

System's percepts

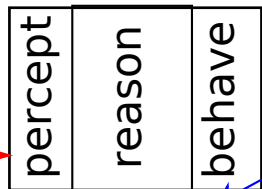
Global reasoning

System's decision

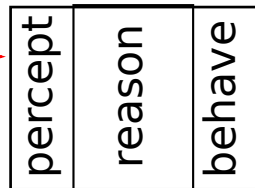
gaze
direction

position
in space

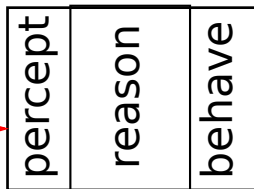
feedback



$M_R[R]$



$M_R[H]$



$M_R[HR]$

exaggerate
a gesture