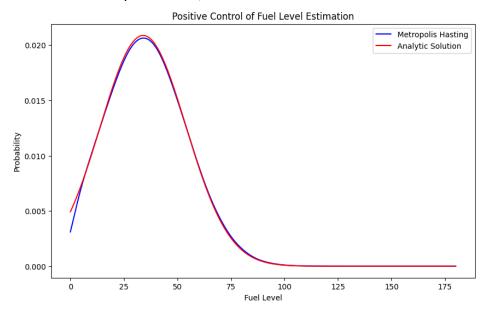
## Problem Set #4: Markov Chain Monte Carlo

To implement a Metropolis Hasting algorithm for the fuel level in problem set 3, I used the same prior and likelihood function, but a different sampling strategy:

- 1. The initial fuel level was selected randomly from a uniform distribution from 0 to 182.
- 2. The next sample was selected by sampling from a normal distribution with a mean of the current sample and a standard deviation of 90 (selected based on trial and error to get an acceptance rate of 24.7%, which is close to, but above 23.4%).
- 3. Then an acceptance threshold was chosen from a uniform distribution from 0 to 1.
- 4. If the ratio of the posterior at the new sample divided by the posterior of the current sample was at or above the threshold, then the new sample was adopted. Otherwise, the current sample remained.
- 5. Steps 2-4 were repeated for 3 million samples, which was the lowest number tested to reach convergence. To test convergence, I calculated the confidence interval and was using a threshold of 0.05 based on the example given in Workflow Example.R.

The required number of runs to reach convergence was actually the same for MCMC and Bayes Monte Carlo, which I found surprising, since I know that MCMC is supposed to be more efficient. This may be a sign that the model was not properly tuned.

To compare the accuracy of the implemented method to a positive control, I used a kernel density estimator to get a pdf from the MCMC samples. I then plotted the pdf against the analytical solution, which would be a normal distribution ( $\mu$  = 34 I,  $\sigma$  = 20 I) that is cut off at 0 I and 180 I and normalized. As you can see, the result deviates the most at 0 L.



## Reproducibility:

The analysis is reproducible. The code is thoroughly commented, has a starting seed of 42 for the random number generation, and is available on GitHub at:

https://github.com/alexis-hudes/BayesianHW4.git

## **Appendix: Code**

Note: this is Python code, not R

```
Bayesian HW Set 4: Markov Chain Monte Carlo
## author: Alexis Hudes
## copyright by the author
## distributed under the GNU general public license
## https://www.gnu.org/licenses/gpl.html
import numpy as np
import matplotlib.pyplot as plt
from scipy.stats import norm, gaussian kde, t
from scipy.integrate import cumtrapz
from scipy.interpolate import interp1d
from scipy.stats import truncnorm
import random
np.random.seed(42)
n = 3*10**6
def prior(x):
def likelihood(x):
   return norm.pdf(x, loc=34, scale=20)
```

```
def met(n, init):
  current sample = init
  for i in range(n):
      proposed_sample = np.random.normal(current_sample, 90)
      current likelihood = likelihood(current sample) * prior(current sample)
      proposed_likelihood = likelihood(proposed_sample) * prior(proposed_sample)
      acceptance ratio = proposed likelihood / current likelihood
      if np.random.rand() < acceptance_ratio:</pre>
          current_sample = proposed_sample
          accept.append(1)
          accept.append(0)
      if i > n*0.01:
          samples.append(current sample)
  return np.array(samples), accept
samples MH, acceptance = met(n, np.random.uniform(low=0, high=182))
aceptance rate=sum(acceptance)/len(acceptance)
print("The acceptance rate is:", aceptance rate)
plt.hist(samples MH, bins=50, density=True, alpha=0.4, edgecolor='black')
```

```
plt.title('Metropolis-Hastings Sampling')
plt.xlabel('Fuel Level')
plt.ylabel('Probability')
plt.show()
plt.close()
workflow.r
def check_convergence(chain, threshold):
   if ci <= threshold:</pre>
converged = check convergence(samples MH, threshold=0.05)
if converged:
else:
#Positive Control
kde = gaussian kde(samples MH, bw method=0.2)
x = np.linspace(0, 180, 1000)
kde_pdf = kde.evaluate(x)
```

```
# Analytical truncated normal distribution

a, b = (0 - 34) / 20, (180 - 34) / 20

trunc_normal_pdf = truncnorm.pdf(x, a, b, loc=34, scale=20)

# Plot the KDE and truncated normal pdfs

plt.figure(figsize=(10, 6))

plt.plot(x, kde_pdf, label='Metropolis Hasting', color='blue')

plt.plot(x, trunc_normal_pdf, label='Analytic Solution', color='red')

plt.title("Positive Control of Fuel Level Estimation")

plt.xlabel("Fuel Level")

plt.ylabel("Probability")

plt.legend()

plt.show()

plt.close()
```