Parameter confidence estimation using the Monte Carlo bootstrap algorithm

Get some confidence estimates

1.1 Introduction

The Monte Carlo plugin is used to get estimates of a models parameters confidence limits. This is in the context where experimental data exists and a parameter minimization method, such as Levenberg-Marquardt or Nelder-Mead is used first in order to find a parameter minimum.

The Monte Carlo algorithm is used subsequently at this minimum and will give an estimate of parameter confidence limits corresponding to the variance in the original experimental data.

The plugin has properties such as the size of the Monte Carlo population, minimization algorithm to use (e.g. Nelder-Mead or Levenberg-Marquardt), and on output, confidence limits for each involved parameter.

Plugin properties are documented in more detail in the next section.

1.2 Plugin Properties

Available properties in the Monte Carlo plugin are listed in the table below.

Property Name	Data Type	Default Value	Description
SBML	string	N/A	SBML document as a string. Model to be used by the
			Monte Carlo plugin.
ExperimentalData	telluriumData	N/A	Input data.
Input Parameter List	listOfProperties	N/A	Parameters to estimate confidence limits for.
MonteCarloParameters	s listOfProperties	N/A	Parameters obtained from a Monte Carlo session.
ConfidenceLimits	listOfProperties	N/A	Confidence limits for each fitted parameter. The confi-
			dence limits are calculated at a 95% confidence level.
Experimental-	stringList	N/A	Selection list for experimental data.
DataSelectionList			
${\bf Fitted Data Selection Lis}$	st stringList	N/A	Selection list for model data.
NrOfMCRuns	int	N/A	Number of Monte Carlo data sets to generate and use.
MinimizerPlugin	string	N/A	Minimizer used by the Monte Carlo Engine, e.g. "Lev-
			$enberg_Marquardt".$

Table 1.1: Plugin Properties

1.3 The execute(bool inThread) function

The execute() function will start the Monte Carlo algorithm. Depending on the problem at hand, the algorithm may run for a long time.

The execute(bool inThread), do support a boolean argument indicating if the execution of the plugin work will be done in a thread, or not. Threading is fully implemented in the Monte Carlo plugin.

The inThread argument defaults to false.

Each generated Monte Carlo dataset is available in a file named, MCDataSets.dat (saved in current working directory).

1.4 Plugin Events

The Monte Carlo plugin are using all of a plugins available plugin events, i.e. the *PluginStarted*, *PluginProgress* and the *PluginFinished* events.

The available data variables for each event are internally treated as *pass trough* variables, so any data, for any of the events, assigned prior to the plugins execute function (in the assingOn() family of functions), can be retrieved unmodified in the corresponding event function.

Event	Arguments	Purpose and argument types
PluginStarted	void*, void*	Signal to application that the plugin has started. Both parameters are pass trough parameters and
		are unused internally by the plugin.
PluginProgress	void*, void*	Communicating progress of fitting. Both parameters are <i>pass trough</i> parameters and are unused internally by the plugin.
PluginFinished	void*, void*	Signals to application that execution of the plugin has finished. Both parameters are <i>pass trough</i> parameters and are unused internally by the plugin.

Table 1.2: Plugin Events

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1.5 Python example

The following Python script illustrate how the plugin can be used.

```
1 from telplugins import *
  import matplotlib.pyplot as plt
3
4
   try:
5
       #Load plugins
                  = Plugin("tel_test_model")
6
       modelP
                   = Plugin("tel_add_noise")
7
       nP
                  = Plugin("tel_chisquare")
8
       chiP
9
       lmP
                  = Plugin("tel_levenberg_marquardt")
                  = Plugin("tel_nelder_mead")
10
       nmP
                   = Plugin("tel_monte_carlo_bs")
11
       mcP
12
       #====== EVENT FUNCTION SETUP ================================
13
14
       def myEventFunction(ignore):
15
           # Get the fitted and residual data
16
           experimentalData = lmP.getProperty ("ExperimentalData").toNumpy
                                = lmP.getProperty ("FittedData").toNumpy
17
           fittedData
                                = lmP.getProperty ("Residuals").toNumpy
18
           residuals
19
20
           telplugins.plot(fittedData
                                                [:,[0,1]], "blue", "-",
                  "S1 Fitted")
21
           telplugins.plot(fittedData
                                                [:,[0,2]], "blue", "-",
                  "S2 Fitted")
                                                [:,[0,1]], "blue", "None", "x",
22
           telplugins.plot(residuals
                 "S1 Residual")
                                                [:,[0,2]], "red", "None", "x",
23
           telplugins.plot(residuals
                 "S2 Residual")
                                                [:,[0,1]], "red",
           telplugins.plot(experimentalData
                                                                   0.0
24
                 "S1 Data")
                                                [:,[0,2]], "blue", "",
25
           telplugins.plot(experimentalData
                 "S2 Data")
26
           print 'Minimization finished. \n==== Result ===='
27
28
           print getPluginResult(lmP.plugin)
29
           telplugins.plt.show()
30
31
       #Communicating event
32
       myEvent = NotifyEventEx(myEventFunction)
33
       #Uncomment the event assignment below to plot each monte carlo data set
34
35
       #assignOnFinishedEvent(lmP.plugin, myEvent, None)
36
37
       #This will create test data with noise. We will use that as '
           experimental, data
38
       modelP.execute()
39
40
       #Setup Monte Carlo properties.
41
                                              = modelP.Model
       mcP.SBML
42
       mcP.ExperimentalData
                                              = modelP.TestDataWithNoise
43
```

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```
44
       #Select what minimization plugin to use
45
       #mcP.MinimizerPlugin
                                               = "Nelder-Mead"
46
       mcP.MinimizerPlugin
                                              = "Levenberg-Marquardt"
       mcP.NrOfMCRuns
47
                                              = 100
       mcP.InputParameterList
                                              = ["k1", 1.5]
48
                                       = "[S1] [S2]"
List = "[S1] [S2]"
       mcP.FittedDataSelectionList
49
50
       mcP.ExperimentalDataSelectionList
51
52
       # Start Monte Carlo
53
       mcP.execute()
54
       print 'Monte Carlo Finished. \n==== Result ===='
55
       print mcP.MonteCarloParameters.getColumnHeaders()
56
57
       paras = mcP.MonteCarloParameters.toNumpy
58
       print paras
59
60
       #Get mean (assuming normal distribution).
       print "The mean: k1= " + 'np.mean(paras)'
61
62
63
64
       PropertyOfTypeListHandle = getPluginProperty(mcP.plugin, "
           ConfidenceLimits")
65
       print 'getNamesFromPropertyList(PropertyOfTypeListHandle)'
66
       aProperty = getFirstProperty(PropertyOfTypeListHandle)
67
       if aProperty:
            print getPropertyValueAsString(aProperty)
68
69
70
       #Show MOnte Carlo parameters as a histogram
71
       plt.hist(paras, 50, normed=True)
72
       plt.show()
73
74
       #Plot Monte Carlo data sets
75
       #dataSeries = DataSeries.readDataSeries("MCDataSets.dat")
76
       #dataSeries.plot()
77
78
       #Finally, view the manual and version
79
       mcP.viewManual()
80
       print 'Plugin version: ' + 'mcP.getVersion()'
81
82
83
   except Exception as e:
84
       print 'Problem.. ' + 'e'
```

Listing 1.1: Monte Carlo plugin example.

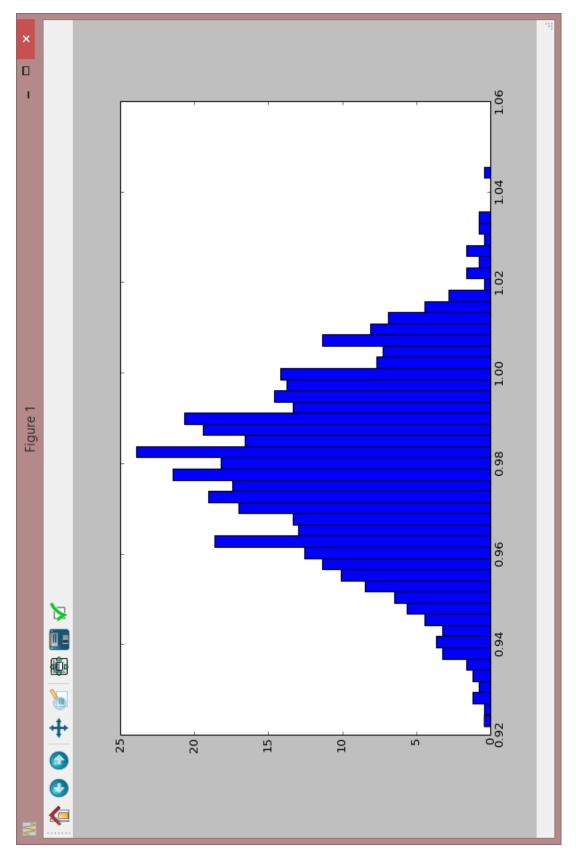


Figure 1.1: Output for the example script above, using 1000 Monte Carlo runs. The histogram shows the distribution for the model parameter, 'k1'. The mean for the distribution was 0.980 and obtained confidence limits were +/- 0.001.