

Random Osborne Algorithm for Matrix Balancing

Optimal transport report

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Table of content

1	Introduction (3 pages)	1
1.1	Presentation of the problem	1
1.2	Related work	1
1.3	Contributions of the paper	2
1.4	Our contributions	2
2	Main body (10 pages)	2
2.1	Notations	2
2.2	Presentation of the method	2
2.3	Theoretical guarantees	3
2.4	Numerics	3
2.4.1	Sparsity	3
3	Conclusion and perspective	3
4	Connexion with the course	3
	References	3

Abstract (½ page): What problems is studied? Why is it relevant? What solutions is proposed? Which contributions (theory, numerics, etc)?

1 Introduction (3 pages)

[AP23]

1.1 Presentation of the problem

Introduce the reasons to do this alg

Notation 1.1 Let c and r respectively be the column-wise sum and the row-wise sum of matrices ie.

$$c : \begin{cases} \mathcal{M}_{n,m}(\mathbb{K}) & \rightarrow \mathbb{K} \\ A & \mapsto A^\top \mathbf{1} \end{cases} \quad \text{and} \quad r : \begin{cases} \mathcal{M}_{n,m}(\mathbb{K}) & \rightarrow \mathbb{K} \\ A & \mapsto A \mathbf{1}. \end{cases}$$

Definition 1.1 Let $A \in \mathcal{M}_n(\mathbb{R}_+)$ be a non negative square matrix, $\varepsilon \geq 0$ and $k \in \mathbb{N}^*$. The matrix A is (ε, k) -balanced if

$$\frac{\|c(A) - r(A)\|_k}{\sum_{i,j} a_{i,j}} \leq 0.$$

Furthermore, if A is $(0, k)$ -balanced, we say that A is balanced.

Definition 1.2 The ε, k -approximate matrix balancing problem is: given a square non-negative matrix $K \in \mathcal{M}_n(\mathbb{R}_+)$, $\varepsilon \geq 0$ and $k \in \mathbb{N}^*$, find a positive diagonal matrix $D \in \mathcal{D}_n(\mathbb{R}_+^*)$ such that DKD^{-1} is (ε, k) -balanced.

1.2 Related work

Previous works (at least a few citations). If relevant, include things that you have seen during the MVA course (or possibly other courses).

Osborn algorithm introduced in [Os60; PR71] and default in Scipy.

[CD00; Che01] improve accuracy of computation of eigen vectors, eigen values.

there are corner cases where balancing can actually worsen the conditioning. [Wat06] also [JLL14] in which they explain it and explain how to modify LAPACK to avoid it.

The standard matrix balancing algorithm is the Sinkhorn-Knopp algorithm [SK67], a special case of Bregman's balancing method [LS81] that iterates rescaling of each row and column until convergence. However, the algorithm converges linearly [Sou91], which is prohibitively slow for recently emerging large and sparse matrices.

Use 2.3 to explain it using convex opti

Use real formal definition from 2.1

[PR71] -> approximately balance matrices with a diagonal with only powers of 2. Advantage : no floating point error in computing the balanced matrix on base two computers. approximately “good enough”

[SNT17] -> matrix balancing on tensors

1.3 Contributions of the paper

Their main contribution is theorem 1.1. It exhibits a variant of OSBORN’s algorithm with near-linear runtime in the input sparsity. It also shows that improving the runtime dependence in ε can be improve from ε^{-2} to ε^{-1} without an additional factor n .

Theorem 1.1 *Let $K \in \mathcal{M}_n(\mathbb{R}_+)$ be a balanceable non negative square matrix and $\varepsilon \geq 0$. Random OSBORN solves $(\varepsilon, 1)$ -approximate matrix balancing problem in T operations where there exists $c > 0, \delta > 0$ such that*

$$\mathbb{E}(T) = \mathcal{O}\left(\frac{m}{\varepsilon} \min\left\{\frac{1}{\varepsilon}; d\right\} \log \kappa\right) \quad \text{and} \quad \mathbb{P}\left(T \leq c \frac{m}{\varepsilon} \min\left\{\frac{1}{\varepsilon}; d\right\} \log \kappa \log \frac{1}{\delta}\right) \geq 1 - \delta$$

where m is the number of nonzero entries in K , d is the diameter of the graph associated to K and $\kappa = \sum_{i,j} K_{i,j} / \min_{i,j} K_{i,j}$.

1.4 Our contributions

numerics? limits?

2 Main body (10 pages)

2.1 Notations

2.2 Presentation of the method

```

1 osborn( $K, \varepsilon$ ):
2    $\mathbf{x} = 0 \in \mathbb{R}^n$ 
3   while not(is_balanced( $\mathbb{D}(e^x)K\mathbb{D}(e^{-x}), \varepsilon$ )):
4     Choose  $k \in [n]$  # This is where variants differ
5      $\mathbf{x} += (\log(c\_k(\mathbb{D}(e^x)K\mathbb{D}(e^{-x}))) - \log(r\_k(\mathbb{D}(e^x)K\mathbb{D}(e^{-x}))))/2$ 
6   return  $\mathbf{x}$ 

```

There are *many* way to choose the next coordinate to update and hence many variants of the algorithm. The article focuses on four of them:

- **Cyclic Osborn** Cycle through the coordinates. (eg. 1, 2, 3, 1, 2, 3, 1, ...).
- **Random-Reshuffle Cyclic Osborn** Cycle through the coordinates using a new random permutation for each cycle. (eg. 2, 1, 3, 1, 2, 3, 1, 3, 2, ...).
- **Greedy Osborn** Choose k where the imbalance is maximal eg.

$$k = \operatorname{argmax}_k \left| \sqrt{r_k(\mathbb{D}(e^x)K\mathbb{D}(e^{-x}))} - \sqrt{c_k(\mathbb{D}(e^x)K\mathbb{D}(e^{-x}))} \right|.$$

- **Random Osborn** Uniformly sample k independently between each call.

Talk about the implementation

2.3 Theoretical guarantees

2.4 Numerics

it indeed converges even with high sparsity (cf theorem)

2.4.1 Sparsity

We conducted numerical experiments to investigate the behavior of Osborn’s algorithm in the presence of varying numbers of zero entries within randomly generated matrices. Each matrix has a size of $(10, 10)$ with uniformly distributed values in the range $[0, 1]$. The number of zero entries in the matrices was systematically varied. Our objective was to assess the algorithm’s ability to find solutions even with a small number of non-zero inputs, as proven in [ref].

The experiment involved measuring the execution time of Osborn’s algorithm for each matrix, with the time recorded as a function of the number of zero entries. This exploration aimed to provide insights into the near-linear convergence time of the algorithm, shedding light on its performance characteristics under different sparsity levels. These results contribute valuable empirical evidence to support the theoretical findings presented in [ref].”

Use observation 2.5 to compare with other convex optim algorithms.

Look at per iteration runtime (5.2)

3 Conclusion and perspective

Summary of the result obtained: pros and cons (limitation, problems, error in the articles, etc) Possible improvement/extension

4 Connexion with the course

MANDATORY SECTION:. What are the notions/results/algorithms presented in the course that are used or related to the one presented in this paper?

Todo list

<input type="checkbox"/> Abstract	1
<input type="checkbox"/> Introduce the reasons to do this alg	1
<input type="checkbox"/> Use 2.3 to explain it using convex opti	1
<input type="checkbox"/> Use real formal definition from 2.1	1
<input type="checkbox"/> code availability	2
<input type="checkbox"/> Link with convex opti	3
<input type="checkbox"/> Per iteration	3

References

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