

Numerical Methods Exercise 3

1) Show that the rotation matrix from the Jacobi algorithm is orthogonal.

Let $Q_{pq} = B$ an identity matrix but with

$$(B)_{pp} = (B)_{qq} = c \quad (B)_{pq} = -s \quad (B)_{qp} = s.$$

checking if $B \cdot B^T = I$ also means to check if the row vectors are orthonormal. Let v_i be a row vector at i .

$$\text{for } v_p \cdot v_q = cs - c^2 = 0, \quad v_p \cdot v_p = c^2 + s^2 = \frac{1+c}{2} + \frac{1-c}{2} = 1$$

for every i, j s.t. $i, j \neq p, q$ we have vectors with 1 at i, j

$$\text{then } v_i \cdot v_j = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$$

and v_i fulfills all the orthonormal requirements

for B to be $B \cdot B^T = I$

2

Calculates the eigenvalues of a given matrix using the Jacobi algorithm.

Run code at jacobi.py using python(3), (it uses numpy and numpy.linalg) use `test_jacobi()` to print eigenvalues of 4 matrices using Jacobi algo and numpy's linalg package.

B

The output of `test_jacobi` for 3 predefined matrices, and one randomly generated 10 x 10 are:

```
For the matrix
[[ 1  2  3]
 [ 2  3 -10]
```

```
[ 3 -10  3]]
the jacobi eigenvalues are: [13.04378227  2.29769964 -8.34148191]
while the result from numpy's linalg is: [-8.34148191  2.29769964
13.04378227]
```

For the matrix

```
[[ 1  5 200 100]
 [ 5  2  0  0]
 [200  0  3  0]
 [100  0  0  5]]
the jacobi eigenvalues are: [ 225.86701533  4.60007698
2.00057659 -221.46766891]
```

while the result from numpy's linalg is: [-221.46766891
225.86701533 4.60007698 2.00057659]

For the matrix

```
[[ 1  0  0 100]
 [ 0  2  0  0]
 [ 0  0  3 10]
 [100  0 10  5]]
the jacobi eigenvalues are: [103.52855059  2. 2.98020586
-97.50875645]
```

while the result from numpy's linalg is: [103.52855059 -97.50875645
2.98020586 2.]

For the matrix

```
[[ -56.  -34.5 -47.   64.5 -90.5   7.   14.  -88.   16.5 -59. ]
 [ -34.5  46.   46.  -83.5   4.5 -61.  -4.5   9.5  32.   4.5]
 [ -47.   46.  -35.  -18.5  22.   48.  -54.  -66.5 -56.5  43.5]
 [  64.5 -83.5 -18.5  70.    1.5  29.   68.5  54.   27.5 -29.5]
 [ -90.5   4.5  22.    1.5 -89.  -25.5  -5.5 -22.  -21.5   0. ]
 [   7.  -61.   48.   29.  -25.5  37.    7.5 -52.  -38.5 -56. ]
 [  14.  -4.5 -54.   68.5  -5.5   7.5  13.   53.   64.5  21. ]
 [ -88.    9.5 -66.5  54.  -22.  -52.   53.   90.  -15.   1.5]
 [  16.5  32.  -56.5  27.5 -21.5 -38.5  64.5 -15.  -31.  -39.5]
 [ -59.    4.5  43.5 -29.5   0.  -56.   21.    1.5 -39.5 -73. ]]
```

```
the jacobi eigenvalues are: [ 247.74302641  200.44069249
97.25290829  13.62744394 -3.64339941
-27.441335  -51.69562761 -113.21591146 -164.50171125 -226.5660864
]
```

while the result from numpy's linalg is: [247.74302641 200.44069249
-226.5660864 97.25290829 -164.50171125
-113.21591146 -51.69562761 -27.441335 13.62744394
-3.64339941]

And we can clearly see that the jacobi method gives exact results compared to the package which actually uses lapack's `_geev` behind the scenes.

I don't see any difference, the 1st problem did state that it fits for small symmetric matrices, hence I used small ones.

3

Run using python(3), prerequisites are again numpy.
Matrices are generated randomly for values between [-100, 100]

B

Calculated using the `err_propag_stats(N, dq)` func.

For N=20, dq=1

The error propag mean: 0.00025601637591712547, standard deviation:
5.4375039899289913e-05

For N=12, dq=0.1

The error propag mean: 0.0005409561519609541, standard deviation:
0.000196768770406304

For N=10, dq=0.001

The error propag mean: 0.0007649821110136015, standard deviation:
0.0002642929156775915

For N=9, dq=2

The error propag mean: 0.0008423355300222206, standard deviation:
0.000297719902599775

I don't see any out of the ordinary error propagations, trying more extreme values I get

For N=30, dq=20

The error propag mean: 0.00014197612235776312, standard deviation:
2.47973311674375e-05

I do see that the mean of the propagation factor grows smaller as we introduce a bigger dq