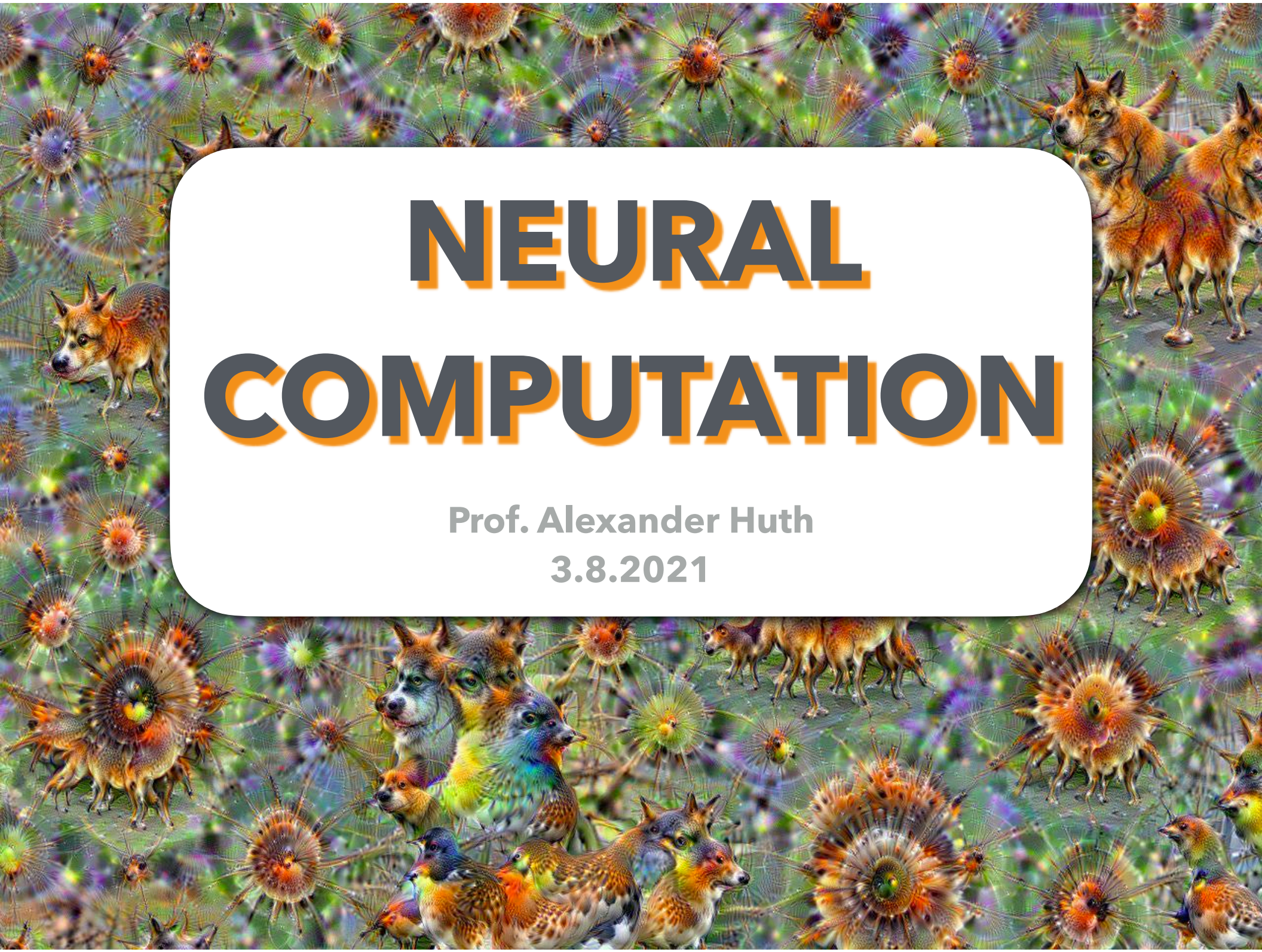


NEURAL COMPUTATION

Prof. Alexander Huth

3.8.2021

RECAP

$$Y = f(X)$$

* System identification
  * Linear
  * Linearized
  * Nonlinear

RECAP

$$Y = f(X)$$

* System identification
  * Linear $Y = X\beta$
  * Linearized $Y = \mathbb{L}(X)\beta$
  * Nonlinear $Y = \Theta(X)$

LINEAR REGRESSION

RESPONSE VARIABLES WEIGHTS NOISE

$$Y = X\beta + \epsilon$$

LINEAR REGRESSION

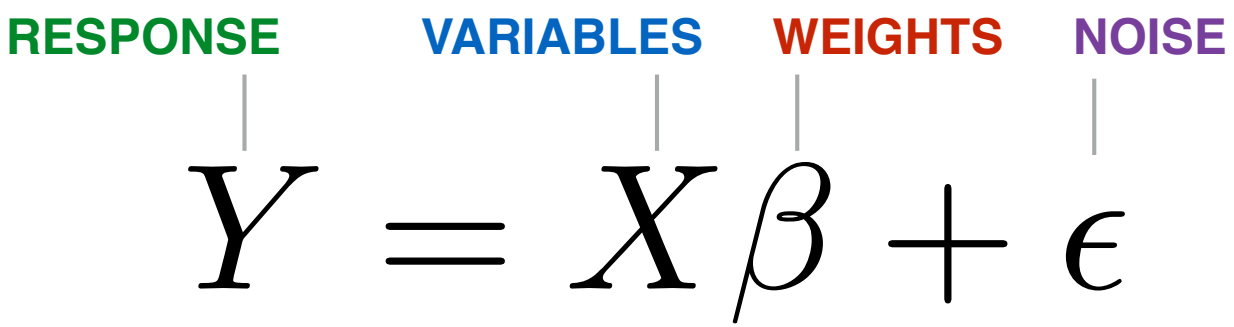
RESPONSE VARIABLES WEIGHTS NOISE

$$Y = X\beta + \epsilon$$

Loss function:

$$||Y - X\beta||_2$$

LINEAR REGRESSION



* How do we solve for beta?
  * Analytically
  * Iteratively

ANALYTIC SOLUTION TO LINEAR REGRESSION

RESPONSE VARIABLES WEIGHTS NOISE

$$Y = X\beta + \epsilon$$

$$\beta = f(X, Y)$$

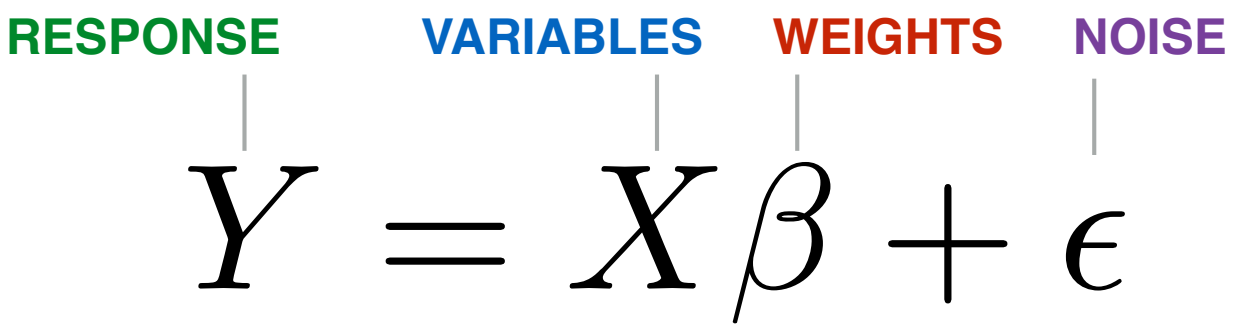
ITERATIVE SOLUTION TO LINEAR REGRESSION

RESPONSE VARIABLES WEIGHTS NOISE

$$Y = X\beta + \epsilon$$

$$\Delta\beta \propto -\frac{\partial(||Y - X\beta||_2)}{\partial\beta}$$

LINEAR REGRESSION



Constraining the values **beta** can take improves model performance:

REGULARIZATION

REGULARIZATION

* Regularization can be thought of in three ways:
  * **Prior**
  * **Penalty**
  * **Geometry**

REGULARIZATION AS PRIOR

RESPONSE VARIABLES WEIGHTS NOISE

$$Y = X\beta + \epsilon$$

$$Y_{t,j} \sim \mathcal{N}(X\beta, \sigma^2)$$

$$\hat{\beta} = \underset{\beta}{\operatorname{argmax}}\ P(Y|X, \beta)$$

REGULARIZATION AS PRIOR

RESPONSE VARIABLES WEIGHTS NOISE

$$Y = X\beta + \epsilon$$

$$Y_{t,j} \sim \mathcal{N}(X\beta, \sigma^2)$$

$$\hat{\beta} = \underset{\beta}{\operatorname{argmax}}\ P(Y|X,\beta)P(\beta)$$

REGULARIZATION AS PENALTY

RESPONSE VARIABLES WEIGHTS NOISE

$$Y = X\beta + \epsilon$$

$$E(\beta) = ||Y - X\beta||_2^2$$

$$\hat{\beta} = \underset{\beta}{\operatorname{argmin}}\ E(\beta)$$

REGULARIZATION AS PENALTY

RESPONSE VARIABLES WEIGHTS NOISE

$$Y = X\beta + \epsilon$$

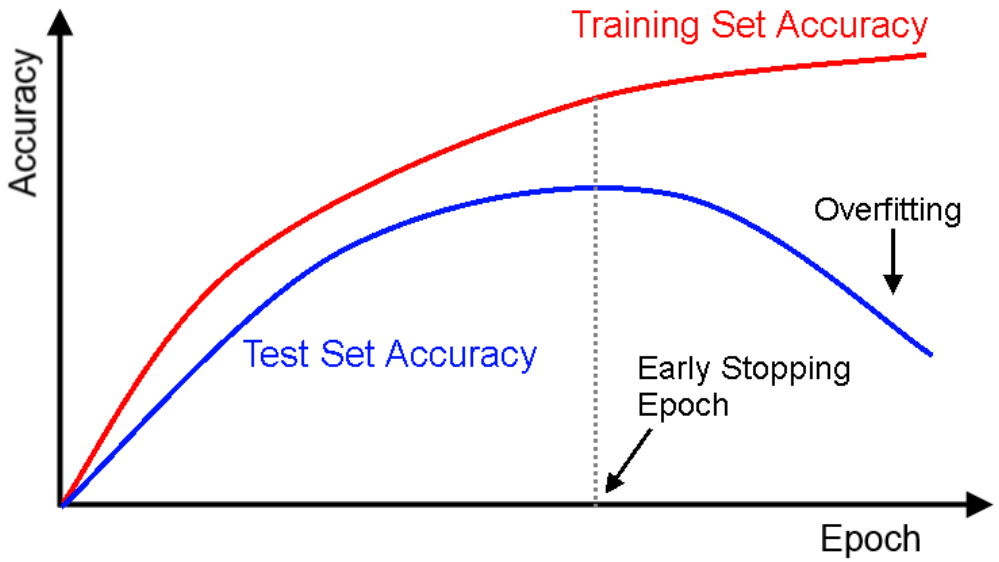
$$E_{pen}(\beta) = ||Y - X\beta||_2^2 + \lambda||\beta||_2^2$$

$$\hat{\beta} = \underset{\beta}{\operatorname{argmin}}\ E_{pen}(\beta)$$

REGULARIZATION AS GEOMETRY - EARLY STOPPING

RESPONSE VARIABLES WEIGHTS NOISE

$$Y = X\beta + \epsilon$$



https://deeplearning4j.org/earlystopping

COMMON TYPES OF REGULARIZATION

* **Beta is small (L2-sense)** = ridge = gradient descent w/ early stopping

* **Beta is small, sparse (L1-sense)** = LASSO = coord. descent w/ early stopping

  * Beta is small & sparse (L1+L2 sense) = elastic net

* **Beta is sparse (L0-sense)** = variable selection

RIDGE REGRESSION

* Multivariate normal (MVN) prior on beta
* L2 penalty on beta
* Gradient descent w/ early stopping

RIDGE REGRESSION

$$Y = X\beta + \epsilon$$

$$\hat{\beta} = \underset{\beta}{\operatorname{argmin}} \left[||Y - X\beta||_2^2 + \lambda ||\beta||_2^2 \right]$$

ERROR or LOSS PENALTY

RIDGE REGRESSION

$$\hat{\beta} = (X^\top X + \lambda I)^{-1} X^\top Y$$

$$\hat{\beta} = X^{+}_{ridge} Y$$

RIDGE REGRESSION

* Efficient solution with SVD

$$\hat{\beta} = (X^\top X + \lambda I)^{-1} X^\top Y$$

(SVD) $X = USV^\top$ $\qquad D = \dfrac{S}{S^2 + \lambda^2}$

$$\hat{\beta} = VDU^\top Y$$

RIDGE REGRESSION

* How to choose lambda?

* GCV - Generalized Cross Validation 👎

* Block-wise cross-validation 👍

RIDGE REGRESSION

* Good implementation: scikit-learn

* Awesome implementation: http://github.com/alexhuth/ridge

LASSO

* Laplacian prior on beta_i

* L1 penalty on beta

* Coordinate descent w/ early stopping

LASSO

$$Y = X\beta + \epsilon$$

$$\hat{\beta} = \underset{\beta}{\operatorname{argmin}} \left[||Y - X\beta||_2^2 + \lambda ||\beta||_1 \right]$$

ERROR or LOSS PENALTY

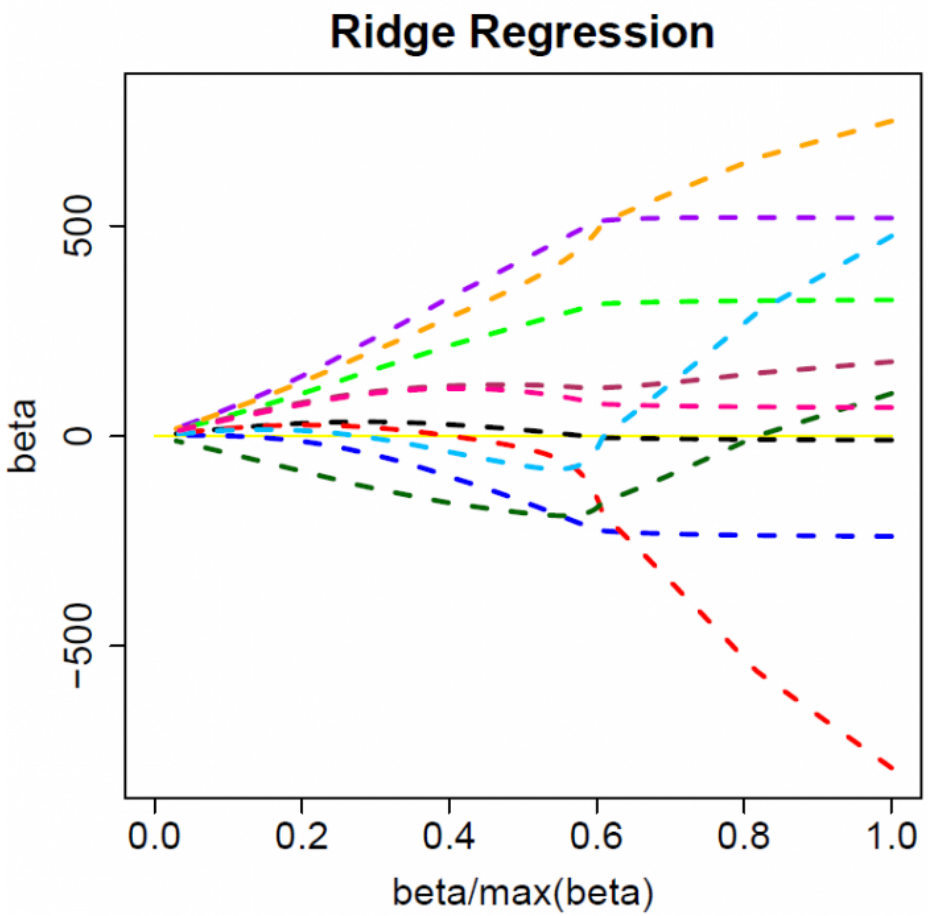
LASSO

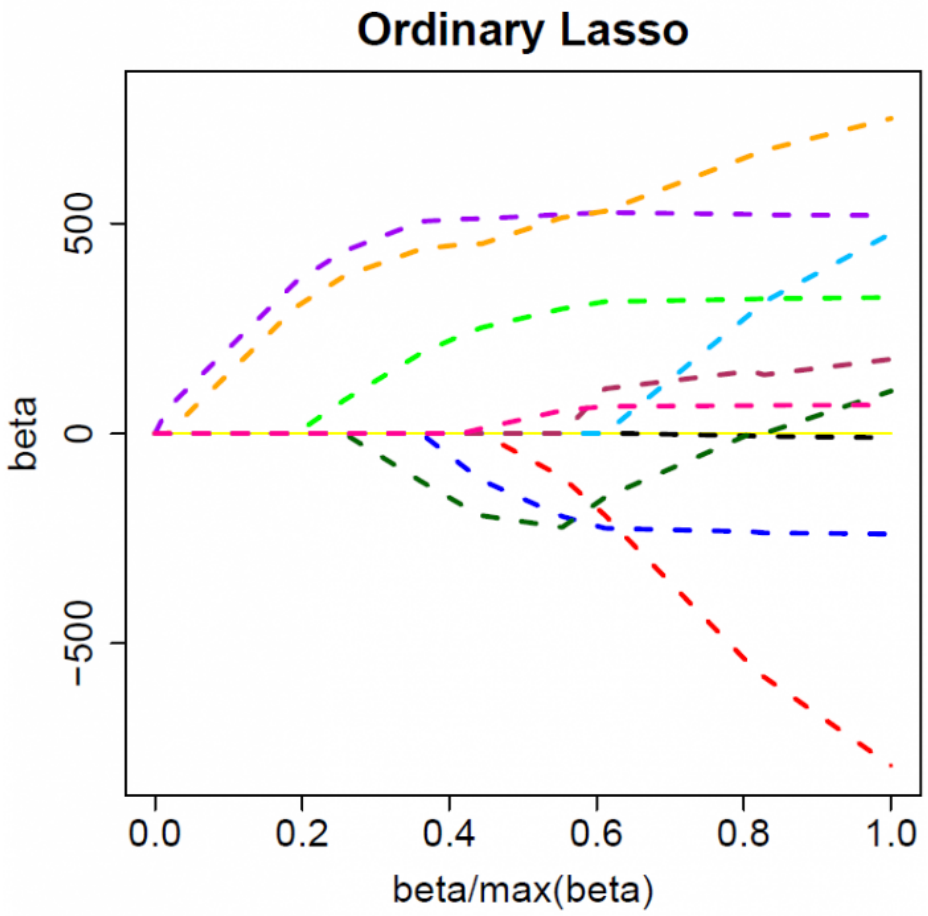
* No closed form solution

* Solved via coordinate descent, LARS (least-angle regression) or other methods

* *Sssssllllloooooowwwww……*

LASSO





h/t https://onlinecourses.science.psu.edu/stat857/node/158

OTHER METHODS

* Neural networks (linear or nonlinear)

* Random forests (nonlinear)

* Feature selection (~L0-norm)

NEXT TIME

* Tikhonov regression