

Electron Spin Resonance

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Abstract

The classical example of a magnetic dipole moment reacting in a magnetic field is the electron. Here we will investigate the reaction of a particle with a dipole moment in a magnetic field and investigate how it changes in analogy to the electron. We begin with a classical analogue of the electron and move on to an ensemble of electrons. These electrons are bound in DPPH, rather than being a 3D gas, but for all intents and purposes will serve to illustrate the properties we are investigating here.

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1 Introduction

The magnetic dipole moment of a charged particle is related to the spin of the particle in the simple analogue of a current loop. Charges going around a closed loop have a magnetic dipole moment

$$\vec{\mu} = IA\hat{n}$$

with \hat{n} being the unit vector normal to the area A . This generates a magnetic dipole field, equal to

$$B = \frac{\mu_0}{4\pi} \left(\frac{3r(\vec{\mu} \cdot \vec{r})}{r^5} - \frac{\mu}{r^3} \right).$$

This assumes no external field, however. If there is an external field, and $\vec{\mu}$ is not perfectly aligned, we will see precession about the external field (assuming a DC field pointing in one direction). We can measure this property both in our classical analogue to an electron, and in actual electrons. This effect is also very important in other physics. For example, in microwave resonators we use crystals of Yttrium-Iron-Garnet which have the property that an AC \vec{B} field of approximately 2000 Gauss will cause them to precess at microwave frequency in such a way that couples strongly to the resonator. This has many useful applications, and there is some extremely interesting physics we can study simply by looking at the precession of the magnetic dipole moment.

2 Theory

2.1 Classical System

We can derive the precession about the external field beginning with the torque felt by $\vec{\mu}$ when placed in an external field. We will begin with the Maxwell Stress Tensor. In the case of a dipole moment that is not aligned to the external field, we see that the stress tensor is asymmetric. Since the stress tensor is given (in this case - neglecting the small \vec{E} fields) by

$$\sigma_{ij} = \frac{H_i H_j}{4\pi} - \frac{H^2}{8\pi} \delta_{ij}$$

for situations in vacuum. We realize from this equation that if two fields are not colinear then the tensor will be asymmetric. In order to recover the symmetry (and minimize the energy by aligning the fields), there will be some torque on the object. Furthermore, since we are interested in the magnetic dipole moment let us recognize that

$$H = \frac{B}{\mu_0} - \int_V \vec{\mu} dV.$$

Thus we can write

$$\begin{aligned} \tau_i &= -\epsilon_{ijk} \sigma_{jk} \\ \tau_i &= -\epsilon_{ijk} \frac{H_j B_k}{4\pi} \\ \vec{\tau} &= \frac{-\vec{H} \times \vec{B}}{4\pi} \\ \vec{\tau} &= \vec{\mu} \times \vec{B} \end{aligned} \tag{1}$$

Now that we know the torque exerted on the magnetic moment by the external field, we can begin to work through the precession and the frequency of precession caused by that torque.

Figure 1 provides us with some intuition into how to go about finding the frequency of precession of the dipole moment. Since we can transform into a rotating frame to describe the motion of \vec{L} , we can write

$$\begin{aligned} \frac{d\vec{L}}{dt} &= \vec{\tau} = \vec{\omega} \times \vec{L} \\ \vec{\mu} \times \vec{B} &= \vec{\omega} \times \vec{L} \end{aligned}$$

and since the angle between $\vec{\mu}$ and \vec{B} is the same as the angle between $\vec{\omega}$ and \vec{L} by definition of our frame, we can write

$$\omega = \frac{\mu}{L} B \tag{2}$$

$$\omega = \gamma B \tag{3}$$

where γ is the gyromagnetic ratio.

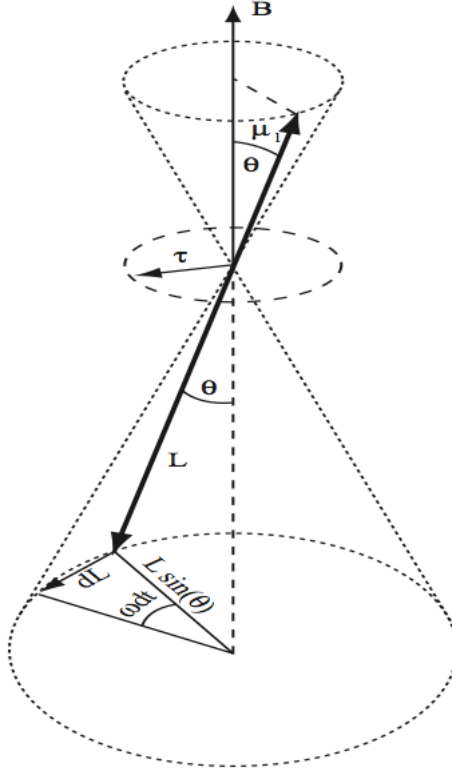


Figure 1: The precession of $\vec{\mu}$ about an external \vec{B} field.

2.2 Quantum System

For an electron, we can express γ as

$$|\gamma_e| = \frac{|-e|}{2m_e} g_e = \frac{g_e \mu_B}{\hbar} \quad (4)$$

where μ_B is the Bohr Magneton and g_e is given by

$$g_e = 2 \left(1 + \frac{\alpha}{2\pi} + \dots \right).$$

We can express the system and its energy using a simple Hamiltonian. Since we have an electron precessing in a \vec{B} field, we know that \mathcal{H} will be given by

$$\begin{aligned}\mathcal{H} &= \frac{\hat{p}^2}{2m} \nabla^2 + V \\ \hat{p} &= -i\hbar\nabla \rightarrow \hat{p}_{eff} = -i\hbar\nabla + \frac{e}{c}A \\ V &= -e\phi\end{aligned}$$

so we can write \mathcal{H} as

$$\mathcal{H} = -\frac{\hbar^2}{2m}\nabla^2 - \frac{ie\hbar}{2mc}(\vec{\nabla} \cdot \vec{A}) - \frac{ie\hbar}{mc}(\vec{A} \cdot \vec{\nabla}) + \frac{e^2}{2mc^2}A^2 - e\phi. \quad (5)$$

Most often this will be simplified by working in the Coulomb gauge,

$$\vec{\nabla} \cdot \vec{A}(\vec{r}, t) = 0$$

or we can choose the Lorentz invariant version in the Lorenz gauge,

$$\vec{\nabla} \cdot \vec{A} + \frac{1}{c^2} \frac{\partial \phi}{\partial t} = 0$$

3 Apparatus

3.1 Classical System

For the classical system the apparatus is shown in figure 2.

We have a billiard ball with a black handle that is placed between two Helmholtz coils, with a control system that allows us to ramp the current in the coils, as well as turn on and off a field gradient that gives approximately zero net field at the ball itself.

3.2 Quantum System

For the quantum system the apparatus is shown in figure x.

4 Data Analysis

5 Error Analysis

6 Conclusion

References

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