

• Momentum conservation

$$\frac{d\mathbf{p}_{\text{mech}}}{dt} = -\epsilon_0\mu_0 \frac{d}{dt} \int_V \mathbf{S} d\tau + \oint_S \mathbf{T} \cdot d\mathbf{a},$$

$$d\mathbf{a} = \hat{n} da$$

$$T_{ij} = \epsilon_0 (E_i E_j - \frac{1}{2} E^2 \delta_{ij}) + \frac{1}{\mu_0} (B_i B_j - \frac{1}{2} B^2 \delta_{ij})$$

Let $\vec{E} = E \hat{x}$, $\vec{B} = B \hat{y}$ (WLOG), xy -plane 이 대칭. 진행방향 $\parallel \hat{z}$

i) $\Rightarrow T_{33}$ 값이 기여한다. ($E_z, B_z = 0$)

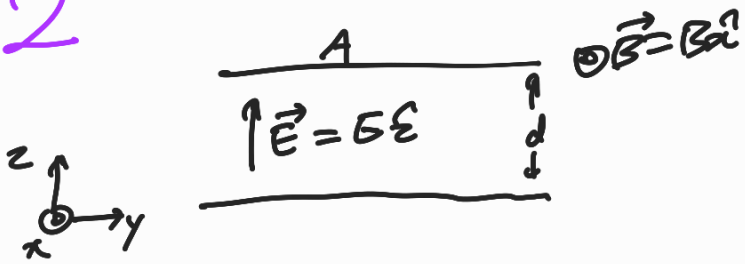
ii) $\& \epsilon_0\mu_0 \frac{d}{dt} \int_V \vec{S} d\tau = \frac{d}{dt} \int_V \epsilon_0 (\vec{E} \times \vec{B}) d\tau \propto \Delta z \rightarrow 0$

\therefore 단위시간당 단위면적당 plane wave가 주는 힘

\equiv Radiation pressure

$$= \mathbf{T} \cdot (-\hat{z}) = -T_{33} = \underline{\frac{1}{2} (\epsilon_0 E^2 + \frac{1}{\mu_0} B^2)} = \underline{\text{field energy density}} \square$$

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$$a) \vec{P} = \epsilon_0 (\vec{E} \times \vec{B}) = \epsilon_0 EB \hat{y}$$

$$\Rightarrow \vec{P} = \epsilon_0 EBAd \hat{y}$$

$$b) \text{ discharge: } \vec{E} = E\hat{z} \rightarrow 0$$

current \$\propto E\$

$$\Rightarrow \vec{F} = i \vec{L} \times \vec{B} = i d B \hat{y}$$

$$\Rightarrow \underline{\text{Impulse}} = \int \vec{F} dt = \hat{y} dB \int i dt = dB \times (\text{total charge}) \hat{y}$$

$$= dB \times \epsilon_0 \frac{A}{d} \times Ed \hat{y} = \underline{\epsilon_0 EBAd \hat{y}}$$

$$3_{(a)} \frac{dW}{dt} = \int_V (\vec{E} \cdot \vec{J}_f) d\tau, \quad \vec{J}_f = \vec{\nabla} \times \vec{H} - \frac{\partial \vec{D}}{\partial t}, \quad \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\begin{aligned} \Rightarrow \vec{E} \cdot \vec{J}_f &= \vec{E} \cdot (\vec{\nabla} \times \vec{H}) - \vec{E} \cdot \frac{\partial \vec{D}}{\partial t} \\ &= \vec{H} \cdot (\vec{\nabla} \times \vec{E}) - \vec{\nabla} \cdot (\vec{E} \times \vec{H}) - \vec{E} \cdot \frac{\partial \vec{D}}{\partial t} \\ &= - \left(\vec{E} \cdot \frac{\partial \vec{D}}{\partial t} + \vec{H} \cdot \frac{\partial \vec{B}}{\partial t} + \vec{\nabla} \cdot (\vec{E} \times \vec{H}) \right) \end{aligned}$$

$$\Rightarrow \frac{dW}{dt} = - \int_V \left(\vec{E} \cdot \frac{\partial \vec{D}}{\partial t} + \vec{H} \cdot \frac{\partial \vec{B}}{\partial t} \right) d\tau - \oint_S \underbrace{(\vec{E} \times \vec{H})}_{\vec{S}} \cdot d\vec{a}$$

$$\therefore \underline{\vec{S} = \vec{E} \times \vec{H}}, \quad \underline{\frac{dW}{dt} = \vec{E} \cdot \frac{\partial \vec{D}}{\partial t} + \vec{H} \cdot \frac{\partial \vec{B}}{\partial t}} \quad \square$$

Linear media: $\vec{D} = \epsilon \vec{E}, \quad \vec{H} = \frac{1}{\mu} \vec{B}, \quad \epsilon, \mu : \text{const. in time}$

$$\Rightarrow \frac{dW}{dt} = \epsilon \vec{E} \cdot \frac{\partial \vec{E}}{\partial t} + \frac{1}{\mu} \vec{B} \cdot \frac{\partial \vec{B}}{\partial t} = \frac{1}{2} \frac{d}{dt} \left(\epsilon E^2 + \frac{1}{\mu} B^2 \right)$$

$$\Rightarrow \underline{W = \frac{1}{2} \epsilon E^2 + \frac{1}{2\mu} B^2 = \frac{1}{2} (\vec{E} \cdot \vec{D} + \vec{B} \cdot \vec{H})} \quad \square$$

$$(b) \vec{f} = \rho \vec{E} + \vec{J}_f \times \vec{B} = (\vec{\nabla} \cdot \vec{D}) \vec{E} + (\vec{\nabla} \times \vec{H} - \frac{\partial \vec{D}}{\partial t}) \times \vec{B},$$

using $\frac{\partial}{\partial t} (\vec{D} \times \vec{B}) = \frac{\partial \vec{D}}{\partial t} \times \vec{B} + \vec{D} \times \frac{\partial \vec{B}}{\partial t}$ & adding $\vec{H}(\vec{\nabla} \cdot \vec{B})$

$$\begin{aligned} \rightarrow \vec{f} &= \vec{E}(\vec{\nabla} \cdot \vec{D}) + (\vec{\nabla} \times \vec{H}) \times \vec{B} + \vec{H}(\vec{\nabla} \cdot \vec{B}) + \vec{D} \times \frac{\partial \vec{B}}{\partial t} - \frac{\partial}{\partial t} (\vec{D} \times \vec{B}) \\ &= \underline{\vec{E}(\vec{\nabla} \cdot \vec{D}) - \vec{D} \times (\vec{\nabla} \times \vec{E}) + \vec{H}(\vec{\nabla} \cdot \vec{B}) - \vec{B} \times (\vec{\nabla} \times \vec{H})} - \frac{\partial}{\partial t} (\vec{D} \times \vec{B}) \\ &\quad \text{divergence of stress tensor} \quad \text{momentum density} \end{aligned}$$

$$\therefore \underline{\vec{g} = \vec{D} \times \vec{B}} \quad \square$$

$$4. \hat{A}_3 = \hat{A}_1 + \hat{A}_2, \quad A_3 e^{i\delta_3} = A_1 e^{i\delta_1} + A_2 e^{i\delta_2}$$

$$|A_3|^2 = (A_1 e^{i\delta_1} + A_2 e^{i\delta_2})(A_1 e^{-i\delta_1} + A_2 e^{-i\delta_2})$$

$$= |A_1|^2 + |A_2|^2 + 2A_1 A_2 \cos(\delta_1 - \delta_2)$$

$$\Rightarrow A_3 = \sqrt{|A_1|^2 + |A_2|^2 + 2A_1 A_2 \cos(\delta_1 - \delta_2)}$$

$$\Rightarrow e^{i\delta_3} = \left(\frac{A_1}{A_3}\right) e^{i\delta_1} + \left(\frac{A_2}{A_3}\right) e^{i\delta_2}$$

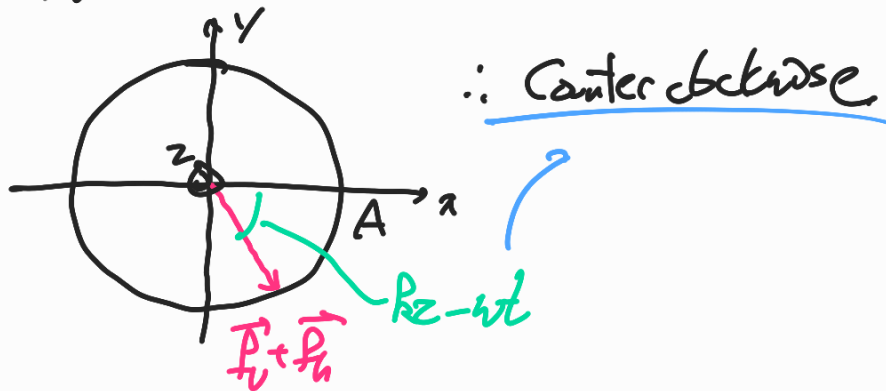
$$\Rightarrow \tan \delta_3 = \frac{\text{Im}(e^{i\delta_3})}{\text{Re}(e^{i\delta_3})} = \frac{A_1 \sin \delta_1 + A_2 \sin \delta_2}{A_1 \cos \delta_1 + A_2 \cos \delta_2}$$

$$\therefore \delta_3 = \tan^{-1} \left[\frac{A_1 \sin \delta_1 + A_2 \sin \delta_2}{A_1 \cos \delta_1 + A_2 \cos \delta_2} \right]$$

5(a) $\vec{P}_v = A \cos(kz - \omega t + \phi_v) \hat{x}$, $\vec{P}_h = A \cos(kz - \omega t + \phi_h) \hat{y}$

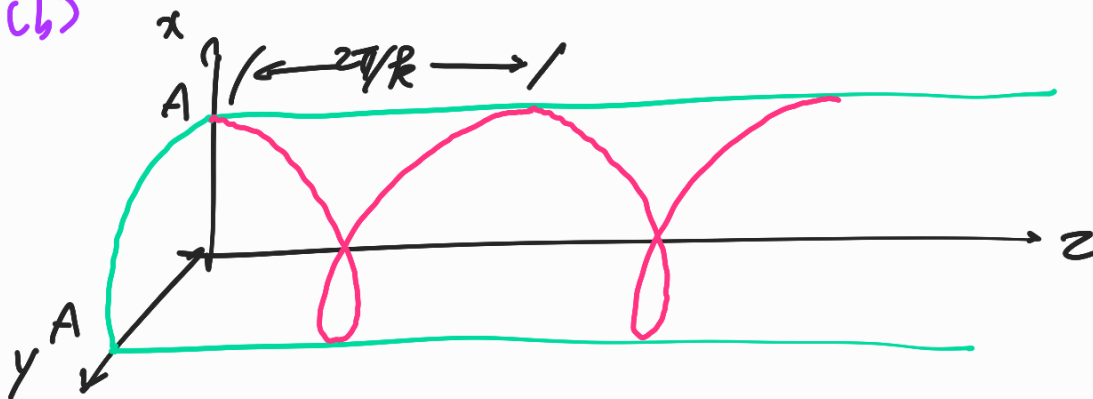
$\Rightarrow \vec{P}_v = A \cos(kz - \omega t) \hat{x}$, $\vec{P}_h = -A \sin(kz - \omega t) \hat{y}$

$|\vec{P}_v|^2 + |\vec{P}_h|^2 = A^2 \dots \text{circle}$



If $\phi_h - \phi_v = -90^\circ$, a wave circles clockwise

6b)



$$6 \quad \vec{E}(r, \theta, \phi, t) = A \frac{\sin \theta}{r} [\cos(Rr - \omega t) - \frac{1}{Rr} \sin(Rr - \omega t)] \hat{\phi}, \quad \frac{\omega}{R} = c$$

$\equiv u$
 $\equiv E\hat{\phi}$

$$(i) \quad \vec{\nabla} \cdot \vec{E} = \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} = 0 \quad \checkmark$$

$$(ii) \quad -\frac{\partial \vec{B}}{\partial t} = \vec{\nabla} \times \vec{E} = \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta E) \hat{r} - \frac{1}{r} \frac{\partial}{\partial r} (rE) \hat{\theta}$$

$$= A \left[\frac{2 \cos \theta}{r^2} \left(\cos u - \frac{1}{Rr} \sin u \right) \right] \hat{r}$$

$$+ A \left[\frac{\sin \theta}{r} \left[\left(R - \frac{1}{Rr^2} \right) \sin u + \frac{1}{r} \cos u \right] \right] \hat{\theta}$$

$$\Rightarrow \vec{B} = \frac{2A \cos \theta}{\omega r^2} \left(\sin u + \frac{1}{Rr} \cos u \right) \hat{r} + \frac{A \sin \theta}{\omega r} \left(\left(-R + \frac{1}{Rr^2} \right) \cos u + \frac{1}{r} \sin u \right) \hat{\theta}$$

$$(iii) \quad \vec{\nabla} \cdot \vec{B} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 B_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta B_\theta)$$

$$= \frac{2A \cos \theta}{\omega r^2} \left(R \cos u - \frac{1}{r} \sin u - \frac{1}{Rr^2} \cos u \right)$$

$$+ \frac{2A \cos \theta}{\omega r^2} \left(\left(-R + \frac{1}{Rr^2} \right) \cos u + \frac{1}{r} \sin u \right) = 0 \quad \checkmark$$

$$(iv) \quad \vec{\nabla} \times \vec{B} = \frac{1}{r} \left(\frac{\partial}{\partial r} (r B_\theta) - \frac{\partial B_r}{\partial \theta} \right) \hat{\phi}$$

$$= \frac{A \hat{\phi}}{\omega r} \left[\sin \theta \left[\left(R^2 - \frac{1}{r^2} \right) \sin u + \frac{R}{r} \cos u - \frac{2}{Rr} \cos u - \frac{1}{r^2} \sin u \right] + \frac{2 \sin \theta}{r^2} \left(\sin u + \frac{1}{Rr} \cos u \right) \right]$$

$$= \frac{A \sin \theta}{c r} \left[R \sin u + \frac{1}{r} \cos u \right] \hat{\phi} \quad \checkmark$$

$$\frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} = \frac{A \sin \theta}{c^2 r} \omega \left[\sin u + \frac{1}{Rr} \cos u \right] \hat{\phi}$$

$$b) \vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B} = \frac{E}{\mu_0} (B_r \hat{\theta} - B_\theta \hat{r})$$

$$= \frac{A^2 \sin \theta}{\mu_0 r^2} \left[\frac{2 \cos \theta}{r} \left(\frac{1}{R_r} (\cos^2 u - \sin^2 u) + \left(1 - \frac{1}{R_r^2}\right) \cos u \sin u \right) \hat{\theta} - \sin \theta \left(\left(-R + \frac{1}{R_r^2}\right) \cos^2 u - \frac{1}{R_r^2} \sin^2 u + \left(\frac{2}{r} - \frac{1}{R_r^2}\right) \cos u \sin u \right) \hat{r} \right]$$

$$\vec{I} = \langle \vec{S} \rangle, \quad \langle \cos^2 u \rangle = \langle \sin^2 u \rangle = \frac{1}{2}, \quad \langle \cos u \sin u \rangle = 0$$

$$\Rightarrow \vec{I} = \frac{A^2 \sin \theta}{\mu_0 r^2} (-\sin \theta) \left(-\frac{1}{2} R \right) \hat{r} = \frac{A^2 \sin^2 \theta}{2 \mu_0 c r^2} \hat{r}$$

$$c) \int_{r=R} \vec{I} \cdot d\vec{\omega} = \int_{r=R} r^2 I d\Omega = \frac{A^2}{2 \mu_0 c} \int_0^\pi \sin^2 \theta (2\pi \sin \theta d\theta)$$

$$= \frac{4\pi}{3} \cdot \frac{A^2}{\mu_0 c}$$