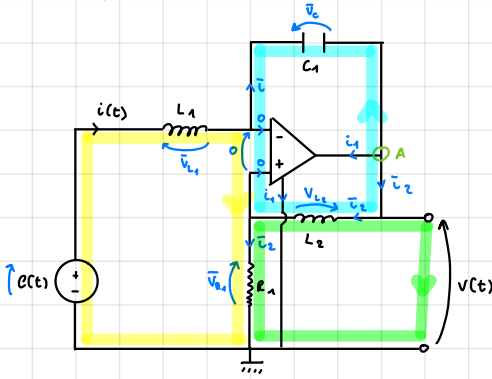


ESERCITAZIONE

ESERCIZIO 14.1



$$L_1 = 1 \text{ H} \quad R_1 = 2 \, \Omega$$

$$L_2 = 2 \text{ H} \quad C_1 = 1 \text{ F}$$

$$v(t) = \sin(\omega t) \text{ V}$$

$$v(t) = ? \quad i(t) = ? \quad p_{\text{avg}}(\omega) = ?$$

$$Z_{L1} = j\omega L_1 = j \, \Omega$$

$$v(t) = \cos(\omega t - \frac{\pi}{2}) \rightarrow \bar{v} = e^{-j\frac{\pi}{2}} = -j \text{ V}$$

$$Z_{L2} = j\omega L_2 = 2j \, \Omega$$

$$Z_{C1} = \frac{1}{j\omega C_1} = -j \, \Omega$$

$$\bar{V}_{L1} = j\bar{v}, \quad \bar{V}_C = -j\bar{v}$$

$$Z_{R1} = R_1 = 2 \, \Omega$$

$$\bar{V}_{L2} = 2j\bar{v}, \quad \bar{V}_{R1} = 2\bar{v}_2$$

$$\bar{v}_C = -\bar{V}_{L2} = +j\bar{v} \rightarrow 2j\bar{v}_2 = j\bar{v} \rightarrow \bar{v}_2 = \frac{\bar{v}}{2}$$

$$\bar{v} - \bar{V}_{L1} = \bar{V}_R \rightarrow \bar{v} - \frac{-j-1}{2} = \dots = \frac{\sqrt{2}}{2} e^{j\frac{\pi}{4}} \Rightarrow i(t) = \frac{\sqrt{2}}{2} \cos(\omega t + \frac{\pi}{4}) \text{ A}$$

$$\bar{v} = \bar{V}_{R1} + \bar{V}_{L2} \rightarrow \bar{v} = (1+j)\bar{v} = \dots = e^{-j\frac{\pi}{2}} \Rightarrow v(t) = \cos \pi t (\omega t - \frac{\pi}{2}) = \sin(\omega t) \text{ V}$$

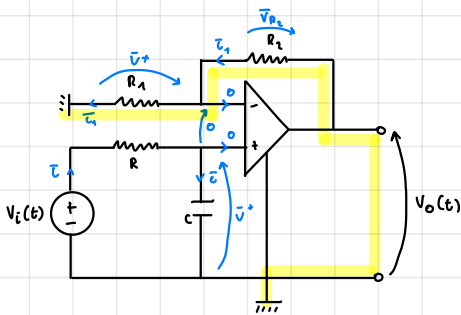
$$\bar{v}_1 = \frac{\bar{v}}{2} = \frac{1+j}{4}$$

$$\bar{A} = \frac{1}{2}(-j) \left(\frac{1-j}{4} \right) = \frac{1}{8} + j\frac{1}{8} \rightarrow P = \frac{1}{8}$$

$$|\bar{A}| = \dots = \frac{\sqrt{2}}{8}$$

$$\Rightarrow P_{\text{avg}}(t) = P + |\bar{A}| \cos(2\omega t + 2\bar{v} + \bar{v}) = \frac{1}{8} + \frac{\sqrt{2}}{8} \cos(2\omega t + \frac{3}{4}\pi)$$

ESERCIZIO 2



$$R_1 = 1 \text{ K}\Omega$$

$$C = 100 \, \mu\text{F}$$

$$R_2 = 10 \text{ K}\Omega$$

$$v_i(t) = 5 \cos(\omega t + \frac{\pi}{3}) \text{ V}$$

$$R = 100 \, \Omega$$

$$v_o(t) = ? \quad \left| \begin{array}{l} \omega_1 = 100 \text{ rad/s} \\ \omega_2 = 100 \text{ Krad/s} \\ \omega_3 = 100 \text{ Mrad/s} \end{array} \right.$$

che filtro è?

$$\bar{v}_i = 5 e^{j\frac{\pi}{3}}$$

$$Z_R = R, \quad Z_{R1} = R_1, \quad Z_{R2} = R_2$$

$$Z_C = -j\frac{1}{\omega C}$$

$$\bar{v}^+ = \bar{v}_i \frac{Z_C}{Z_R + Z_C} \rightarrow \bar{v}_1 = \frac{\bar{v}^+}{Z_{R1}}$$

$$\bar{v}_0 = \bar{v}_{R1} + \bar{v}^+ = Z_{R2} \bar{v}_1 + \bar{v}^+ = \bar{v}_i \left(1 + \frac{Z_{R2}}{Z_{R1}} \right) = \bar{v}_i \left(\frac{Z_C}{Z_R + Z_C} \right) \left(1 + \frac{Z_{R2}}{Z_{R1}} \right) = \left(1 + \frac{R_2}{R_1} \right) \frac{1}{1 + j\omega RC} \bar{v}_i$$

$$H(j\omega) = \frac{\bar{v}_0(j\omega)}{\bar{v}_i(j\omega)} = \left(1 + \frac{R_2}{R_1} \right) \frac{1}{1 + j\omega RC} = \left(1 + \frac{R_2}{R_1} \right) \frac{1}{1 + j\frac{\omega}{\omega_1}}$$

$$|H(j\omega)| = \left| 1 + \frac{R_2}{R_1} \right| \cdot \left| 1 + j\frac{\omega}{\omega_1} \right| = \left(1 + \frac{R_2}{R_1} \right) \cdot \sqrt{1 + \frac{\omega^2}{\omega_1^2}}$$

$$\arg(H(j\omega)) = \angle \left(1 + \frac{R_2}{R_1} \right) + \angle \left(1 + j\frac{\omega}{\omega_1} \right) = -\arctan\left(\frac{\omega}{\omega_1}\right)$$

$$\left. \begin{array}{l} |H(j\omega)| = \prod |P| \\ \arg(H(j\omega)) = \sum \angle P \end{array} \right\}$$

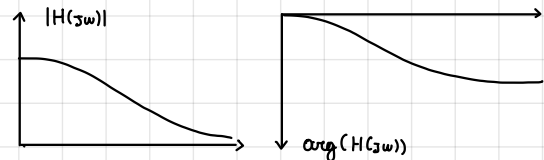
↓

$$\omega \rightarrow 0 : |H(j\omega)| = 1 + \frac{R_2}{R_1} ; \arg(H(j\omega)) = 0$$

$$\omega \rightarrow \infty : |H(j\omega)| = 0 ; \arg(H(j\omega)) = -\frac{\pi}{2}$$

$$\omega \rightarrow \omega_1 : |H(j\omega)| = \frac{\sqrt{2}}{2} ; \arg(H(j\omega)) = -\frac{\pi}{4}$$

⇒



↓
filtro passa-basso

$$v_o(j\omega) = \bar{H}(j\omega) \cdot \bar{v}_i(j\omega) = |H| |\bar{v}_i| e^{j(LH + L\phi)} \Rightarrow v_o(t) = \dots = 5 \cdot \frac{1}{\sqrt{1 + (\omega/\omega_1)^2}} \cdot \cos(\omega t + \frac{\pi}{3} - \arctan(\frac{\omega}{\omega_1}))$$

$$v_o(t) \quad \left| \begin{array}{l} \omega_1 \\ \omega_2 \end{array} \right. = \dots$$

