

Denoising-Diffusion Models

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Introduction

- Denoising Diffusion Models (DDMs) are a class of generative models that have gained significant attention in recent years.
- They play a crucial role in the field of generative modeling, offering a unique approach to image generation and data synthesis.
- DDMs are composed of two fundamental components: the diffusion process and the generation process. These components work together to create high-quality and realistic samples.

Diffusion Process

- The diffusion process is a fundamental component of Denoising Diffusion Models (DDMs). It serves as the foundation for generating high-quality samples.
- In the diffusion process, noise is incrementally added to an input image. This step-by-step addition of noise gradually transforms the clean image into a noisy version.

Diffusion Process

$$x_{t+1} = \sqrt{\beta} x_t + \epsilon_t, \epsilon_t \in N(0, \beta)$$

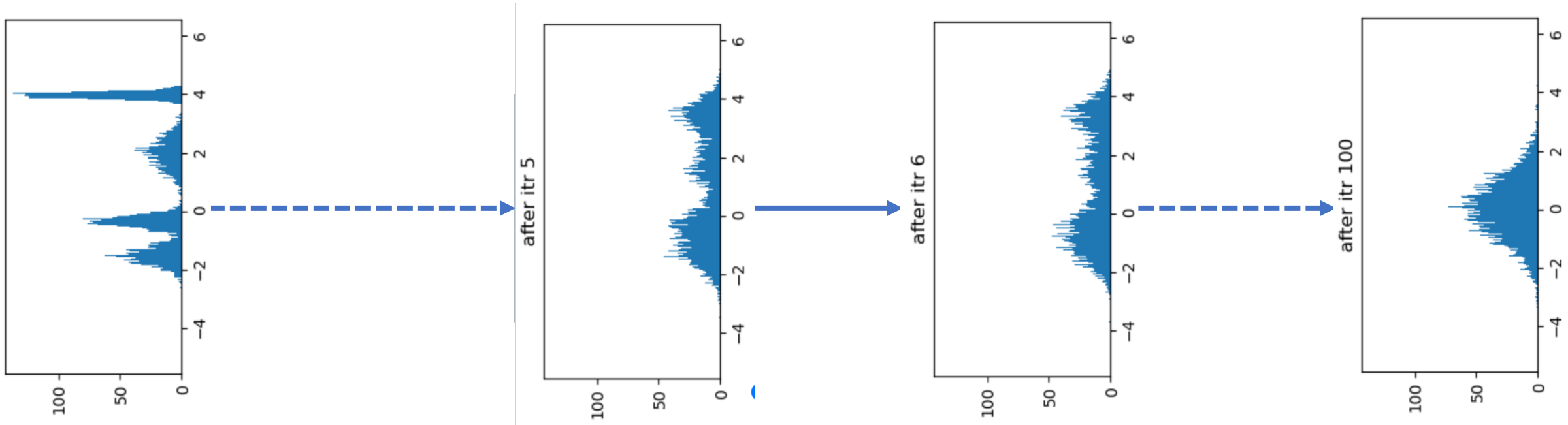
$$x_t = \alpha_t x_0 + \epsilon, \epsilon \in N(0, \sigma_t)$$

$$\alpha_t = \sqrt{\prod_{i=1..t} (1 - \beta_i)}$$

$$\sigma_t = \sqrt{1 - \alpha_t^2}$$

Diffusion Process

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after itr 20



0 200 400 600 800

after itr 24



0 200 400 600 800

after itr 196



0 200 400 600 800

Denoising Model

The denoising model is then trained to predict the added noise on each step.

$$\min_{\theta} \mathbb{E}_{t \sim U\{1, T\}, \mathbf{x}_0 \sim p(\mathbf{x}_0), \epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})} [w(t) \|\epsilon - \epsilon_{\theta}(\alpha_t \mathbf{x}_0 + \sigma_t \epsilon, t)\|_2^2], \quad w(t) = \frac{\beta_t^2}{2\rho_t^2(1 - \beta_t)(1 - \alpha_t^2)},$$



$$\mathbf{x}_{t-1} = \frac{1}{\sqrt{1-\beta_t}} \left(\mathbf{x}_t - \frac{\beta_t}{\sqrt{1-\alpha_t^2}} \epsilon_{\theta}(\mathbf{x}_t, t) \right) + \rho_t \boldsymbol{\eta},$$

Generation Process

- In DDMs, the generation process is where high-quality samples are created from noisy images generated during the diffusion process.
- The generation process involves a generative network that transforms noisy data into realistic samples.
- The process is sequentially predicting the noise to be subtracted at each denoising iteration

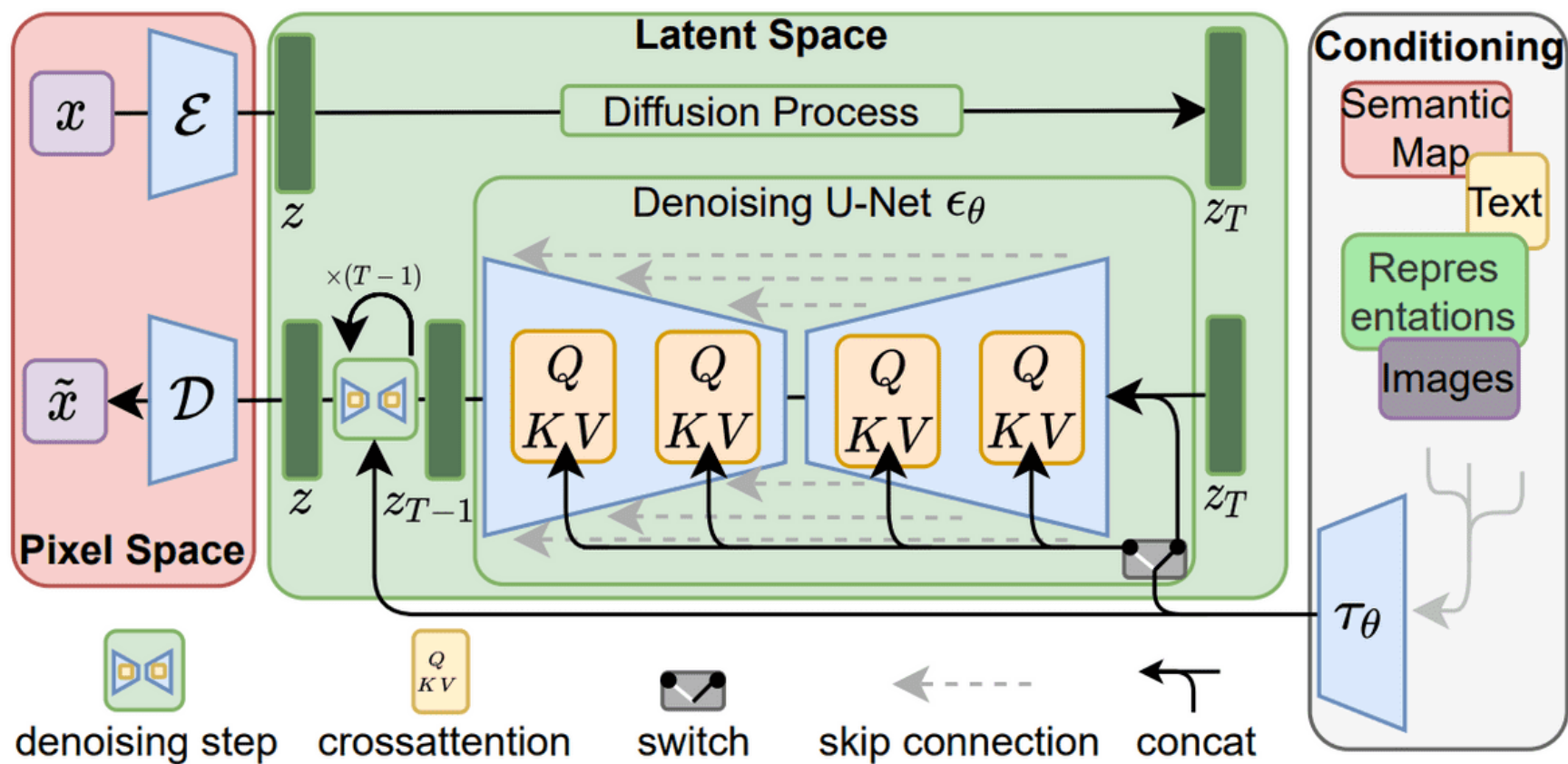
Generation Process

- **Generative Network:** A neural network, often a deep neural network or a variational autoencoder (VAE), is employed to map noisy images to high-quality samples.
- **Gradual Improvement:** The generative network progressively refines the noisy images, reducing noise and enhancing details at each step.
- **Sampling:** During training, the generative network samples from a noise distribution to generate various versions of the same image.

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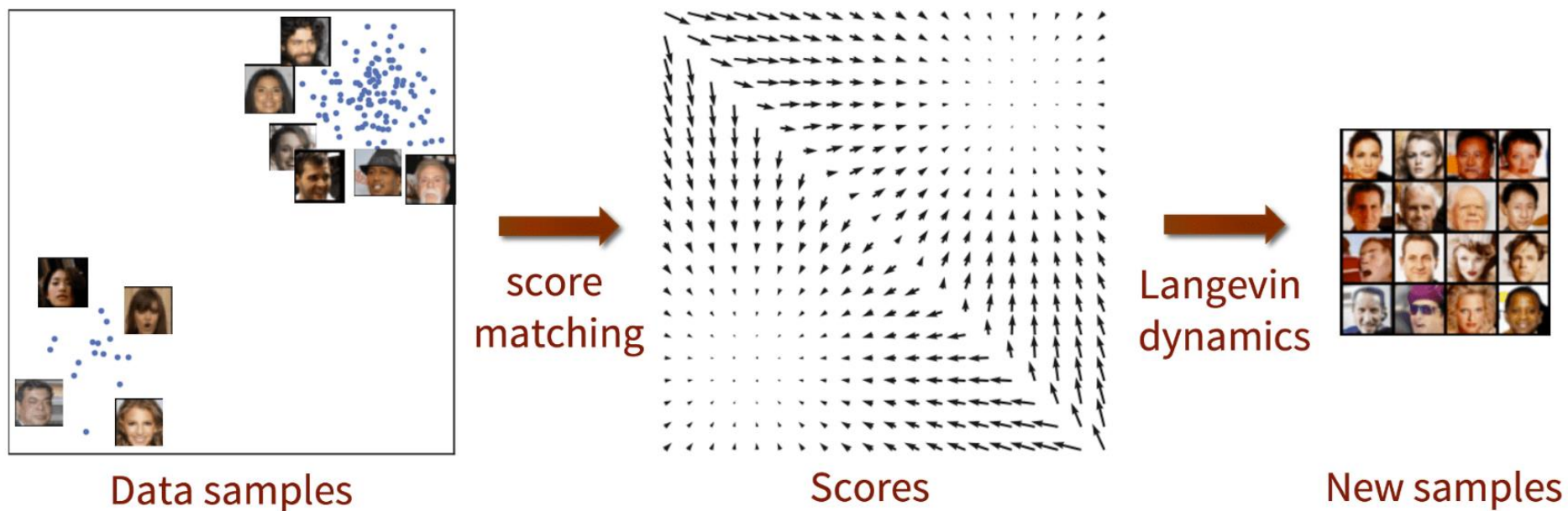
Rombach et al

Challenges in Training DDMs

- **Computational Complexity:** DDMs can be computationally intensive, requiring substantial resources for training and inference.
- **Hyperparameter Tuning:** Properly configuring hyperparameters is crucial for DDMs, and finding the right settings can be challenging.
- **Data Size:** DDMs often require large datasets for effective training, which may not be readily available in some domains.

Advances in DDMs

- **Improved Sampling Methods:** Recent research has introduced more efficient sampling techniques, reducing the computational burden of DDMs.
- **Transfer Learning:** Applying pre-trained DDMs to new tasks or domains has become more accessible, thanks to advances in transfer learning.
- **Scalability:** Efforts to make DDMs more scalable have led to the development of smaller, more efficient models suitable for various applications.



$$\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N\} \stackrel{\text{i.i.d.}}{\sim} p(\mathbf{x})$$

$$\mathbf{s}_\theta(\mathbf{x}) \approx \nabla_{\mathbf{x}} \log p(\mathbf{x})$$

Score-based generative modeling with score matching + Langevin dynamics. Source: [Generative Modeling by Estimating Gradients of the Data Distribution](#)