

From Auctions to Mechanism Design

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May 11, 2020

Introduction

Is Auction The Best Allocation Mechanism?

- Auction is one of many ways to sell an object.
- In an auction, object is sold at a price determined by competition among buyers according to rules set out by the seller.
- Other possible methods include:
 - Seller could post a fixed price and sell the object to the first arrival;
 - Seller could negotiate with one buyer (e.g., chosen at random);
 - Seller could hold an auction and then negotiate with winner; etc.
- This week, we abstract away from the details of any particular selling format and ask: *“What is the best way to allocate an object?”*

General Mechanism Design Problem

- Design of a game (structure, rules, sequence of actions) among agents that implements certain desirable outcomes.
- Agents have private information (adverse selection).
- Principal wants to achieve certain outcomes and has commitment power: commits to a decision rule.
- Typical mechanism design questions:
 - ① Which decision rules (social choice functions) are implementable?
 - ② Which decision rule is optimal, i.e., preferred by the principal?
 - ③ Which decision rule is efficient, i.e., maximizes overall surplus?
- This week: Optimal allocation rule to sell an object?

From Auctions to a General Mechanism Design Problem

Setup

- As before, seller has one indivisible object to sell.
- For simplicity, suppose the value of the object to the seller is 0.
- N risk-neutral buyers come from the set $\mathcal{N} = \{1, \dots, N\}$.
- Buyers have independently distributed private valuations.
- Buyer i 's valuation V_i is distributed over the interval $\mathcal{V}_i = [0, \omega_i]$ according to c.d.f. F_i with density f_i .

Setup

- Let $\mathcal{V} = \times_{j=1}^N \mathcal{V}_j$ denote the product of the sets of buyers' values and, for all i , let $\mathcal{V}_{-i} = \times_{j \neq i} \mathcal{V}_j$
- Define $f(\mathbf{v})$ be the joint density of $\mathbf{v} = (v_1, \dots, v_N)$.
- Since valuations are independent, $f(\mathbf{v}) = f_1(v_1) \times \dots \times f_N(v_N)$.
- Similarly, define $f_{-i}(\mathbf{v}_{-i})$ to be the joint density of $\mathbf{v}_{-i} = (v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_N)$

Mechanism

Definition

A selling *mechanism* (\mathcal{B}, π, μ) is a combination of:

- 1 A set of possible *messages* (or “bids”) \mathcal{B}_i for each buyer i ;
- 2 An *allocation rule* $\pi : \mathcal{B} \rightarrow \Delta$ where Δ is the set of probability distributions over the set of buyers \mathcal{N} ;
- 3 A *payment rule* $\mu : \mathcal{B} \rightarrow \mathbb{R}^N$.

Intuitively:

- Allocation rule determines, as a function of all N messages, the probability $\pi_i(\mathbf{b})$ that i will get the object.
- Payment rule determines, as a function of all N messages, for each buyer i , the expected payment $\mu_i(\mathbf{b})$ that i must make.

FPSB and SPSB as Mechanisms

- First- and second-price auctions are mechanisms.
- In both, the set of possible bids can be assumed to be $\mathcal{B}_i = \mathcal{V}_i$
- In both, the allocation rule is (ignoring ties):

$$\pi_i(\mathbf{b}) = \begin{cases} 1 & \text{if } b_i > \max_{j \neq i} b_j \\ 0 & \text{if } b_i < \max_{j \neq i} b_j \end{cases}$$

- However, the payment rules are different. First-price auction:

$$\mu_i^I(\mathbf{b}) = \begin{cases} b_i & \text{if } b_i > \max_{j \neq i} b_j \\ 0 & \text{if } b_i < \max_{j \neq i} b_j \end{cases}$$

- Second-price auction:

$$\mu_i^{II}(\mathbf{b}) = \begin{cases} \max_{j \neq i} b_j & \text{if } b_i > \max_{j \neq i} b_j \\ 0 & \text{if } b_i < \max_{j \neq i} b_j \end{cases}$$

Game Within a Mechanism

- Every mechanism defines a game of incomplete information among the buyers.
 - Strategies: $\beta_i : [0, \omega_i] \rightarrow \mathcal{B}_i$
 - Payoffs: Expected payoff for a given strategy profile and selling mechanism
- A strategy profile $\beta(\cdot)$ is a **Bayesian Nash Equilibrium** of a mechanism if for all i and for all v_i , given strategies β_{-i} of other buyers, $\beta_i(v_i)$ maximizes i 's expected payoff.
- *Note:* Today, we focus on **Bayesian Mechanism Design**, i.e., with BNE as an underlying equilibrium concept. Later, we will come back and consider **Dominant Strategies Mechanism Design** which relies on the Dominant Strategy Equilibrium.

Direct Mechanisms and Revelation Principle

Direct Mechanisms

- Mechanisms could be quite complicated since we made no assumptions on the sets of “bids” or “messages” \mathcal{B}_i .
- A smaller and simpler class are mechanisms for which the set of messages is the same as the set of values—that is, $\mathcal{B}_i = \mathcal{V}_i \forall i$.
- Such mechanisms are called *direct*, since every buyer is asked to directly report a value.

Direct Mechanisms

- Formally, direct mechanism (\mathbf{Q}, \mathbf{M}) consists of functions $\mathbf{Q} : \mathcal{V} \rightarrow \Delta$ and $\mathbf{M} : \mathcal{V} \rightarrow \mathbb{R}^N$, where $Q_i(\mathbf{v})$ is the probability that i will get the object and $M_i(\mathbf{v})$ is the expected payment by i .
- If it is an equilibrium for each buyer to reveal his true value, then the direct mechanism is said to have a *truthful* equilibrium.
- *Revelation principle*: outcomes of any mechanism's equilibrium can be replicated by a truthful equilibrium of a direct mechanism.
- Hence, no loss of generality in focusing on direct mechanisms.

Proposition. Revelation Principle.

Given a mechanism and an equilibrium for that mechanism, there exists a direct mechanism in which (i) it is an equilibrium for each buyer to report his valuation truthfully and (ii) the outcomes are the same as in the given equilibrium of the original mechanism.

Proof: Let $\mathbf{Q} : \mathcal{V} \rightarrow \Delta$ and $\mathbf{M} : \mathcal{V} \rightarrow \mathbb{R}^N$ be defined as follows: $\mathbf{Q}(\mathbf{v}) = \pi(\beta(\mathbf{v}))$ and $\mathbf{M}(\mathbf{v}) = \mu(\beta(\mathbf{v}))$. Then both statements must be true. Intuitively:

- Fix a mechanism and equilibrium β of that mechanism.
- Instead of buyers submitting messages $b_i = \beta_i(v_i)$, we directly ask buyers to report their values v_i and then make sure that the outcomes are the same as if they had submitted bids $\beta_i(v_i)$.
- Now suppose that some buyer finds it profitable to be untruthful and report a value \hat{v}_i when his value is v_i .
- Then in the original mechanism same buyer would have found it profitable to submit $\beta_i(\hat{v}_i)$ instead of $\beta_i(v_i)$. Contradiction. ■

Buyer's Payoff Function

Given a direct mechanism (\mathbf{Q}, \mathbf{M}) :

$$q_i(\hat{v}_i) = \int_{\mathcal{V}_{-i}} Q_i(\hat{v}_i, \mathbf{v}_{-i}) f_{-i}(\mathbf{v}_{-i}) d\mathbf{v}_{-i}$$

is the probability that i gets the object when he reports \hat{v}_i and all other buyers report their values truthfully. Similarly,

$$m_i(\hat{v}_i) = \int_{\mathcal{V}_{-i}} M_i(\hat{v}_i, \mathbf{v}_{-i}) f_{-i}(\mathbf{v}_{-i}) d\mathbf{v}_{-i}$$

is expected payment when i reports \hat{v}_i and others tell the truth. Then:

$$q_i(\hat{v}_i)v_i - m_i(\hat{v}_i)$$

is the expected payoff of i when he reports \hat{v}_i and others tell the truth.

Incentive Compatibility

The direct revelation mechanism is incentive compatible (IC) if:

$$U_i(v_i) \equiv q_i(v_i)v_i - m_i(v_i) \geq q_i(\hat{v}_i)v_i - m_i(\hat{v}_i)$$

$$\forall i \in \mathcal{N}; \forall v_i, \hat{v}_i \in [0, \omega_i]$$

where U_i is the *equilibrium payoff function*.

Incentive Compatibility: Implications

- Incentive compatibility has several important implications.
- First, for each reported value \hat{v}_i , expected payoff $q_i(\hat{v}_i)v_i - m_i(\hat{v}_i)$ is an affine function of true value v_i . Thus, IC implies that:

$$U_i(v_i) = \max_{\hat{v}_i \in \mathcal{V}_i} \{q_i(\hat{v}_i)v_i - m_i(\hat{v}_i)\}$$

- That is, U_i is a maximum of a family of affine functions, therefore U_i is a *convex function*.

Incentive Compatibility: Implications

- Second, we can rewrite:

$$\begin{aligned}U_i(\hat{v}_i) &= q_i(\hat{v}_i)\hat{v}_i - m_i(\hat{v}_i) \geq q_i(v_i)\hat{v}_i - m_i(v_i) \\&= q_i(v_i)v_i - m_i(v_i) + q_i(v_i)(\hat{v}_i - v_i) \\&= U_i(v_i) + q_i(v_i)(\hat{v}_i - v_i)\end{aligned}$$

- Since the above inequality has to hold for all v_i and \hat{v}_i , $q_i(v_i)$ is the subgradient of the function U_i at v_i .
- Since U_i is convex, it must be that q_i is *non-decreasing*.

Incentive Compatibility: Implications

- Third, since convexity implies differentiability almost everywhere:

$$U'_i(v_i) = q_i(v_i) \implies U_i(v_i) = U_i(0) + \int_0^{v_i} q_i(x_i) dx_i$$

- That is, up to an additive constant, buyer's expected payoff in an IC direct mechanism (\mathbf{Q}, \mathbf{M}) depends only on allocation rule \mathbf{Q} .
- Thus, if (\mathbf{Q}, \mathbf{M}) and $(\mathbf{Q}, \bar{\mathbf{M}})$ are two IC mechanisms with same allocation rule but different payment rules, then their expected payoff functions, U_i and \bar{U}_i , differ by at most a constant.
- In other words, (\mathbf{Q}, \mathbf{M}) and $(\mathbf{Q}, \bar{\mathbf{M}})$ are *payoff equivalent*.

Revenue Equivalence Strikes Again!

Generalized Revenue Equivalence

If the direct mechanism (\mathbf{Q}, \mathbf{M}) is incentive compatible, then for all i and v_i , the expected payment is

$$m_i(v_i) = m_i(0) + q_i(v_i)v_i - \int_0^{v_i} q_i(x_i)dx_i$$

Thus, expected payments in any two incentive compatible mechanisms with the same allocation rule are equivalent up to a constant.

Proof: Since $U_i(v_i) = q_i(v_i)v_i - m_i(v_i)$ and $U_i(0) = -m_i(0)$, then:

$$\begin{aligned} U_i(v_i) &= U_i(0) + \int_0^{v_i} q_i(x_i)dx_i \implies \\ \implies m_i(v_i) &= m_i(0) + q_i(v_i)v_i - \int_0^{v_i} q_i(x_i)dx_i \quad \blacksquare \end{aligned}$$

Generalized Revenue Equivalence

Remarks:

- Given two BNE of two different auctions such that for each i :
 - For all (v_1, \dots, v_N) , probability of i getting the object is the same,
 - Two equilibria have the same expected payment at 0 value.

These auctions generate same expected revenue for the seller.

- This generalizes the result from last time:
 - Revenue equivalence at the symmetric equilibrium of standard auctions (object allocated to buyer with the highest bid).

Incentive Compatibility: Implications

- Finally, can show that a mechanism is incentive compatible *if and only if* the associated q_i is nondecreasing.
- We have shown that IC implies that q_i is nondecreasing.
- To see that nondecreasing q_i implies IC, note that:

$$\begin{aligned} U_i(\hat{v}_i) &\geq U(v_i) + q_i(v_i)(\hat{v}_i - v_i) \iff \\ &\iff \int_{v_i}^{\hat{v}_i} q_i(x_i) dx_i \geq q_i(v_i)(\hat{v}_i - v_i) \end{aligned}$$

- The latter inequality certainly holds if q_i is nondecreasing.

Individual Rationality

- Mechanism's payments may be too high and can scare off buyers.
- Direct mechanism (\mathbf{Q}, \mathbf{M}) is *individually rational* if equilibrium expected payoffs are: $U_i(v_i) \geq 0 \ \forall i \in N, v_i \in [0, \omega_i]$.
- (We implicitly assume that by not participating, a buyer can guarantee himself a payoff of zero.)
- If the mechanism is IC, then IR is equivalent to $U_i(0) \geq 0$, and since $U_i(0) = -m_i(0)$ this is equivalent to $m_i(0) \leq 0$.