Technical Computing for the Earth Sciences, Lecture 2:

Solving some linear inverse problems for the Earth sciences

EARS 80.03

You're already solving a linear inverse problem: Project 1!

 All the detailed matrix math is there, so I won't repeat it here, just a few really general concepts instead..

Generalized linear inverse problem: you have

- some data y
- an equation of the form y =

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a*(something) + b*(something\ else) + c*(something\ else\ else) + \dots
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(where each *something* is a different function of x)

and you want to invert for a, b, c, ...

Or in matrix form: $y = A * \phi$ where $\phi = [a, b, c, ...]$

What's the difference between *linear* and *nonlinear* inverse problems??

Invert for constants a through Linear or nonlinear inverse problem?

$$y =$$

1)
$$a + b * x + c * x^2 + d * x^3 + \dots$$

2)
$$a + b * x + c * x^2 + d * x^3 + e * sin(x) + f * log(x)$$

3)
$$a+b*x+c*x^2+d*x^3+e*sin(x/g)+f*log(h*x)$$

$$a + b * x^c$$

Invert for constants a through Linear or nonlinear inverse problem?

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3)
$$a + b * x + c * x^2 + d * x^3 + e * sin(x/g) + f * log(h * x)$$

$$a + b * x^c \times$$