

The Multivariate Normal distribution

- 1) We say that a random vector has the standard normal distribution on \mathbb{R}^n if the coordinates are indep. standard normal RVs.

$$g = (g_1, \dots, g_n)^{\text{tr}}, \quad g_1, \dots, g_n - \text{indep.} \\ g_i \sim N(0, 1).$$

$$Eg = (Eg_1, \dots, Eg_n)^{\text{tr}} = (0, \dots, 0)^{\text{tr}}$$

$$\begin{aligned} (\text{cov}(g))_{ij} &= E((g_i - Eg_i)(g_j - Eg_j)) = E g_i g_j = \begin{cases} E g_i^2 & i=j \\ E g_i E g_j & i \neq j \end{cases} \\ &= \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases} \end{aligned}$$

So $\text{cov}(g) = I_n$ - the identity matrix.
We write $g \sim N(0, I_n)$.

- 2) General normal random vectors.

Say X is a normal RV. Eg $X \sim N(\mu, \sigma^2)$

$$\text{Then } \frac{X - \mu}{\sigma} \sim N(0, 1).$$

If we denote $Z = \frac{X - \mu}{\sigma}$, then
 $X = \mu + \sigma Z$

i.e. any normal RV is a linear transformation of a standard normal.

We can use this to generalize the notion of a standard normal RV in \mathbb{R}^n .

We will say a random vector X in \mathbb{R}^n has the (multi-variate) normal distribution if $\exists \mu \in \mathbb{R}^n$, $Z \sim \mathcal{N}(0, I_n)$ & an $n \times n$ matrix Q s.t.

$$X = \mu + QZ.$$

Remark 1: The book is not consistent whether vectors in \mathbb{R}^n are columns ($n \times 1$) or rows ($1 \times n$), but you can figure it out from the context.

Remark 2: The book's def is a bit different, it requires the matrix Q to be invertible, but it doesn't have to be. What the book defines should be called the non-degenerate normal distribution.

$$\begin{aligned} E(X) &= \mu, \quad \text{Cov}(X) = E((X - E X)(X - E X)^T) \\ &= E(QZ(QZ)^T) = QE(ZZ^T)Q^T \\ &\quad \uparrow \text{(multi)linearity of expectation} \\ &= QI_nQ^T = QQ^T =: \Sigma \\ &\quad \uparrow \\ &\quad Z \sim \mathcal{N}(0, I_n) \end{aligned}$$

So X has mean μ & cov. Σ . Write $X \sim \mathcal{N}(\mu, \Sigma)$.

Density

Let $g \sim \mathcal{N}(0, I_n)$.

Since the coordinates of g are indep $\mathcal{N}(0, 1)$'s, g has density, which is given by the product of the densities of the components:

$$f(x) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi}} e^{-x_i^2/2} = \frac{1}{(2\pi)^{n/2}} e^{-\|x\|_2^2/2}.$$

By a change of variables, can show that if Σ is invertible, then X has density

$$f_X(x) = \frac{1}{(2\pi)^{n/2} (\det \Sigma)^{1/2}} e^{-\frac{1}{2}(x-\mu)^T \Sigma^{-1} (x-\mu)}$$

If Σ is not invertible, X does not have density.

Rank: Recall that if $X \sim N(0, I)$, then $M_X(t) = e^{t^T/2}$
Check that if $X \sim N(\mu, \sigma^2)$, then $M_X(t) = e^{\mu t + \sigma^2 t^2/2}$.

Check that if $X \sim N(\mu, \Sigma)$, then $M_X(t) := E(e^{\langle X, t \rangle}) = e^{\frac{1}{2} t^T \Sigma t + \mu^T t}$

Sometimes this is used as the defn of a multivariate normal. Note that

$$M_X(t) = e^{\frac{1}{2} t^T \Sigma t + \mu^T t} \quad \& \text{ is defined even}$$

when Σ is not invertible, so X has no density.

Rank: If $X \sim N(\mu, \Sigma)$ & $t \in \mathbb{R}^n$ is arbitrary, then $\langle X, t \rangle$ is actually normal.

I.e. any linear combination of the coordinates of a multivariate normal is normal

In fact the converse is also true.

X is multivariate normal iff $\langle X, t \rangle$ is normal $\forall t \in \mathbb{R}^n$.

Rank: This would not be true if we only restricted normals to those invertible covariance matrices Σ .

Remark: In particular, it follows that if $X \sim N(\mu, \Sigma)$ then every component of X is normal.

The converse is not true.

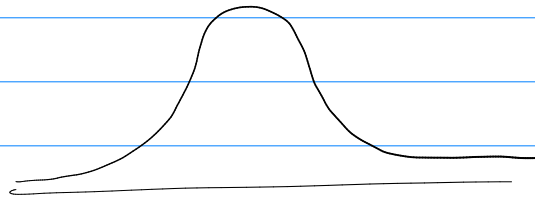
Exercise: Constant RVs X, Y etc. They are both normal, but (X, Y) is not a multivariate normal.

Q: What does a multidimensional normal "look like"?
Let $X \sim N(0, I_n)$.

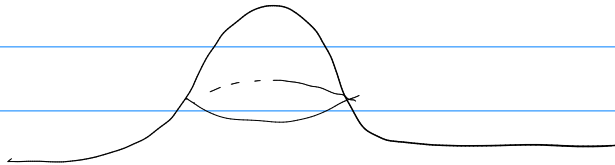
1) Since $E(X) = 0$, $\text{Cov}(X) = I_n$, we get X is isotropic.

2)

If $n=1$,



If $n=2$



What if n is large?

Recall that X has density

$$f(x) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi}} e^{-x_i^2/2} = \frac{1}{(2\pi)^{n/2}} e^{-\|x\|_2^2/2}.$$

Note that the density only depends on the length $\|x\|_2$ and not the direction of x , so the density is rotation invariant: if U is an orthogonal matrix (i.e. multiplying a vector by U simply rotates it) we have

$$P(ug \in A) = P(g \in u^{-1}A) = \int_{u^{-1}A} \frac{1}{(2\pi)^{n/2}} e^{-\|x\|_2^2/2} dx$$

ch. of var. $y = ux$

$$= \int_A \frac{1}{(2\pi)^{n/2}} e^{-\frac{\|y\|_2^2}{2}} \underbrace{\frac{\det(u^{-1})}{1}}_1 dy = P(g \in A).$$

It follows that $P(g \in A) = P(g \in u^{-1}A) \quad \forall \text{ opul } u,$
 $\& \quad ug \sim N(0, I_n) \quad \forall \text{ opul } u.$

So the distr of X is rotation invariant $\forall n$.
 What can we say about the length of X ?

Last time you saw that $\|X\|_2$ concentrates around \sqrt{n} :

$$\|\|X\|_2 - \sqrt{n}\|_{\psi_2} \leq Ck^2, \text{ where } k = \|X\|_{\psi_2}$$

or, equivalently that

$$P(|\|X\|_2 - \sqrt{n}| \geq t) \leq 2e^{-\frac{ct^2}{k^4}} \quad \forall t \geq 0.$$

so with very high probability $\|X\|_2$ is within a constant of \sqrt{n} .

let's write X as

$$\frac{X}{\sqrt{n}} = \frac{X}{\|X\|_2} \cdot \frac{\|X\|_2}{\sqrt{n}}.$$

The distribution of X is rotationally invariant \Rightarrow
 so is the distr of $\frac{X}{\|X\|_2}$, but $\frac{X}{\|X\|_2}$ has length 1, so

$\frac{X}{\|X\|_2}$ is distributed uniformly over the sphere of radius one.

On the other hand $\|X\|_2$ is within a constant of \sqrt{n} w/ high prob., so $\frac{\|X\|_2}{\sqrt{n}} \approx 1$, so $\frac{X}{\sqrt{n}}$ is roughly uniformly distributed over the sphere of radius 1, so $X \approx \sqrt{n} \text{Unif}(S^{n-1})$.

$$\text{i.e. } N(0, I_n) \approx \text{Unif}(\sqrt{n} S^{n-1}).$$

Sub-gaussian distributions in higher dimensions

Recall that a random vector X in \mathbb{R}^n is gaussian if $\langle X, t \rangle$ is gaussian $\forall t \in \mathbb{R}^n$. We can use this characterization of the gaussian distr. to define the notion of a multivariate subgaussian.

Def: A random vector X in \mathbb{R}^n is sub-gaussian if $\forall t \in \mathbb{R}^n$, $\langle X, t \rangle$ is sub-gaussian.

Q: Can we extend the notion of a sub-gaussian norm?

Could take $\sup \|\langle X, t \rangle\|_{\psi_2}$, but that would be ∞ . Restricted only to $t \in S^{n-1}$:

The sub-gaussian norm of X is defined to be

$$\|X\|_{\psi_2} := \sup_{t \in S^{n-1}} \|\langle X, t \rangle\|_{\psi_2}.$$

Examples of sub-gaussian distributions

1) Suppose X is an n -dimensional sub-gaussian random vector.
Q: what can we say about its coordinates?

$\langle X, t \rangle$ is sub-gaussian $\forall t \in \mathbb{R}^n$. Taking $t = (0, \dots, 0, 1, 0, \dots, 0)$ we see that all coordinates have to be sub-gaussian.

What if we know $X = (X_1, \dots, X_n)$ w/ X_1, \dots, X_n sub-gaussian.

Can we claim X is sub-gaussian as well?

Let $t \in \mathbb{R}^n$. Need to check $\langle X, t \rangle$ is sub-g.

$$\langle X, t \rangle = X_1 t_1 + \dots + X_n t_n.$$

If X_i is sub-g, then $X_i t_i$ is also, thus

$X_1 t_1 + \dots + X_n t_n$ is also sub-gaussian $\Rightarrow X$ is sub-g.

So X is sub-gaussian iff all its components are.

However, the sub-gaussian norm of X might be much larger than that of its components.

That's not the case if the components are indep.

Lemma: If X_1, X_2, \dots, X_n are indep. mean-zero sub-gaussian RVs, then

$X = (X_1, \dots, X_n) \in \mathbb{R}^n$ is sub-gaussian &

$$\|X\|_{\psi_2} \leq C \max_{1 \leq i \leq n} \|X_i\|_{\psi_2} \text{ for some}$$

absolute constant C .

Pf: Let $t \in S^{n-1}$.

shown previously: uses independence

$$\|\langle X, t \rangle\|_{\psi_2}^2 = \|\sum_{i=1}^n t_i X_i\|_{\psi_2}^2 \leq C \sum_{i=1}^n \|t_i X_i\|_{\psi_2}^2 = C \sum_{i=1}^n t_i^2 \|X_i\|_{\psi_2}^2$$

$$\leq C \max_{1 \leq i \leq n} \|X_i\|_{\psi_2}^2 \sum_{i=1}^n t_i^2 = C \max_{1 \leq i \leq n} \|X_i\|_{\psi_2}^2 \triangleq$$

$$2) X \sim N(0, I_n).$$

Of course σ is sub-g. What is its sub-g norm?

If $t \in S^{n-1}$, then

$$(X, t) = X_1 t_1 + \dots + X_n t_n \sim N(0, t_1^2 + \dots + t_n^2) = N(0, 1)$$

So

$$\|X\|_{\psi_2} = \|N(0, 1)\|_{\psi_2} < C \text{ indep of } n.$$