$$\begin{aligned}R_1 &= 10 \text{ k}\Omega \\R_2 &= 30 \text{ k}\Omega \\R_3 &= 20 \text{ k}\Omega \\C &= 25 \text{ nF}\end{aligned}$$

Considerando una risoluzione di $1V$ e $\Delta V = 1/1000 A_p$, qual è il n_{bit} minimo?

$$\Delta V_{DAC} < \frac{1}{1000} \text{ V} = 1 \text{ mV}$$

$$LSB = \frac{FS}{2^n_{bit}} \rightarrow n_{bit} = \log_2 \left(\frac{3V}{1 \text{ mV}} \right) \approx 11,55 \Rightarrow n_{bit} = 12$$

Considerando una $V_{os} = \pm 0,4 \text{ mV}$ e $I_B = 20 \text{ nA}$ entrante, qual è il massimo numero di bit affinché l'LSB in uscita sia maggiore del contributo delle non idealità.



$$V_o | V_{os} = V_{os} \left(1 + \frac{R_1}{R_2} \right) = \dots = \pm 1,6 \text{ mV}$$

$$V_o | I_B = I_B R_2 = \dots = 0,6 \text{ mV}$$

$$V_o | V_{os} + I_B = \pm 1,6 \text{ mV} + 0,6 \text{ mV} = \begin{cases} 2,2 \text{ mV} & (\text{per verso}) \\ -1 \text{ mV} & \end{cases}$$

$$LSB_{out} = LSB_{DAC} \left(1 + \frac{R_1}{R_2} \right) = 4 \cdot LSB_{DAC} \geq 2,2 \text{ mV}$$

$$\rightarrow \dots \rightarrow n = 12,41 \Rightarrow n = 12$$

Si assume ora $A(3)=A_0=10^4$. Qual è l'errore massimo

$$G_{ID} = 4$$

$$G_{LOOP} = -A(s) \frac{V_-}{V_T} = A_0 \cdot \frac{R_1}{R_1 + R_2 + R_3} = \dots = -\frac{10^4}{6} \Rightarrow G_{REALE} = \frac{G_{ID}}{1 - \frac{1}{G_{LOOP}}} = \dots \\ = 4(1 - 6 \cdot 10^4)$$

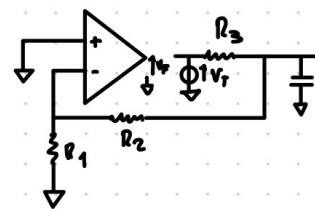
$$\epsilon = V_{DAC} (G_{REALE} - G_{ID}) = V_{DAC} (4 \cdot 4 \cdot 6 \cdot 10^{-4} + 4)$$

$$\hookrightarrow \epsilon_{MAX} = \pm 3,6 \text{ mV}$$

All'istante $t=0$ il DAC passa dal valore minimo al quello massimo.
In quale istante di tempo $V_{out} = 0V$?



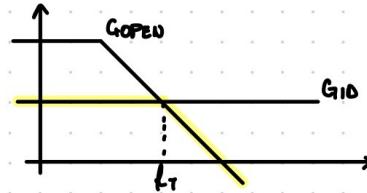
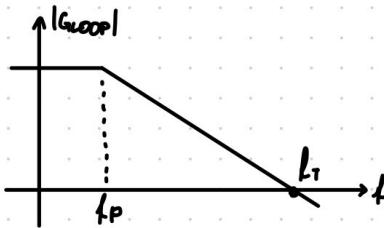
Se consideriamo C , varia G_{LOOP} :



$$-A_0 \cdot \frac{(R_1 + R_2) / 1^{1/SC}}{(R_1 + R_2) / 1^{1/SC} + R_3} \cdot \frac{R_1}{R_1 + R_2} = \\ = -A_0 \frac{R_1}{R_1 + R_2 + R_3} \frac{1}{1 + SC(R_1 + R_2)/R_3}$$

$$\hookrightarrow f_P = \dots = 482,53 \text{ Hz}$$

$$G_{OPEN} = -G_{ID} \cdot G_{LOOP} = \dots = -\frac{2}{3} \cdot 10^4 \frac{1}{1 + s \tau_p}$$



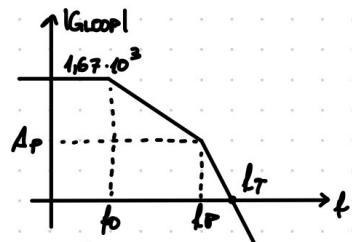
\Rightarrow Voor esponentiële con $\tau = \frac{1}{2\pi f_P}$

$$V_C = -6V + 12Ve^{-\frac{t}{\tau}} \Rightarrow \dots \Rightarrow t^* = 137,9 \text{ ms}$$

Considerando $A(s)$ con un polo e $A_0 = 10^4$, $G_{BWP} = 1 \text{ MHz}$ discutere la stabilità.

$$G_{LOOP} = -\frac{A_0}{1 + s \tau_0} \cdot \frac{R_1}{R_1 + R_2 + R_3} \cdot \frac{1}{1 + SC(R_1 + R_2)/R_3}$$

$$f_0 = \frac{G_{BWp}}{A_0} = 100 \text{ MHz}$$



$$A_P/f_P = \frac{1,67 \cdot 10^3 \cdot 100 \text{ Hz}}{482,53 \text{ Hz}} = 346,2$$

$$f_T = \sqrt{A_P f_P} = 9,97 \text{ kHz}$$

$$\phi_H = 180 - \text{arctg}\left(\frac{f_T}{f_0}\right) - \text{arctg}\left(\frac{f_T}{f_P}\right) \approx 180 - 90^\circ - 90^\circ = 0^\circ \quad \text{AS. STABILE}$$