

EDUCATION	<p>UC Berkeley, B.S. Electronic Engineering and Computer Science, 2018 - 2022, GPA: NA/4.00</p>
WORK EXPERIENCE	<p>NASA Jet Propulsion Laboratory, Pasadena, CA</p> <p><i>Research Intern</i> June 2018 – July 2018</p> <p>Development of a a seismometer applicable to lunar and ocean world missions, as well as lunar strange quark nugget detection, using feedback-control circuits, low-temperature applied physics, and complex variable analysis to be 10 more sensitive than the current state-of-the-art.</p> <p>NASA Ames Research Center, Moffett Field, CA</p> <p><i>Research Intern – Intelligent Systems Division</i> January 2017 – March 2018</p> <p>Utilized artificial intelligence background in planning and decision making to develop a POMDP based decision support system for the Resource Prospector Mission lunar rover and a novel mission to Titan.</p> <p>Stinger Ghaffarian Technologies, Moffett Field, CA</p> <p><i>Research Intern at NASA Ames</i> October 2017 – December 2017</p> <p>Government contractor. See above.</p> <p>rLoop Inc, Menlo Park, CA</p> <p><i>Embedded Controls Engineer</i> August 2016 – November 2016</p> <p>Implemented and tested control and signal processing algorithms for hardware development test rigs. Won the Innovation Award in the January 2017 SpaceX Hyperloop competition</p> <p>OPPO, Menlo Park, CA</p> <p><i>Intern</i> June 2016 – August 2016</p> <p>Worked on software and electronic tests, along with electronic prototyping for various devices. Wrote optimization software and automated common tasks.</p> <p>Stanford, Stanford, CA</p> <p><i>Research Intern</i> January 2016 – March 2017</p> <p>Conducted research with Prof. Kochenderfer and the Stanford Intelligent Systems Laboratory on algorithms for multi-agent deep reinforcement learning systems and decision making under uncertainty.</p>
RELEVANT EXPERIENCE	<p>Gunn Zero Robotics Team, Gunn High School, CA</p> <p><i>Founder and Captain</i> August 2016 – December 2017</p> <p>Founded and led space robotics programming team to the international finals for the Zero Robotics Competition. Code ran on SPHERE satellites on the International Space Station.</p> <p>Gunn Robotics Team, Gunn High School, CA</p> <p><i>Controls Member</i> August 2015 – August 2017</p> <p>Developed robotics controls systems for the FIRST Robotics Competition. Wrote code for vision tracking, autonomous programs, and PID control with Python.</p>
SELECT PUBLICATIONS	<ul style="list-style-type: none"> • E. Balaban, T. Arnon, A. Gao, M. Shirley, S. Brisson, M. Kochenderfer, "Realtime Traverse Synthesis for Planetary Rovers Under State and Execution Uncertainty", in <i>AIAA Space and Astronautics Conference</i>, Orlando FL, September 2018. • E. Balaban, T. Arnon, M. Shirley, S. Brisson, and A. Gao, "A System Health Aware POMDP Framework for Planetary Rover Traverse Evaluation and Refinement", in <i>AIAA Information Systems Conference</i>, 2018 • E. Balaban, T. Arnon, A. Gao, S. Brisson, and M. Kochenderfer, "System Health Enabled Real-time Planning Advisor (SHERPA)", Manuscript in preparation for <i>AIAA Journal for Aerospace Information Systems</i>, 2018 • A. Gao, "Development of a Real-Time Decision Support System", <i>NASA Office of Education</i>, 2017