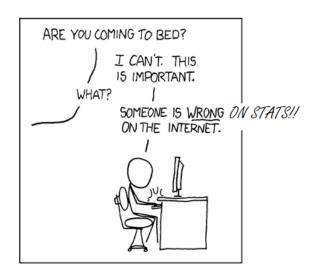
Using TMB (Template Model Builder) to predict the winner of a ping pong match

Alex Fun @quicklingbard github.com/alexfun

20180712 (3.50 pm @ useR!2018/P7)

Part 1: The stats.stackexchange problem



(adapted from www.xkcd.com/386)



QUESTIONS TAGS USERS BADGES UNANSWERED

If I have a 58% chance of winning a point, what's the chance of me winning a ping pong game to 21, win by 2?

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▼

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|--------|-------------|-----|--------|
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| 2 | 17 | 21 | Me |
| 3 | 11 | 21 | Me |
| 4 | 13 | 21 | Me |
| 5 | 15 | 21 | Me |
| 6 | 15 | 21 | Me |
| 7 | 16 | 21 | Me |
| 0 | 0 | 0.4 | 14- |

asked 4 months ago viewed 13,670 times active 3 months ago

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If a tennis match was a single large set, how many games would give the same accuracy?

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Why don't contestants use this strategy when playing Secret X on the Price is Right

(https://stats.stackexchange.com/questions/329521)



Cross Validated

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Assume:

have a bet with a coworker that out of 50 ninn nonn names (first to win 21 noints, win bv.2). Lull wind ill 50.5 of ar we've played 15 games and on average I win 58% of the points, plus I we would be games so far. 50 we're wondering if I have a 58% chance of winning a point and he has a 42% chance of winning a point what's the excreent chance that I would win the banne? I st there is nome? I st there is nome? I st there is nome?

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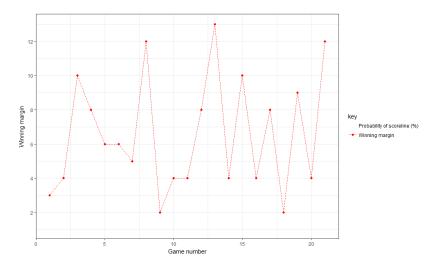
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But what if the assumption is wrong?



But what if the assumption is wrong?

▶ Postulate that in a truly competitive game, the original poster has a much higher (than 59%) chance of winning a point

Part 2: Why use automatic derivatives in

optimisation?

Optimisation

- Objective function (e.g. log-likelihood) and decision variables (e.g. regression coefficients).
- ▶ Gradient based vs non-gradient based (not relevant here).

Suppose one wishes to find the value of (the decision variables) \mathbf{x} such that $y = f(\mathbf{x})$ is maximised. Start with an initial guess \mathbf{x}_0 for the optimal values, and iteratively build better guesses $\mathbf{x}_1, \mathbf{x}_2, \ldots$, via:

$$\mathbf{x}_{n+1} = \mathbf{x}_n - \frac{f'(\mathbf{x}_n)}{f''(\mathbf{x}_n)}$$

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If x is a vector:

$$\mathbf{x}_{n+1} = \mathbf{x}_n - [\mathbf{H}f(\mathbf{x}_n)]^{-1} \nabla f(\mathbf{x}_n)$$

(https:

 $//en.wikipedia.org/wiki/Newton\%27s_method_in_optimization)$

Nabla is the gradient and \mathbf{H} is the hessian:

$$\nabla = \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_m}\right)$$

$$\mathbf{H} = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_m} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \cdots & \frac{\partial^2 f}{\partial x_2 \partial x_m} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_m \partial x_1} & \frac{\partial^2 f}{\partial x_m \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_m^2} \end{bmatrix}$$

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Wow, much derivatives to find! (LaTeX from Wikipedia)

► Logistic regression:

$$\log(\frac{p_i}{1-p_i}) = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \dots$$

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► After some algebra (or consultation of https://stats.stackexchange.com/a/16541):

$$\frac{\partial \ell}{\partial \beta_j} = \dots$$

$$= \sum_{i} y_i x_{ij} - \sum_{i} p_i x_{ij},$$

$$\frac{\partial^2 \ell}{\partial \beta_i \partial \beta_{\nu}} = \dots$$

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(ellipses are left as an exercise for the reader.)

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Automatic differentiation

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- https://justindomke.wordpress.com/2009/02/17/ automatic-differentiation-the-most-criminally-underused-tool-in-the-p

Part 3: TMB

What is TMB

- Website for installation and tutorial: https://github.com/kaskr/adcomp/wiki
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- Website for installation and tutorial: https://github.com/kaskr/adcomp/wiki
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- ▶ R package that calculates first and second derivatives of any objective function written in C++.
- ▶ Very, very fast \leftrightarrow uses state of the art C++ packages like Eigen, CppAD, . . .
- Used where more 'complex' log-likelihood functions are required. E.g.:
 - the glmmTMB package allows you to "fit linear and generalized linear mixed models with various extensions, including zero-inflation".
 - A Laplace approximation for the likelihood is implemented to deal with models containing random effects.

Let s_i be the observed score difference in the i-th game.

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- ▶ Postulate that the probability of the original poster winning the i + 1-th game is:

$$p_{i+1} = \alpha p_0 + (1 - \alpha)(\operatorname{expit}(\operatorname{logit}(p_i) + \beta))$$

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where α is a 'mixing' coefficient:

$$\alpha = \operatorname{expit}(\alpha_0 + \alpha_1 s_i)$$

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- ► The aim is to find values for the following parameters that maximise the likelihood of observing the game scorelines:
 - \triangleright p_0 : probability of point win when original poster is not playing at their best.
 - β : changes probability of winning in the next game depending on the scoreline this game.
 - ho_0 and $lpha_1$: coefficients governing the averaging between p_0 and p_i .

Modelling: Probability to win a game with a certain scoreline

- ▶ In a game, suppose player one wins points with probability *p*, and let *x* and *y* be the total number of points player one and two won, respectively.
- ▶ Suppose player one reaches 21 points first with a margin of two:

$$\Pr(21:y) = \binom{20+y}{y} p^{21} (1-p)^y$$

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$$\Pr(21:y) = \binom{20+y}{y} p^{21} (1-p)^y$$

Else:

$$\Pr(x:y) = 2^{y-20} \binom{40}{20} p^{x} (1-p)^{y}$$

(whuber: https://stats.stackexchange.com/a/329554)

Code: R

```
R_obi_fun_template <- function(par, me, vou, score_diff) {</pre>
    p_0 < -par[1]
    alpha 0 <- par[2]
    alpha 1 \leftarrow par[3]
    beta <- par[4]
    n_obs <- length(score_diff)</pre>
    p <- p_0 # initialise initial model fitted probability
    nll <- 0 # initialise model negloglik
    for (i in seq_along(you)) {
        if (i > 1) {
            # mixing coefficient
            alpha <- plogis(alpha_0 + alpha_1 * score_diff[i - 1]);
            # update p with model
            p <- alpha * p 0 + (1 - alpha) * plogis(glogis(p) + beta);
        # increment nll
        nll <- nll - log(get_prob_of_scoreline(me[i], vou[i], p));
    return(n11)
optim_in_R$fn <- function(par) R_obj_fun_template(par, df$Me, df$Opponent, df$score_diff)
optim in R$par <- c(0.592246, 0, 0, 0)
# quasi-Newton optimisation with approximations to the Hessian
# i.e. second derivatives are never required
optim_in_R$method <- 'BFGS'
```

Code: R

```
get_prob_of_scoreline <- function(me, you, prob_win_point){
    # warning, not vectorised!
    stopifnot(all(length(me) == 1, length(you) == 1, length(prob_win_point) == 1))
    min_me_you <- min(me, you)

if (you >= 20) {
    out_prob <- choose(40, 20) * 2^(min_me_you - 20) * prob_win_point^me * (1 - prob_win_point)^you
} else {
    out_prob <- choose(20 + min_me_you, min_me_you) * prob_win_point^me * (1 - prob_win_point)^you
}
return(out_prob);
}</pre>
```

Code: Rcpp

```
R_obi_fun_template_Rcpp <- cppFunction(
    "double R obj fun templatep Rcpp(NumericVector par, IntegerVector me, IntegerVector you, IntegerVector score diff) {
    // parameters:
    double p_0 = par[0];
    double alpha_0 = par[1];
    double alpha_1 = par[2];
    double beta = par[3]:
    int n obs = me.size():
    double p = p_0; // initialise initial model fitted probability
    double nll = 0; // initialise model negloglik
    for (int i = 0; i < n_obs; i++) {
        if (i > 0) {
            // mixing coefficient
            double alpha = Rf plogis(alpha 0 + alpha 1 * score diff[i - 1], 0.0, 1.0, 1, 0);
            // update p with model
            p = alpha * p 0 + (1 - alpha) * Rf plogis(Rf glogis(p, 0.0, 1.0, 1, 0) + beta, 0.0, 1.0, 1, 0);
       nll += -log(get_prob_of_scoreline_Rcpp(me[i], you[i], p));
    return nll:
    includes = "double get prob of scoreline Rcpp(int me, int you, double prob win point) {
    double out prob:
```

Code: TMB

```
template<class Type>
Type objective_function<Type>::operator() () {
   DATA_VECTOR(you);
   DATA_VECTOR(me):
   DATA_VECTOR(score_diff):
   // parameters:
   PARAMETER(p_0);
   PARAMETER(alpha 0):
   PARAMETER(alpha_1);
   PARAMETER(beta);
    int n obs = me.size():
   Type p = p_0; // initialise initial model fitted probability
    Type nll = 0: // initialise model negloglik
   vector<Type> p_vec_out(n_obs);
    for (int i = 0; i < n_obs; i++) {
       if (i > 0) {
            // mixing coefficient
            Type alpha = invlogit(alpha_0 + alpha_1 * score_diff[i - 1]);
           // update p with model
           p = alpha * p_0 + (1 - alpha) * invlogit(logit(p) + beta);
       nll += -log(get_prob_of_scoreline(me[i], you[i], p));
       // store into vector to be returned to R
       p_vec_out[i] = p;
   REPORT(p_vec_out):
    return nll;
```

Example usage

```
## Get TMB objective function which includes .$gr (gradient) and .$he (hessian) elements.
optim_in <- MakeADFun(data = list(me = df$Me, you = df$Opponent, score_diff = df$Me - df$Opponent),
                     parameters = list(p_0 = 0.592246, alpha_0 = 0, alpha_1 = 0, beta = 0).
                     DLL = 'req_20180312_init_obj_fun',
                     silent = T)
# see that optim_in has the right elements to be passed into R's optimisation function optim.
str(optim in)
# List of 10
     $ par : Named num [1:4] 0.592246 0 0 0
     ..- attr(*, "names")= chr [1:4] "p_0" "alpha_0" "alpha_1" "beta"
     $ fn :function (x = last.par, ...)
     $ gr :function (x = last.par, ...)
     $ he :function (x = last.par. atomic = usingAtomics())
    $ hessian : logi FALSE
    $ method : chr "BFGS"
    $ retape :function (set.defaults = TRUE)
     $ env :<environment: 0x000000001bd5b158>
    $ report :function (par = last.par)
     $ simulate:function (par = last.par. complete = FALSE)
```

Results: Speed of optimisation

```
> microbenchmark(TMB = do.call(optim, optim_in),
                TMB_numerical = do.call(optim, optim_in_no_jac),
+
                Rcpp = do.call(optim, optim_in_Rcpp),
+
                base_R = do.call(optim, optim_in_R))
Unit: milliseconds
                                 ٦q
                                                  median
                     min
         expr
                                          mean
                                                                 uq
              4.028838
                         4.326319 4.737954 4.430616
                                                          4.755356
          TMR
TMB_numerical
              16.559796 17.426758 18.959108 17.864092
                                                          18.819943
               15.682760 16.367006 18.124086
         Rcpp
                                              16.978561
                                                          18.956832
       base R 553.979831 571.790193 607.814579 581.838190 609.109290
```

Results: Coefficients

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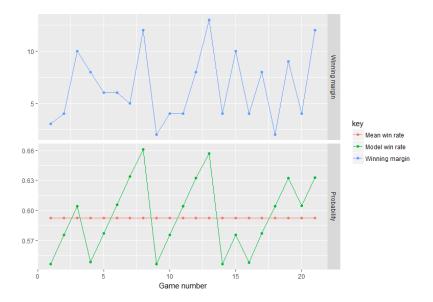
- \triangleright Recall that s_i is the observed score difference in the i-th game.
- ▶ The probability of the original poster winning the i+1-th game, given by the model, is:

$$p_{i+1} = 0.546\alpha + (1 - \alpha)(\text{expit}(\text{logit}(p_i) + 0.119))$$

where the mixing coefficient α is:

$$\alpha = \operatorname{expit}(-34 + 3.77s_i)$$

Results: fitted game win probs





The last word



Your thoughts on whether points and games are independent? Not to mention stationary over time (cumulated games and experience playing each other)? – Mark L. Stone Mar 21 at 15:58

I don't think the points and games were independent. The more I won, the more complacent I got and my opponent took advantage of that. – richard Mar 21 at 19:28

Thank you

- ➤ TMB developers: Kasper Kristensen [aut, cre, cph], Hans Skaug [ctb], Arni Magnusson [ctb], Casper Berg [ctb], Anders Nielsen [ctb], Martin Maechler [ctb], Theo Michelot [ctb], Mollie Brooks [ctb], Alex Forrence [ctb], Christoffer Moesgaard Albertsen [ctb], Cole Monnahan [ctb]Thank you to user organisers + TMB developers
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