

A (very) brief introduction to probability

Purpose: Build models of experiments with random outcomes & analyze these models.

By random outcomes we mean anything that we cannot predict with certainty.

E.g. roll dice, toss coins, throw darts, etc.

Ingredients of a probability model

"Defn" of probability space

- Sample space - Ω

Set of all possible outcomes

Elements of Ω are called sample points

- The set of events \mathcal{F}

An event is a subset of Ω .

E.g. roll a die $\Omega = \{1, 2, 3, 4, 5, 6\}$

The subset $A = \{2, 4, 6\}$, $A \subseteq \Omega$ is the event the roll is even.

The event "not a 6" is $B = \{1, 2, 3, 4, 5\} \subseteq \Omega$

$$\mathcal{F} = \{A, B, \dots\}$$

- Probability measure (probability distribution)

P a function: $\mathcal{F} \rightarrow \mathbb{R}$

that associates with every event A a real number $P(A)$ called its probability.

P must satisfy the following properties

i) $0 \leq P(A) \leq 1 \quad \forall A \in \mathcal{F}$

ii) $P(\Omega) = 1$ & $P(\emptyset) = 0$

iii) For any sequence of pairwise disjoint events A_1, A_2, \dots we have $P(\bigcup_i A_i) = \sum_i P(A_i)$.

If A, B not disjoint, can write $P(A \cup B) = P(A) + P(B) - P(A \cap B)$.
Generalizes to A_1, \dots, A_n as well.

$$P(A_1 \cup \dots \cup A_n) = \sum P(A_i) - \sum_{i < j} P(A_i \cap A_j) + \sum_{i < j < k} P(A_i \cap A_j \cap A_k) - \dots + (-1)^{n+1} P(A_1 \cap \dots \cap A_n)$$

Ex: If modeling a fair die

$$\Omega = \{1, 2, 3, 4, 5, 6\}$$

\mathcal{F} = set of subsets of $\Omega = \{\emptyset, \{1\}, \{2\}, \dots, \{6\}, \{1, 2\}, \dots, \Omega\}$

$$P(\{1\}) = P(\{2\}) = \dots = P(\{6\}) = \frac{1}{6}$$

$$P(\{2, 3\}) = \frac{2}{6}, \text{ etc.}$$

If have a biased die, say the side with 6 is heavy, so lands on 6 more often, could have

$$P(\{1\}) = \dots = P(\{5\}) = \frac{1}{10}, \quad P(\{6\}) = \frac{1}{2}$$

$$P(\{2, 6\}) = \frac{1}{10} + \frac{1}{2}, \text{ etc.}$$

Remark: If Ω is finite, can specify P by giving $P(\omega) \forall \omega \in \Omega$. These determine P uniquely.
E.g. if we know the prob a die is 1, 2, 3, 4, 5, 6 then know P (die is odd).

Q: What if Ω is infinite?

Ex: Flip a fair coin until 1st head. Count the number of flips.

$$\Omega = \{\infty, 1, 2, 3, \dots\}$$

$$P(k) = P(\text{takes } k \text{ flips to get 1st H}) = \frac{1}{2^k}$$

$$P(\infty) = 1 - \sum_{k \in \mathbb{N}} P(k) = 1 - \sum_{k=1}^{\infty} \frac{1}{2^k} = 0.$$

As in the finite case, P is determined by specifying $P(\omega) \forall \omega \in \Omega$.

Random Variables

Sometimes interested not in the outcome itself, but a number associated with an outcome.

Defn: A random variable (RV) is a function from Ω to \mathbb{R} .

Ex: Roll 2 fair dice. $\Omega = \{(a,b) : a,b \in \{1,\dots,6\}\}$.

random
Variables

- $X_1 =$ outcome of 1st die.
- $X_2 =$ ——— 2nd die.
- $X_3 =$ Sum of the outcomes

$$P(X_3=3) = P(\{(1,2), (2,1)\}) = \frac{2}{36}.$$

$$P(X_1=2, X_3=8) = P(\{(2,6)\}) = \frac{1}{36}.$$

Defn: Let X be a RV. The probability distribution of the RV X is the collection of probabilities $P(X \in B)$ for "reasonable" sets B of real numbers.

Ex1) We say the RV X has the Bernoulli distribution with parameter p if

$$P(X=1)=p, \quad P(X=0)=1-p.$$

(Think of a biased coin with prob. p of heads)

2) We say the RV X has the Binomial distribution with parameters n, p if

$$P(X=m) = \begin{cases} \binom{n}{m} p^m (1-p)^{n-m} & \text{if } 0 \leq m \leq n \\ 0 & \text{otherwise.} \end{cases}$$

(Ex: Toss a Bernoulli(p) coin n times & let X be the number of heads)

3) We say the RV X has the Poisson distribution with parameter λ if

$$P(X=k) = \begin{cases} e^{-\lambda} \frac{\lambda^k}{k!} & \text{if } k \in \mathbb{Z}_{\geq 0} \\ 0 & \text{otherwise.} \end{cases}$$

Ex: Pick a number uniformly at random from $[0,2]$.

x is equally likely to lie anywhere in $[0,2]$.

$P(x \in [a,b]) = ?$ Should be the proportion of $[0,2]$ covered by $[a,b]$ so if $0 \leq a < b \leq 2$ should have $P(x \in [a,b]) = \frac{b-a}{2}$.

We cannot specify such a distribution by specifying $P(X=t) \forall t \in \mathbb{R}$ since $P(X=t) = 0 \forall t$.

Defn: Let X be a RV. If a function f satisfies $P(X \leq b) = \int_{-\infty}^b f(x) dx \quad \forall b \in \mathbb{R}$,

then f is called the prob. density func (pdf) of X .

For such an f , $P(X \in B) = \int_B f(x) dx$.

Ex: If $X \sim \text{Uniform}[0,2]$, then $f(x) = \frac{1}{2} \mathbb{1}_{[0,2]}$ is a pdf for X .

Remark: If X has a pdf, then $P(X=b) = 0 \quad \forall b \in \mathbb{R}$.

Q: Which f 's can be pdf's?

A: Any $f \geq 0$ s.t. $\int_{-\infty}^{\infty} f(x) dx = 1$ (since that is $P(X \in (-\infty, \infty)) = P(\mathbb{R})$)

A useful object to describe the distribution of a RV whether it is discrete, has density, or neither, is the cumulative distribution function (c.d.f.) defined by

$$F_X(t) := P(X \leq t).$$

If X has density $f_X(t)$ then $f_X(t) = F'_X(t)$.

Ex1 A RV Z has the normal distr with parameters μ, σ^2 , $Z \sim N(\mu, \sigma^2)$ if Z has density

$$f_Z(t) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(t-\mu)^2}{2\sigma^2}}$$

The case $\mu=0, \sigma=1$ is called the standard normal & the density denoted $\phi(t) = \frac{1}{\sqrt{2\pi}} e^{-t^2/2}$.

Q: Is $f_Z(t)$ a density? Clearly $f_Z(t) \geq 0$, so is $\int f_Z(t) dt = 1$?

By a change of variable it is enough to do the \mathbb{R}^2 case of $N(0,1)$.

$$\begin{aligned} \left(\int \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx \right)^2 &= \int \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx \int \frac{1}{\sqrt{2\pi}} e^{-\frac{y^2}{2}} dy = \frac{1}{2\pi} \iint e^{-\frac{x^2+y^2}{2}} dx dy \\ &= \frac{1}{2\pi} \int_0^{2\pi} \int_0^\infty e^{-\frac{r^2}{2}} r dr d\theta = \frac{1}{2\pi} \int_0^{2\pi} d\theta \int_0^\infty e^{-\frac{r^2}{2}} r dr = \frac{1}{2\pi} \cdot 2\pi \int_0^\infty e^{-s} ds = 1. \end{aligned}$$

Ex: A RV X has the exponential distribution with parameter λ if it has density

$$f(t) = \begin{cases} \lambda e^{-\lambda t}, & t \geq 0 \\ 0, & t < 0. \end{cases}$$

Independence

Defn: Events A, B are called independent if $P(A \cap B) = P(A)P(B)$.

Defn: Events A_1, \dots, A_n are independent if
$$P(A_{i_1} \cap \dots \cap A_{i_k}) = P(A_{i_1}) \dots P(A_{i_k})$$

for all $1 \leq i_1 < i_2 < \dots < i_k \leq n$.

Remark: A_1, \dots, A_n indep is not the same as
 A_i, A_j indep $\forall i, j$.

Ex: Toss a fair coin 3 times.

A_1 - event 1st 2 match

A_2 - event last 2 match

A_3 - event 1st & last match.

A_1, A_2, A_3 - pairwise indep. but A_1, A_2, A_3 not indep.

Defn: Random variables X_1, X_2, \dots, X_n are indep
iff $\forall B_1, \dots, B_n \subseteq \mathbb{R}$, the events
 $X_1 \in B_1, \dots, X_n \in B_n$ indep.

I.e. $\forall 1 \leq i_1 < \dots < i_k \leq n$,

$$P(X_{i_1} \in B_{i_1}, \dots, X_{i_k} \in B_{i_k}) = \prod_{l=1}^k P(X_{i_l} \in B_{i_l}).$$

Ex: If X_1, X_2, \dots, X_n indep Bernoulli(p), then
 $S_n = X_1 + \dots + X_n \sim \text{Binomial}(n, p)$

Expectation

Defn: Let X be a discrete RV.

The expected value of X , EX is defined to be

$$EX = \sum_t t P(X=t) \quad \text{where the sum ranges over the possible values of } X$$

If X has density f , then EX is defined as

$$EX = \int_{\mathbb{R}} t f(t) dt.$$

Think of EX has follows: If you "measured" X a lot of times, it would be EX on average.

The precise statement behind that is

Thm: (The weak law of large numbers)

Let X_1, X_2, \dots be independent, identically distributed (i.i.d.) random variables with finite expectation.

Let $S_n = X_1 + \dots + X_n$ & $\mu = EX_1$. Then

$$\frac{S_n}{n} \xrightarrow[\text{in probability}]{P} \mu$$

$$\text{i.e. } \forall \varepsilon > 0, P\left(\left|\frac{S_n}{n} - \mu\right| > \varepsilon\right) \xrightarrow[n \rightarrow \infty]{} 0.$$

Given a s'ce of RVs X_1, X_2, X_3, \dots , what does it mean for X_1, X_2, X_3, \dots to converge to a RV X ?

Def: A sequence of RVs X_1, X_2, \dots w to a RV X in probability if $\forall \varepsilon > 0$

$$P(|X_n - X| > \varepsilon) \xrightarrow[n \rightarrow \infty]{} 0.$$

We write this as $X_n \xrightarrow{P} X$.

Def: A sequence of RVs X_1, X_2, \dots w to a RV X (all defined on the same space Ω) almost surely if

$$P\left(\lim_{n \rightarrow \infty} X_n = X\right) = 1$$

$$P\left(\left\{\omega : \lim_{n \rightarrow \infty} X_n(\omega) = X(\omega)\right\}\right) = 1.$$

Write as $X_n \xrightarrow{\text{a.s.}} X$

Def: A sequence of RVs X_1, X_2, \dots conv to a RV X in distribution if

$$\lim_{n \rightarrow \infty} F_{X_n}(t) = F_X(t) \quad \forall t \text{ where } F_X(t) \text{ is cts,}$$

where $F_X(t)$ stands for the cdf of a RV X

i.e. $F_X(t) := P(X \leq t)$.

Write as $X_n \xrightarrow{d} X$.

Def: A sequence of RVs X_1, X_2, \dots conv to X (all defined on the same space) if

$$\lim_{n \rightarrow \infty} E(|X_n - X|^p) = 0.$$

Thm: Suppose X_1, X_2, \dots, X are RVs defined on the same space (Ω, \mathcal{F}, P) . Then

$$\begin{array}{lcl} X_n \xrightarrow{\text{as.}} X & \Rightarrow & X_n \xrightarrow{P} X \Rightarrow X_n \xrightarrow{d} X \\ X_n \xrightarrow{L^p} X & \Rightarrow & \end{array}$$

Exercise: For all other implications come up with examples that show they fail.