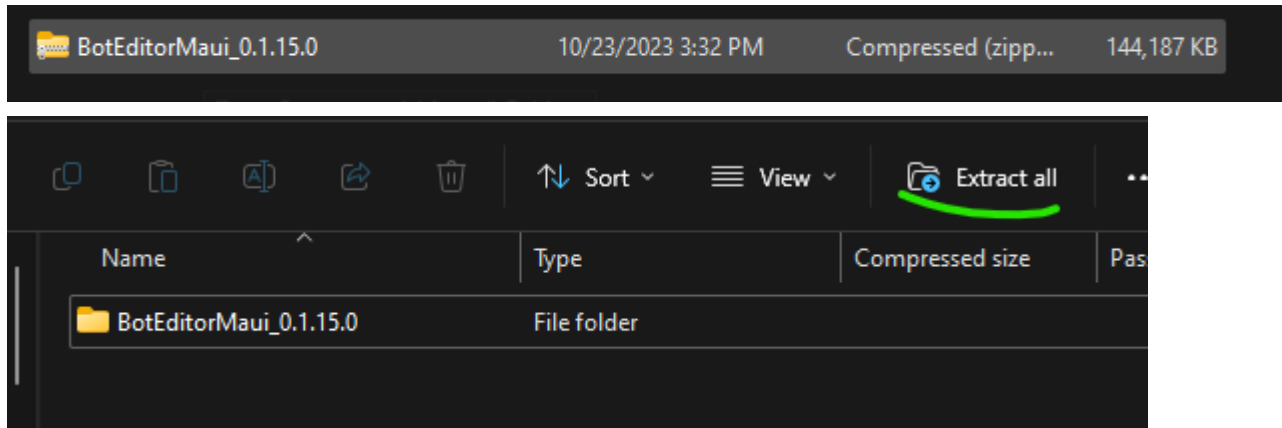


Initial setup.

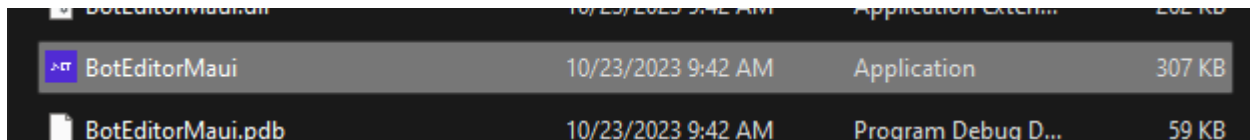
Connect the Robo Arm that has been assembled and powered with a 5V power adapter

- **FOR DIY OR DIGITAL VERSION OF ROBO ARM:**
- **Do not assemble the horns for motors 1, 2, 3, and the gear rack system for the 4th motor.**

Extract the contents from the zipped application folder.

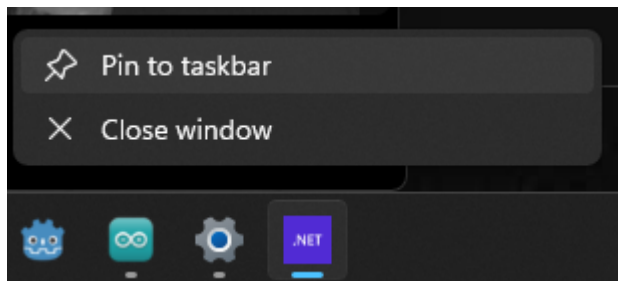


Find BotEditorMaui.exe file in unpacked folder

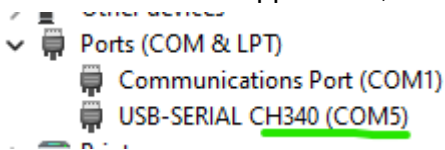


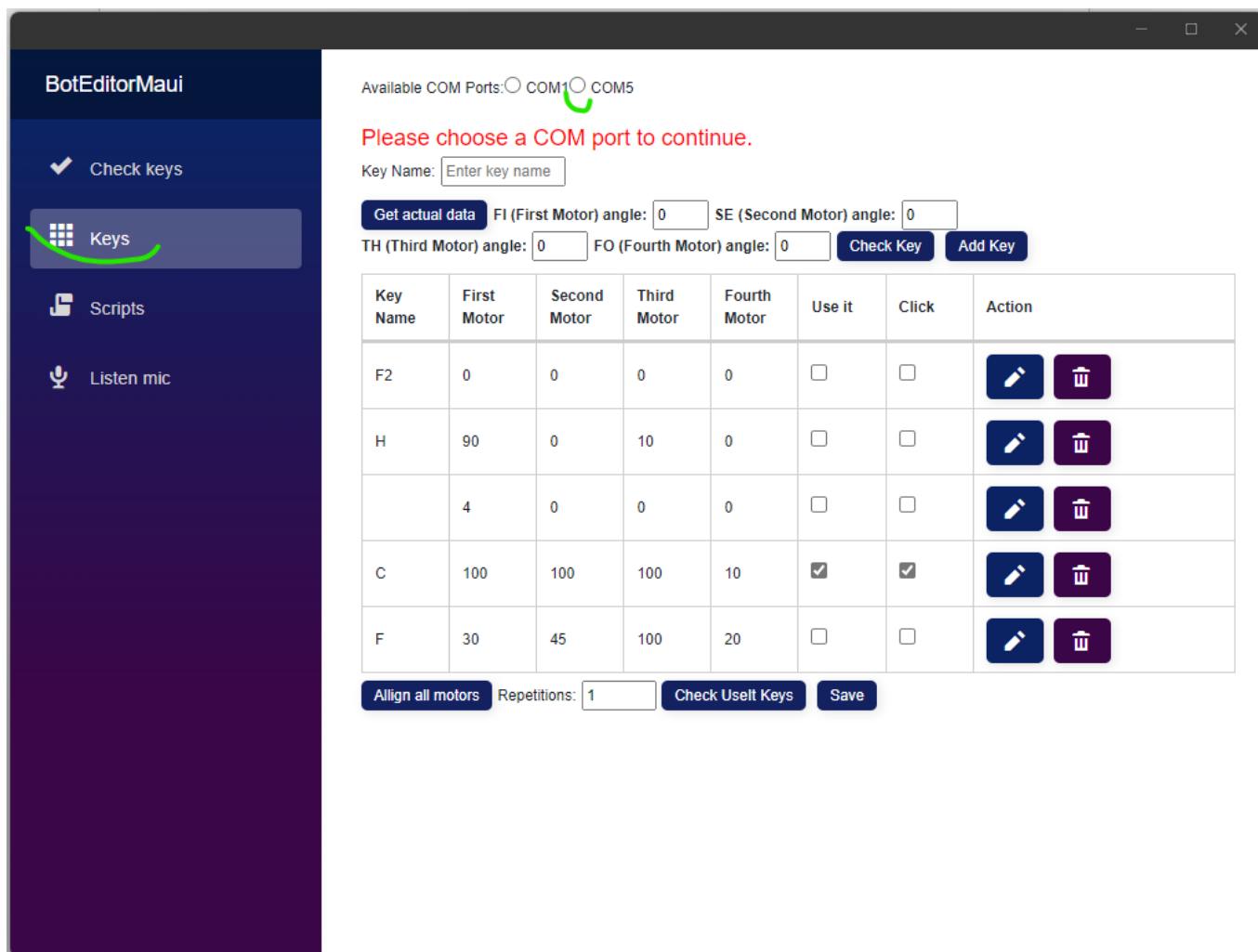
Double-click the application to launch it.

Once the app is running, locate its icon in the taskbar. Right-click on the icon and select "Pin to taskbar".



In the BotEditorMaui application, navigate to the "Keys" tab and locate the COM PORT for your Arduino.





Select it and then click the "Save" button to store your choice.

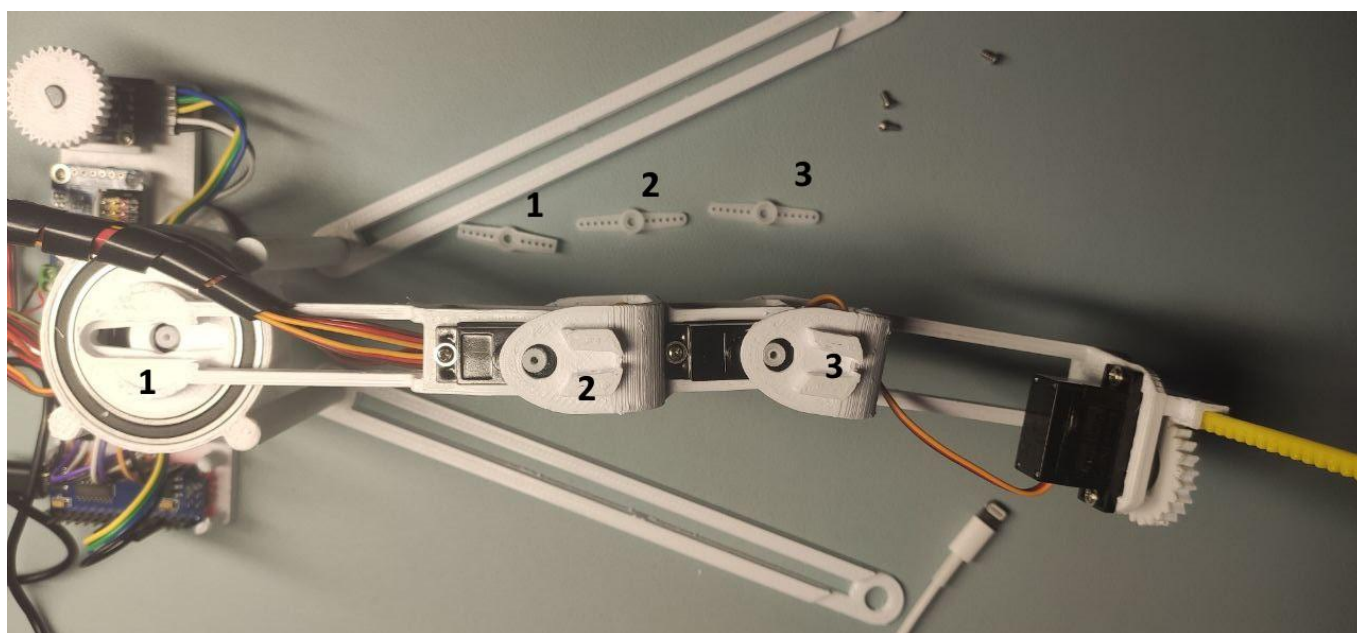
Before assembling the Robo Arm:

Ensure the PCA9685 board's power cable is connected.

Click "Align all motors" to ensure all motors are set to the neutral (middle) position.



Following that, attach the horns to motors 1, 2, and 3.



Additionally, configure the gear and rack system for the 4th motor.

