April 28
The question: are there problems that can't be
solved efficiently no matter how hard use revoli.
Computational Complexity / NP-C. NP-hard
Efficiently = polynomial time solution /alswichen
1) Polynomial Time Reduction
DP. NP, NP-had NP-C
3) Hur to show a publish is MP-hand by vedy rion

Problem & 2-pareition. non-negative integral

Given a set Styn numbers.

S= {Si, Si, -, Sn}

Is there a subset Si of Si such that the

sum of all the integers below to Si, is enearly

1/2 of the sun of all the numbers in Si;

Find S, such that

$$\frac{5}{5} s = \frac{1}{2} \frac{5}{5} s$$

$$seS$$

Example: S= {1,2,3,4}

Answer: Yes, Si= {1,4}

Solution:

(1) Fireach SES, we will invulue an icom obj

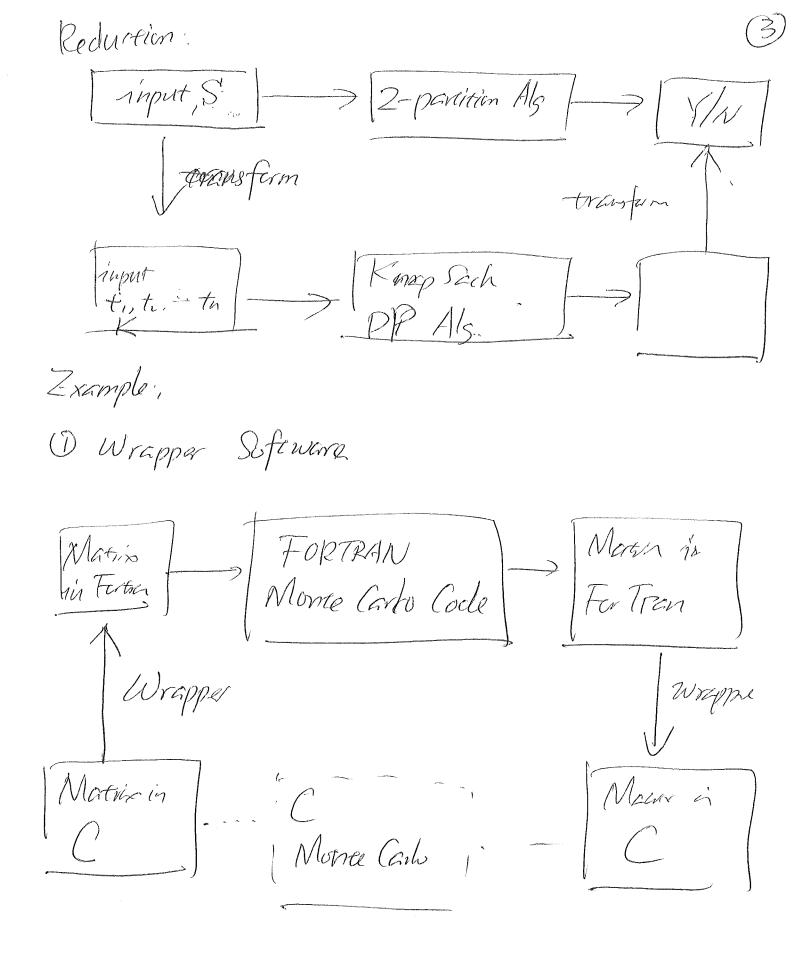
rubose value is Sj and whose size is also Sj.

Let the Knapsach size $K = \frac{1}{2} \sum_{S \in S} S_j$ (1) The Knapsach Problem

(2) The Knapszch Publem
Items: t., t., - , ta

Find a subset of items to fit in the Knapsachahile maximing the value.

(5) If the optimal solution has value K, answer Yes to 2-pareity



Polynomial Time Reduction

Let A, B he two dage algorithmic problems.

A: input (A) -> solution (A)

B: input (B) -> Solution (B)

We say that A is polynomial time reducible

to B if arbitrary input invance of A can

be solved using a polynomial number of disvete sceps

for conversion of the input (A) to input (B) and

solveton (B) to solveton (A) plus a polynomial

number of calls to the black has for solving B.

Trapet (A) = Rublen A = Sche (A)

polynomial polynomial

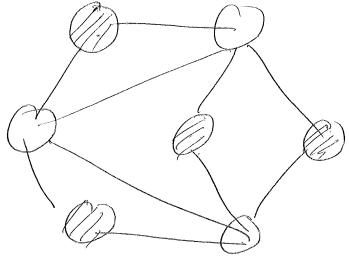
Trapet (B) = Schra (B)

Schra (B)

Zxample:

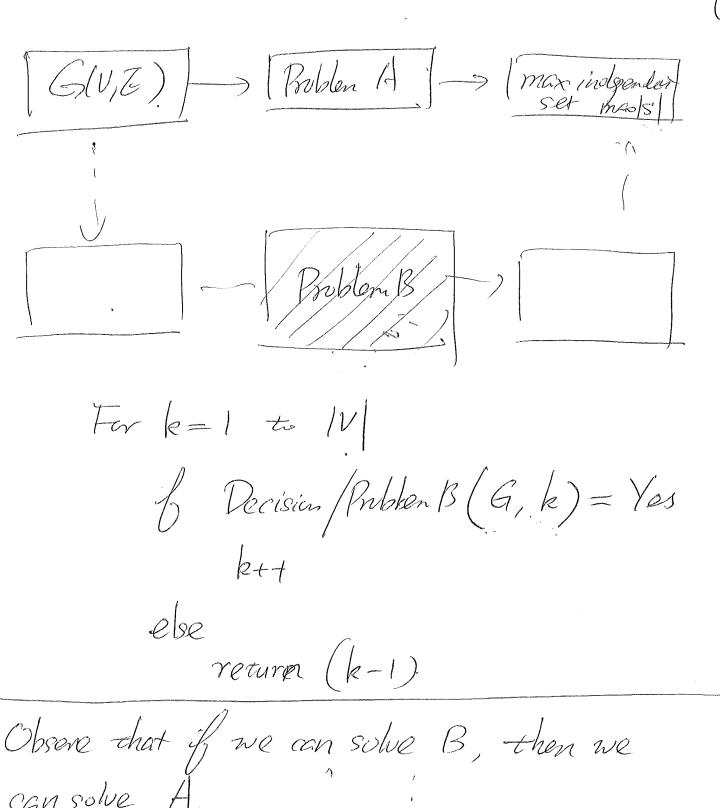
independent set: Given an undirected graph G(V,E) con independent set is a subset S of vertice, such that no two vertices in S are adjacent

(joined by an edge in E)



Problem A: maximum inclependent set maximie [5]

Problem B: Given G(V,Z) and an inceps $k \leq |V|$ Is there an independent set of size k? Can you reduce A to B in polynomial time?



can solve A:

B is at lean as hard as A

Running time of the detour T(A) = polynomial + polynemost. T(B) $T(A) = P(n) + Q(n) \cdot T(R)$ Observation 1: if B can be solved in polynomial time, then A can be solved in polynomial time also Observation 2: If A can't be solved in polynomial time, schen B can't be solved in polynomial time eider T(A) of polynomial T(A) & T(A) & polynamid P(h)+ Q(h). T(b) De polynomial T(B) > polynomia |

Observe that if your problem is B,

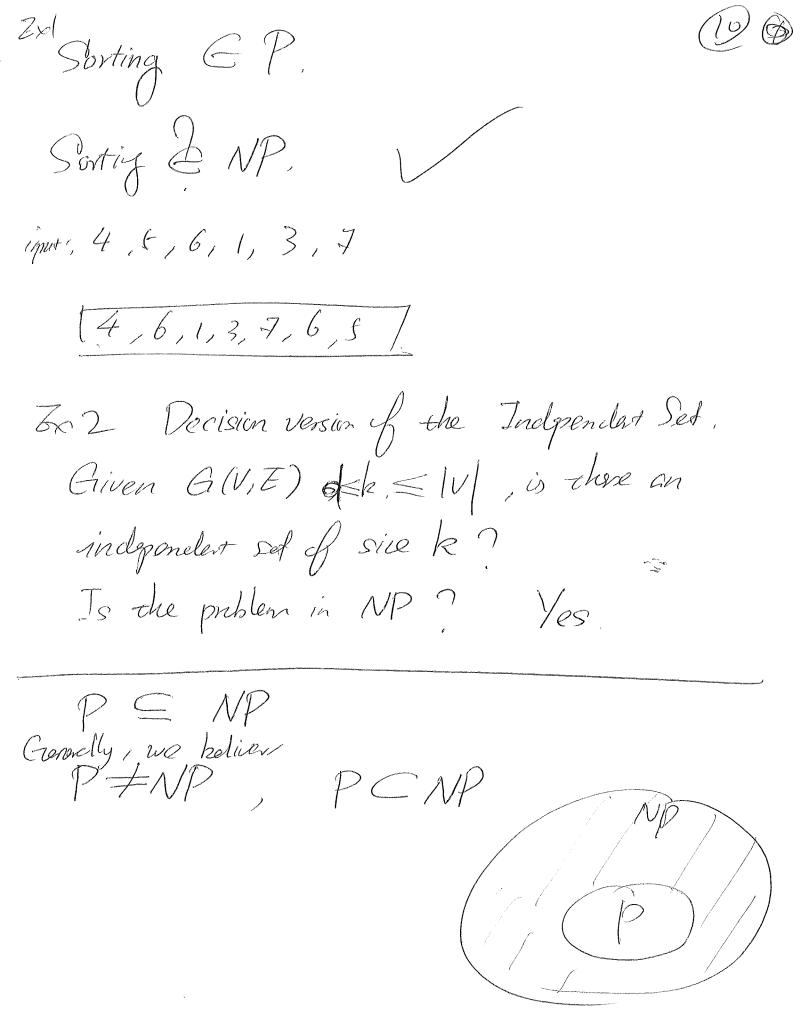
to show that B is NOT polynomial time
solvable, it suffices to find a

KNOWN problem A NOT polynomial time
Solvable and reduce A to B

When we can reduce A-to B in polynomial time we write $A \leq p$. B

The Class of P: Deterministic Polynomial Time Solvable. include all problems that can be solved in polynomial deterministically O(nK) All the publems - (knapsack) are in P. The Class of NP: Mon-doterministic (Polynomial Time Solvable. We say a computational problem is NP if it has a non-desterministe paymental time

algerham, i.e., given somochig we can verify if this schisa solution or not in polynomial time, (pelynomial time vorifiable)



Cohat & are the harder problems in NP?

NP-hard.

Dels A problem is NP-hard if it is at leave as hard as every problem in NP.

A problem is NP-hard if we can reduce

Aproblem is NP-hand of we can reduce every NP problem to A

NP-Comple

NP

P