2.Ocean Proximity. Linear Regression

1 Ocean Proximity as a Linear Regression Problem

```
In [1]: import numpy as np
        import pandas as pd
        import tensorflow as tf
        import matplotlib.pyplot as plt
        import time
        from tqdm import tqdm
After importing the libraries, the datasets a file
```

After importing the libraries, the datasets are loaded: the *magic command* %run executes a .py file

1.1 Initialization

Some data is displayed:

```
In [5]: x_train[:5]
```

```
Out[5]: array([[ 0.42031873, -0.66206164, -0.64705882, -0.69739051, -0.58752328,
                -0.82056672, -0.61914159, -0.69639039, -0.60742018],
               [0.43027888, -0.98087141, -0.01960784, -0.91784933, -0.91371819,
                -0.84629614, -0.91810557, -0.58127474, -0.78350192],
               [0.26294821, -0.72582359, -0.1372549, -0.94485986, -0.91713222,
                -0.95392248, -0.91810557, -0.72952097, -0.15628802],
               [-0.44621514, -0.05632306, -0.49019608, -0.73401495, -0.74674115,
                -0.85251829, -0.73754317, -0.3834154, 0.09195838],
               [-0.39243028, 0.16471838, -0.41176471, -0.86189532, -0.80757294,
                -0.81277502, -0.78885052, -0.7176039 , -0.62350258]])
In [6]: t_train[:5]
Out[6]: array([1, 3, 0, 1, 1])
In [7]: x_dev[:5]
Out[7]: array([[-0.07171315, -0.10733262, -0.1372549, -0.89343303, -0.88081937,
                -0.94910171, -0.86712712, -0.58443332, -0.56041006],
               [-0.4123506, -0.18384697, 0.49019608, -0.88371738, -0.83612663,
                -0.91894392, -0.86548265, -0.60979849, -0.27587515],
               [-0.61952191, 0.11583422, 1.
                                                    , -0.9123048 , -0.88112973,
                -0.96575016, -0.88324289, -0.56120605, 0.99999588],
               [0.45418327, -0.9957492, -0.17647059, -0.88961799, -0.82557418,
                -0.88531069, -0.82798882, -0.79089944, -0.48742067],
               [0.15338645, -0.64930925, 0.33333333, -0.96032352, -0.95561763,
                -0.97634463, -0.95428383, -0.31657494, -0.23133925]])
In [8]: t_dev[:5]
Out[8]: array([1, 0, 2, 3, 0])
1.2 Hyperparameters
In [9]: n_epochs = 2000
```

```
learning_rate = 0.1
```

Definition of the neural network tensor graph

A placeholder is a special variable whose value will be assigned later. X stands for the input tensor, the inputs to the neural network, y is the output, and t is the target output of the supervised learning.

```
In [10]: X = tf.placeholder (dtype=tf.float32, shape=[None,INPUTS], name="X")
         t = tf.placeholder (dtype=tf.float32, shape=[None], name="t")
```

A variable can change its value during the execution phase. W is a matrix of weights (kernel). In this case, a column vector since there is just one output. b is the bias vector, an scalar in this study case.

```
In [11]: W = tf.Variable (tf.random_uniform([INPUTS,1], -1.0,1.0), name="W")
    b = tf.Variable (.0, name="bias")
```

Now, the output y is computed:

```
In [12]: y = tf.matmul(X,W)+b
```

The loss function is the SSE, defined by $E_p(W) = (y_p - t_p)^2$. The cost function is defined by $MSE = \frac{1}{P} \sum_{i=1}^{P} (y_i - t_i)^2$

```
In [13]: loss = tf.square(y-t)
    mse = tf.reduce_mean(loss,name="cost")
```

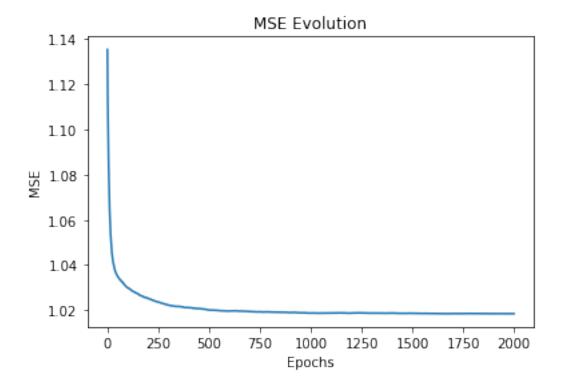
The learning method is the gradient descent to minimize the cost MSE, with the previously defined (hyperparameter) learning rate α :

Finally, all variables are initialized prior to executing the graph:

```
In [15]: init = tf.global_variables_initializer()
```

1.4 Running the tensorflow graph

```
In [16]: mse_array = []
         # First, a session is executed
         with tf.Session() as sess:
             sess.run(init)
             for epoch in tqdm(range(n_epochs)): #for each epoch a learning iteration is compute
                 sess.run(training_op, feed_dict={X: x_train[:NUM_TRAINING_EXAMPLES],
                                                  t: t_train[:NUM_TRAINING_EXAMPLES]})
                 mse_array.append (mse.eval(feed_dict={X: x_train[:NUM_TRAINING_EXAMPLES],
                                                          t: t_train[:NUM_TRAINING_EXAMPLES]}))
             final_training_mse = mse.eval(feed_dict={X: x_train[:NUM_TRAINING_EXAMPLES],
                                                      t: t_train[:NUM_TRAINING_EXAMPLES]})
             dev_mse = mse.eval(feed_dict={X: x_dev[:NUM_DEV_EXAMPLES],
                                           t: t_dev[:NUM_DEV_EXAMPLES]})
             computed_outputs = y.eval(feed_dict={X: x_dev[:NUM_DEV_EXAMPLES]})
100%|| 2000/2000 [02:04<00:00, 16.06it/s]
In [17]: plt.title("MSE Evolution")
        plt.xlabel("Epochs")
         plt.ylabel("MSE");
         plt.plot(range(n_epochs),mse_array)
Out[17]: [<matplotlib.lines.Line2D at 0xb292fdbe0>]
```



The learning process falls into a local optimum in a MSE of about 1. The MSE evolution turns into a flat line from 1,500 epochs. A non-linear problem is tried to be solved with linear regression.

```
In [18]: "Final training MSE: " + str(final_training_mse)
Out[18]: 'Final training MSE: 1.0184555'
In [19]: "Dev MSE: " + str(dev_mse)
Out[19]: 'Dev MSE: 0.97868484'
```

The final MSE for both the training and development datasets are too high. Good results were not expected even though a small subset of the training samples are involved since a linear regression algorithm is being used to solve a non-linear problem. Next, the comparison between computed and target outputs is shown for the 10 first development examples.

```
3 0.885280 3
4 0.891493 0
5 0.885119 0
6 0.882976 0
7 0.885779 0
8 0.882598 1
9 0.890736 1
```

Note that the computed values are all around 0.9, the mean value of the discretized target outputs, considering that the class 0 contains most of the examples, to achieve the lowest error. More accurate results can not be computed since this is a linear neural network