

A Disk Model Version of Hejhal's Algorithm

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Note: These are pretty old notes. While I do believe they are correct, we use the less common definition which takes $\Delta = -y^2(\partial_{xx} + \partial_{yy})$. I had done this because it makes the operator Δ positive definite.

Instead, most authors take $\Delta = y^2(\partial_{xx} + \partial_{yy})$ but define the λ values by the equation $\Delta u + \lambda u = 0$. In either case, the values of interest λ are strictly positive.

I should update these notes at some point to match the convention.

1 Fourier Expansion in the Disk Model

Recall that we can map our work in the upper half plane to the unit disk via

$$z \mapsto \frac{z - i}{z + i}$$

(The inverse map is $\tau \mapsto i(1 + \tau)/(1 - \tau)$, where τ is taken in the unit disk).

The new idea here is to apply Hejhal's algorithm to the fundamental domain in \mathbb{D} . To do this, we begin by writing a Maass form f in polar form $f(\rho, \theta)$. Then f is 2π -periodic in θ , and so it has a Fourier expansion

$$f(\rho, \theta) = \sum_n a_n(\rho) \exp(in\theta)$$

Next, since f is a Maass form, it is an eigenfunction of the hyperbolic Laplace operator, say $\Delta f = s(1 - s)f$. After mapping to \mathbb{D} and converting to polar coordinates, this operator is

$$\Delta = - \left(\frac{(1 - \rho^2)^2}{4} \frac{\partial^2}{\partial \rho^2} + \frac{(1 - \rho^2)^2}{4\rho} \frac{\partial}{\partial \rho} + \frac{(1 - \rho^2)^2}{4\rho^2} \frac{\partial^2}{\partial \theta^2} \right) \quad (1)$$

If we would like to treat our function with θ taking values in the range $[0, \pi]$, then the operator changes according to the map $\theta \mapsto \theta/2$. The new operator is then

$$\Delta = - \left(\frac{(1 - \rho^2)^2}{4} \frac{\partial^2}{\partial \rho^2} + \frac{(1 - \rho^2)^2}{4\rho} \frac{\partial}{\partial \rho} + \frac{(1 - \rho^2)^2}{16\rho^2} \frac{\partial^2}{\partial \theta^2} \right)$$

This version is often used when one identifies the upper half plane with $PSL(2, \mathbb{R})$, for then the θ in the KAK decomposition corresponds to half of the polar θ .

Applying (1) to the Fourier expansion, then using uniqueness of Fourier coefficients, we have that the $a_n(\rho)$'s satisfy the differential equation

$$\frac{(1 - \rho^2)^2}{4} a_n''(\rho) + \frac{(1 - \rho^2)^2}{4\rho} a_n'(\rho) - \frac{n^2(1 - \rho^2)^2}{4\rho^2} a_n(\rho) = s(s - 1)a_n(\rho)$$

This equation has solution

$$a_n(\rho) = a_n(1 - \rho^2)^s \rho^{|n|} {}_2F_1(s, s + |n|, 1 + |n|; \rho^2) \quad (2)$$

where ${}_2F_1$ is a hypergeometric function.

To get a linear system, we first approximate f by a finite Fourier expansion with $|n| \leq M$ (we are no longer assuming f is a cusp form). We choose M large enough that

$$f(\rho, \theta) = \sum_{|n| \leq M} a_n(\rho) \exp(in\theta) + E(\rho)$$

where $E(\rho)$ is “small” (like, smaller than 10^{-D} if we are looking for D digits of precision). The reason we can make this error small is that the $a_n(\rho)$ ’s are decaying exponentially as $|n| \rightarrow \infty$.

Next, we fix a distance $\rho = P$ from the origin and take $N \geq 2M + 1$ equally spaced θ ’s to produce sample points. For example, we could take the points (P, θ_j) where

$$\theta_j = \frac{2\pi}{N} \left(j + \frac{1}{2} \right) \quad \text{for } 0 \leq j < N$$

We can then extract an expression for the Fourier coefficients by taking an appropriate linear combination of the function evaluated at the sample points. This expression is

$$a_n(P) = \frac{1}{N} \sum_{j=0}^{N-1} f(P, \theta_j) e^{-in\theta_j} + E(P)$$

Finally, we can set up a $(2M + 1) \times (2M + 1)$ linear system by using the Γ -automorphicity of f . Let (P_j^*, θ_j^*) be the point in the chosen fundamental domain which is equivalent to $(P, \theta_j) \bmod \Gamma$. Some straightforward computation gives the following system

$$a_n c_n(P) = \sum_{|\ell| \leq M} a_\ell V_{n\ell} + 2E(P)$$

where

$$c_n(\rho) = (1 - \rho^2)^s \rho^{|n|} {}_2F_1(s, s + |n|, 1 + |n|; \rho^2) \quad \text{and} \quad V_{n\ell} = \frac{1}{N} \sum_{j=0}^{N-1} c_\ell(P_j^*) e^{i(\ell\theta_j^* - n\theta_j)}$$

Note: recall that the code is varying the parameter ν in $\lambda = (1/2 + \nu)(1/2 - \nu)$; so we can set $s = 1/2 + \nu$ or $s = 1/2 - \nu$ so that $\lambda = s(1 - s)$.

Since the a_n ’s should give the Fourier coefficients for a Maass form, which is an eigenfunction of the Laplacian, any scalar multiple of these coefficients will be a solution as well. We assume the scaling $a_2 = 1$ then solve the resulting system.

Remark: it is most natural to scale a_2 for the following reason.
FINISH THIS IDEA!

Verification of Formula (1)

In the upper half plane model of hyperbolic space, the Laplace-Beltrami operator is

$$\Delta = -y^2 \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right)$$

where $z = x + iy \in \mathbb{H}$.

We can map from the upper half plane to the unit disk via the conformal map

$$z \mapsto \tau = \frac{z - i}{z + i}$$

Now if we write $\tau = u + iv \in \mathbb{D}$, we can rewrite (u, v) in polar coordinates (ρ, θ) so that

$$u = \rho \cos \theta \quad v = \rho \sin \theta$$

(these are the normal polar coordinates in \mathbb{R}^2).

We can go from (ρ, θ) coordinates to (x, y) coordinates via the formulas

$$x = \frac{-2\rho \sin \theta}{1 + \rho^2 - 2\rho \cos \theta} \quad y = \frac{1 - \rho^2}{1 + \rho^2 - 2\rho \cos \theta}$$

For the other direction, we have

$$\rho = \sqrt{\frac{x^2 + (y-1)^2}{x^2 + (y+1)^2}} \quad \tan \theta = \frac{-2x}{x^2 + y^2 - 1}$$

(Note: the sign of $x^2 + y^2 - 1$ matches the sign of u in (u, v) coordinates in the disk). I wrote some code to verify these formulas.

Next, we wish to rewrite the Laplace-Beltrami operator in our new (ρ, θ) coordinates. To achieve this, let us be very clear about what we are trying to do. If $f : \mathbb{H} \rightarrow \mathbb{C}$ is a function in (x, y) coordinates and $g : \mathbb{D} \rightarrow \mathbb{C}$ is a function in (ρ, θ) coordinates, then we think of f and g as the same function if

$$f(x, y) = g(\rho(x, y), \theta(x, y)) \quad \forall x + iy \in \mathbb{H}$$

Now, the functions we are interested in are those which are differentiable in the \mathbb{R}^2 sense. So by applying the chain rule for functions from \mathbb{R}^2 to \mathbb{R}^2 , we conclude that

$$\begin{aligned} \frac{\partial^2 f}{\partial x^2} &= \frac{\partial^2 \rho}{\partial x^2} \frac{\partial g}{\partial \rho} + \frac{\partial^2 \theta}{\partial x^2} \frac{\partial g}{\partial \theta} + \left(\frac{\partial \rho}{\partial x} \right)^2 \frac{\partial^2 g}{\partial \rho^2} + 2 \frac{\partial \rho}{\partial x} \frac{\partial \theta}{\partial x} \frac{\partial^2 g}{\partial \rho \partial \theta} + \left(\frac{\partial \theta}{\partial x} \right)^2 \frac{\partial^2 g}{\partial \theta^2} \\ \frac{\partial^2 f}{\partial y^2} &= \frac{\partial^2 \rho}{\partial y^2} \frac{\partial g}{\partial \rho} + \frac{\partial^2 \theta}{\partial y^2} \frac{\partial g}{\partial \theta} + \left(\frac{\partial \rho}{\partial y} \right)^2 \frac{\partial^2 g}{\partial \rho^2} + 2 \frac{\partial \rho}{\partial y} \frac{\partial \theta}{\partial y} \frac{\partial^2 g}{\partial \rho \partial \theta} + \left(\frac{\partial \theta}{\partial y} \right)^2 \frac{\partial^2 g}{\partial \theta^2} \end{aligned}$$

In the computation for the Laplacian, we will end up adding these two expressions together. I used sympy (python's symbolic programming package) to do the computations. One finds that

$$\frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} = 0 \quad \text{and} \quad \frac{\partial \rho}{\partial x} \frac{\partial \theta}{\partial x} + \frac{\partial \rho}{\partial y} \frac{\partial \theta}{\partial y} = 0$$

So, the $\partial g / \partial \theta$ and $\partial^2 g / \partial \rho \partial \theta$ terms vanish. For the other three terms, we get

$$\begin{aligned} \frac{\partial^2 \rho}{\partial x^2} + \frac{\partial^2 \rho}{\partial y^2} &= ??? \\ \left(\frac{\partial \rho}{\partial x} \right)^2 + \left(\frac{\partial \rho}{\partial y} \right)^2 &= \frac{4}{(x^2 + (y+1)^2)^2} \\ \left(\frac{\partial \theta}{\partial x} \right)^2 + \left(\frac{\partial \theta}{\partial y} \right)^2 &= \frac{4}{(x^2 + (y-1)^2)(x^2 + (y+1)^2)} \end{aligned}$$

Multiplying by y^2 , then substituting in the expressions for x and y in terms of ρ and θ , we get

$$y^2 \left(\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} \right) = \frac{(1 - \rho^2)^2}{4} \frac{\partial^2 g}{\partial \rho^2} + (???) \frac{\partial g}{\partial \rho} + \frac{(1 - \rho^2)^2}{4\rho^2} \frac{\partial^2 g}{\partial \theta^2}$$

It turns out sympy has a little trouble with one of the terms, but following the pattern and plugging in a few test points suggests that the missing piece should be $(1 - \rho^2)^2 / 4\rho$.

Verification of Formula (2)

In the literature, it is claimed that the differential equation

$$\frac{(1-\rho^2)^2}{4}a_n''(\rho) + \frac{(1-\rho^2)^2}{4\rho}a_n'(\rho) - \frac{n^2(1-\rho^2)^2}{16\rho^2}a_n(\rho) = s(1-s)a_n(\rho) \quad (3)$$

has solution

$$a_n(\rho) = (1-\rho^2)^s \rho^{|n|} {}_2F_1(s, s+|n|, 1+|n|; \rho^2) \quad (4)$$

We will first verify this, as it is a simple change of variables to verify our solution (2).

An Aside on the Hypergeometric Function

Here, we list a few properties of the hypergeometric function which we shall use. The hypergeometric function ${}_2F_1$ is defined for $|z| < 1$ by

$${}_2F_1(a, b, c; z) = \sum_{n=0}^{\infty} \frac{(a)_n (b)_n}{(c)_n} \frac{z^n}{n!}$$

where $(q)_n$ is the Pochhammer symbol

$$(q)_n = \begin{cases} 1 & n = 0 \\ q(q+1) \cdots (q+n-1) & n \neq 0 \end{cases}$$

It can also be defined as a solution to the differential equation

$$z(1-z)\frac{d^2w}{dz^2} + [c - (a+b+1)z]\frac{dw}{dz} - abw = 0 \quad (5)$$

Let us verify that our power series solves this differential equation. First, notice that $(q)_{n+1} = q(q+1)_n$ (this is a simple exercise). Hence,

$$\frac{d}{dz} {}_2F_1(a, b, c; z) = \sum_{n=0}^{\infty} \frac{(a)_{n+1}(b)_{n+1}}{(c)_{n+1}} \frac{z^n}{n!} = \frac{ab}{c} \sum_{n=0}^{\infty} \frac{(a+1)_n(b+1)_n}{(c+1)_n} \frac{z^n}{n!} = \frac{ab}{c} {}_2F_1(a+1, b+1, c+1; z)$$

and

$$\frac{d^2}{dz^2} {}_2F_1(a, b, c; z) = \frac{a(a+1)b(b+1)}{c(c+1)} {}_2F_1(a+2, b+2, c+2; z)$$

Plugging this into the differential equation, one finds that there are five series to deal with. Computing coefficients of z^n for every n is a tedious exercise, but I went for it. All of them came out to be zero, verifying that the hypergeometric function is a solution to (5).

Verifying Equation (4)

Next, we return to the differential equation (3). We take q_k to be the k^{th} coefficient in the power series expansion of ${}_2F_1$; that is,

$$q_k = \frac{(s)_k (s+|n|)_k}{(1+|n|)_k k!}$$

Then our conjectured solution is

$$a_n(\rho) = (1-\rho^2)^s \sum_{k=0}^{\infty} q_k \rho^{2k+|n|}$$

Now we can take $n \geq 0$, since this solution (as well as the differential equation) is invariant under the map $n \mapsto -n$.

We begin with the case $n \geq 2$, since for $n = 0$ and $n = 1$, the first one or two terms are annihilated by taking derivatives. In the case $n \geq 2$, we have

$$\begin{aligned} a'_n(\rho) &= -2s(1-\rho^2)^{s-1} \sum_{k=0}^{\infty} q_k \rho^{2k+n+1} + (1-\rho^2)^s \sum_{k=0}^{\infty} (2k+n) q_k \rho^{2k+n-1} \\ a''_n(\rho) &= 4s(s-1)(1-\rho^2)^{s-2} \sum_{k=0}^{\infty} q_k \rho^{2k+n+2} - 2s(1-\rho^2)^{s-1} \sum_{k=0}^{\infty} (4k+2n+1) q_k \rho^{2k+n} \\ &\quad + (1-\rho^2)^s \sum_{k=0}^{\infty} (2k+n)(2k+n-1) q_k \rho^{2k+n-2} \end{aligned}$$

Old Ideas

First, note that we are working with the function $h(\rho) = {}_2F_1(a, b, c; \rho^2)$; that is, we have a square in the last component instead of just a z . Applying the chain rule, one can verify that the differential equation satisfied by the original hypergeometric function turns into the following for $h(\rho)$:

$$\frac{1-\rho^2}{4} h''(\rho) + \left(\frac{2c-2(a+b)\rho^2-\rho^2-1}{4\rho} \right) h'(\rho) - abh(\rho) = 0 \quad (6)$$

This will come up in our computation.

Next, to solve the differential equation, we make the guess

$$a_n(\rho) = g(\rho)h(\rho)$$

where $h(\rho) = {}_2F_1(a, b, c; \rho^2)$ as before, and $g(\rho)$ is to be determined. Plugging this into (7) gives

$$\begin{aligned} \left[\frac{(1-\rho^2)^2}{4} g(\rho) \right] h''(\rho) + \left[\frac{(1-\rho^2)^2}{4} \left(2g'(\rho) + \frac{1}{\rho} g(\rho) \right) \right] h'(\rho) \\ + \left[\frac{(1-\rho^2)^2}{4} \left(g''(\rho) + \frac{1}{\rho} g'(\rho) - \frac{n^2}{\rho^2} g(\rho) \right) \right] h(\rho) = s(1-s)g(\rho)h(\rho) \end{aligned}$$

It seems to me that this differential equation could be solved by choosing a g which makes the coefficient of $h(\rho)$ on the left hand side equal to 0. Then the hope is that we can choose a, b, c in the definition of $h(\rho)$ so that applying equation (6) gives the solution we are looking for. **This step is just a guess; if this method fails to provide a solution, may need to come back and change this.**

Making the coefficient of $h(\rho)$ equal to zero in the equation above is equivalent to the differential equation

$$\rho^2 g''(\rho) + \rho g'(\rho) - n^2 g(\rho) = 0$$

This is an Euler differential equation with solutions $g_1(\rho) = \rho^n$ and $g_2(\rho) = \rho^{-n}$. Thinking ahead to the Fourier expansion in the disk model, it will be far preferable to have $\rho^{|n|}$ as opposed to $\rho^{-|n|}$, so we will start with this guess. **At this step, we have made the assumption $n \neq 0$; we will have to return to the DE later to consider the case $n = 0$.**

Solving the Differential Equation for the Fourier Coefficients

We are trying to solve the differential equation

$$\frac{(1-\rho^2)^2}{4} a''_n(\rho) + \frac{(1-\rho^2)^2}{4\rho} a'_n(\rho) - \frac{n^2(1-\rho^2)^2}{4\rho^2} a_n(\rho) = s(1-s)a_n(\rho) \quad (7)$$

for the function $a_n(\rho)$.

Since the coefficients of $a_n(\rho)$ and its derivatives in Equation (7) are all polynomials in ρ , we attempt to find a power series solution. So we guess

$$a_n(\rho) = \sum_{m=0}^{\infty} c_m \rho^m$$

Plugging this in and putting everything into one series, we get

$$A(c_0, c_1, c_2, c_3, \rho, \rho^2, \rho^3) + \sum_{m=4}^{\infty} B_m(c_m, c_{m-2}, c_{m-4}) \rho^m = 0$$

where A and B_m are the following polynomials:

$$\begin{aligned} A = & (-4s(1-s)c_1 + 2c_1n^2 - 2c_1 + 6c_2 - c_3n^2 + 3c_3)\rho^3 \\ & + (-4s(1-s)c_0 + 2c_0n^2 - c_2n^2 + 4c_2)\rho^2 + (c_1 - c_1n^2)\rho - c_0n^2 \end{aligned}$$

$$B_m = (m^2 - n^2)c_m - (2(m-2)^2 + 4s(1-s) - 2n^2)c_{m-2} + ((m-4)^2 - n^2)c_{m-4}$$

Now, to solve the differential equation, we need every power of ρ to have a coefficient of 0. In other words, the coefficients in A as a polynomial of ρ need to be 0, and B_m must be equivalently 0 for all m . We proceed by making some observations about the c_m 's which will simplify the computation.

Observation 1: The first coefficient c_k which can be nonzero is for $k = |n|$. To see this, consider the four cases $n^2 = 0, n^2 = 1, n^2 = 4$, and $n^2 > 4$ separately. In the first three cases, the result follows from studying the polynomial A . In the fourth case, one finds that $c_0 = c_1 = c_2 = c_3 = 0$ by studying A . Then since c_m depends linearly on c_{m-2} and c_{m-4} for $m \geq 4$, we must have that $c_m = 0$ until the coefficient of c_m is 0. This happens when $m = |n|$.