

# **PARCS: Parallel Advanced Reactor Core Simulator**

**U.S. NRC version 3.0**

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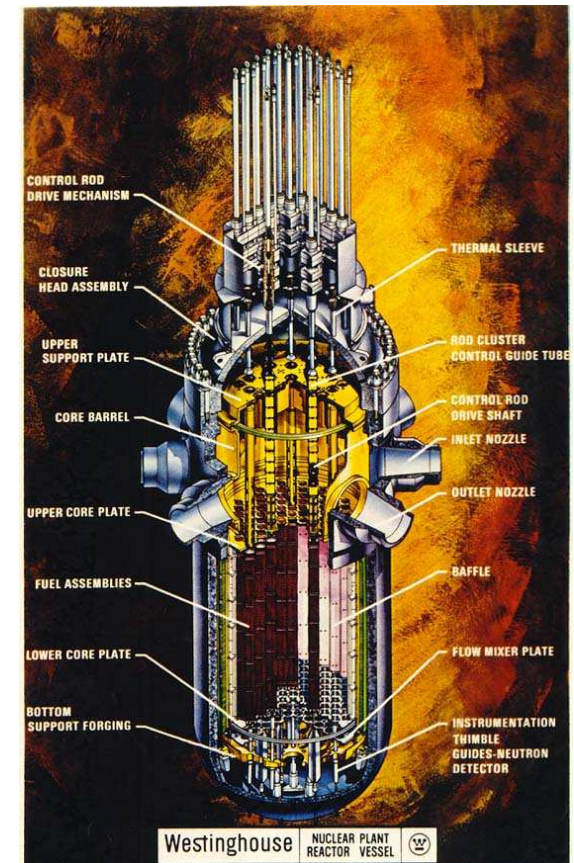
# Coupled Neutron / Nuclide and Temperature/ Fluid Field Equations

## ☀ Neutron Transport Equation (Boltzmann)

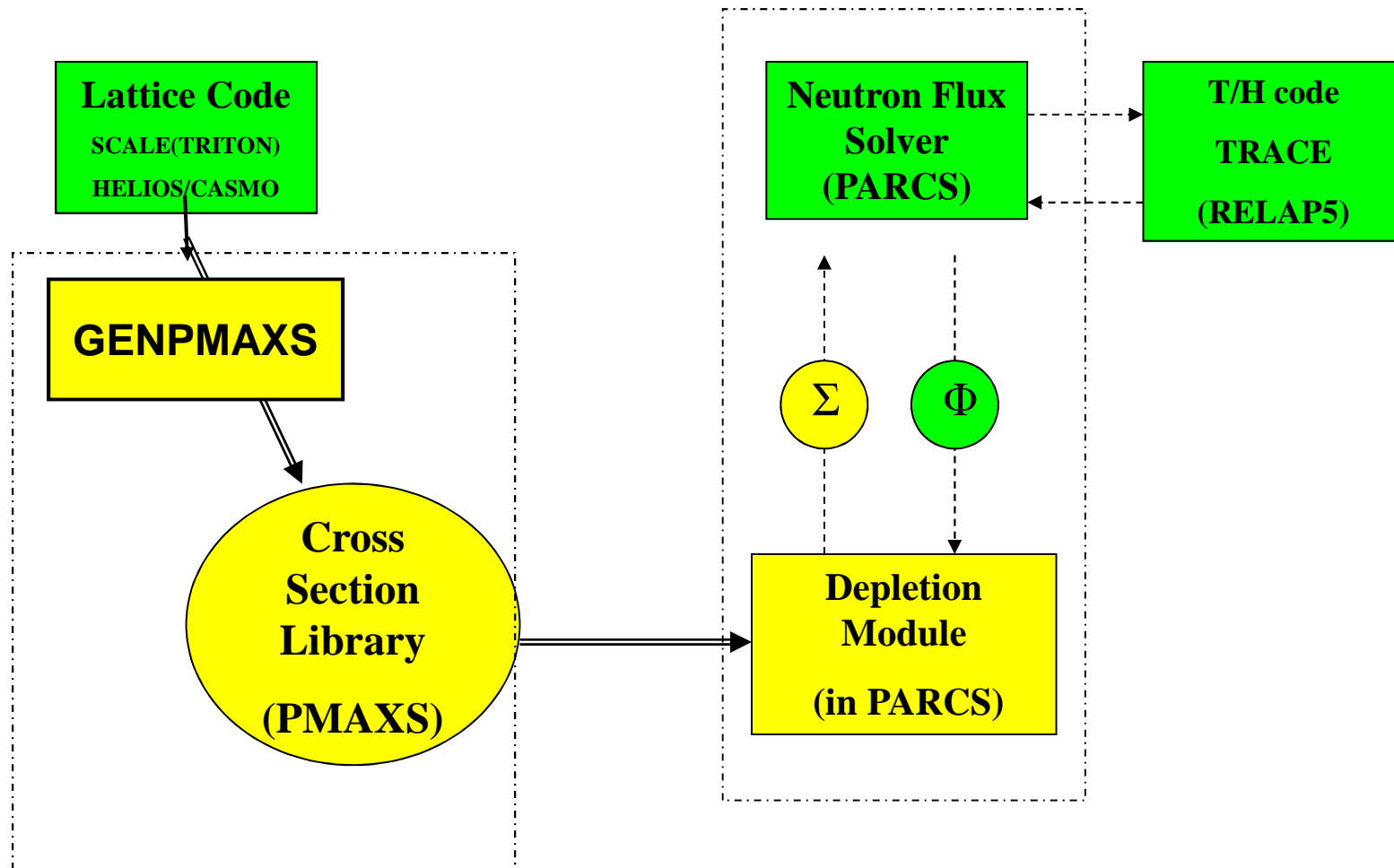
$$\frac{1}{v} \frac{\partial \phi}{\partial t} + \Omega \cdot \nabla \phi(r, E, \Omega, t) + \Sigma_t(r, E) \phi(r, E, \Omega, t) = \frac{1}{4\pi} S_f(r, E, t) + \int \int \Sigma_s(r, E \rightarrow E', \Omega \rightarrow \Omega') \phi(r, E', \Omega', t) dE' d\Omega'$$

## • Nuclide depletion equation (Bateman)

$$\frac{dN_A(t)}{dt} = -(\sigma_A^a \phi + \lambda_A) N_A(t) + \sigma_C^r \phi N_C(t) + \lambda_B N_B(t)$$



# U.S. NRC Coupled Code System



# Solution of Coupled Neutronics / Thermal-Hydraulics Field Equations

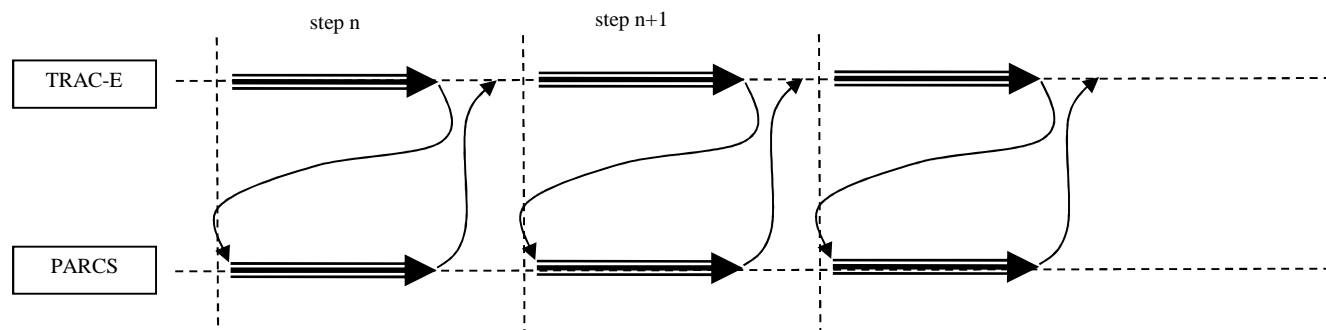
$$N(T)T = Q(\Phi) \quad \text{Thermal-Hydraulic equation}$$

$$M(T)\Phi = S \quad \text{Neutronics spatial kinetic equation}$$

*T*: the vector of T/H variables

*Φ*: the vector of Neutronics variables

Current “Marching” Solution Method



# Coupling of Neutronics and Thermal-Hydraulics

- Neutron Cross Section Model

$$\Sigma(\alpha, T_f, T_m, D_m, S_b) = \Sigma^r + \alpha \Delta \Sigma^{cr} + \frac{\partial \Sigma}{\partial \sqrt{T_f}} \Delta \sqrt{T_f} + \frac{\partial \Sigma}{\partial T_m} \Delta T_m + \frac{\partial \Sigma}{\partial D_m} \Delta D_m + \frac{\partial \Sigma}{\partial S_b} \Delta S_b + \frac{\partial^2 \Sigma}{\partial D_m^2} (\Delta D_m)^2$$

$$\Delta \Sigma^{cr} = \Delta \Sigma^{cr}(BU, HIS1, HIS2)$$

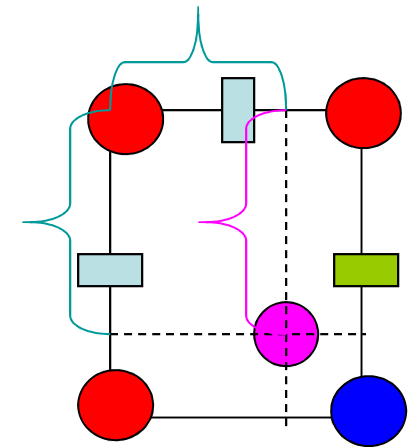
$$\frac{\partial \Sigma}{\partial \sqrt{T_f}} = \frac{\partial \Sigma}{\partial \sqrt{T_f}}(\sqrt{T_f}, BU, HIS1, HIS2)$$

$$\frac{\partial \Sigma}{\partial D_m} = \frac{\partial \Sigma}{\partial D_m}(D_m, BU, HIS1, HIS2)$$

$$\frac{\partial \Sigma}{\partial S_b} = \frac{\partial \Sigma}{\partial S_b}(S_b, BU, HIS1, HIS2)$$

$$\frac{\partial \Sigma}{\partial T_m} = \frac{\partial \Sigma}{\partial T_m}(T_m, BU, HIS1, HIS2)$$

$$\frac{\partial^2 \Sigma}{\partial D_m^2} = \frac{\partial^2 \Sigma}{\partial D_m^2}(D_m, BU, HIS1, HIS2)$$



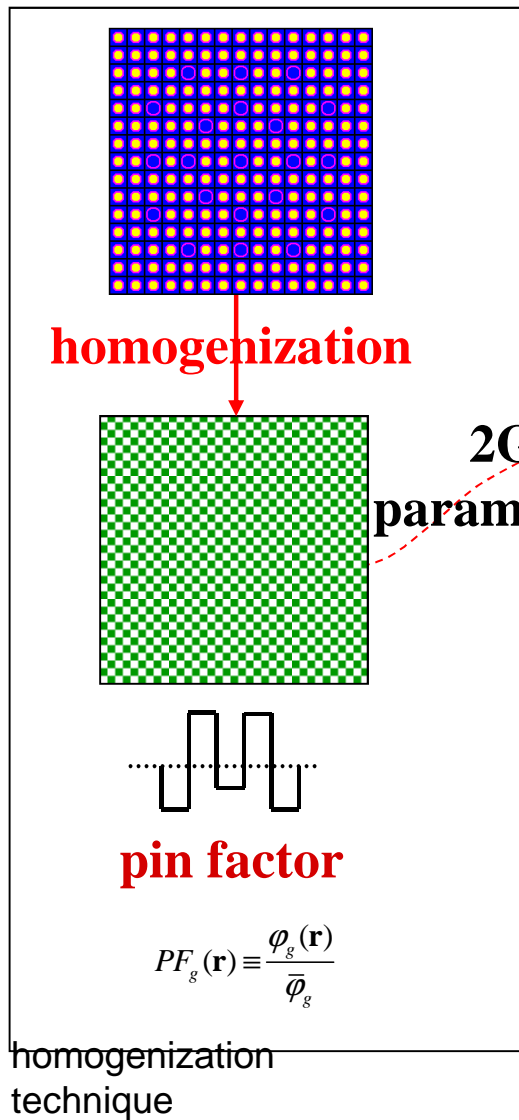
- Partials obtained by piecewise linear interpolation
- Burnup and burnup “history” dependence

# Primary Code Solution Features of PARCS

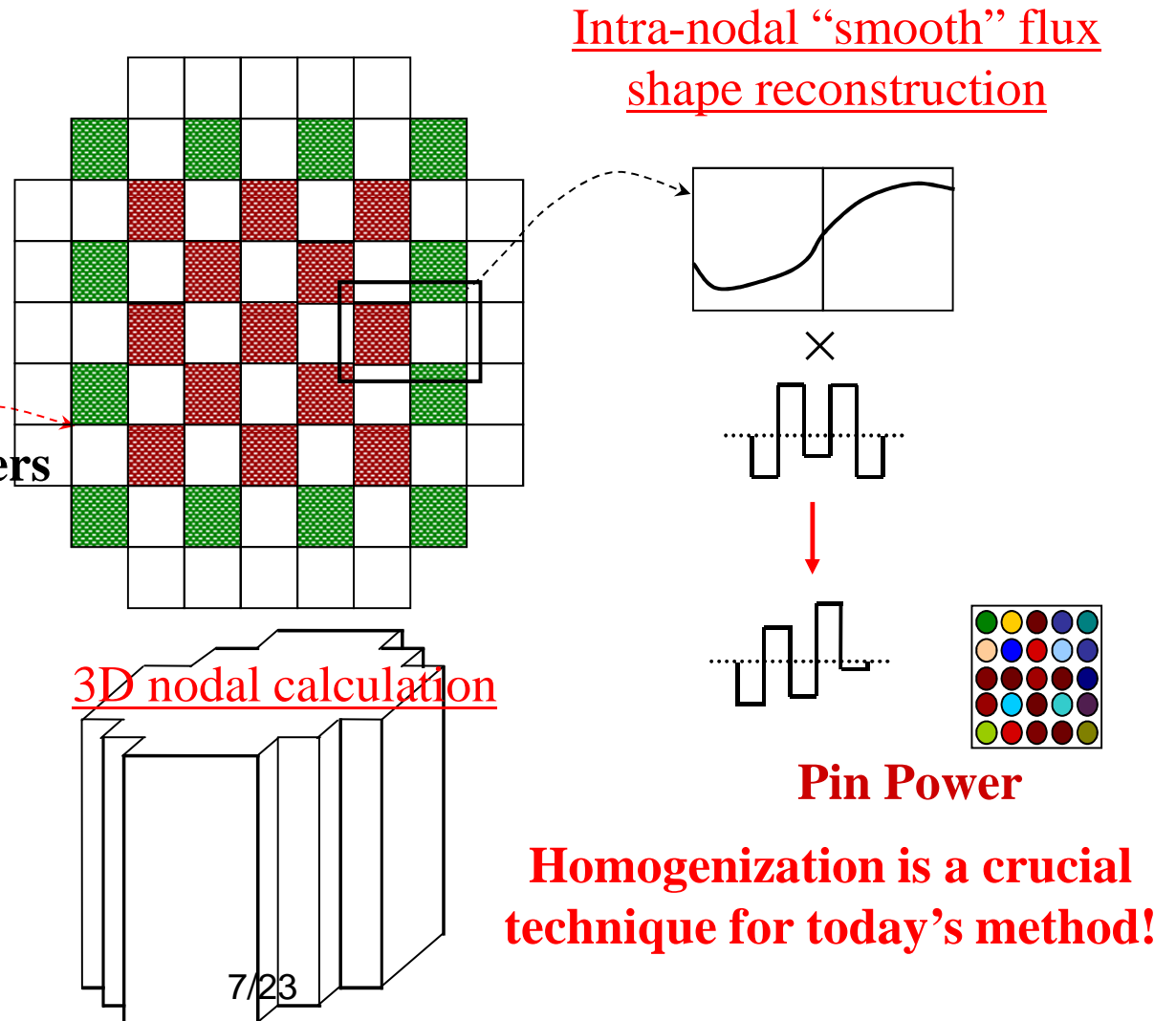
- Steady-state (Eigenvalues) and Transient Simulations
- Multigroup Nodal Diffusion for Rectangular/Hexagonal/Cylindrical Geometries
- CMFD Formulation with Krylov Subspace Linear Solver
- Consistent Pin Power Reconstruction
- Coupled to RELAP5 and TRACE
- Macroscopic Depletion for Fuel Cycle Analysis
- Pin-by-pin Multigroup FMFD or NEM Transport by  $SP_3$
- Multidimensional Cross Section Table Functionalization

# “Two-Step” Solution Method

## 1. Lattice calculation



## 2. Core calculation



Why don't we directly go to whole-core deterministic transport calculation without homogenization?

- **Scale of one single 3-D steady state problem:**

- Number of fuel Assemblies ~200
- Number of axial planes ~100
- Number of pins per assembly ~300
- Number of depletion regions per pin ~ 10
- Number of angular directions ~100
- Number of neutron energy groups ~100

**Total unknowns ~600 Billion**

- At 100 FLOPS/unknown on 1 gigaflop machine = 16 CPU hours

- Not yet tractable for full-scale LWR steady state core analysis, let alone transient or depletion calculation.



# PARCS Neutronics Methods: Solution Kernels

Geometry Type	Kernel Name	Solution Method	Energy Treatment	Angle Treatment
<b>Cartesian 3D</b>	CMFD	FD	2G	Diffusion
	ANM	nodal	2G	Diffusion
	FMFD	FD	MG	SP3
	NEMMG	nodal	MG	SP <sub>3</sub>
<b>Hexagonal 3D</b>	CMFD	FD	2G	Diffusion
	TPEN	nodal	MG	Diffusion
<b>Cylindrical 3D</b>	CMFD	FD	2G	Diffusion
	FMFD	FD	MG	Diffusion/ SP <sub>3</sub>

**CMFD** = Coarse Mesh Finite Difference

**ANM** = Advanced Nodal Method

**FMFD** = Fine Mesh Finite Difference

**NEM** = Nodal Expansion Method

**MG** = Multigroup

# COARSE MESH NODAL METHODS

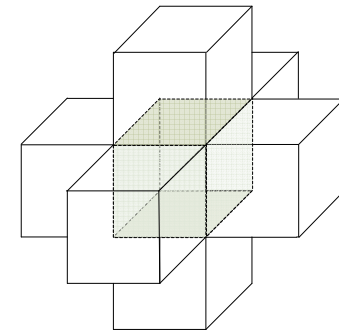
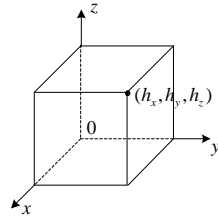
- 3-D Steady-State Multigroup Neutron Diffusion Equation

$$\nabla \cdot \vec{J}_g(\vec{r}, E) + \Sigma_{rg} \phi_g(\vec{r}, E) = \lambda \chi_g \sum_{g'=1}^G \nu \Sigma_{fg'} \phi_{g'}(\vec{r}, E) + \sum_{g'=1}^G \Sigma_{sg'g} \phi_{g'}(\vec{r}, E)$$

- Fick's Law of Diffusion for Current out of Flux

$$\vec{J}_g(\vec{r}, E) = -D_g(\vec{r}, E) \nabla \phi_g(\vec{r}, E)$$

- Computational Node in 3-D Space



- Property assumed constant within each homogenized node
  - FDM sufficiently accurate only if the node size is sufficiently small ( $\sim < 10\text{cm}$ )
  - Nodal methods to achieve high accuracy with large nodes (20 cm)

# Transverse Integrated One-Dimensional Neutron Diffusion Equation

- Transverse Integration of 3-D Neutron Diffusion Equation

$$\sum_{u=y,z} \frac{\bar{J}_{gur}(\xi_x) - \bar{J}_{gul}(\xi_x)}{h_u} - \frac{D}{h_x^2} \frac{d^2}{d\xi_x^2} \bar{\phi}_{gx}(\xi_x) + \Sigma_{rg} \bar{\phi}_{gx}(\xi_x) = \lambda \chi_g \sum_{g'=1}^G \nu \Sigma_{fg'} \bar{\phi}_{g'x}(\xi_x) + \sum_{g'=1}^G \Sigma_{sg'g} \bar{\phi}_{g'x}(\xi_x)$$

- Define Transverse Leakage to Move to RHS

$$L_{gu}(\xi_x) = \frac{1}{h_u} (\bar{J}_{gur}(\xi_x) - \bar{J}_{gul}(\xi_x)) \quad , \quad u = y, z$$

- Transverse Integrated One-Dimensional Neutron Diffusion Equation (Final Form)

$$-\Sigma_{Dg}^x \frac{d^2}{d\xi_x^2} \bar{\phi}_{gx}(\xi_x) + \Sigma_{rg} \bar{\phi}_{gx}(\xi_x) = \lambda \chi_g \sum_{g'=1}^G \nu \Sigma_{fg'} \bar{\phi}_{g'x}(\xi_x) + \sum_{g'=1}^G \Sigma_{sg'g} \bar{\phi}_{g'x}(\xi_x) - L_{gy}(\xi_x) - L_{gz}(\xi_x)$$

- Diffusion Equivalent Group Constant

$$\Sigma_{Dg}^x = \frac{D}{h_x^2}$$

# Transverse Integrated One-dimensional Neutron Diffusion Equations

- Set of 3 Directional 1-D Neutron Diffusion Equations

$$-\Sigma_{Dg}^x \frac{d^2}{d\xi_x^2} \bar{\phi}_{gx}(\xi_x) + \Sigma_{rg} \bar{\phi}_{gx}(\xi_x) = \lambda \chi_g \sum_{g'=1}^G \nu \Sigma_{fg'} \bar{\phi}_{g'x}(\xi_x) + \sum_{g'=1}^G \Sigma_{sg'g} \bar{\phi}_{g'x}(\xi_x) - L_{gy}(\xi_x) - L_{gz}(\xi_x)$$

$$-\Sigma_{Dg}^y \frac{d^2}{d\xi_y^2} \bar{\phi}_{gy}(\xi_y) + \Sigma_{rg} \bar{\phi}_{gy}(\xi_y) = \lambda \chi_g \sum_{g'=1}^G \nu \Sigma_{fg'} \bar{\phi}_{g'y}(\xi_y) + \sum_{g'=1}^G \Sigma_{sg'g} \bar{\phi}_{g'y}(\xi_y) - L_{gz}(\xi_y) - L_{gx}(\xi_y)$$

$$-\Sigma_{Dg}^z \frac{d^2}{d\xi_z^2} \bar{\phi}_{gz}(\xi_z) + \Sigma_{rg} \bar{\phi}_{gz}(\xi_z) = \lambda \chi_g \sum_{g'=1}^G \nu \Sigma_{fg'} \bar{\phi}_{g'z}(\xi_z) + \sum_{g'=1}^G \Sigma_{sg'g} \bar{\phi}_{g'z}(\xi_z) - L_{gx}(\xi_z) - L_{gy}(\xi_z)$$

- 3-D Partial Differential Equation

→ Three 1-D Ordinary Differential Equations

- Coupled through average transverse leakage term

- **Exact** if the proper transverse leakages are used

- Approximation on Transverse Leakage

- Quadratic Shape (2<sup>nd</sup> order polynomial)
- based on observation that change of flux distribution is not sensitive to change of transverse leakage
- Iteratively update transverse leakage

# Nodal Expansion Method

- Intranodal Flux Expansion of 1-D Flux
  - Approximate 1-D Flux by 4<sup>th</sup> Order Polynomial

$$\bar{\phi}(\xi) = \sum_{i=0}^4 a_i P_i(\xi)$$

- Basis Functions

$$P_0(\xi) = 1$$

$$P_1(\xi) = 2\xi - 1$$

$$P_2(\xi) = 6\xi(1-\xi) - 1$$

$$P_3(\xi) = 6\xi(1-\xi)(2\xi - 1)$$

$$P_4(\xi) = 6\xi(1-\xi)(5\xi^2 - 5\xi + 1)$$

$$L(\xi) = \sum_{i=0}^2 l_i P_i(\xi)$$

# Response Matrix Equation

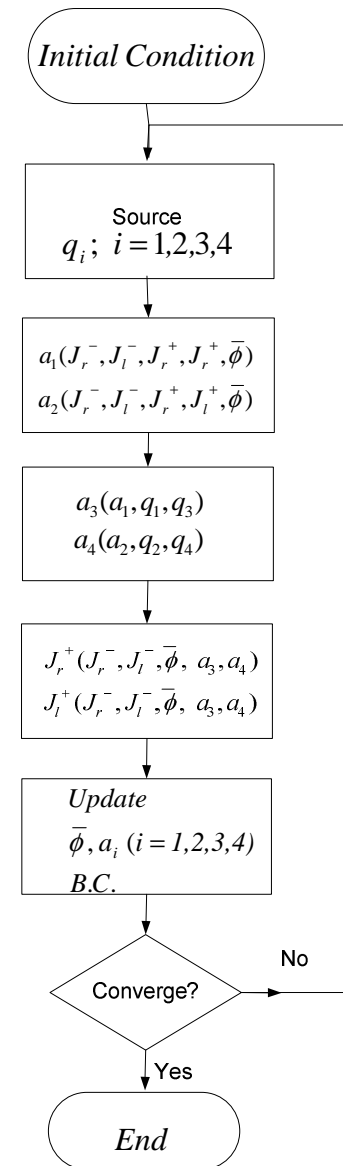
- Three-Directional Outgoing Currents Described Altogether

$$\begin{bmatrix} J_{xl}^+ \\ J_{xr}^+ \\ J_{yl}^+ \\ J_{yr}^+ \\ J_{zl}^+ \\ J_{zr}^+ \end{bmatrix} = \begin{bmatrix} c_2^x & c_3^x & & & & \\ c_3^x & c_2^x & & & & \\ & & c_2^y & c_3^y & & \\ & & c_3^y & c_2^y & & \\ & & & & c_2^z & c_3^z \\ & & & & c_3^z & c_2^z \end{bmatrix} \begin{bmatrix} c_1^x \\ c_1^x \\ c_1^y \\ c_1^y \\ c_1^z \\ c_1^z \end{bmatrix} \begin{bmatrix} J_{xl}^- \\ J_{xr}^- \\ J_{yl}^- \\ J_{yr}^- \\ J_{zl}^- \\ J_{zr}^- \end{bmatrix} + \begin{bmatrix} c_1^x a_4^x + c_4^x a_3^x \\ c_1^x a_4^x - c_4^x a_3^x \\ c_1^y a_4^y + c_4^y a_3^y \\ c_1^y a_4^y - c_4^y a_3^y \\ c_1^z a_4^z + c_4^z a_3^z \\ c_1^z a_4^z - c_4^z a_3^z \end{bmatrix}$$

- $a_3$  and  $a_4$  are treated as known by using  $a_1$  and  $a_2$  which are approximated by previously known surface fluxes
- otherwise, to solve rigorously, need to solve for 13 unknowns including  $a_3$  and  $a_4$  for each direction simultaneously.

# NEM Iterative Solution Sequence

- For a given group
  - Determine sequentially
    - Source expansion coeff.
    - $a_1$  and  $a_2$  from previous surface fluxes
    - $a_3$  and  $a_4$  using source moments and  $a_1$  and  $a_2$
    - node average flux
    - outgoing current
  - Move to next group
  - Move to next node once all groups are done
- Group sweep and node sweep can be reversed (node sweep then group sweep)
- Update eigenvalue



# Analytic Nodal Method for 2-G Problem

- 1D, Two-Group Diffusion Equation

$$-D_1 \frac{d^2 \phi_1(x)}{dx^2} + \Sigma_{r1} \phi_1(x) - \lambda (\nu \Sigma_{f1} \phi_1(x) + \nu \Sigma_{f2} \phi_2(x)) = -L_1(x)$$

$$-D_2 \frac{d^2 \phi_2(x)}{dx^2} + \Sigma_{r2} \phi_2(x) - \Sigma_{l2} \phi_1(x) = -L_2(x)$$

- All source terms except transverse leakage now on LHS

- Analytic Solution: Homogeneous + Particular Sol.

$$\phi_g(x) = \phi_g^H(x) + \phi_g^P(x)$$

$$\phi_g^H(x) = \hat{\phi}_g^H \exp(iBx)$$



# Determination of Buckling Eigenvalues

- Characteristic Equation 
$$\begin{bmatrix} D_1 B^2 + \Sigma_{r1} - \lambda \nu \Sigma_{f1} & -\lambda \nu \Sigma_{f1} \\ -\Sigma_{12} & D_2 B^2 + \Sigma_{r2} \end{bmatrix} \begin{bmatrix} \hat{\phi}_1^H \\ \hat{\phi}_2^H \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

– For Nontrivial Solution

$$\text{Det}(A) = 0 \Rightarrow (D_1 B^2 + \Sigma_{r1} - \lambda \nu \Sigma_{f1})(D_2 B^2 + \Sigma_{r2}) - \lambda \nu \Sigma_{f2} \Sigma_{12} = 0$$

$$(B^2)^2 + \left( \frac{\Sigma_{r1}}{D_1} + \frac{\Sigma_{r2}}{D_2} - \frac{\lambda \nu \Sigma_{f1}}{D_1} \right) B^2 + \left( 1 - \frac{k_\infty}{k_{eff}} \right) \frac{\Sigma_{r1}}{D_1} \frac{\Sigma_{r2}}{D_2} = 0 \Leftrightarrow (B^2)^2 + 2b B^2 + c = 0$$

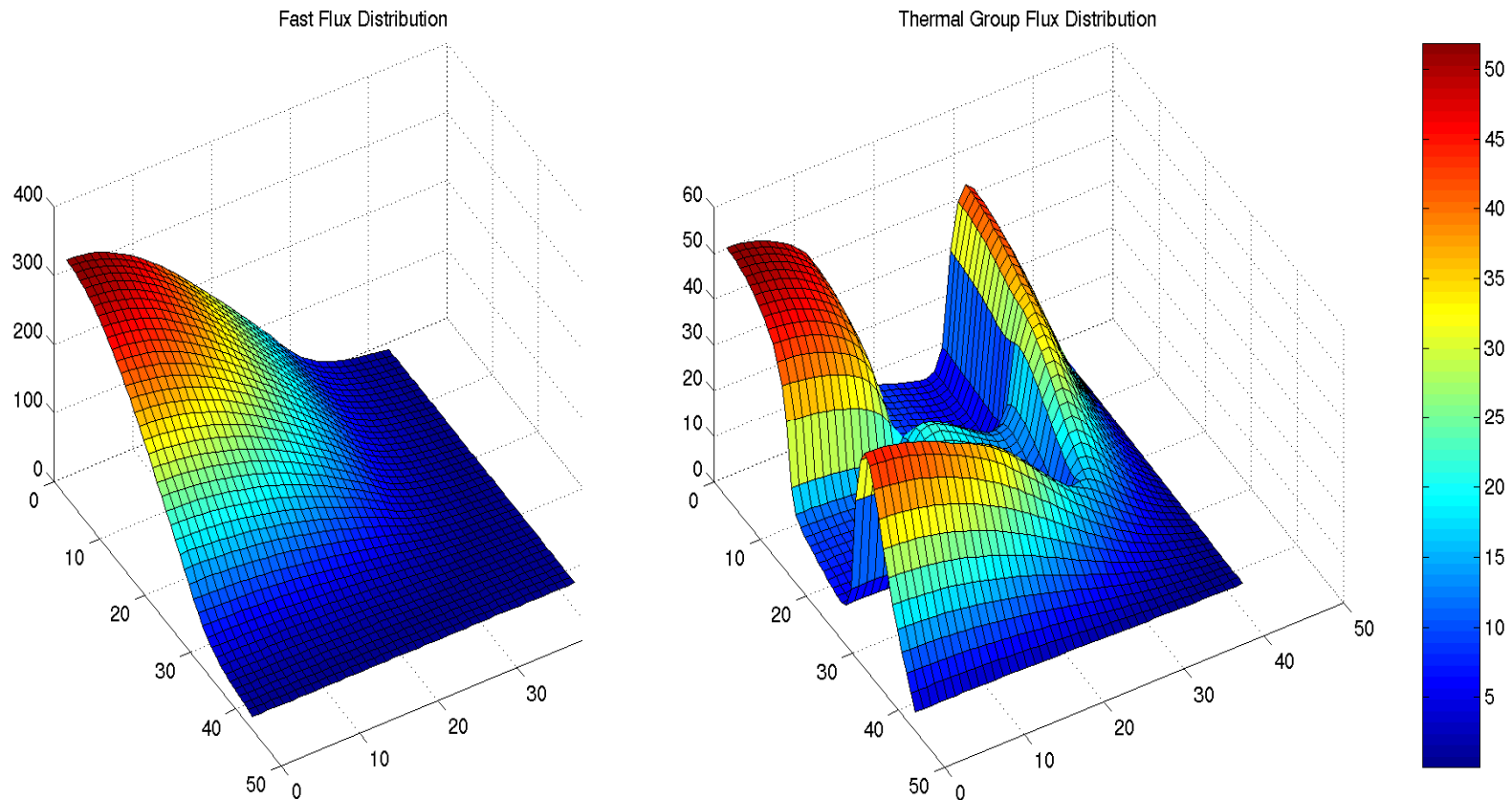
– Solution 
$$B_1^2 = b \left( -1 + \sqrt{1 - \frac{c}{b^2}} \right) \quad \begin{cases} > 0 & , \quad k_\infty > k_{eff} \\ < 0 & , \quad k_\infty < k_{eff} \end{cases}$$

$$\phi_{g1}^H(x) = \begin{cases} a_{g1} \sin(B_1 x) + a_{g2} \cos(B_1 x) & , \quad k_\infty > k_{eff} \\ a_{g1} \sinh(B_1 x) + a_{g2} \cosh(B_1 x) & , \quad k_\infty < k_{eff} \end{cases}$$

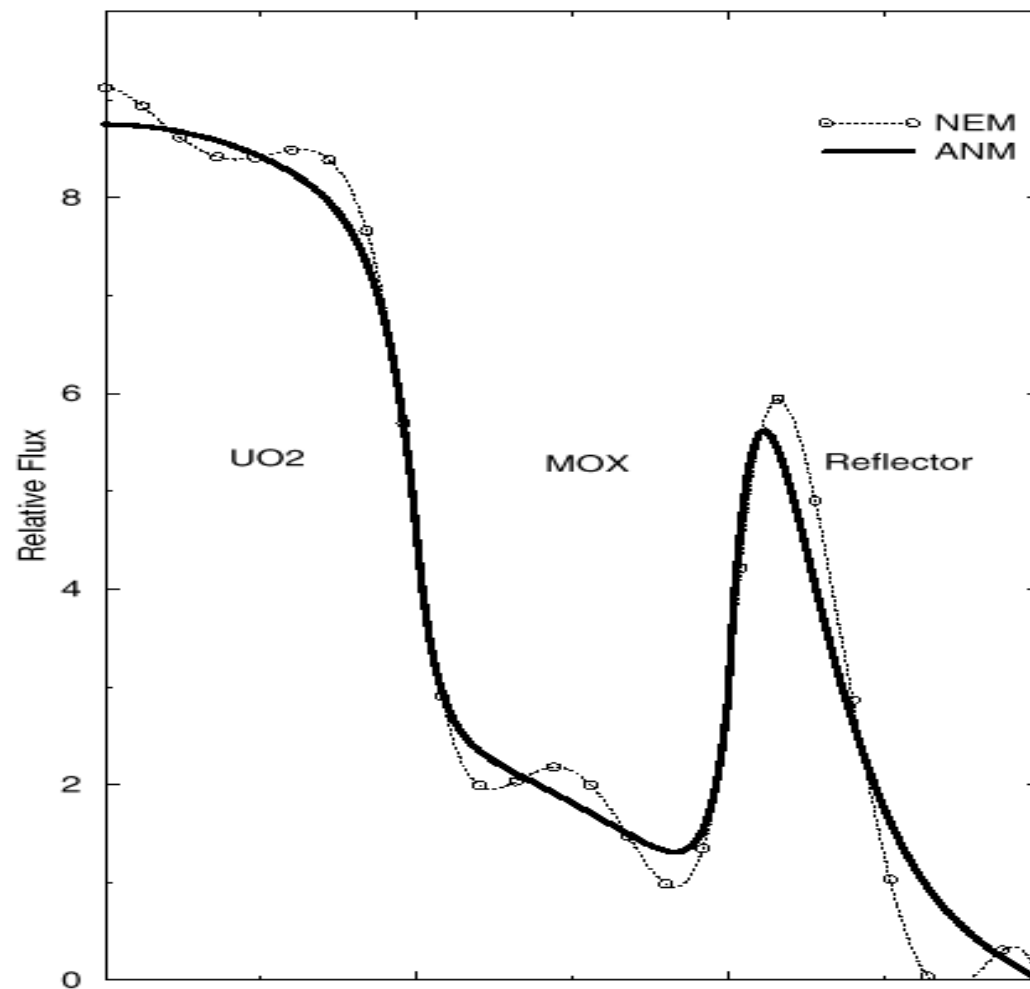
# Two-Node ANM Solution

- Boundary Condition and Given Parameters
  - Quadratic Transverse Leakage for Two Nodes,  $k_{\text{eff}}$
  - Node-Average Fluxes for Two Nodes
- 8 Unknown Coefficients
  - 4 per node x 2 nodes
- 8 Constraints → Unique Solution
  - 4 Node Average Fluxes (2 Groups x 2 Nodes)
  - 2 Flux Continuity at Interface (2 Groups)
  - 2 Current Continuity at Interface (2 Groups)
- Solution Sequence
  - Assume Node-Average Flux
  - Solve for Net Currents for each Direction from 2-Node
  - Update Node-Average Flux from Nodal Balance
  - Repeat

# SS Cartesian: NEACRP L336 C5 problem, flux distribution



# SS Cartesian: NEACRP L336 C5 problem, nodal flux shape



# “HYBRID” ANM/NEM Method

- ANM is more accurate than NEM for many applications
- However, the ANM implementation is not stable for “just critical” nodes where a linear is required:

$$f(x) \in \begin{cases} \{\sin(\kappa x), \cos(\kappa x), \sinh(\mu x), \cosh(\mu x)\} & , \quad k_\infty > k_{eff} \\ \{x, 1, \sinh(\mu x), \cosh(\mu x)\} & , \quad k_\infty = k_{eff} \\ \{\sinh(\kappa x), \cosh(\kappa x), \sinh(\mu x), \cosh(\mu x)\} & , \quad k_\infty < k_{eff} \end{cases}$$

- Therefore a “hybrid” was implemented in which ANM is the base solution and NEM is invoked whenever the node k-inf approaches unity.

$$\delta = \left| \frac{k_\infty}{k_{eff}} - 1 \right| < \epsilon$$

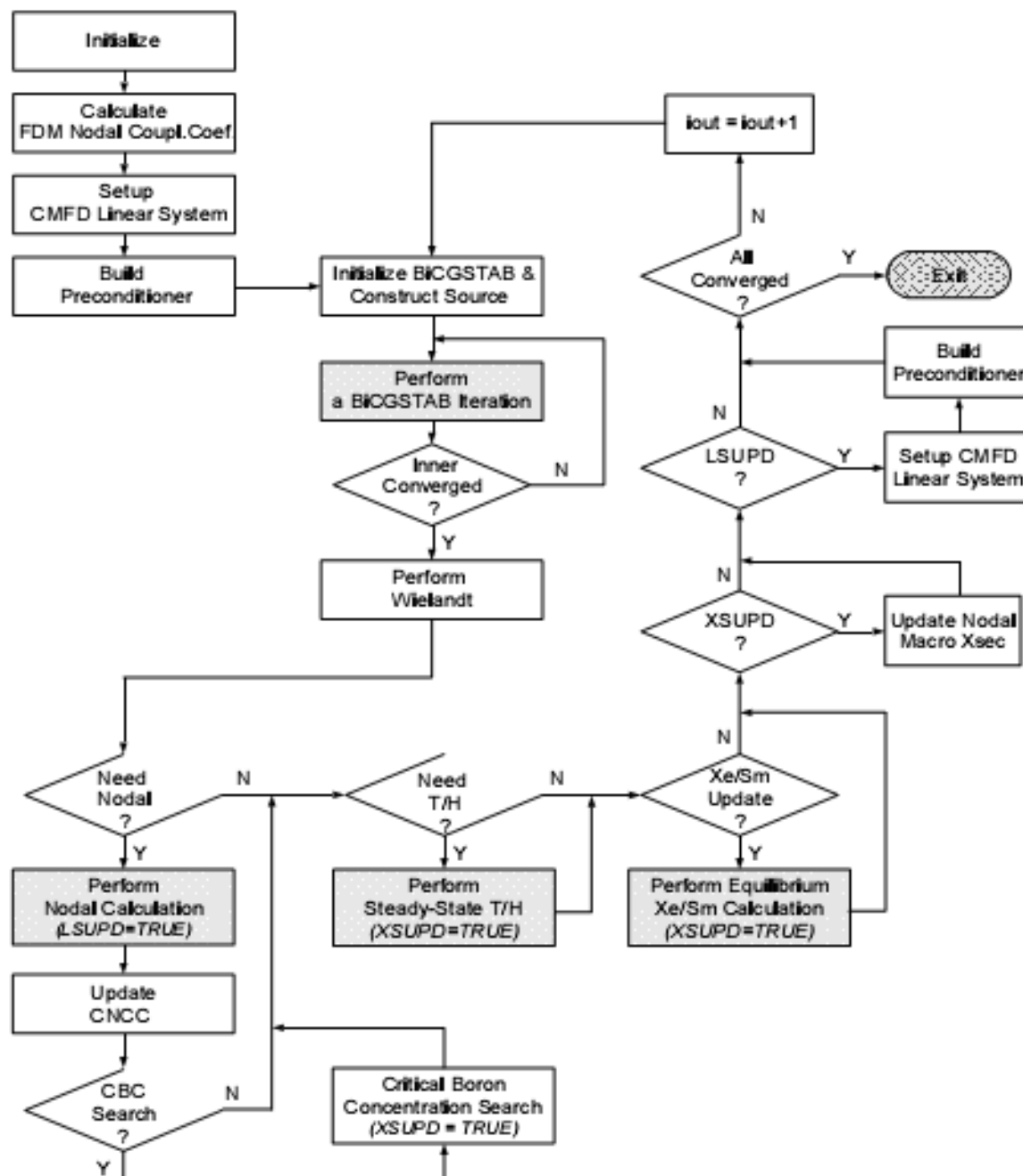


Figure 8.1: Eigenvalue Calculation Flow

# Linear Solver: Krylov Method

$$Ax = b$$

- Traditional “Stationary” Methods (e.g. Successive Over Relaxation  
SOR)
  - Rate of convergence depends on spectral radius of iteration matrix

$$x^{n+1} = Gx^n + k$$

- Preconditioned Krylov Methods
  - “Three term recurrence relation”

$$x^{n+1} = G(n)x^n + G(n-1)x^{n-1} + k$$

- Acceleration by Preconditioner

$$M^{-1}Ax = M^{-1}b$$

- PARCS uses BICGSTAB w/ BILU3D Preconditioner

# Solving the Eigenvalue problem: the Power Method

- ◆ Eigenvalues of Matrix A  $Av_i = \lambda_i v_i$

Assume:  $\lambda_1 > |\lambda_2| \geq |\lambda_3| \geq \dots \geq |\lambda_n|$   $\|v_i\|_2 = 1$  are unit eigenvectors

- ◆ Power method for finding maximum eigenvalue and its eigenvector

1. Given any initial guess of eigenvector

2. Power iteration

$$x_0 = \sum_{i=1}^n c_i v_i, \quad c_1 \neq 0$$

$$x_k = \frac{Ax_{k-1}}{\|Ax_{k-1}\|_2} = \frac{A^k x_0}{\|A^k x_0\|_2}$$

$$A^k x_0 = \sum_{i=1}^n c_i A^k v_i = \sum_{i=1}^n c_i \lambda_i^k v_i = \lambda_1^k \left( c_1 v_1 + \sum_{i=2}^n c_i \left( \frac{\lambda_i}{\lambda_1} \right)^k v_i \right)$$

$$x_k = \left( c_1 v_1 + \sum_{i=2}^n c_i \left( \frac{\lambda_i}{\lambda_1} \right)^k v_i \right) / \left\| c_1 v_1 + \sum_{i=2}^n c_i \left( \frac{\lambda_i}{\lambda_1} \right)^k v_i \right\|_2$$

$$\lim_{k \rightarrow \infty} x_k = \frac{c_1 v_1 + 0}{\|c_1 v_1 + 0\|_2} = \frac{c_1 v_1}{|c_1|}$$

$$\lambda_1 = \lim_{k \rightarrow \infty} \frac{\|Ax_k\|_2}{\|x_k\|_2}$$



# Inverse Power Iteration with Wielandt Shift in PARCS

- Neutronic steady state problem (generalized eigenvalue-eigenvector problem)

$$M\phi = \lambda F\phi \equiv \frac{1}{k_{eff}} F\phi$$

- ◆ Looking for minimum eigenvalue which is largest  $k_{eff}$
- ◆ Let  $\phi^0$  be initial guess of flux solution,  $\delta k$  is user input parameter

$$k_{eff}^0 = \langle F\tilde{\phi}^0, u \rangle$$

$$k_s^n = k_{eff}^n + \delta k$$

$$\phi^{n+1} = \left( M - \frac{1}{k_s^n} F \right)^{-1} S_f^n$$

$$S_f^n = \left( \frac{1}{k_{eff}^n} - \frac{1}{k_s^n} \right) F\phi^n = \left( \frac{\delta k}{k_{eff}^n k_s^n} \right) F\phi^n$$

$$k_{eff}^{n+1} = \left[ \left( \frac{1}{k_{eff}^n} - \frac{1}{k_s^n} \right) \frac{\langle F\phi^n, u \rangle}{\langle F\phi^{n+1}, u \rangle} + \frac{1}{k_s^n} \right]^{-1}$$

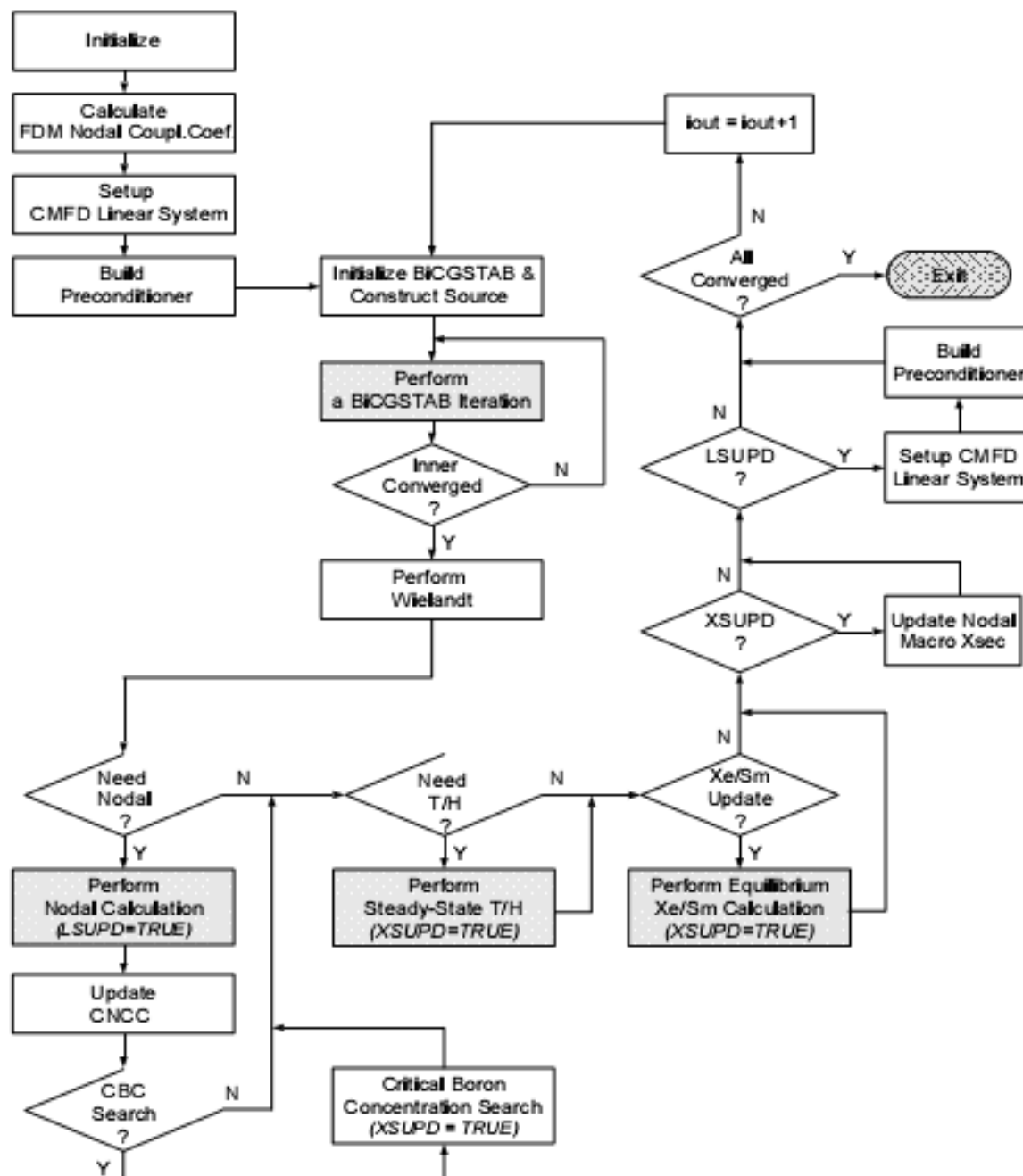


Figure 8.1: Eigenvalue Calculation Flow

# PARCS Convergence

```

=====
      Executing Case I336C5
      by downar on NUCL112BPCLAP at 17:36:25, Oct.  8, 2006...
      Allocated Memory:      0.49 MBytes
=====
00:00.04  Input Processing Completed.
00:00.04  Performing Steady-State Eigenvalue Calculation...
  Itr Nin      k-eff      Global F.S.      Local F.S.      Dom. R      PPM
-----
   1  1  0.9142296 F   9.1466E-01 F   3.2386E+00 F 10.0000      0.00
   2  3  0.9296559 F   2.5440E-01 F   3.7089E-01 F  0.2186      0.00
   3  3  0.9326269 T   4.8136E-02 F   7.9696E-02 F  0.2155      0.00
00:00.07  Nodal update...   1, NEM=      0, ANM= 288
   4  3  0.9377496 F   1.4679E-01 F   2.7124E-01 F  3.3320      0.00
   5  3  0.9373990 T   9.3391E-03 F   1.1604E-02 F  0.0679      0.00
   6  4  0.9373904 T   3.0558E-04 T   5.3557E-04 F  0.0326      0.00
00:00.09  Nodal update...   2, NEM=      0, ANM= 288
   7  3  0.9380279 T   1.7485E-02 F   3.7725E-02 F 10.0000      0.00
   8  3  0.9379567 T   1.9051E-03 F   2.4129E-03 F  0.1097      0.00
   9  4  0.9379550 T   6.2407E-05 T   1.1129E-04 T  0.0327      0.00
00:00.11  Nodal update...   3, NEM=      0, ANM= 288
  10  4  0.9381323 T   4.6583E-03 F   9.9657E-03 F 10.0000      0.00
  11  3  0.9381143 T   4.8244E-04 T   6.1868E-04 F  0.1038      0.00
  12  4  0.9381139 T   1.6327E-05 T   2.9306E-05 T  0.0338      0.00
00:00.14  Nodal update...   4, NEM=      0, ANM= 288
  13  4  0.9381586 T   1.1621E-03 F   2.5203E-03 F 10.0000      0.00
  14  3  0.9381542 T   1.1933E-04 T   1.5350E-04 T  0.1027      0.00
00:00.17  Nodal update...   5, NEM=      0, ANM= 288
  15  3  0.9381651 T   2.8123E-04 T   6.2931E-04 F  2.3569      0.00
  16  3  0.9381639 T   3.0126E-05 T   3.8955E-05 T  0.1071      0.00
00:00.17  Nodal update...   6, NEM=      0, ANM= 288
  17  3  0.9381666 T   6.8972E-05 T   1.5674E-04 T  2.2895      0.00
00:00.18  k-eff= 0.938167 , Tout=  0.00 , ppm=  0.00
Number of CMFD/Nodal/TH Updates/Inners and Sweeps:      17      6      0

Time for Init.      0.020
      CMFD      0.140
      Nodal      0.020
      T/H      0.000
      Xsec      0.000
  
```

$$\delta_k = |k_{eff}^{n+1} - k_{eff}^n|, \quad \delta_{L2} = \frac{|\Psi_{n+1} - \Psi_n|_2}{\langle \Psi_{n+1}, \Psi_n \rangle^2},$$

$$\delta_{L\infty} = \max \left| \frac{\Psi_{n+1}^n - \Psi_n^n}{\Psi_{n+1}^n} \right|, \quad \delta_{Dep} = \max \left| \frac{T_{D_n,t+1}^n - T_{D_n,t}^n}{T_{D_n,t+1}^n} \right|$$

```

CASEID I336C5                      L336 Case C5
*****
CNTL
  PIN_POWER      F
  TH_FDBK        F
      input      iteration      planar      pin      adj
      edit      table      power      T      reac
  print_opt      T      T      T      T      F
      fdbk      flux      planar
      rho      precurs      flux      Xe      T/H
  print_opt      F      T      T      F      F
*****
PARAM
! Basic Iteration Control Parameters
  n_iters      10 500                      !nirmax, noutmax

! Convergence Criteria
  conv_ss      5.e-3 5.e-4 5.e-4 0.1      !epseig,epsl2,epsl1nf,epstf!

! nodal_kern      nemmg
!   eps_arm      1.0E-15
!   eps_arm      5.0
! nodal_kern      fmfcd
! nodal_kern      fdm
  
```

# PARCS Neutronics Methods: Solution Kernels

Geometry Type	Kernel Name	Solution Method	Energy Treatment	Angle Treatment
<b>Cartesian 3D</b>	CMFD	FD	2G	Diffusion
	ANM	nodal	2G	Diffusion
	FMFD	FD	MG	<b>SP3</b>
	NEMMG	nodal	MG	<b>SP<sub>3</sub></b>
<b>Hexagonal 3D</b>	CMFD	FD	2G	Diffusion
	TPEN	nodal	MG	Diffusion
<b>Cylindrical 3D</b>	CMFD	FD	2G	Diffusion
	FMFD	FD	MG	Diffusion/ SP <sub>3</sub>

CMFD = Coarse Mesh Finite Difference

ANM = Advanced Nodal Method

FMFD = Fine Mesh Finite Difference

NEM = Nodal Expansion Method

MG = Multigroup

# Time-dependent SP<sub>3</sub> Equations

- Governing Equations

$$\begin{aligned}
 \frac{1}{v} \frac{\partial \phi_{0g}}{\partial t} + \nabla \cdot \phi_{1g} + \Sigma_{rg} \phi_{0g} &= s_{0g} \\
 \frac{1}{v} \frac{\partial \phi_{1g}}{\partial t} + \frac{2}{3} \nabla \phi_{2g} + \frac{1}{3} \nabla \phi_{0g} + \Sigma_{trg} \phi_{1g} &= 0 \\
 \frac{1}{v} \frac{\partial \phi_{2g}}{\partial t} + \frac{3}{5} \nabla \cdot \phi_{3g} + \frac{2}{5} \nabla \cdot \phi_{1g} + \Sigma_{tg} \phi_{2g} &= 0 \\
 \frac{1}{v} \frac{\partial \phi_{3g}}{\partial t} + \frac{3}{7} \nabla \phi_{2g} + \Sigma_{tg} \phi_{3g} &= 0
 \end{aligned}
 \quad \left\{ \begin{array}{l} D_1^* \equiv \frac{1}{3\Sigma_{tr}^*} \quad \Sigma_\alpha^* = \Sigma_\alpha + \frac{1}{v\Delta t} \\ D_3^* \equiv \frac{3}{7\Sigma_t^*} \quad q_i^n = \frac{1}{v} \frac{\phi_i^n}{\Delta t} \end{array} \right.$$

- Second-order Differential Equations

$$\begin{bmatrix} -D_1^* \nabla^2 + \Sigma_r^* & -2D_1^* \nabla^2 \\ -\frac{2}{5} D_1^* \nabla^2 & -\left(\frac{3}{5} D_3^* + \frac{4}{5} D_1^*\right) \nabla^2 + \Sigma_t^* \end{bmatrix} \begin{bmatrix} \phi_0^{n+1} \\ \phi_2^{n+1} \end{bmatrix} = \begin{bmatrix} q_0^n - 3D_1^* \nabla \cdot q_1^n + S_{0t}^{n+1} \\ q_2^n - \frac{6}{5} D_1^* \nabla \cdot q_1^n - \frac{7}{5} D_3^* \nabla \cdot q_3^n \end{bmatrix}$$

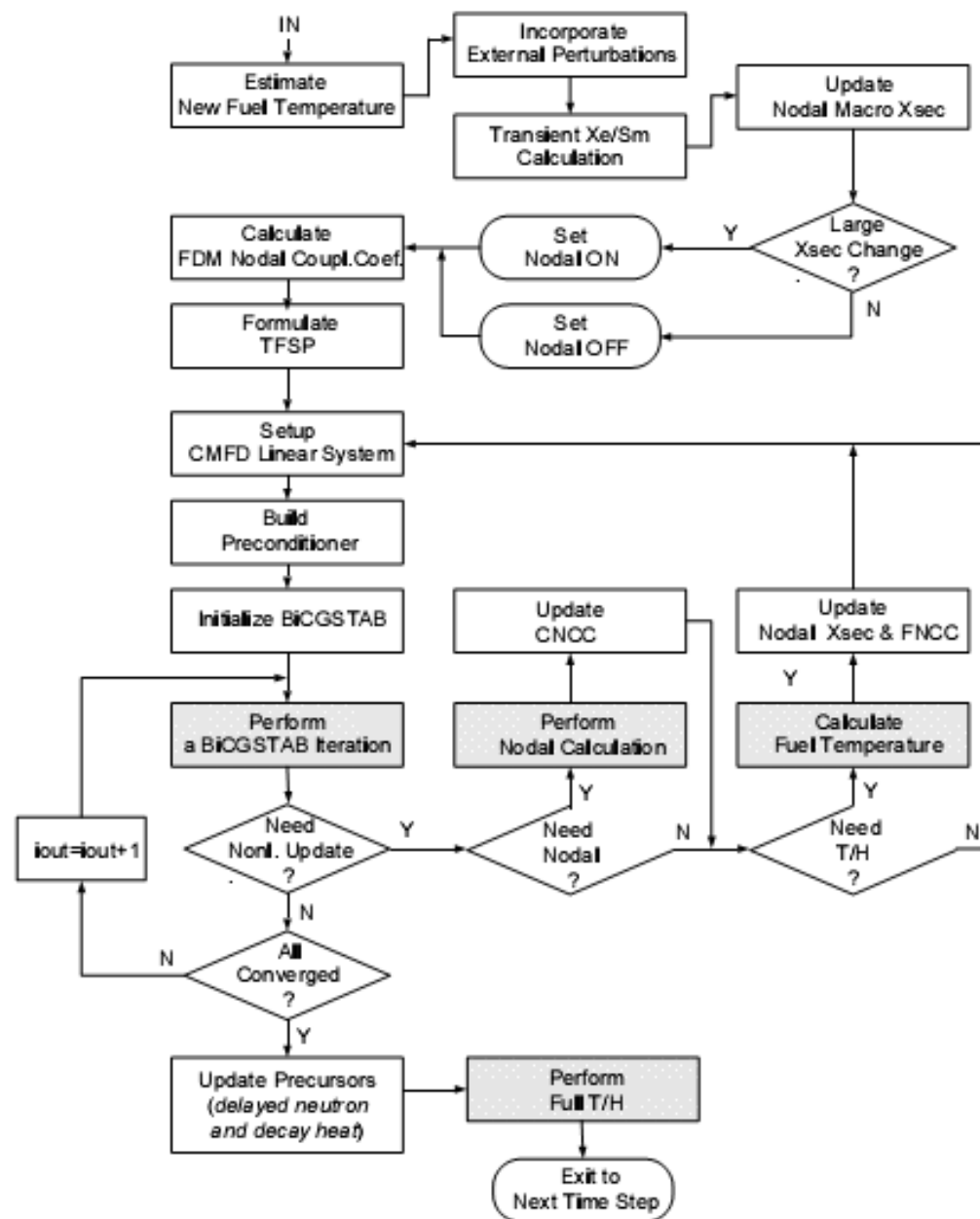
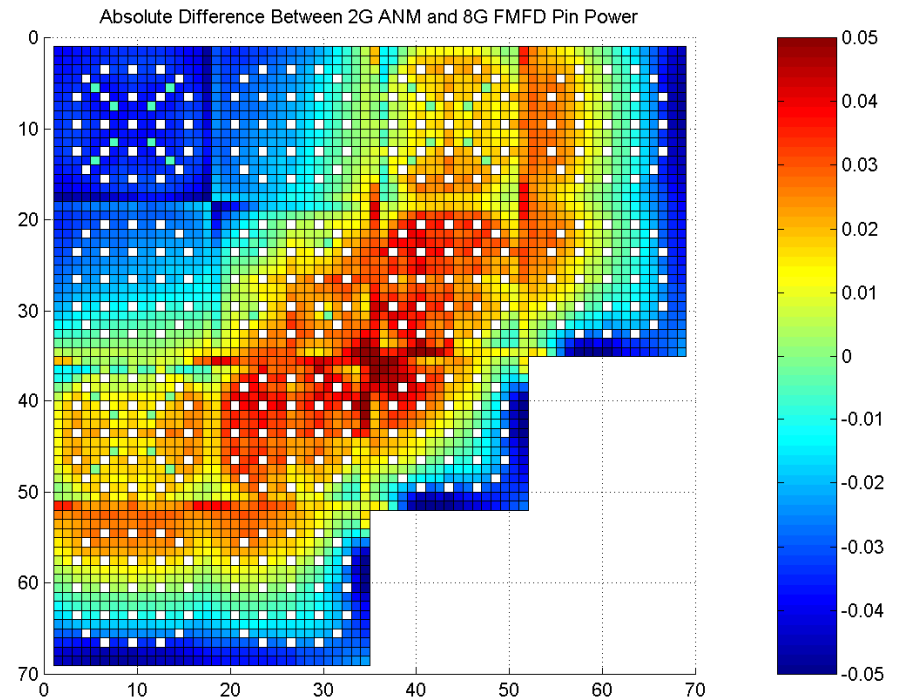
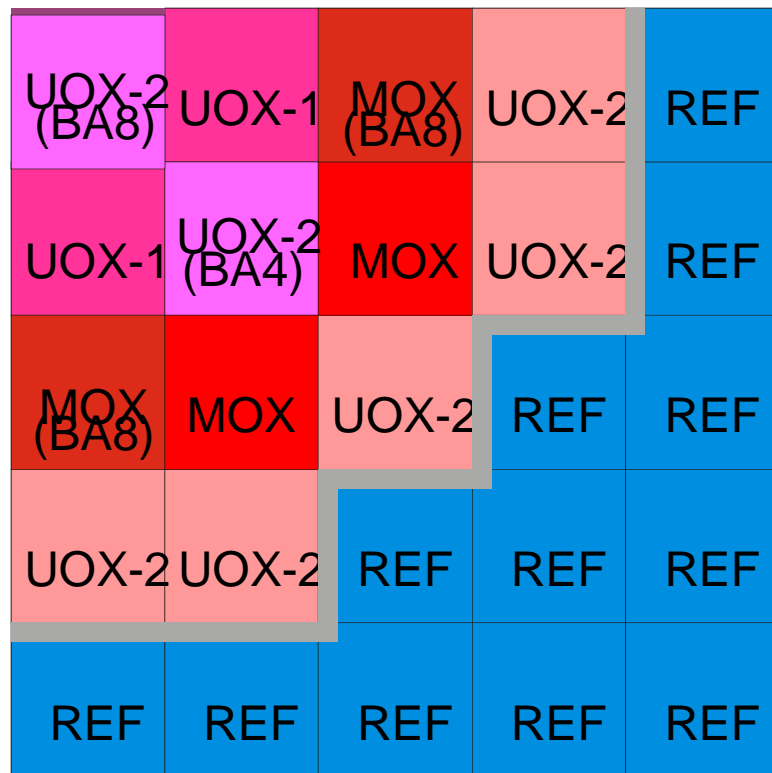


Figure 8.3: Transient Calculation Algorithm

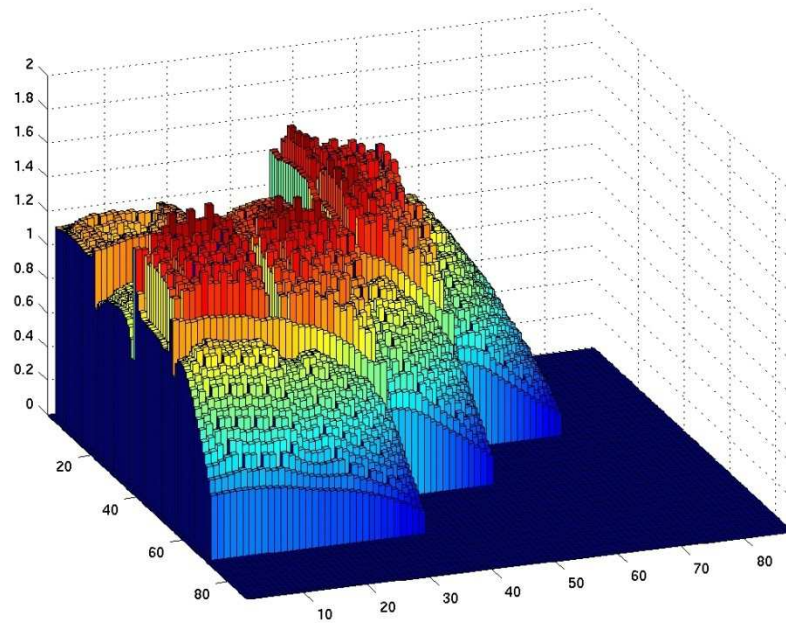
# MOX Core Loading



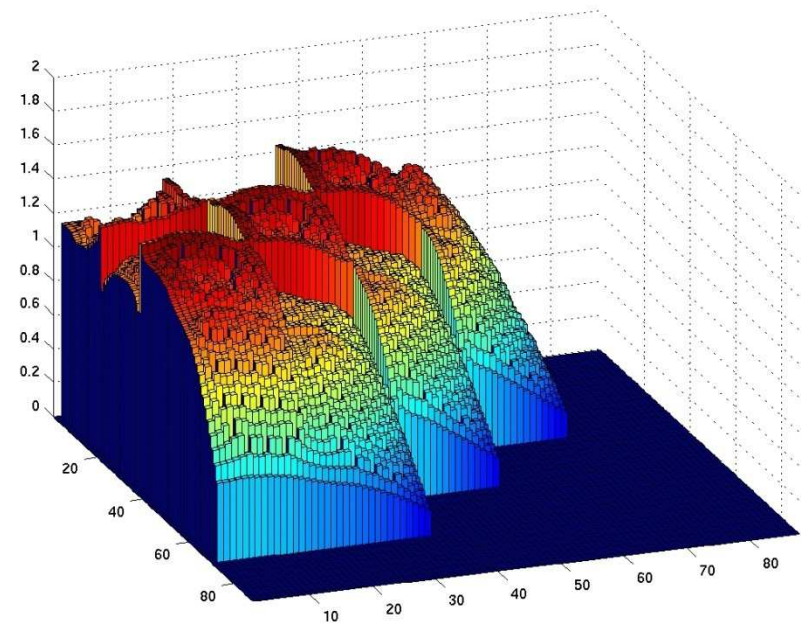
\* Diff. =  $(P_{2G\ Nodal} - P_{Reference})$

# Reference Results: Steady-State Power Distributions

MOX/UOX

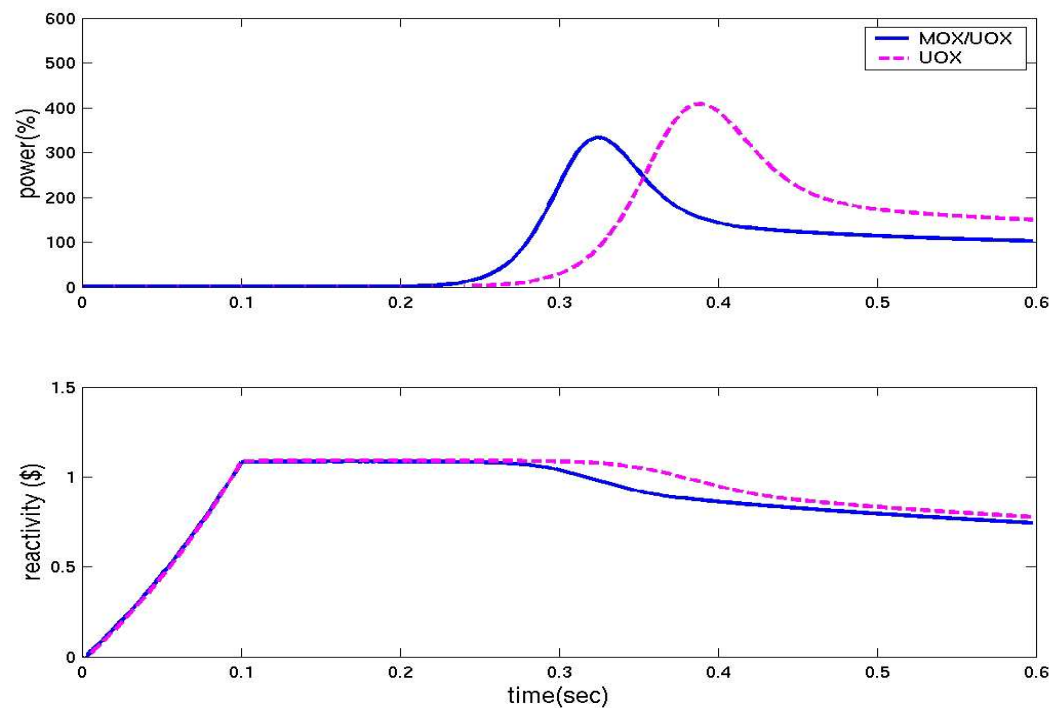


UOX





# Core Power and Reactivity (MOX/UOX and UOX Cores)



” Analysis of Results for the OECD/NEA and U.S. NRC PWR MOX/UO<sub>2</sub> Core Transient Benchmark, T. Kozłowski C. A. Cotton T. J. Downar, Reactor Physics ANS Topical Meeting, PHYSOR-04, April, 2004, Chicago, IL

# Some Recent References

- Methods:
  - Multigroup SP3 Methods for Neutronics Analysis of MOX Fueled Cores," C. Lee and T. Downar, *Nuclear Science and Engineering*, Vol. 146, No.2, February, 2004.
  - "Convergence Analysis of the Nonlinear Coarse Mesh Finite Difference Method for One-dimensional Fixed Source Neutron Diffusion Problem," Deokjung Lee, Thomas J. Downar, and Yonghee Kim, *Nucl. Sci. Eng.*, Vol. 147, No.2, June, 2004.
- Applications
  - "Consistent Comparison of the Codes RELAP5/PARCS and TRAC-M/PARCS for the **OECD MSLB Coupled Code Benchmark**," T. Kozlowski, R. Miller, T. Downar, H. Joo, D. Barber *Nuclear Technology*, Vol. 146, No. 1, April, 2004.
  - "Analysis of the **OECD/NRC Peach Bottom Turbine Trip Transient Benchmark** with the Coupled Neutronics and Thermal-hydraulics Code TRAC-M/PARCS," Deokjung Lee, Thomas J. Downar, Anthony Ulses, Bedirhan Akdeniz, Kostadin N. Ivanov, *Nucl. Sci. Eng.*, Vol. 148, No.2, October, 2004.

# Code Assessment

- Stand-alone Neutronics Tests
  - NEACRP-L336 Pin Benchmark
  - **NEACRP PWR Rod Ejection/Withdrawal Benchmarks**
  - VVER1000 Rod Ejection Benchmark
  - VENUS-2 Critical Benchmark
  - OECD MOX Core Transient Benchmark
- Coupled Code Tests (TRACE/RELAP5/PARCS)
  - OECD PWR-MSLB Benchmark
  - OECD BWR PBTT BWR: Peach Bottom
  - BWR Ringhalls Stability
  - BWR: Peach Bottom Cycle 1 and 2 Depletion Benchmark

# TR Cartesian: NEACRP L335

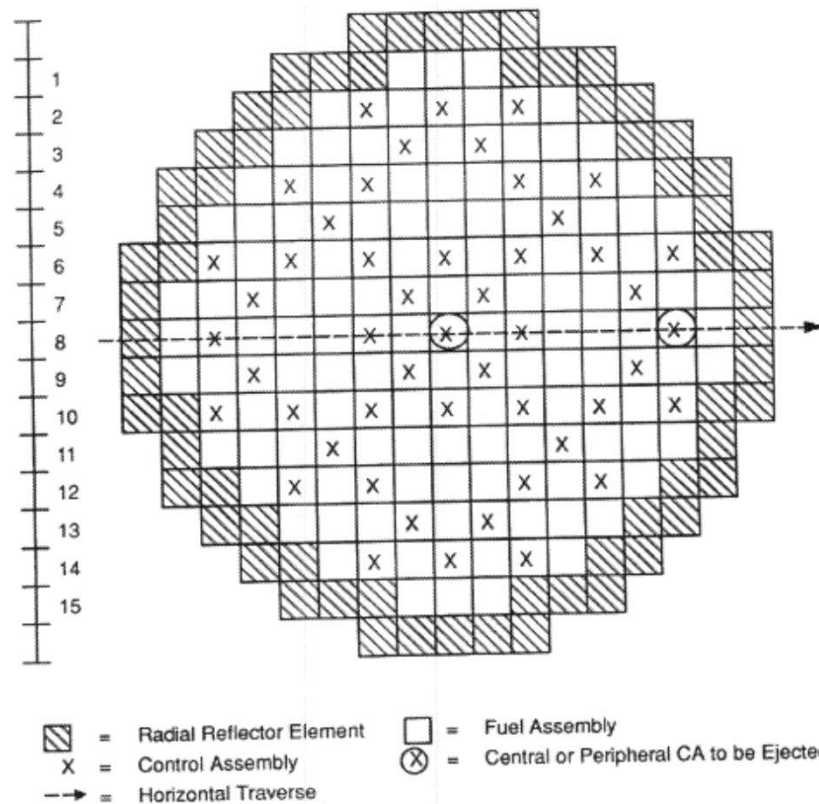
## PWR rod ejection

Table 2.1 PWR. Participants of the Benchmark Problems A1-C2

<u>Part.No.</u>	<u>Organization</u>	<u>Country</u>	<u>Code</u>	<u>A1</u>	<u>A2</u>	<u>B1</u>	<u>B2</u>	<u>C1</u>	<u>C2</u>
1	TRACTEBEL	Belgium	OKAPI (s) (a)	X	X	X	X	X	X
2	VTT	Finland	BOREAS, TRAB	X	X	X	X	X	X
4	FRAMATOME	France	CESAR	X	X	X	X	X	X
5	EDF	France	COCCINELLE				X	X	
6	SIEMENS	Germany	PANBOX	X	X	X	X	X	X
7	GRS	Germany	QUABOX-CUBBOX	X	X	X	X	X	X
10	ENEL	Italy	QUANDRY-EN			X		X	
13	JAERI	Japan	REFLA/TRAC	X					
14	JAERI	Japan	THYDE-NEU				X		
19	ECN	Netherl.	PRORIA	X	X			X	X
20	NV KEMA	Netherl.	LWRSIM	X	X	X	X	X	X
21	ETS	Spain	SIMTRAN	X	X	X	X	X	X
23	INER	Taiwan	ARROTTA					X	X
24	NE Ber Lab	UK	PANTHER	X	X	X	X	X	X
<u>total number</u>		<u>14</u>		<u>10</u>	<u>9</u>	<u>9</u>	<u>9</u>	<u>12</u>	<u>11</u>

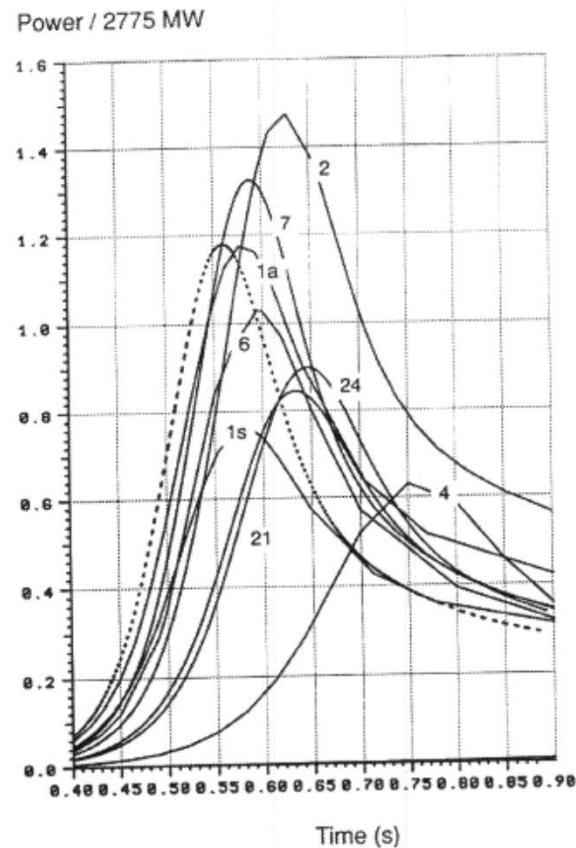
# TR Cartesian: NEACRP L335

## PWR rod ejection



# TR Cartesian: NEACRP L335

## PWR rod ejection



PWR: Key to Figures 2.1-7.6

---	REFERENCE
1 s	OKAPI (s)
1 a	OKAPI (a)
2	TRAB
4	CESAR
5	COCCINELLE
6	PANBOX
7	QUABOX-CUBBOX
10	QUANDRY-EN
13	REFLA/TRAC
14	THYDE-NEU
19	PRORIA
20	LWRSIM
21	SIMTRAN
23	ARROTTA
24	PANTHER

# Important items to remember about PARCS input

- Input was design to use as many default values as possible
  - Very short inputs are possible for 2G nodal PWR problems
- Input restrictions
  - Block names start in 1<sup>st</sup> column (CASEID, PARAM, CNTL, GEOM, TH, TRAN, PFF, ONEDK, PLOT)
  - Card names start in 2<sup>nd</sup> or later column
  - Card input can be in external files through “file” card
  - In general, block order is arbitrary (exception is FMFD, there FMFD block have to be before GEOM)
  - In general, cards order within a block can be in arbitrary order
  - BANG (!) is a comment
  - SLASH (/) is end of case
  - DOT (.) is end of input
  - Input is case insensitive
  - Multiple data on single card can be separated by space or TAB
  - Fortran style free format STAR (\*) can be used for repeating data, 8\*1.2 means repeat 1.2 eight times
  - Any empty lines are ignored

# TR Cartesian: NEACRP L335

## PWR rod ejection

Block 1:

CASEID A1

Neacrp Case A1



# TR Cartesian: NEACRP L335

## PWR rod ejection

Block 2:

CNTL

```
core_power 0.0001 0.0 !in %
bank_pos 0.0 0. 0. 228. 0. 0. 0. 228.
ppm 561.26
transient T
! search ppm
! input iteration planar adj
! edit table power pin reac
print_opt F F F F T
! fdbk flux planar
! rho precurs flux Xe T/H
print_opt F F F F F
```

# TR Cartesian: NEACRP L335

## PWR rod ejection

Block 3:

```
PARAM
! no parameters are specified, all defaults
!      n_iters 100 10
```

# TR Cartesian: NEACRP L335

## PWR rod ejection

Block 4:

XSEC

file ./xsec/XSEC\_NEACRP

# TR Cartesian: NEACRP L335

## PWR rod ejection

Block 4 (external file):

```
ref_cond 1200.2 306.6 0.7125 618.3 !ppm, Tm in C, rho in gm/cc, Tf in C
comp_num 4 !fuel 1
!-----
base_macro 2.221170e-01 8.717740e-03 4.982770e-03 6.111896e-14 1.824980e-02
            8.031400e-01 6.525500e-02 8.390260e-02 1.101520e-12
dxs_dppm 3.478090e-08 1.285050e-07 -1.120990e-09 -1.761878e-20 -1.085900e-07
          -9.765100e-06 7.088070e-06 -2.430450e-06 -3.190845e-17
dxs_dtm -2.033100e-06 2.121910e-07 1.247090e-07 1.430354e-18 8.096760e-07
          -1.086740e-04 -3.155970e-05 -4.164390e-05 -5.467221e-16
dxs_ddm 1.356650e-01 1.551850e-03 9.206940e-04 1.023919e-14 2.931950e-02
          9.926280e-01 2.526620e-02 2.477460e-02 3.252554e-13
dxs_dtf -3.091970e-05 3.497090e-05 6.401340e-07 7.154124e-18 -2.755360e-05
          -1.372920e-04 -3.718060e-05 -5.630370e-05 -7.391879e-16
cdf 1.0069 0.9307 1.0034 0.9646 1.1040 1.4493 1.0096 1.1580

delcr_comp 1 1 -5 7 -11 !compostions that this set applies
!-----
delcr_base 3.732200e-03 2.477700e-03 -1.027860e-04 -1.214480e-15 -3.192530e-03
            -2.199260e-02 2.558750e-02 -2.823190e-03 -3.702378e-14

!Delayed Neutron Precurosor Data
!-----
dnp_ngrp 6
kin_comp 1 1 -11 !Compostions that this set applies
dnp_lambda 0.0128 0.0318 0.119 0.3181 1.4027 3.9286 !decay constants
dnp_beta 0.0002584 0.00152 0.0013908 0.0030704 0.001102 0.0002584 !beta
neut_velo 2.8E7 4.4E5 ! Neutron Velocities (cm/sec)
```

# TR Cartesian: NEACRP L335

## PWR rod ejection

Block 5:

GEOM

file ./xsec/GEOM\_QC

# TR Cartesian: NEACRP L335 PWR rod ejection

Block 5 (external file):

```
geo_dim      9 9 18          !nasyx,nasyy,nz
rad_conf
2 2 2 2 2 2 2 2 1
2 2 2 2 2 2 2 2 1
2 2 2 2 2 2 2 1 1
2 2 2 2 2 2 2 1 0
2 2 2 2 2 2 1 1 0
2 2 2 2 2 1 1 0 0
2 2 2 2 1 1 0 0 0
2 2 1 1 1 0 0 0 0
1 1 1 0 0 0 0 0 0
grid_x       10.803      8*21.606
neutmesh_x 1           8*2
grid_y       10.803      8*21.606
neutmesh_y 1           8*2
grid_z       30.   7.7   11.0  15.0  10*30.0  2*12.8  8.0  30.
boun_cond    0 1 0 1 1 1          !ibcw,ibce,ibcn,ibcs,ibcb,ibct
Planar_Reg 1
1 1 1 1 1 1 1 1 2
1 1 1 1 1 1 1 1 2
1 1 1 1 1 1 1 3 2
1 1 1 1 1 1 1 2
1 1 1 1 1 1 3 2
1 1 1 1 1 3 2
1 1 1 1 3 2
1 1 3 2 2
2 2 2
```

# TR Cartesian: NEACRP L335

## PWR rod ejection

Block 5 (external file):

Planar\_Reg 3

```
4 9 4 9 4 7 4 6 2
9 4 8 4 8 4 11 6 2
4 8 4 8 4 8 6 3 2
9 4 8 4 8 10 6 2
4 8 4 8 4 6 3 2
7 4 8 10 6 3 2
4 11 6 6 3 2
6 6 3 2 2
2 2 2
```

PR\_Assign 1 2 15\*3 1

cr\_axinfo 37.7 1.5942237 !fully inserted position and step size

bank\_conf

```
1 0 2 0 0 0 3 0 0
0 4 0 0 0 6 0 0 0
2 0 5 0 6 0 6 0 0
0 0 0 4 0 0 0 0
0 0 6 0 7 0 0 0
0 6 0 0 0 0 0
3 0 6 0 0 0
0 0 0 0 0
0 0 0
```

# TR Cartesian: NEACRP L335

## PWR rod ejection

Block 6:

TH

file ./xsec/TH\_QC



# TR Cartesian: NEACRP L335

## PWR rod ejection

Block 6 (external file):

```
n_pingt      264 25                                !npin,ngt
  fa_powpit   17.67516    21.606                    !assembly power(Mw) and pitch(cm)
  pin_dim     4.1195 4.7585 0.571 6.1295 !pin radii, rs,rw,tw, and rgt in mm
  flow_cond   286.0 82.12102                !tin,cmfrfa(Kg/sec)
  gamma_frac  0.019                        !direc heating fraction
  hgap        10000.                        !hgap(w/M^2-C)
  n_ring      10                          !number of meshes in pellet
  thmesh_x    1    8*2                     !Number of T/H Nodes per FA in X-dir
  thmesh_y    1    8*2                     !Number of T/H Nodes per FA in y-dir
  thmesh_z    1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 !junctions
```

# TR Cartesian: NEACRP L335

## PWR rod ejection

Block 7:

```
TRAN
      time_step      5.00 0.01 1.0 10.0 !tend,delt0,tswitch,texpand
      move_bank      1 0.0 0.0 0.1 228.0
      conv_tr        0.0001 !eps_r2
!      sum_step      1.0 10 5.0 2
!
!
!      rho           % power      peaking      temp
!      plot_cntl     T -0.3 1.2    0. 130.     1. 7.     280. 560.
.
```

# PARCS GUI

