

# SPATIOTEMPORAL MODELS

Prof. Alexander Huth

2.25.2020

# LAST TIME

- \* Analytic solutions to L2-regularized regression problems:
  - \* Ridge regression
  - \* Tikhonov regression

# TODAY

- \* Spatiotemporal models
  - \* Space-time separable
  - \* Space-time inseparable
- \* Capturing real dynamics vs. output filtering

# SPATIOTEMPORAL MODEL

- \* We often think of responses as instantaneous & time-invariant (i.e. like a feedforward CNN)
- \* Real neural systems *always* function across time
- \* i.e. neural responses are not just a function of the current stimulus, but also of previous stimuli

# SPATIOTEMPORAL MODEL

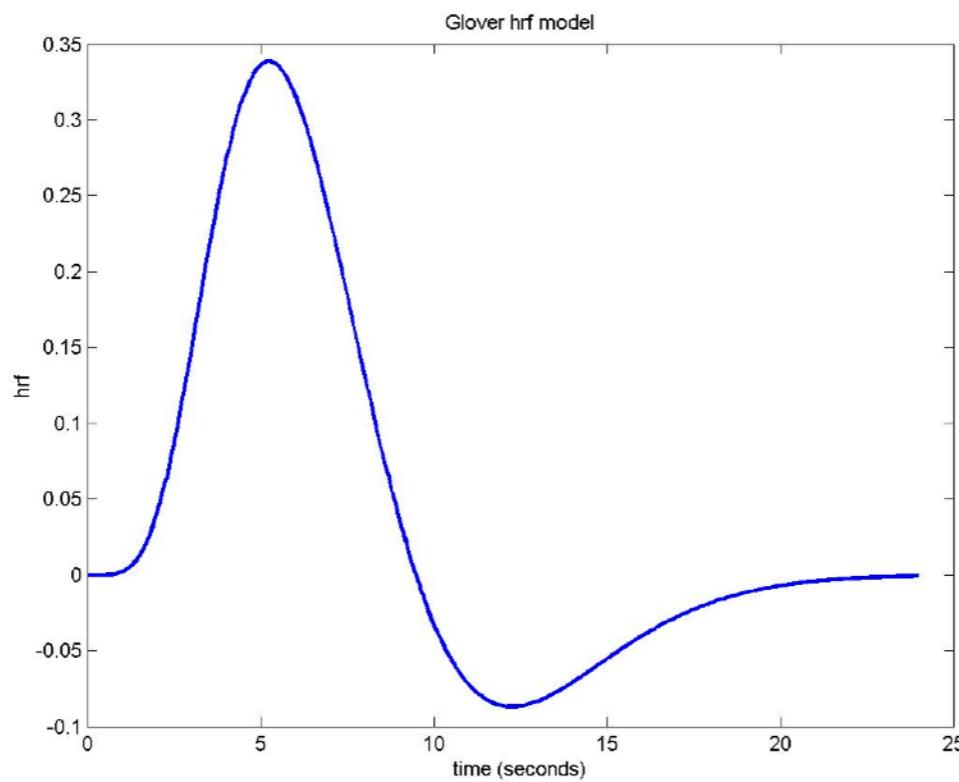
- \* Temporal dependence can be “real” /  
*computationally useful*
  - \* e.g. change detection
  - \* e.g. computing temporal derivative  
(chemotaxis/thermotaxis)

# SPATIOTEMPORAL MODEL

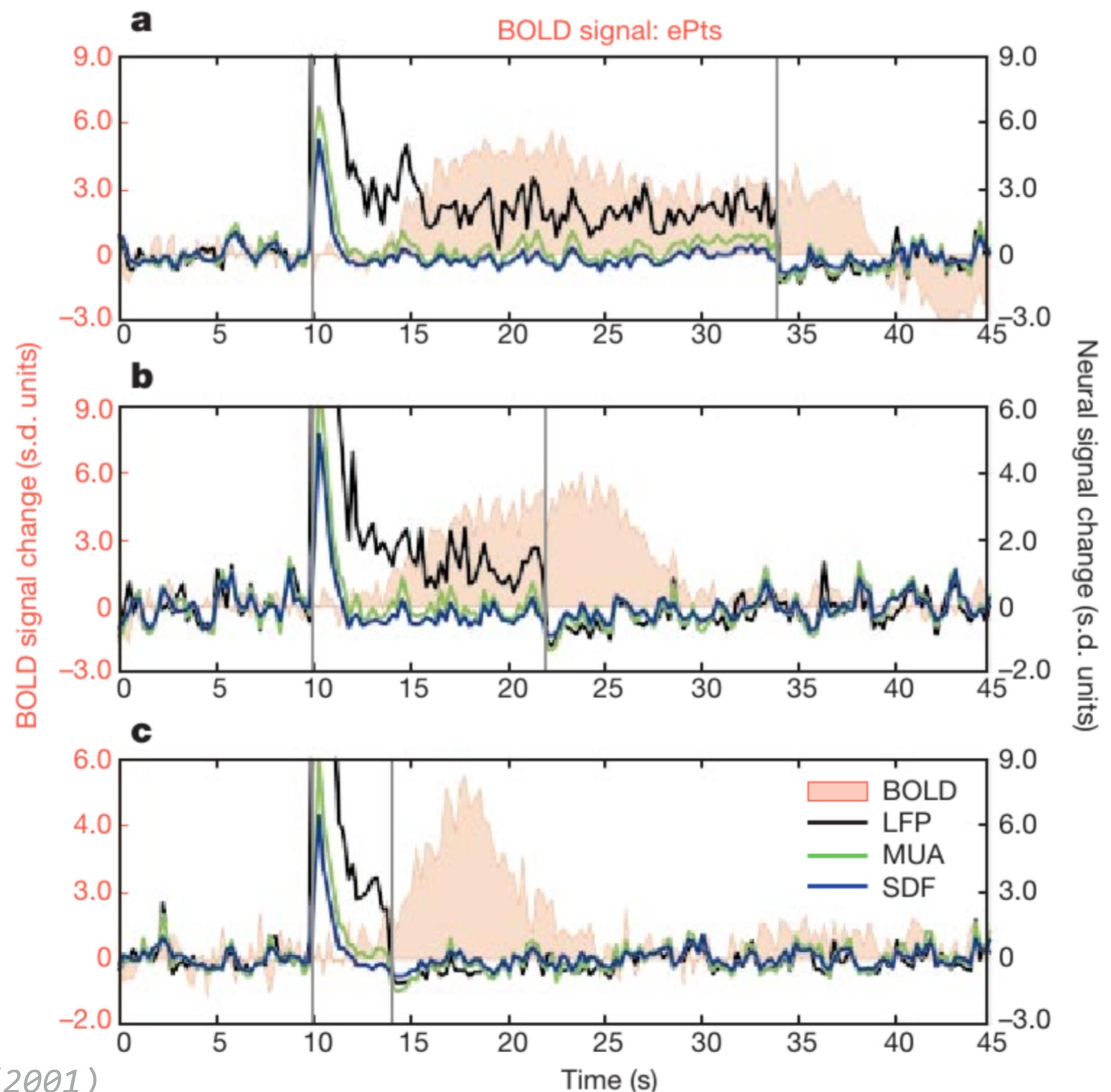
- \* Temporal dependence can also be “artifactual” / *imposed by the measurement system*
  - \* e.g. the hemodynamic response in BOLD fMRI
  - \* e.g. fluorescence decay in GCaMP-based calcium imaging

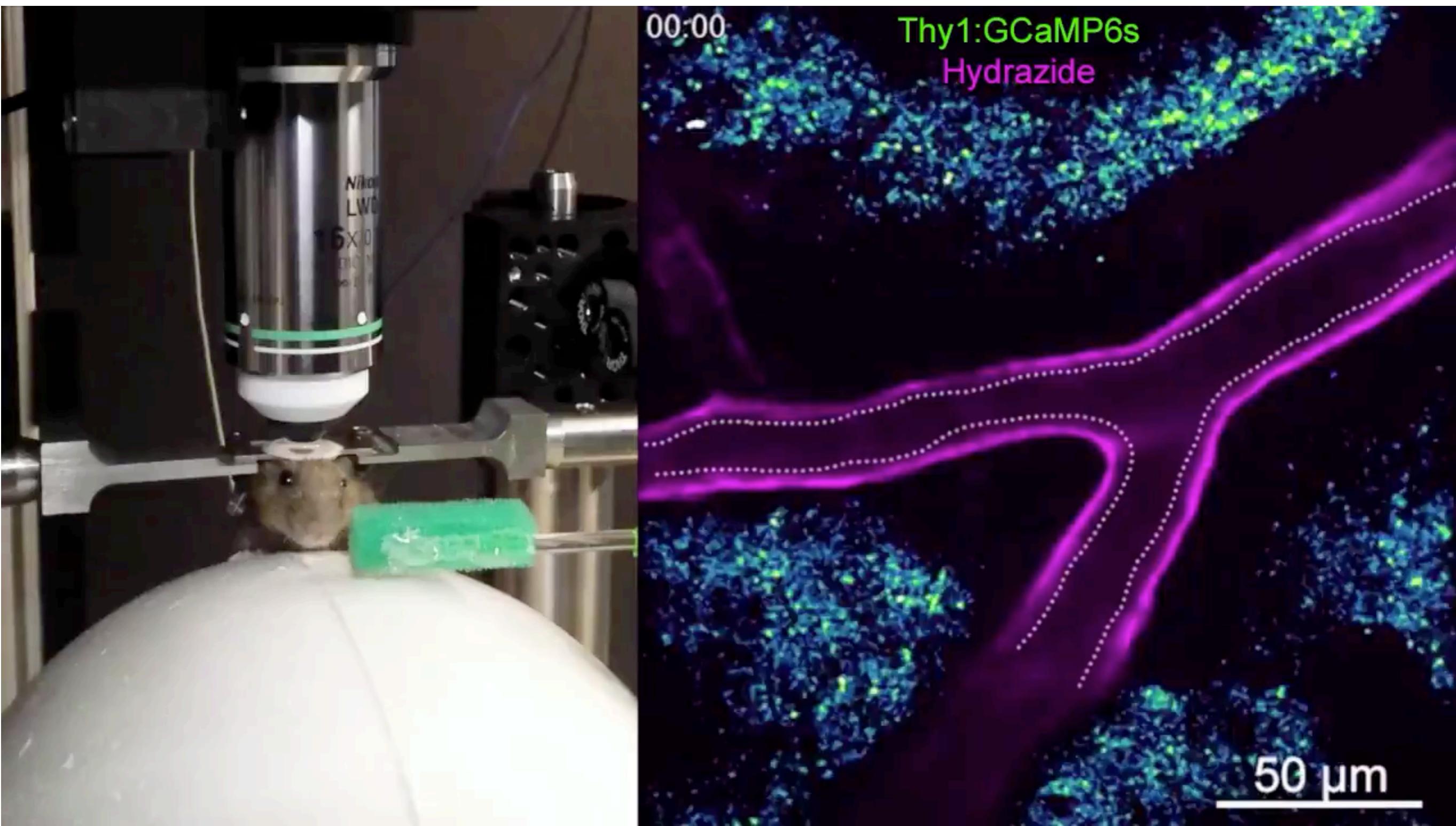
# BOLD & HRF

- \* BOLD = blood-oxygen level dependent
- \* HRF = hemodynamic response function



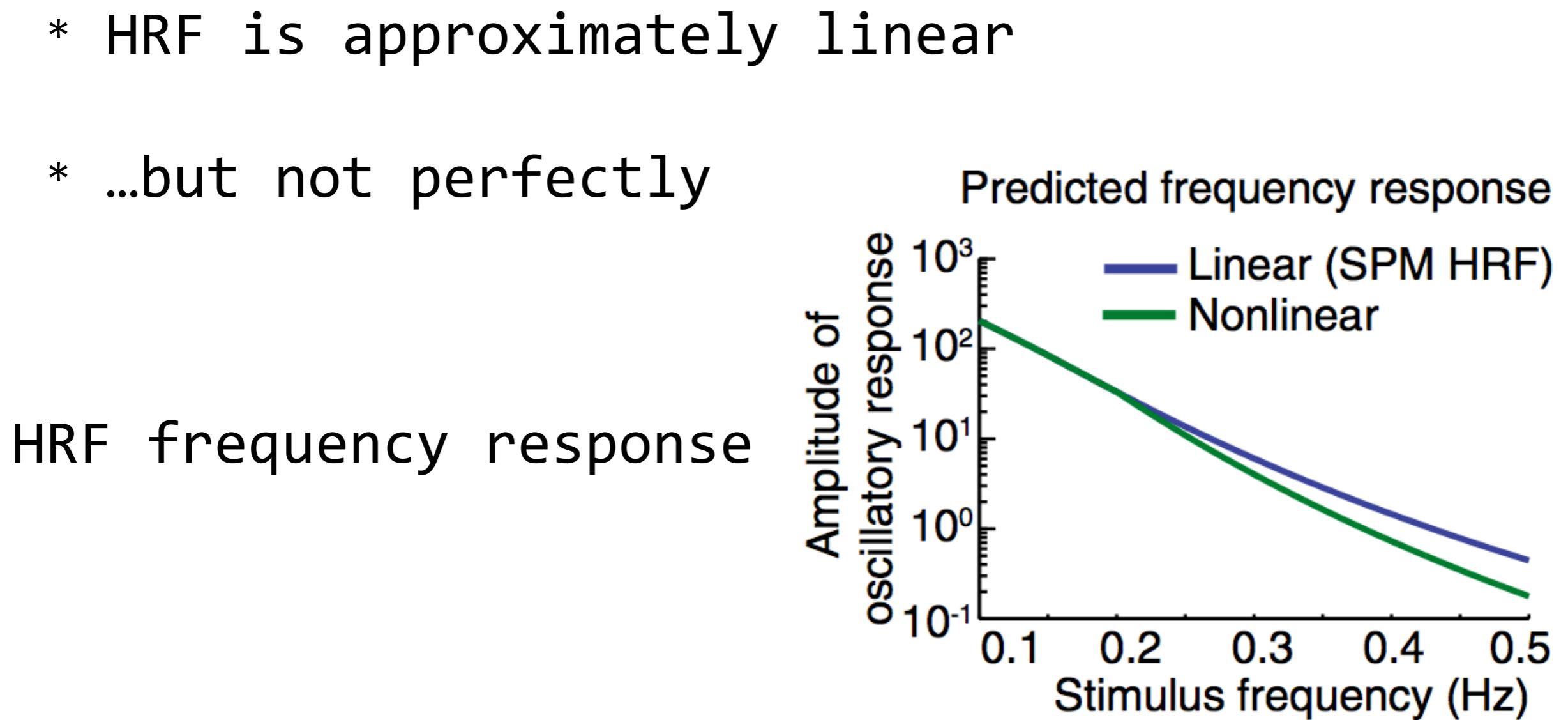
typical model HRF





[https://twitter.com/Dr\\_Alex\\_Crimi/status/1230633683675222016](https://twitter.com/Dr_Alex_Crimi/status/1230633683675222016)

# BOLD & HRF



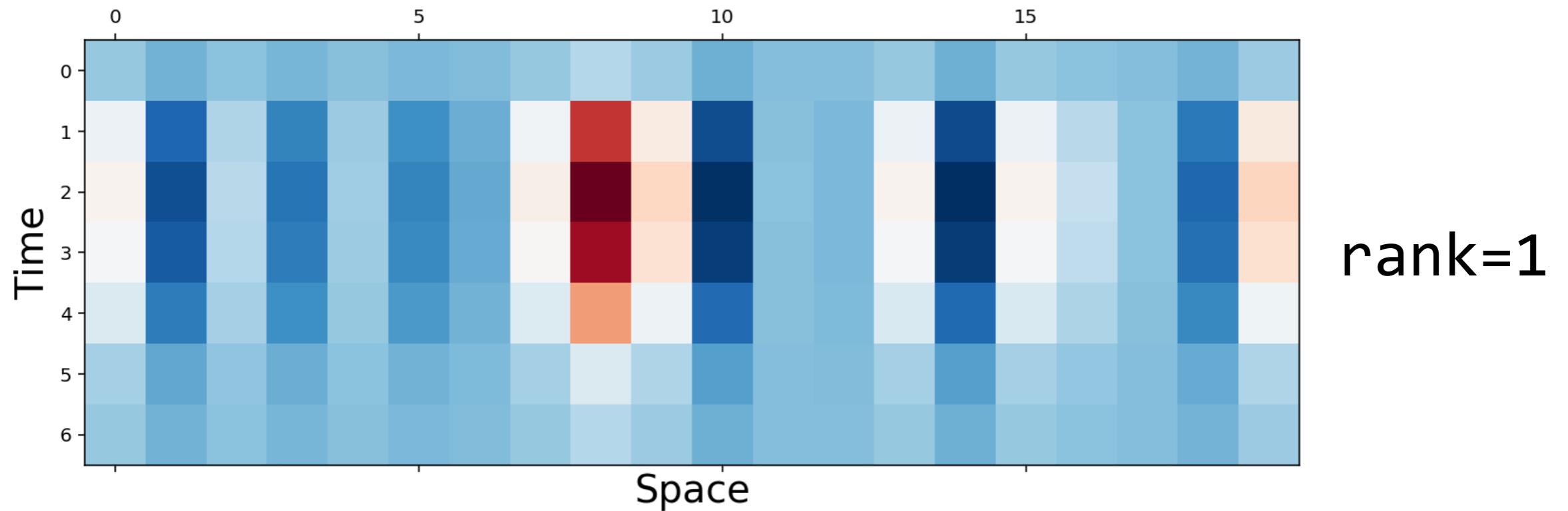
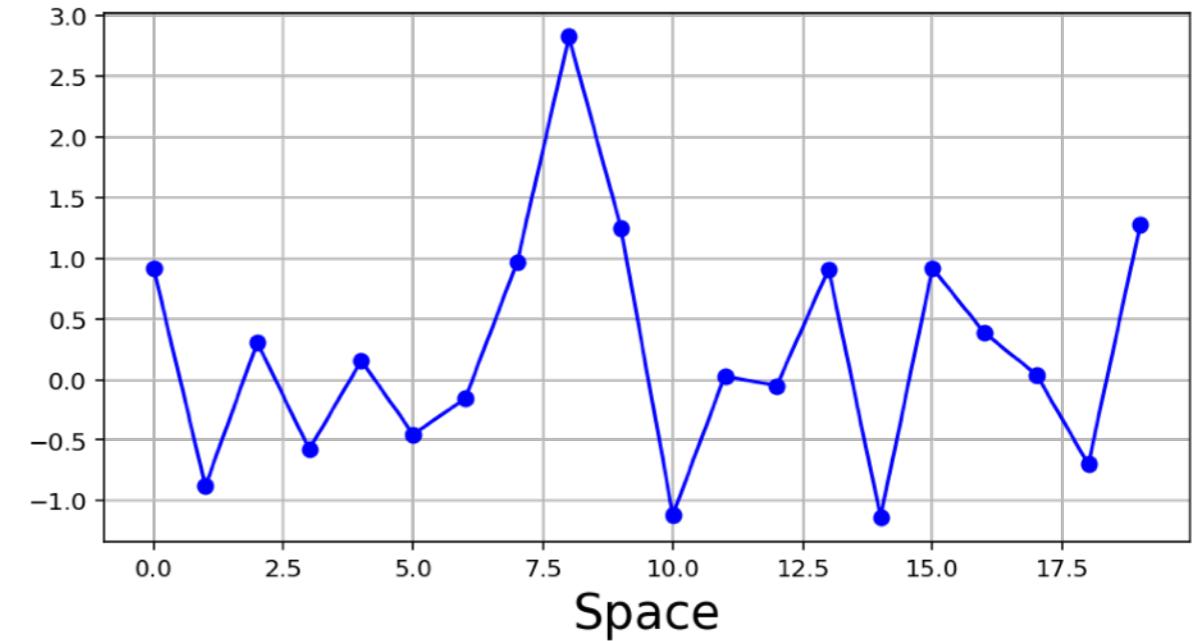
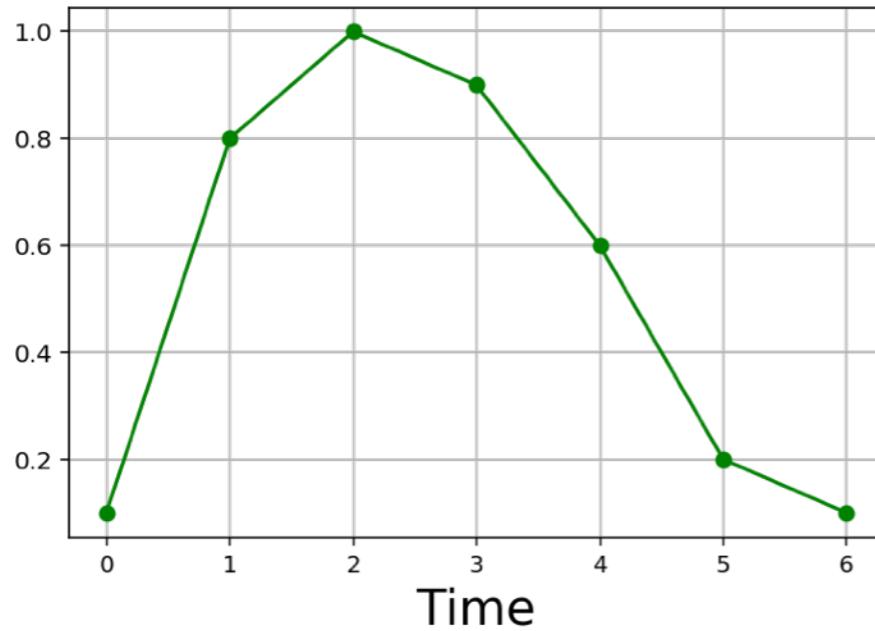
# SPATIOTEMPORAL MODEL

- \* HRF needs to be accounted for in model
- \* Three approaches:
  - \* assume HRF  
  - \* fit **space-time separable** model
  - \* fit **space-time inseparable** model

# SPACE-TIME SEPARABLE

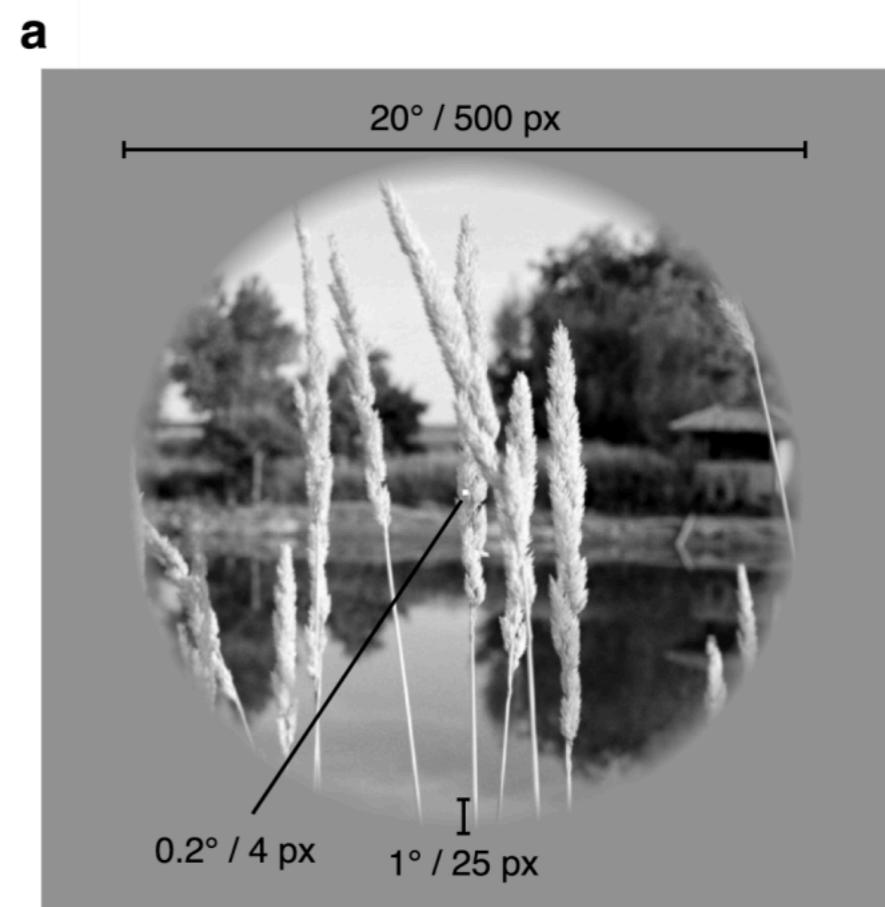
- \* Model is outer product of one spatial kernel & one temporal kernel
- \* Fit using e.g. generalized least squares (GLS)
  - \* Each model (i.e. each voxel) must be fit separately

# SPACE - TIME SEPARABLE



# SPACE-TIME SEPARABLE EXAMPLE

- \* Record BOLD signal using fMRI from visual cortex
- \* Flash images in random order w/ ~4s spacing



Kay, Naselaris, Prenger, & Gallant (2008)

Kay, David, Prenger, Hansen, & Gallant (2007)

# SPACE-TIME SEPARABLE EXAMPLE

- \* Build 1st stage model: what is response to each image in each voxel?

$$y = (X * k)h + \epsilon$$

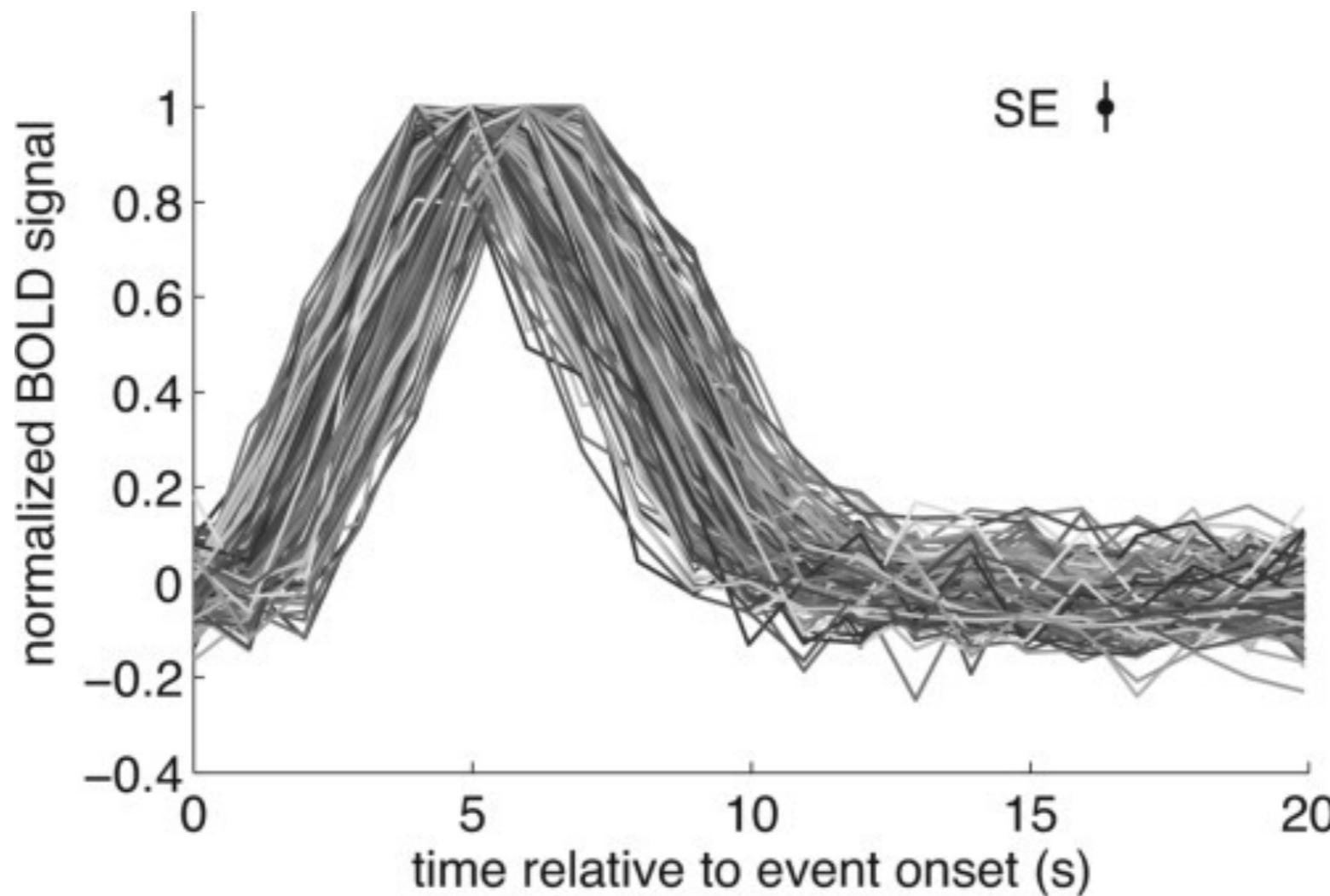
design matrix      |      response to each image  
                          |  
                          kernel

*Kay, Naselaris, Prenger, & Gallant (2008)*

*Kay, David, Prenger, Hansen, & Gallant (2007)*

# SPACE-TIME SEPARABLE EXAMPLE

$k$  for several images & voxels



Kay, Naselaris, Prenger, & Gallant (2008)

Kay, David, Prenger, Hansen, & Gallant (2007)

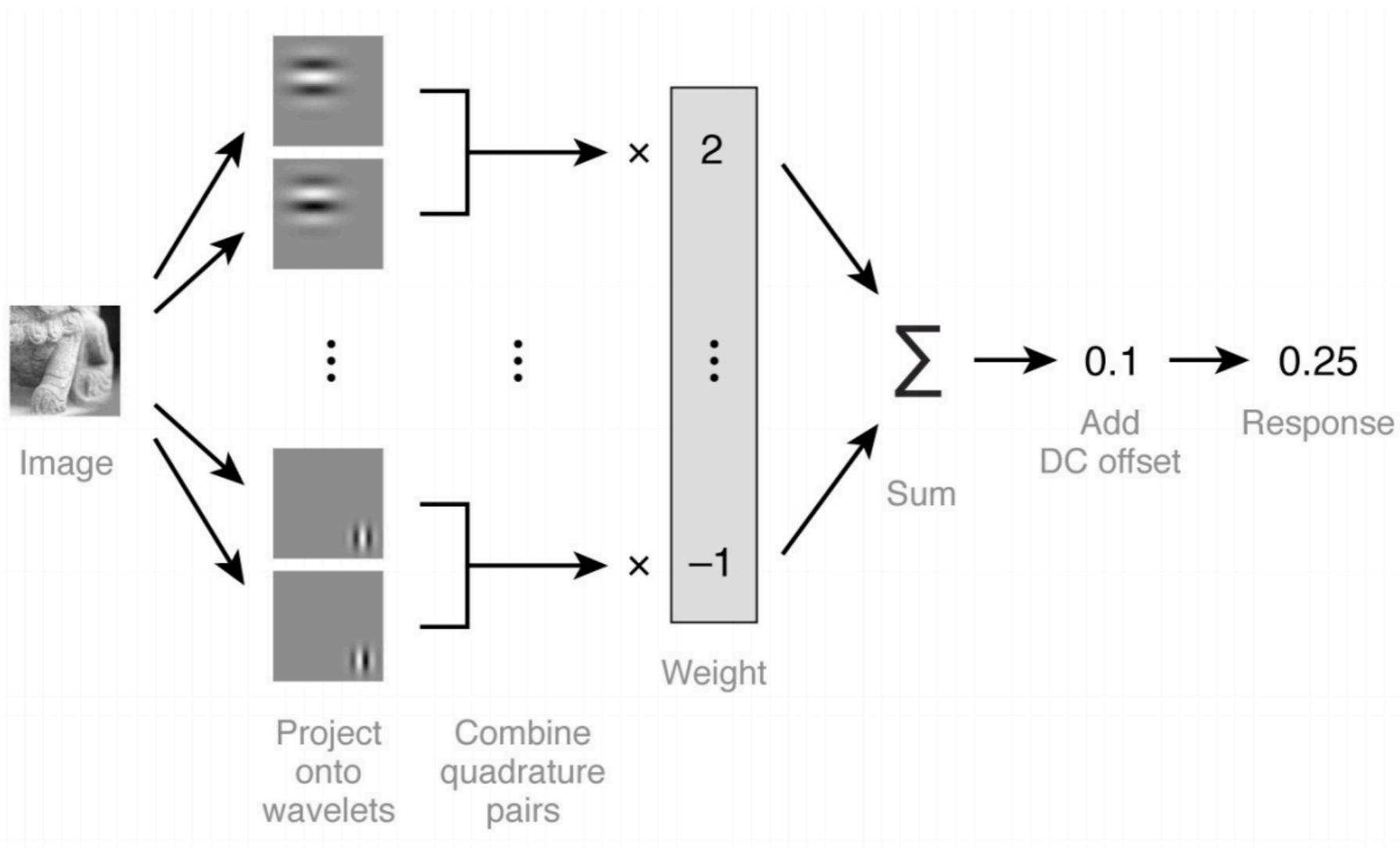
# SPACE - TIME SEPARABLE EXAMPLE

- \* Build 2nd stage model: what is response to each feature in each voxel?

Kay, Naselaris, Prenger, & Gallant (2008)

*Kay, David, Prenger, Hansen, & Gallant (2007)*

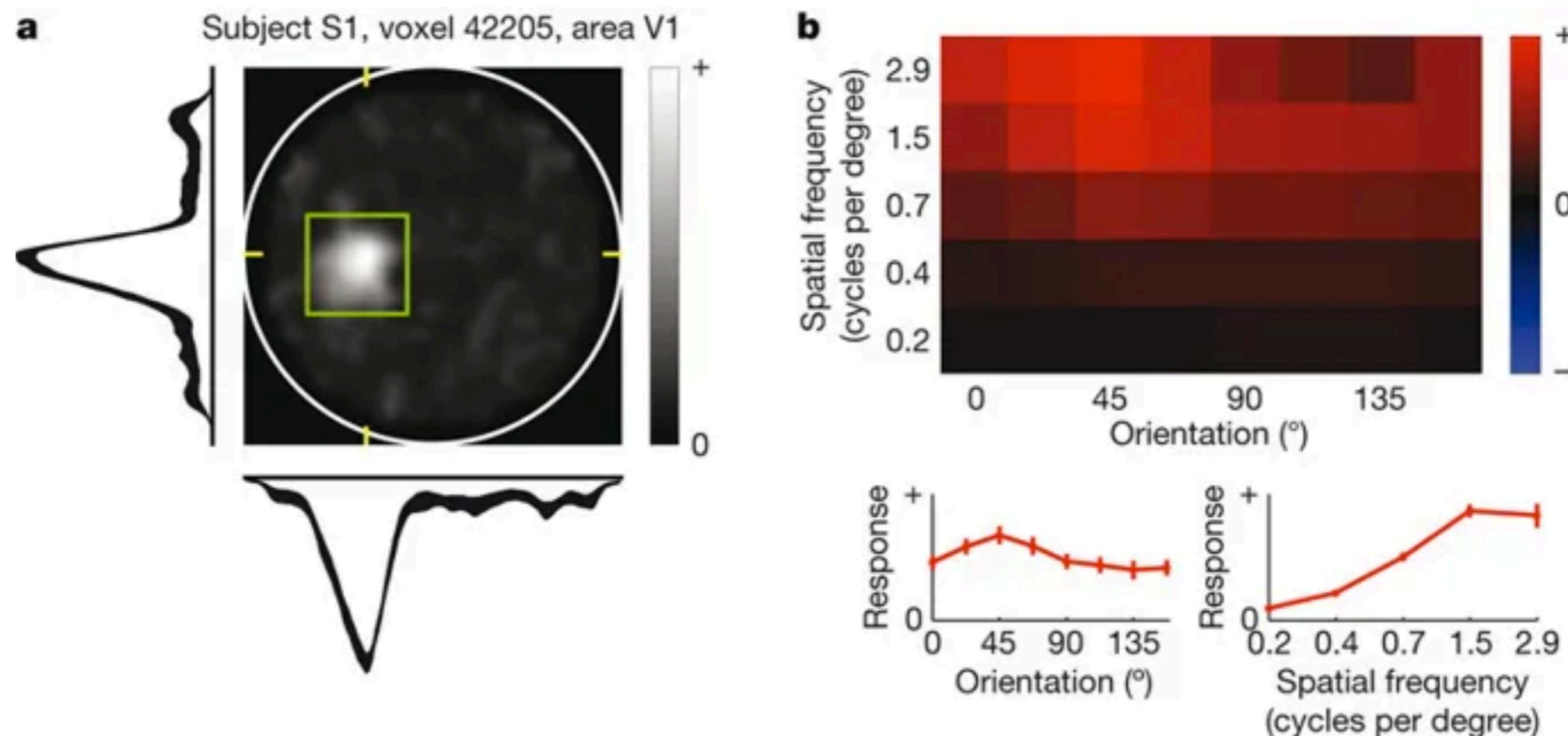
# SPACE-TIME SEPARABLE EXAMPLE



Kay, Naselaris, Prenger, & Gallant (2008)

Kay, David, Prenger, Hansen, & Gallant (2007)

# SPACE - TIME SEPARABLE EXAMPLE



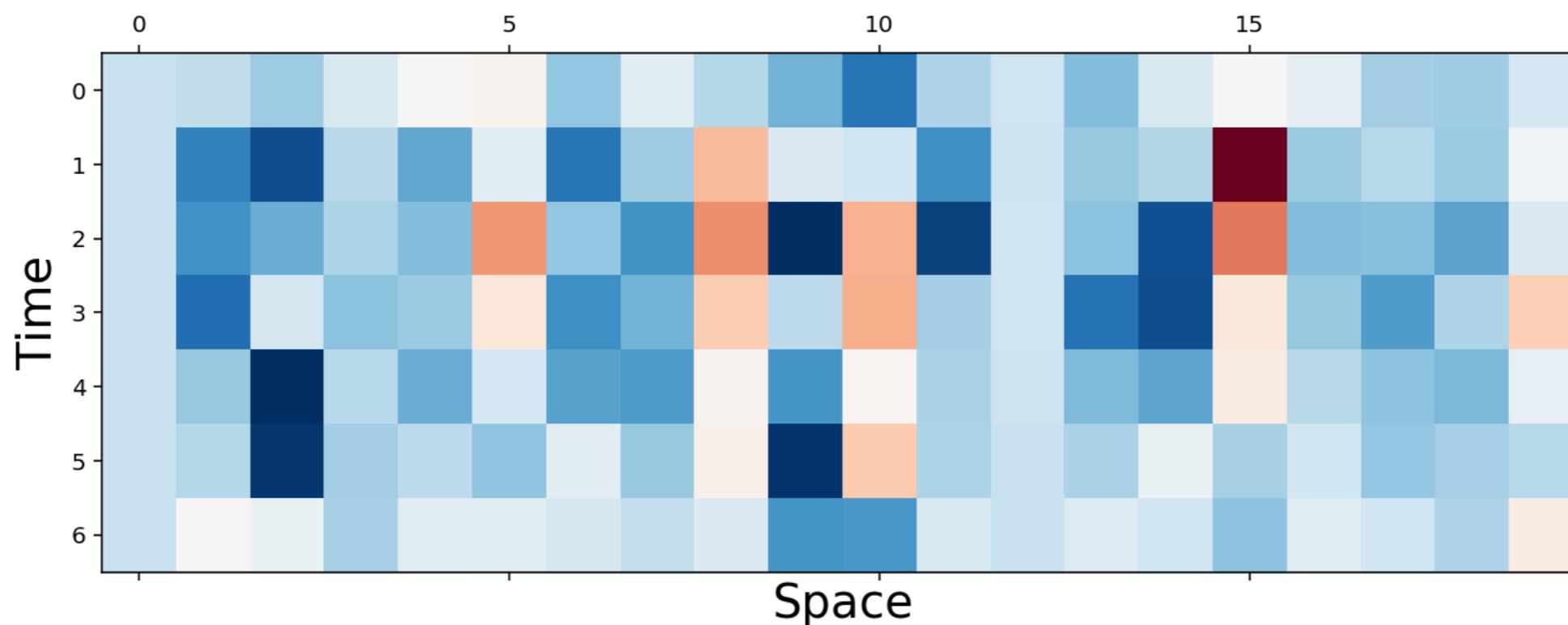
Kay, Naselaris, Prenger, & Gallant (2008)

Kay, David, Prenger, Hansen, & Gallant (2007)

# SPACE - TIME INSEPARABLE

- \* Different temporal kernel for each spatial dimensions (i.e. each feature)
- \* Fit using ordinary methods

# SPACE - TIME INSEPARABLE



# FINITE IMPULSE RESPONSE (FIR)

- \* Concatenate delayed copies of the stimulus matrix

$$X = \begin{matrix} p \\ | \\ t \end{matrix} \quad X_{del} = \boxed{\begin{matrix} X & X & X & X \\ | & | & | & | \end{matrix}}^t \quad pD$$

# FINITE IMPULSE RESPONSE (FIR)

$$X_{del} = \begin{bmatrix} X & X & X & X \end{bmatrix}^t \quad Y = X_{del} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \\ \beta_4 \end{bmatrix}$$

$$Y(t) = \beta_1 X(t) + \beta_2 X(t-1) + \beta_3 X(t-2) + \beta_4 X(t-3)$$

$Y(t) = \beta_1 X(t) + \beta_2 X(t-1) + \beta_3 X(t-2) + \beta_4 X(t-3)$

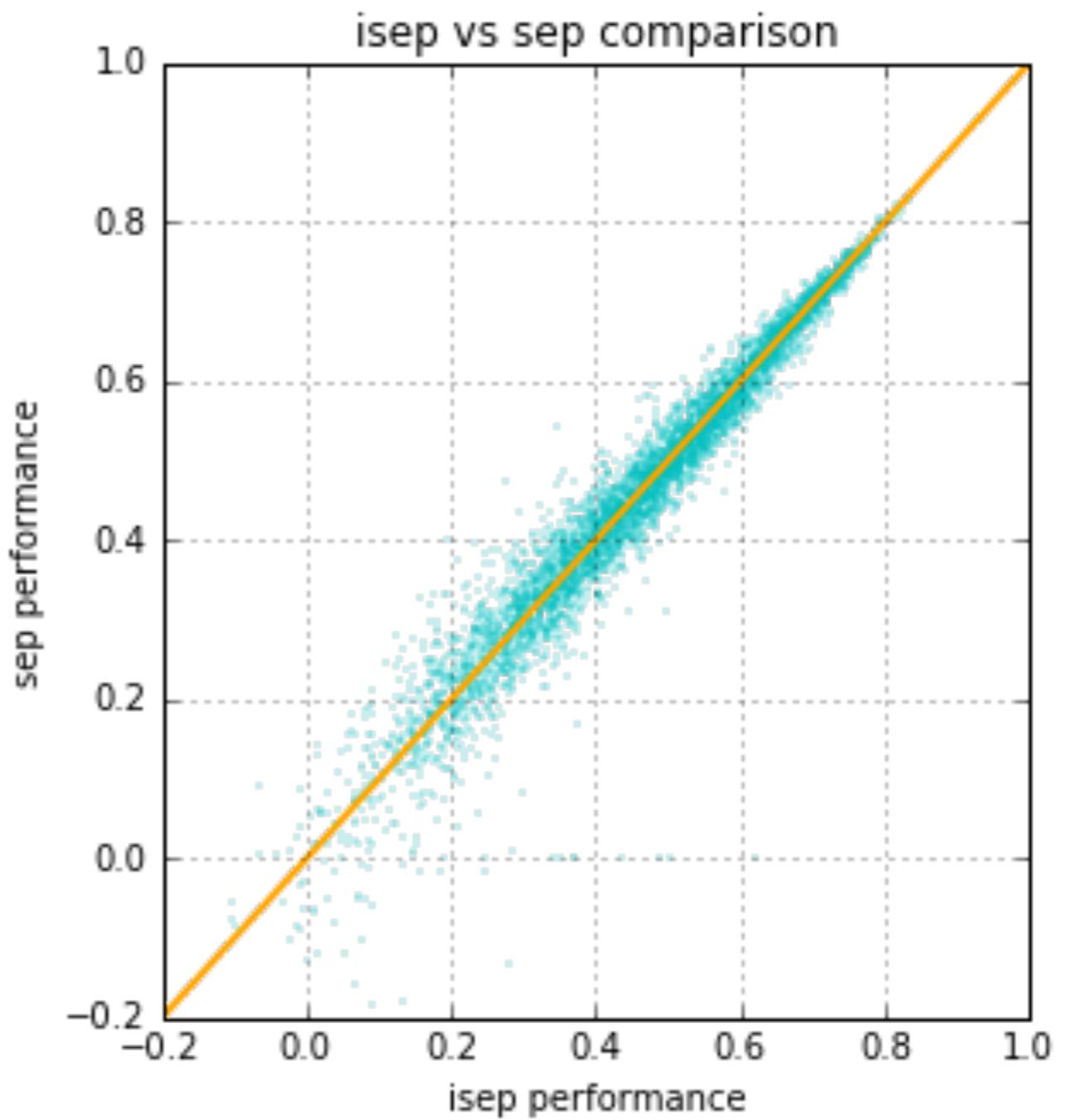
$Y = X_{\{del\}} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \\ \beta_4 \end{bmatrix}$

# SPATIOTEMPORAL MODEL

- \* **Separable**
  - \* Expensive
  - \* Highly constrained
- \* **Inseparable**
  - \* Cheap
  - \* Unconstrained

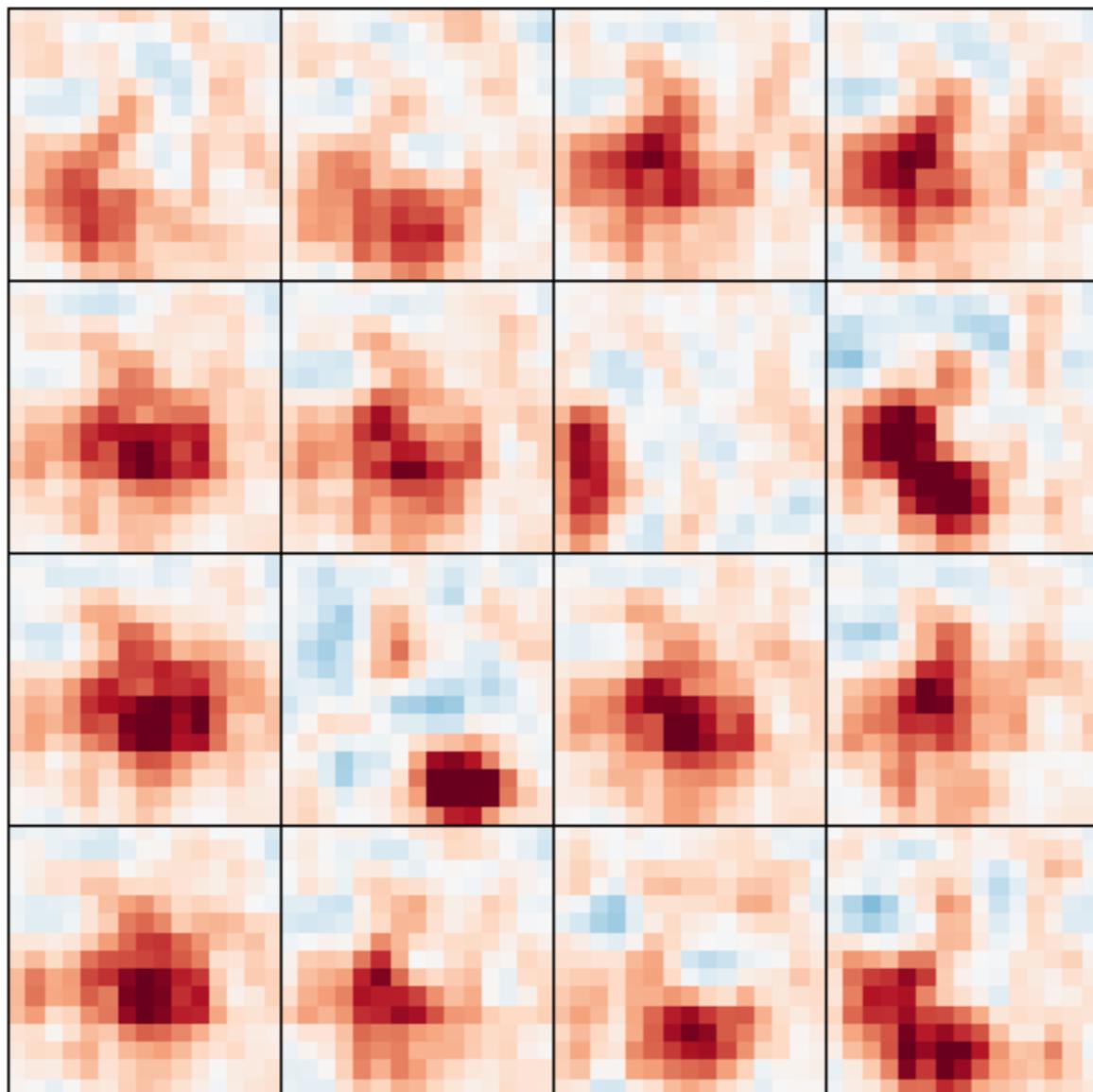
# SPATIOTEMPORAL MODEL

- \* In practice, both perform very similarly, so I prefer inseparable models

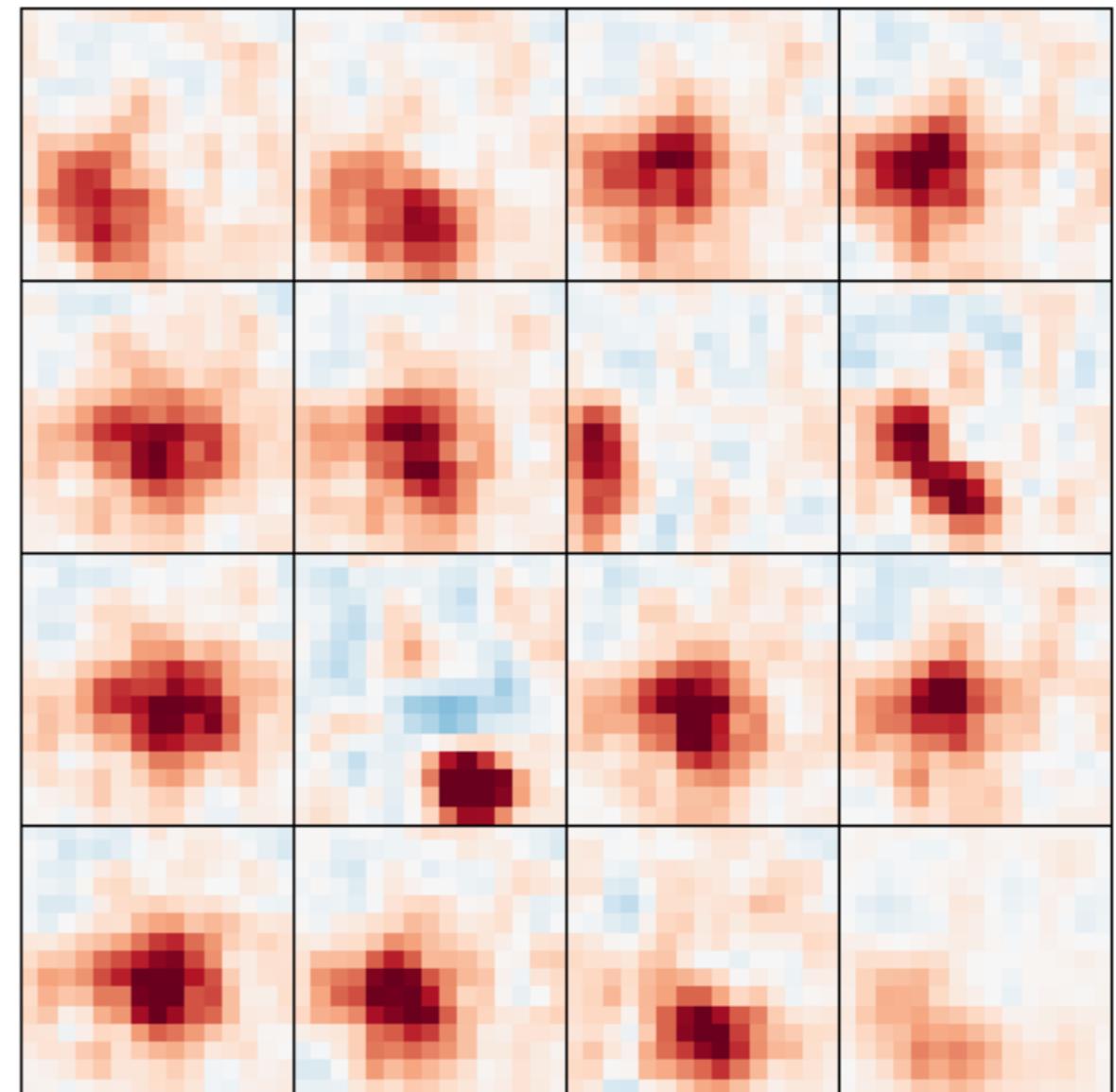


# SPATIOTEMPORAL MODEL

inseparable model weights

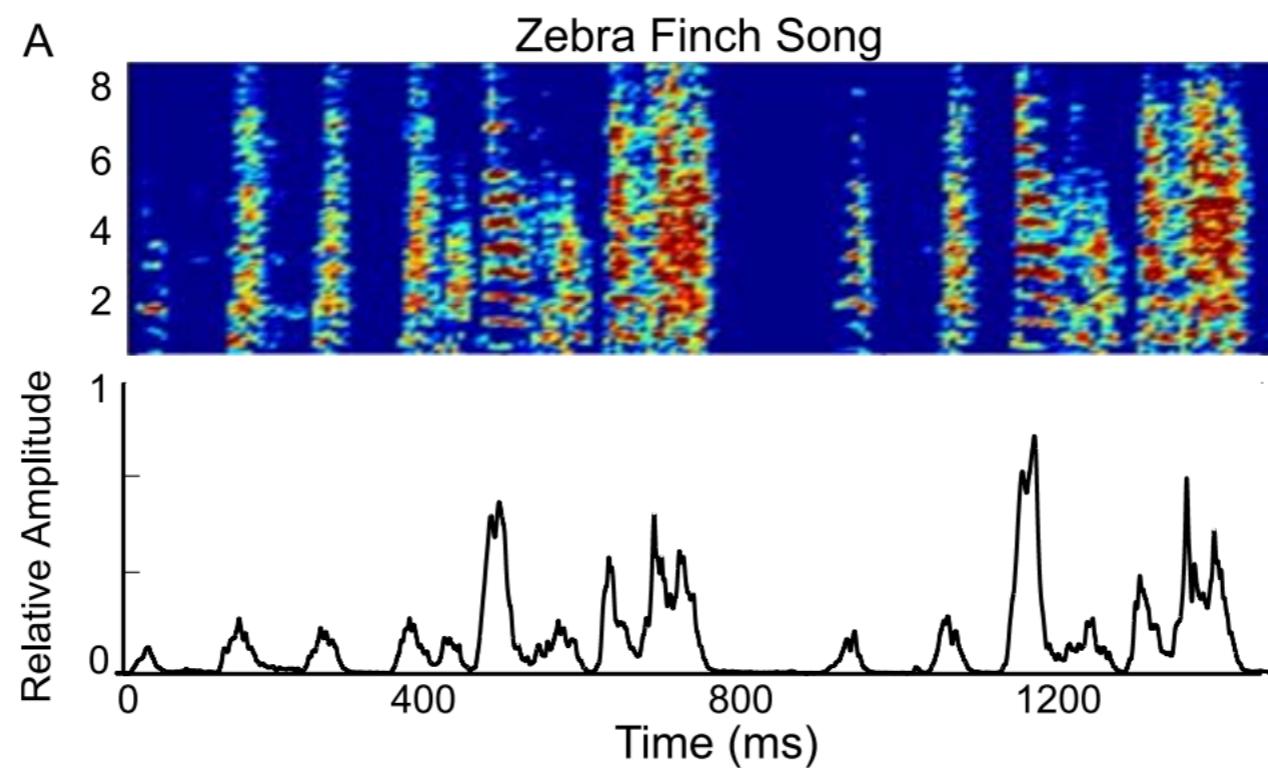


separable model weights



# INSEPARABLE EXAMPLE

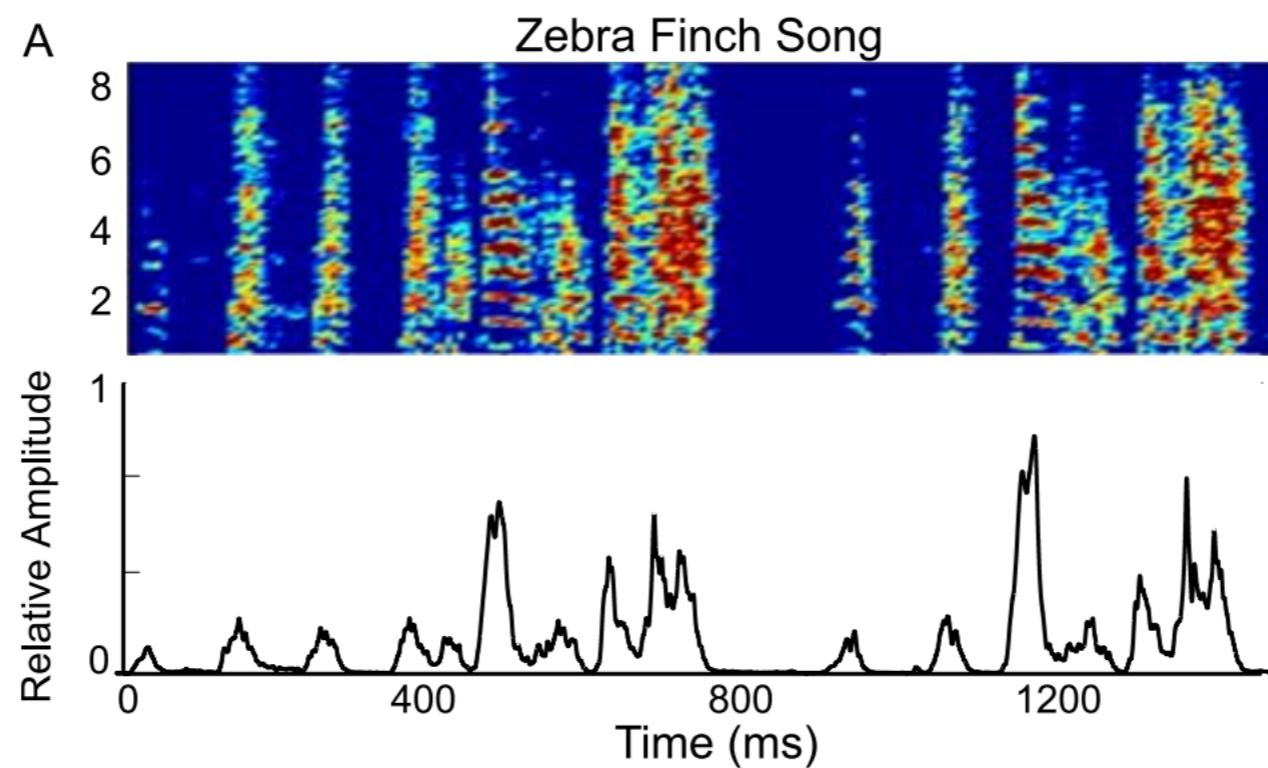
- \* Measure responses in zebra finch neurons while playing them birdsongs



Woolley, Gill, & Theunissen (2006)

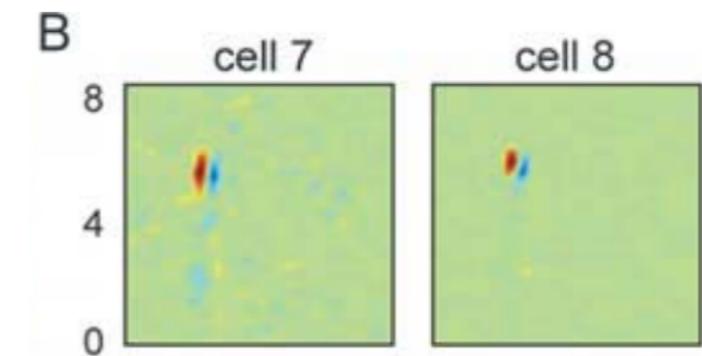
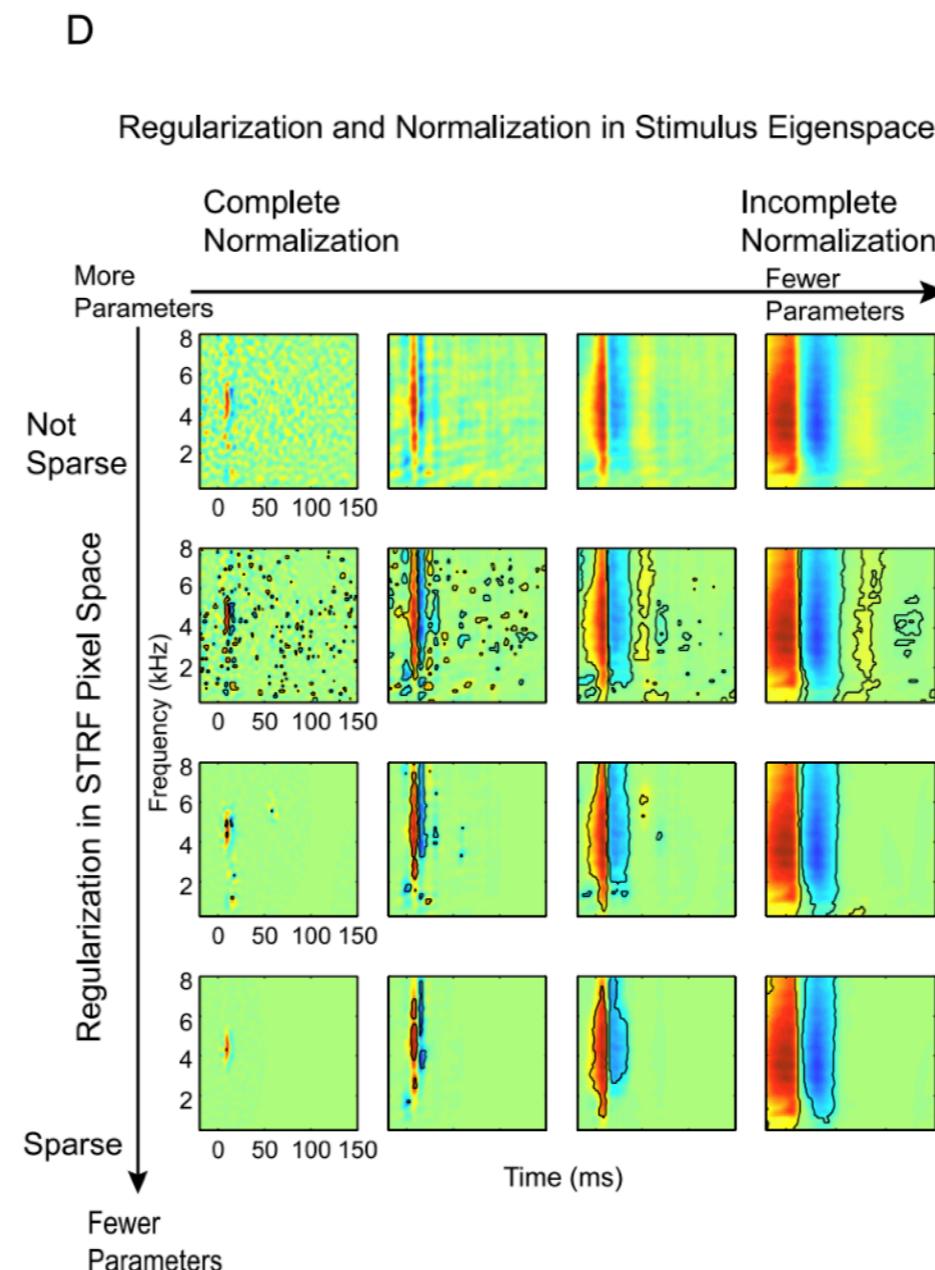
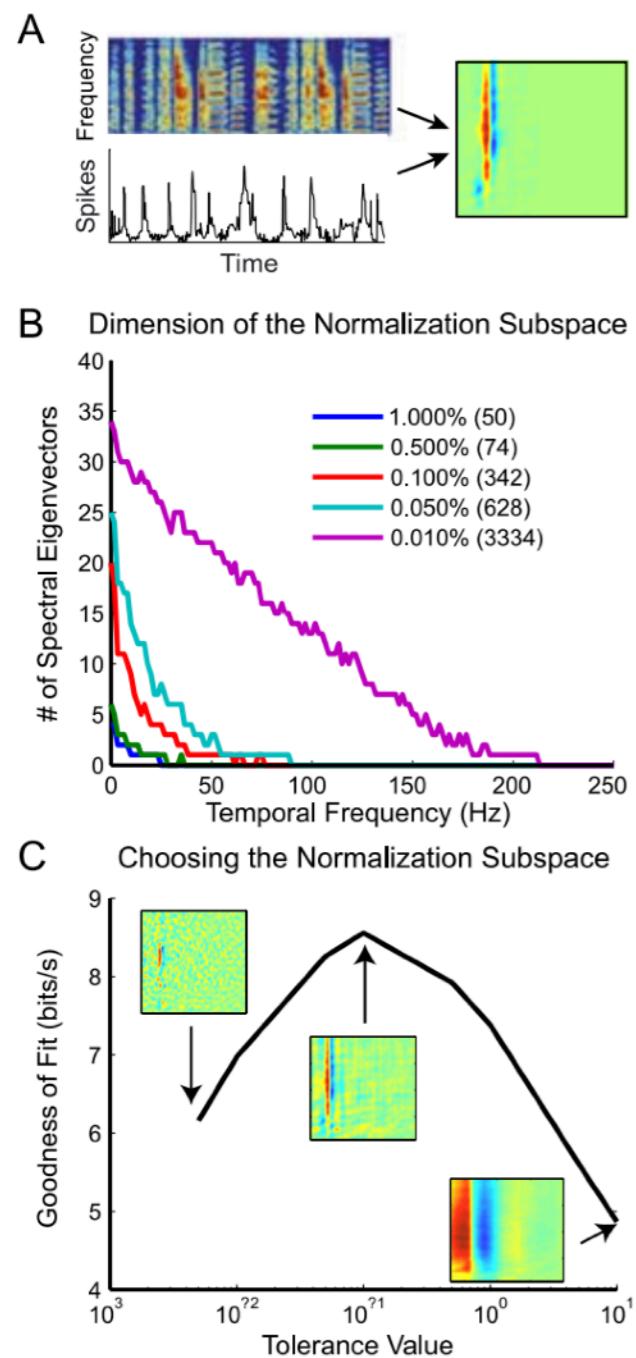
# INSEPARABLE EXAMPLE

- \* Fit model that relates spectrogram of birdsong to neural response
- \* Regularize using method similar to elastic net ( $L_1 + L_2$ )



Woolley, Gill, & Theunissen (2006)

# INSEPARABLE EXAMPLE



Inseparable-like response properties!

# RECAP

- \* Need to model temporal dependence in system identification
- \* Temporal dependence can be “real” or “artifactual” (BOLD)
- \* Spatiotemporal models can be “space-time separable” or “space-time inseparable”

# **NEXT TIME**

- \* Data quality!