# Alexis Cruz-Ayala

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#### **EDUCATION**

## Duke University | Durham, NC | Graduation Expected in May 2025 | Current GPA: 3.96

- Majors: Electrical and Computer Engineering (B.S.E.), Computer Science (B.S.)
- Minors: Mathematics, Machine Learning and Artificial Intelligence
- Questbridge National College Match Recipient | Gates Scholarship Recipient
- Relevant coursework: Operating Systems, Software Design & Implementation, Computer Systems/Architecture, Data Structures & Algorithms, Linear Algebra

### **SKILLS**

Software Development: Model-Based Systems Engineering, API-First Development, SCRUM/AGILE, Unit Testing

Hardware: Raspberry Pi, Arduino, Jetson Nano, Intel Realsense Cameras, FPGA, Verilog, Teensy

**Platforms:** Linux, GitHub, Gitlab, **Languages:** Spanish, Chinese

Programming: Java, C++, Python, C, MATLAB, x86 Assembly, Rust Lang, Ruby, Node.js, JavaScript, Go, Simulink

**Machine Learning:** TensorFlow, Pytorch, Sklearn, Keras, OpenCV, Theano **Communication**: Technical Reports, Documentation, Presentations

### **WORK EXPERIENCE**

#### **U.S. Department of Energy | Robotics Engineer Intern**

Miami, FL | May 2022 - Aug 2022

- Derived and simulated an updated admittance control algorithm using MATLAB and Simulink for an exoskeleton used in nuclear waste management
- Implemented the admittance control into a raspberry pi in C++ to operate Maxon motors through a CAN-bus, and integrated all I2C sensors to record human-computer interaction
- Designed and built a fundamental exoskeleton system (operating in 1 DOF) for investigating future control algorithms and studying human-computer response using the simplest model possible. The setup is still in use today

#### **Duke Robotics | Robotics and Embedded Systems Researcher**

Durham, NC | Dec 2021 - Jun 2022

- Designed a drone cyber-physical system meant for trajectory planning, with the intent that it would be used to study autonomous vehicles' susceptibility to different cyber-security attacks
- Programmed a simple deep reinforcement learning algorithm using TensorFlow, running on an Nvidia Jetson with an Intel Realsense D435 camera
- Documented and properly maintained Python code using Agile software development
- Both the code and drone have been used as frameworks for future projects in the laboratory since its inception

## Matrix Labs | Systems Software Developer

Miami, FL | Jun 2019 - Aug 2019

Member | 2022 - Present

Member | 2022 - Present

Member | 2021 - Present

President | 2021 - Present

Team Captain | 2017 - 2021

- Created and documented an accessible API for using ESP32 capabilities on the company's own development boards
- Built projects and made tutorials on Hackster.io using the Matrix devices with the above API, thus fostering community engagement and greater sales
- Made tutorials on how to use the onboard FPGA of the Matrix Creator, as well as live-streams teaching others how to get started with Verilog and digital systems development

#### **ORGANIZATIONS**

Duke IEEE Student Group Combat Robotics Society of Hispanic Professional Engineers Academy Of Model Aeronautics FIRST Robotics Competition