



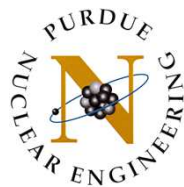
NUCL 511

Nuclear Reactor Theory and Kinetics

Lecture Note 9

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Numerical Solution of PKE

■ Prompt kinetics (simplest case)

$$\dot{p}(t) = \frac{\rho(t) - \beta}{\Lambda} p(t) = \alpha_p(t) p(t) = f(t, p)$$

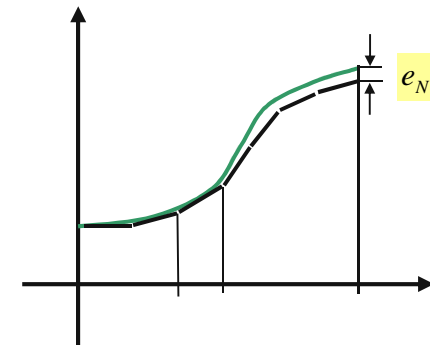
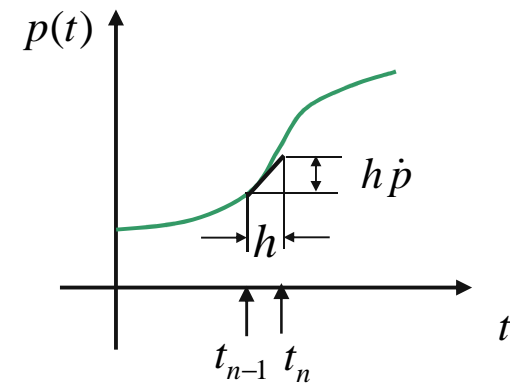
■ Explicit Euler method

- Discretize time with a time step size h
- Find the solution at $t = t_n$ using the solution at $t = t_{n-1}$
 - Initial condition p_0 is known for $n = 1$

$$\dot{p}_{n-1} \approx \frac{p_n - p_{n-1}}{h}$$

$$p_n = p_{n-1} + \dot{p}_{n-1} h = p_{n-1} \left(1 + \frac{\rho_{n-1} - \beta}{\Lambda} h \right)$$

- Involves errors because the finite difference approximation of the slope cannot be exact
- The error will be accumulated as well



Euler Method

■ Normal form of first order ODE

$$\frac{dy}{dx} = f(x, y), \quad y(x_0) = y_0$$

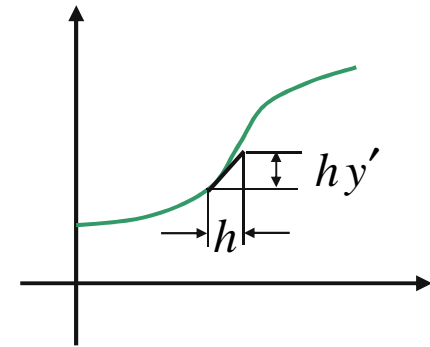
■ Explicit Euler Method

$$y_0 = y(x_0)$$

$$y_1 = y_0 + y'_0 h = y_0 + f(x_0, y_0)h$$

...

$$y_{n+1} = y_n + y'_n h = y_n + f(x_n, y_n)h$$



■ Local error of Euler method (single step)

– Let $\bar{y}(x)$ be the true solution and suppose $y_n = \bar{y}_n$ and $y'_n = \bar{y}'_n$

$$\bar{y}_{n+1} = \bar{y}(x_n + h) = \bar{y}_n + \bar{y}'_n h + \frac{1}{2} \bar{y}''(\xi_n) h^2, \quad x_n \leq \xi_n \leq x_{n+1}$$

$$y_{n+1} = y_n + y'_n h = \bar{y}_n + \bar{y}'_n h$$

$$e_{n+1} = y_{n+1} - \bar{y}_{n+1} = -\frac{1}{2} \bar{y}''(\xi_n) h^2 = O(h^2)$$

Global Error of Euler Method

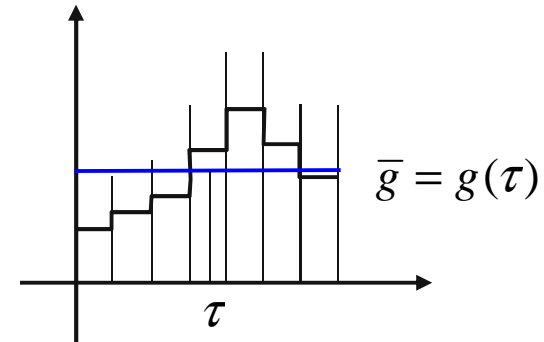
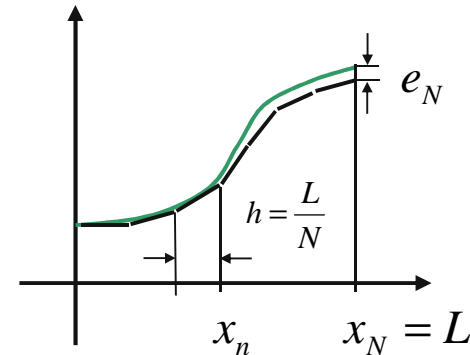
- Error at the end of the problem domain

$$e_N = \sum_{n=1}^N e_n = -\sum_{n=1}^N \frac{1}{2} \bar{y}_n''(\xi_n) h^2, \quad x_{n-1} < \xi_n < x_n$$

$$\begin{aligned} e_N &= \sum_{n=1}^N \left[-\frac{1}{2} \bar{y}_n''(\xi_n) h \right] h \\ &= \sum_{n=1}^N g(x_n) h = \bar{g} L = \frac{1}{2} \bar{y}_n''(\tau) h L \end{aligned}$$

$$0 < \tau < L$$

$$\Rightarrow e_N = O(h): \text{First order accuracy}$$



Stability of Explicit Euler Method

- Suppose the following ODE

$$\frac{dy}{dt} = -\alpha y, \quad y(0) = y_0 \Rightarrow y(t) = y_0 e^{-\alpha t}$$

- Explicit Euler method

$$y_{n+1} = y_n - \alpha y_n h = (1 - \alpha h) y_n$$

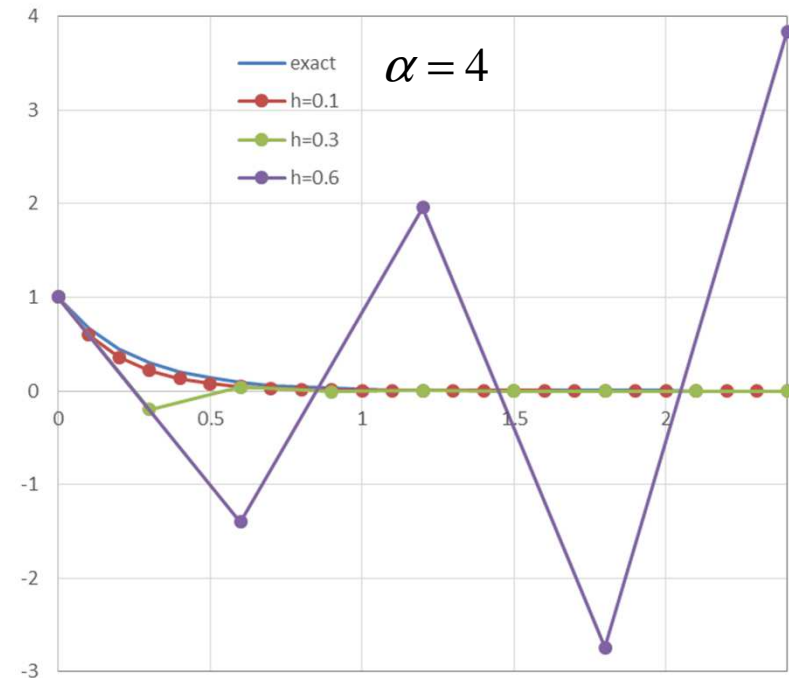
- Solution behavior vs. time step size

$$1 - \alpha h > 0 \Rightarrow h < \frac{1}{\alpha}: \text{Stable}$$

$$-1 < 1 - \alpha h < 0 \Rightarrow \frac{1}{\alpha} < h < \frac{2}{\alpha}: \text{Overshoot, Unstable}$$

$$1 - \alpha h < -1 \Rightarrow \frac{2}{\alpha} < h: \text{Divergent}$$

Unstable behavior is noted if there is fluctuation in the solution
(not monotonous increase)



Implicit Euler Method

- Use the endpoint slope of the interval

$$y'_{n+1} = f(x_{n+1}, y_{n+1})$$

$$y_{n+1} = y_n + y'_{n+1}h$$

- Example for the exponential decay

$$y_{n+1} = y_n - \alpha y_{n+1}h \Rightarrow y_{n+1} = \frac{1}{1 + \alpha h} y_n$$

$$0 < \frac{1}{1 + \alpha h} < 1 \Rightarrow \text{unconditionally stable}$$

- Unconditionally stable, but may lead to a nonlinear equation

$$y_{n+1} = y_n + f(x_{n+1}, y_{n+1})h$$

- The order of accuracy is a first order like the explicit scheme

$$\dot{p}_{n-1} \cong \frac{p_n - p_{n-1}}{h} = \alpha_p(t_n) p_n = \frac{\rho_n - \beta}{\Lambda} p_n \Rightarrow p_n = \frac{p_{n-1}}{1 + \alpha_n h}$$

Euler Methods for 6G PKE

■ Point kinetics equation

$$\dot{p} = \frac{\rho(t) - \beta}{\Lambda} p + \frac{1}{\Lambda} \sum_{k=1}^K \lambda_k \zeta_k$$

$$\dot{\zeta}_k = \beta_k p - \lambda_k \zeta_k$$

■ Explicit method

$$\begin{aligned} \frac{p_n - p_{n-1}}{h} &= \frac{1}{\Lambda} \left[(\rho_{n-1} - \beta) p_{n-1} + \sum_{k=1}^K \lambda_k \zeta_k^{(n-1)} \right] \equiv \frac{1}{\Lambda} R_{n-1} \\ \frac{\zeta_k^{(n)} - \zeta_k^{(n-1)}}{h} &= \beta_k p_{n-1} - \lambda_k \zeta_k^{(n-1)} \end{aligned} \quad \Rightarrow \quad \begin{aligned} p_n &= p_{n-1} + \frac{h}{\Lambda} R_{n-1} \\ \zeta_k^{(n)} &= (1 - \lambda_k h) \zeta_k^{(n-1)} + \beta_k h p_{n-1} \end{aligned}$$

■ Implicit method

$$\begin{aligned} \frac{p_n - p_{n-1}}{h} &= \frac{1}{\Lambda} \left[(\rho_n - \beta) p_n + \sum_{k=1}^K \lambda_k \zeta_k^{(n)} \right] \\ \frac{\zeta_k^{(n)} - \zeta_k^{(n-1)}}{h} &= \beta_k p_n - \lambda_k \zeta_k^{(n)} \end{aligned} \quad \Rightarrow \quad \begin{aligned} \left[\frac{\Lambda}{h} + (\beta - \rho_n) \right] p_n - \sum_{k=1}^K \lambda_k \zeta_k^{(n)} &= \frac{\Lambda}{h} p_{n-1} \\ -\beta_k p_n + \left(\frac{1}{h} + \lambda_k \right) \zeta_k^{(n)} &= \frac{\zeta_k^{(n-1)}}{h} \end{aligned}$$

Implicit Euler Method for 6G PKE

- Implicit scheme yields a system of 7 coupled equations

$$\left[\frac{\Lambda}{h} + (\beta - \rho_n) \right] p_n - \sum_{k=1}^K \lambda_k \zeta_k^{(n)} = \frac{\Lambda}{h} p_{n-1}$$

$$-\beta_k p_n + \left(\frac{1}{h} + \lambda_k \right) \zeta_k^{(n)} = \frac{\zeta_k^{(n-1)}}{h}$$

$$\begin{bmatrix} \Lambda/h + (\beta - \rho_n) & -\lambda_1 & \cdots & -\lambda_6 \\ -\beta_1 & 1/h + \lambda_1 & & \\ & & \ddots & \\ -\beta_6 & & & 1/h + \lambda_6 \end{bmatrix} \begin{bmatrix} p_n \\ \zeta_1^{(n)} \\ \vdots \\ \zeta_6^{(n)} \end{bmatrix} = \begin{bmatrix} \Lambda p_{n-1} / h \\ \zeta_1^{(n-1)} / h \\ \vdots \\ \zeta_6^{(n-1)} / h \end{bmatrix}$$

- Arrow head form

$$\begin{bmatrix} 1/h + \lambda_1 & & & -\beta_1 \\ & \ddots & & \\ & & 1/h + \lambda_6 & -\beta_6 \\ -\lambda_1 & \cdots & -\lambda_6 & \Lambda/h + (\beta - \rho_n) \end{bmatrix} \begin{bmatrix} \zeta_1^{(n)} \\ \vdots \\ \zeta_6^{(n)} \\ p_n \end{bmatrix} = \begin{bmatrix} \zeta_1^{(n-1)} / h \\ \vdots \\ \zeta_6^{(n-1)} / h \\ \Lambda p_{n-1} / h \end{bmatrix}$$

Predictor-Corrector Method

■ Predictor step

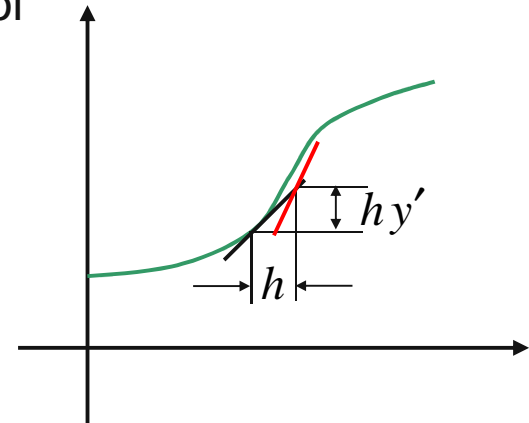
- Determine the new provisional value by the use of the explicit Euler method

$$y'_n = f(x_n, y_n)$$

$$\tilde{y}_{n+1} = y_n + h y'_n$$

- Determine the slope at the new point

$$\tilde{y}'_{n+1} = f(x_{n+1}, \tilde{y}_{n+1}) = f(x_n + h, y_n + h y'_n)$$



■ Corrector step

- Determine the interval average slope using the beginning and end point slopes

$$\hat{y}'_n = \frac{1}{2}(y'_n + \tilde{y}'_{n+1})$$

- Obtain the final value using the average slope

$$y_{n+1} = y_n + h \hat{y}'_n$$

$$= y_n + \frac{1}{2}[y'_n + f(x_n + h, y_n + h y'_n)]h$$

Predictor-Corrector Method

■ Error of Predictor-Corrector Method

– Predictor-corrector solution

$$\begin{aligned}\tilde{y}'_{n+1} &= f(x_n + h, y_n + hy'_n) \\ &= f(x_n, y_n) + \frac{\partial f}{\partial x} h + \frac{\partial f}{\partial y} hy'_n + O(h^2) \\ &= f(x_n, y_n) + \left(\frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y'_n \right) h + O(h^2) \quad \Leftarrow \quad \frac{df}{dx} = \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} \frac{dy}{dx} = \frac{dy'}{dx} = y'' \\ &= y'_n + y''_n h + O(h^2)\end{aligned}$$

$$\begin{aligned}y_{n+1} &= y_n + \frac{1}{2} \left[y'_n + \{ y'_n + y''_n h + O(h^2) \} \right] h \\ &= y_n + y'_n h + \frac{1}{2} y''_n h^2 + O(h^3)\end{aligned}$$

– Taylor series expansion of true solution

$$\bar{y}_{n+1} = \bar{y}_n + \bar{y}'_n h + \frac{1}{2} \bar{y}''_n h^2 + \frac{1}{6} \bar{y}'''_n h^3 + O(h^4)$$

Predictor-Corrector Method

■ One step error

- Assume the solution is exact at x_n

$$y'_n = f(x_n, y_n) = \bar{y}'_n$$

$$y''_n \equiv \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y'_n = \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} \bar{y}'_n = \bar{y}''_n$$

- Then the error at x_{n+1} becomes

$$e_{n+1} = y_{n+1} - \bar{y}_{n+1} = -\frac{1}{6} \bar{y}'''_n h^3 + O(h^3) - O(h^4) = O(h^3)$$

- Third order accurate local error
- Second order accurate global error