

MR 513 Homework No. 2

Solution

2.4.1.

Wave equation: $\frac{\partial^2 y}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = 0$

or $\frac{\partial^2 y}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2}$.

(a) $f_1(x-ct) = f_1(\xi)$

LHS = $\frac{\partial}{\partial x} \left(\frac{df_1}{d\xi} \frac{\partial \xi}{\partial x} \right) = \frac{\partial}{\partial x} \left(\frac{df_1}{d\xi} \right) = \frac{d^2 f_1}{d\xi^2} \frac{\partial \xi}{\partial x} = \frac{d^2 f_1}{d\xi^2}$.

RHS = $\frac{1}{c^2} \frac{\partial}{\partial t} \left(\frac{df_1}{d\xi} \frac{d\xi}{dt} \right) = \frac{1}{c^2} \frac{\partial}{\partial t} \left(-c \frac{df_1}{d\xi} \right)$

$= \frac{1}{c^2} (-c) \frac{d^2 f_1}{d\xi^2} \frac{d\xi}{dt} = \frac{d^2 f_1}{d\xi^2}$.

\therefore LHS = RHS. Satisfied.

(b). $\ln[a(ct-x)]$.

LHS = $\frac{\partial^2 y}{\partial x^2} = \frac{\partial}{\partial x} \left[\frac{-a}{a(ct-x)} \right] = - \frac{1}{(x-ct)^2}$.

RHS = $\frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = \frac{1}{c^2} \frac{\partial}{\partial t} \left[\frac{-ac}{a(ct-x)} \right] = \frac{1}{c^2} \frac{\partial}{\partial t} \left[\frac{1}{t-\frac{x}{c}} \right]$

$= \frac{1}{c^2} \left[- \frac{1}{(t-\frac{x}{c})^2} \right] = - \frac{1}{(x-ct)^2}$.

\therefore LHS = RHS. Satisfied.



$$(c). a(ct-x)^2$$

$$LHS = \frac{\partial^2 y}{\partial x^2} = \frac{\partial}{\partial x} [2a(x-ct)] = 2a.$$

$$RHS = \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = \frac{1}{c^2} \frac{\partial}{\partial t} [2a(ct-x) \cdot c] \\ = \frac{1}{c^2} 2ac^2 = 2a.$$

$$\therefore LHS = RHS. \text{ satisfied.}$$

$$(d). \cos[a(ct-x)].$$

$$LHS = \frac{\partial^2 y}{\partial x^2} = \frac{\partial}{\partial x} [-\sin[a(ct-x)] \cdot (-a)] \\ = a \cos[a(ct-x)] (-a) \\ = -a^2 \cos[a(ct-x)].$$

$$RHS = \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = \frac{1}{c^2} \frac{\partial}{\partial t} [-\sin[a(ct-x)] \cdot ac] \\ = \frac{1}{c^2} (-ac) \cos[a(ct-x)] \cdot ac \\ = -a^2 \cos[a(ct-x)].$$

$$\therefore LHS = RHS. \text{ Satisfied.}$$

(e). $a(ct - x^2)$

$$LHS = \frac{\partial^2 y}{\partial x^2} = \frac{\partial}{\partial x}[-a \cdot 2x] = -2a.$$

$$RHS = \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = \frac{1}{c^2} \frac{\partial}{\partial t}[ac] = 0.$$

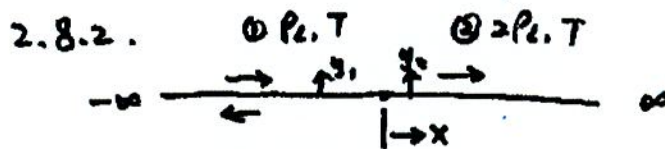
$LHS \neq RHS$. Wave equation not satisfied.

(f). $ax(ct - x)$.

$$LHS = \frac{\partial^2 y}{\partial x^2} = \frac{\partial}{\partial x}[-at] = 0.$$

$$\begin{aligned} RHS &= \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = \frac{1}{c^2} \frac{\partial}{\partial t}[2act - ax] \\ &= \frac{1}{c^2} \cdot 2ac = \frac{2a}{c}. \end{aligned}$$

$\therefore LHS \neq RHS$. Wave equation not satisfied.



Two wave equations,

$$\frac{\partial^2 y_1}{\partial x^2} + k_1^2 y_1 = 0.$$

$$\frac{\partial^2 y_2}{\partial x^2} + k_2^2 y_2 = 0.$$

The B.C.s are:

at $x=0$, $y_1 = y_2$ — (1)

Draw FBD for $x=0$.

we have:



$$T_1 \sin \theta_1 + T_2 \sin \theta_2 = 0$$

$$\Rightarrow -T_1 \frac{dy_1}{dx} + T_2 \frac{dy_2}{dx} = 0 \Rightarrow \frac{dy_1}{dx} = \frac{dy_2}{dx} \quad \text{--- (2)}$$

Assume the solutions to the wave equations are:

$$y_1 = A e^{-jk_1 x} e^{j\omega t} + B e^{jk_1 x} e^{j\omega t}$$

$$y_2 = C e^{-jk_2 x} e^{j\omega t}$$

where: $k_1 = \frac{\omega}{c_1} = \frac{\omega}{\sqrt{T/\rho_1}}$, $k_2 = \frac{\omega}{c_2} = \frac{\omega}{\sqrt{T/2\rho_1}} = \sqrt{2} k_1$.

Substitute into (1)

$$\Rightarrow A + B = C \quad \text{--- (3)}$$

substitute into (2):

$$\Rightarrow -Ajk_1 + Bj^2k_1 = -Cjk_1.$$

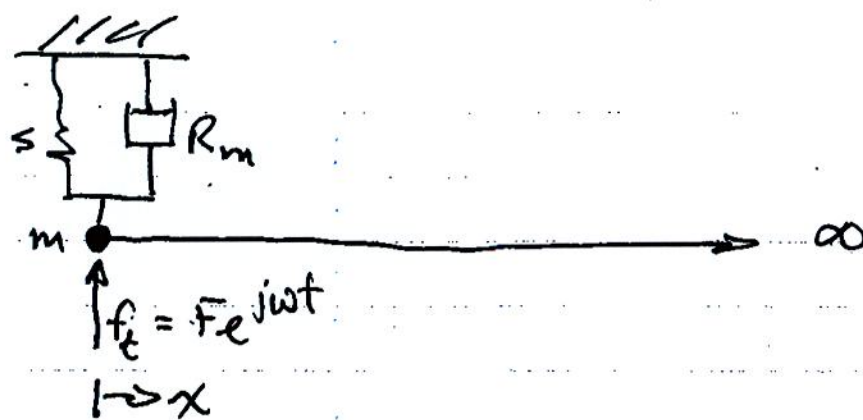
$$\Rightarrow (A-B)k_1 = \sqrt{2} Ck_1,$$

$$\Rightarrow A-B = \sqrt{2} C \quad - (4).$$

Solve (3) & (4) for B, C in terms of A:

$$\Rightarrow \begin{cases} C = \frac{1}{2}(\sqrt{2}-1)A \\ B = (2\sqrt{2}-3)A. \end{cases}$$

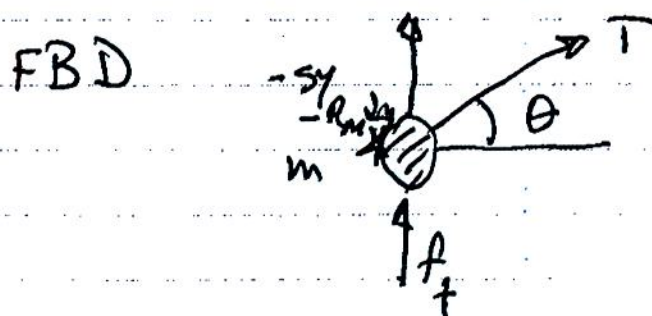
2.9.2



Semi-infinite string - nothing coming back from the +ve x-direction!
So, assumed solution

$$y(x, t) = A e^{j(\omega t - kx)} \quad k = \frac{\omega}{c} \quad c = \sqrt{\frac{T}{\rho}}$$

to determine A, apply b.c. at $x=0$



$$\sum f_y = m a \big|_{x=0}$$

$$T \sin \theta \big|_{x=0} - s y \big|_{x=0} - R_m \frac{dy}{dt} \big|_{x=0} + f_t = m \frac{d^2 y}{dt^2} \big|_{x=0}$$

$$T \frac{dy}{dx} \big|_{x=0} - s y \big|_{x=0} - R_m \frac{dy}{dt} \big|_{x=0} + f_t = m \frac{d^2 y}{dt^2} \big|_{x=0}$$

$$\frac{dy}{dx} = -jkA e^{j(\omega t - kx)}$$

$$\frac{dy}{dt} = j\omega A e^{j(\omega t - kx)}$$

$$\frac{\partial^2 y}{\partial x^2} = -\omega^2 A e^{j(\omega t - kx)}$$

$$-jkTA e^{j\omega t} - sA e^{j\omega t} - j\omega R_m A e^{j\omega t} + F e^{j\omega t} = -\omega_m^2 A e^{j\omega t}$$

$$F = (jkT + s + j\omega R_m - \omega_m^2) A$$

$$A = \frac{F}{jkT + s + j\omega R_m - \omega_m^2}$$

$$= \frac{F}{j\omega \left(\frac{k}{\omega} T - \frac{j s}{\omega} + R_m + j\omega m \right)}$$

$$k = \frac{\omega}{c}$$

$$c = \sqrt{\frac{T}{\rho_L}} \Rightarrow T = c^2 \rho_L$$

$$A = \frac{F}{j\omega \left(\rho_L c + R_m + j\omega m - j \left(\frac{s}{\omega} \right) \right)}$$

$$y(x,t) = A e^{j(\omega t - kx)}$$

mechanical Impedance at drive point

$$Z_{m0} = \frac{\text{driving force}}{\text{complex velocity}} \Big|_{x=0}$$

$$\frac{dy}{dt} = j\omega A e^{j(\omega t - kx)}$$

$$\therefore Z_{m0} = \frac{F e^{j\omega t}}{\frac{j\omega F e^{j\omega t}}{j\omega(p_c + R_m + j\omega m - j(\frac{s}{\omega}))}}$$

$$= p_c + R_m + j\omega m - j(\frac{s}{\omega})$$

2.9.3.



The wave equations are:

(assume P , T in both segments).

$$\frac{\partial^2 y_1}{\partial x^2} + k^2 y_1 = 0$$

$$\frac{\partial^2 y_2}{\partial x^2} + k^2 y_2 = 0$$

The B.C.s are:

$$\text{At } x=0 \quad y_1(0, t) = 0. \quad - (1)$$

$$\text{At } x=L \quad y_2(L, t) = 0 \quad - (2)$$

$$\text{At } x=L/4, \quad y_1 = y_2 \quad - (3)$$

Draw FBD.

$$T \sin \theta_1 + T \sin \theta_2 + F e^{j\omega t} = 0$$

$$\Rightarrow T \left(\frac{dy_1}{dx} - \frac{dy_2}{dx} \right) + F e^{j\omega t} = 0 \quad - (4)$$



Assume the solutions are in the form,

$$y_1(x, t) = (A e^{-jkx} + B e^{jkx}) e^{j\omega t}$$

$$y_2(x, t) = (C e^{-jkx} + D e^{jkx}) e^{j\omega t}$$

substitute into the B.C.s. we get:

$$(5) \quad A + B = 0$$

$$(6) \quad Ce^{-jkL} + De^{jkL} = 0$$

$$(7) \quad Ae^{-jkL/4} + Be^{jkL/4} = Ce^{-jkL/4} + De^{jkL/4}$$

$$(8) \quad Ce^{-jkL/4} - De^{jkL/4} - Ae^{-jkL/4} + Be^{jkL/4} = \frac{F}{jkT}$$

Express B, C, D in terms of A:

$$B = -A$$

$$D = -e^{-jkL} C = \frac{-e^{-jk9L/4} + e^{-jk7L/4}}{e^{-jkL/4} - e^{-jk7L/4}} A$$

$$C = \frac{e^{-jkL/4} - e^{-jkL/4}}{e^{-jkL/4} - e^{-jk7L/4}} A$$

Then substitute into (8), solving for A:

$$A = \frac{F}{2jkT} \frac{e^{-jkL/4} - e^{-jk7L/4}}{e^{-jkL/4} - e^{-jk7L/4} - 1}$$

\Rightarrow

$$B = -A$$

$$D = \frac{F}{2jkT} \frac{e^{-jk7L/4} - e^{-jk9L/4}}{e^{-jkL/4} - 1}$$

$$C = \frac{F}{2jkT} \frac{e^{-jkL/4} - e^{-jkL/4}}{e^{-jkL/4} - 1}$$

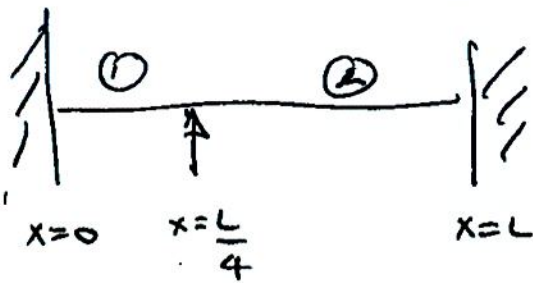
substitute back into $y_2(x, t)$:

$$\begin{aligned}
 y_2 &= (C e^{-jkx} + D e^{jkx}) e^{j\omega t} \\
 &= \frac{F}{2jkT} \frac{e^{j\omega t}}{e^{-jk2L} - 1} \left[(e^{-jkL/4} - e^{jkL/4}) e^{-jkx} \right. \\
 &\quad \left. + (e^{-jk7L/4} - e^{jk7L/4}) e^{jkx} \right] \\
 &= \frac{F}{2jkT} \frac{e^{-jkL/4} - e^{jkL/4}}{e^{-jk2L} - 1} e^{j\omega t} [e^{-jkx} - e^{-jk2L} e^{jkx}] \\
 &\quad F e^{j\omega t}
 \end{aligned}$$

(a). $z = \frac{\text{Transverse velocity}}{F e^{j\omega t}}$

$$\begin{aligned}
 \frac{\partial y_2}{\partial t} \Big|_{x=L/4} &= \frac{F}{2jkT} \frac{e^{-jkL/4} - e^{jkL/4}}{e^{-jk2L} - 1} [e^{-jkL/4} - e^{-jk7L/4}] \\
 &\quad \cdot j\omega e^{j\omega t} \\
 \Rightarrow z &= \frac{F e^{j\omega t}}{\frac{\partial y_2}{\partial t} \Big|_{x=L/4}} \\
 &= \frac{2\rho_2 c (e^{-jk2L} - 1)}{(e^{-jkL/4} - e^{jkL/4})(e^{-jkL/4} - e^{-jk7L/4})} \\
 &= -j\rho_2 c \left[\cot \frac{kL}{4} + \cot \frac{3kL}{4} \right].
 \end{aligned}$$

2.9.3 (Alternative)



$$y_1 = A e^{-ikx} + B e^{ikx}$$

① at $x=0$ $y_1 = 0$

$$0 = A + B$$

$$B = -A$$

$$y_1 = A (e^{-ikx} - e^{+ikx})$$

$$= -2jA \sin kx$$

$$y_2 = C e^{-ikx} + D e^{ikx}$$

② at $x=L$ $y_2 = 0$

$$0 = C e^{-ikL} + D e^{ikL}$$

$$D e^{ikL} = -C e^{-ikL}$$

$$D = -C e^{-2ikL}$$

$$y_2 = C e^{-ikx} - C e^{-2ikL} e^{ikx}$$

$$= e^{-ikL} C (e^{-ikx} e^{ikL} - e^{-ikL} e^{ikx})$$

$$= e^{-ikL} C (e^{ik(L-x)} - e^{-ik(L-x)})$$

$$= 2j e^{-ikL} C \sin k(L-x)$$

③ at $x = \frac{L}{4}$ $y_1 = y_2$

$$-2jA \sin k \frac{L}{4} = 2j e^{-ikL} C \sin k(L - \frac{L}{4})$$

$$-A \sin \frac{kL}{4} = e^{-ikL} C \sin \frac{3kL}{4}$$

$$-A \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} e^{+ikL} = C$$

$$C = -A \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} e^{+ikL}$$

$$y_1 = -2jA \sin kx$$

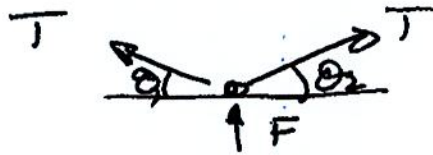
$$y_2 = -2j e^{-ikL} A \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} e^{+ikL} \sin k(L-x)$$

$$= -2jA \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \sin k(L-x)$$

$$\frac{dy_1}{dx} = -2jkA \cos kx$$

$$\frac{dy_2}{dx} = +2jkA \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \cos k(L-x)$$

④ at $x = \frac{L}{4}$ $\sum f_y = 0$



$$F + T \sin \theta_1 + T \sin \theta_2 = 0$$

$$F - T \frac{dy_1}{dx} + T \frac{dy_2}{dx} = 0$$

$$F + 2jkTA \cos \frac{kL}{4} + 2jkTA \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \cos \frac{3kL}{4} = 0$$

$$F + 2jkTA \left(\cos \frac{kL}{4} + \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \cos \frac{3kL}{4} \right) = 0$$

$$2jkTA \left(\cos \frac{kL}{4} + \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \cos \frac{3kL}{4} \right) = -F$$

$$A = - \frac{F}{2jkT \left[\cos \frac{kL}{4} + \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \cos \frac{3kL}{4} \right]}$$

⑤ Drive point impedance

$$Z_{mo} = \frac{F}{j\omega y_1|_{x=\frac{L}{4}}}$$

$$y_1 = + \cancel{Z} \ddot{x} \frac{F}{\cancel{Z} kT \left[\cos \frac{kL}{4} + \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \cos \frac{3kL}{4} \right]} \sin kx$$

$$\frac{\partial y_1}{\partial t} = \frac{j\omega F}{kT} \frac{1}{\cos \frac{kL}{4} + \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \cos \frac{3kL}{4}} \sin kx$$

$$Z_{mo} = \frac{F}{\frac{j\omega F}{kT} \frac{1}{\cos \frac{kL}{4} + \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \cos \frac{3kL}{4}} \sin \frac{kL}{4}}$$

=

$$\frac{F}{\frac{j\omega F}{kT} \frac{1}{\frac{\cos \frac{kL}{4}}{\sin \frac{kL}{4}} + \frac{\cos \frac{3kL}{4}}{\sin \frac{3kL}{4}}}}$$

=

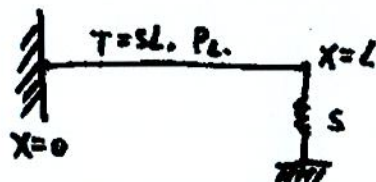
$$= -j \frac{\omega}{kT} \frac{1}{\cot \frac{kL}{4} + \cot \frac{3kL}{4}}$$

$$c = \sqrt{\frac{T}{\rho_L}}$$

$$t_L c^2 = T$$

$$k = \frac{\omega}{c}$$

2.11.1.



The wave equation is $\frac{\partial^2 y}{\partial x^2} + k^2 y = 0$.

The B.C.s are:

at $x=0$, $y=0$ (1)

at $x=L$

$T \sin \theta - S y = 0$.

$\Rightarrow T \frac{dy}{dx} + S y = 0$ (2).



Assume the solution is:

$$y(x,t) = (A e^{-jkx} + B e^{jkx}) e^{j\omega t}$$

substitute into B.C.s.

$$A + B = 0 \quad \text{---(3)}$$

$$T[-jkA e^{-jkL} + jkB e^{jkL}] + S[A e^{-jkL} + B e^{jkL}] = 0. \quad \text{---(4)}$$

From (3) $\Rightarrow B = -A$. substitute into (4):
and rearrange, obtain:

$$\tan(kL) = -kL. \quad \text{---(5)}$$

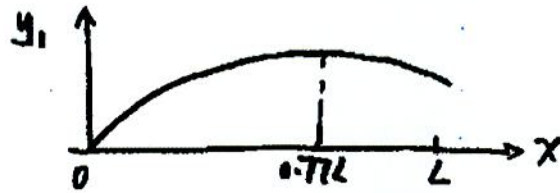
(5) is solved graphically, we get:

$$(KL)_1 \approx 0.65\pi.$$

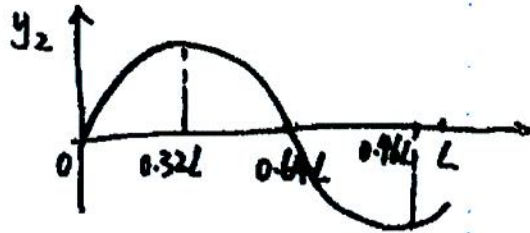
$$(KL)_2 \approx 1.57\pi.$$

$$(KL)_3 \approx 2.54\pi.$$

The fundamental is $\sin \frac{(KL)_1}{L} x = \sin \frac{0.65\pi}{L} x$.



First overtone: $\sin \frac{(KL)_2}{L} x = \sin \frac{1.57\pi}{L} x$.



2.11.1.

