

Conditional Subspace VAE

Alexander Lyzhov, Artem Shafarostov,
Marina Pominova, Elizaveta Lazareva

CSVAE architecture

Idea: minimize MI between label and subspace

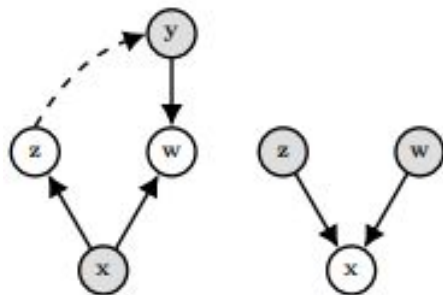
Can find features correlated with labels for manipulation

Alternative to VAE, CondVAE, CondVAE-info

Introduced in “Learning Latent Subspaces in Variational Autoencoders” (NIPS’18)

CSVAE architecture

$$\log p_{\theta, \gamma}(\mathbf{x}, \mathbf{y}, \mathbf{w}, \mathbf{z}) = \log p_{\theta}(\mathbf{x} | \mathbf{w}, \mathbf{z}) + \log p(\mathbf{z}) + \log p_{\gamma}(\mathbf{w} | \mathbf{y}) + \log p(\mathbf{y})$$



$$\begin{aligned} & -\beta_1 \mathbb{E}_{q_{\phi}(\mathbf{z}, \mathbf{w} | \mathbf{x}, \mathbf{y})} [\log p_{\theta}(\mathbf{x} | \mathbf{w}, \mathbf{z})] + \beta_2 D_{KL}(q_{\phi}(\mathbf{w} | \mathbf{x}, \mathbf{y}) \| \log p(\mathbf{w} | \mathbf{y})) \\ & + \beta_3 D_{KL}(q_{\phi}(\mathbf{z} | \mathbf{x}, \mathbf{y}) \| p(\mathbf{z})) + \beta_4 \mathbb{E}_{q_{\phi}(\mathbf{z} | \mathbf{x}) \mathcal{D}(\mathbf{x})} \left[\int_Y q_{\delta}(\mathbf{y} | \mathbf{z}) \log q_{\delta}(\mathbf{y} | \mathbf{z}) d\mathbf{y} \right] \\ & - \log p(\mathbf{y}) \\ & \quad \text{--- } \beta_5 \mathbb{E}_{q(\mathbf{z} | \mathbf{x}) \mathcal{D}(\mathbf{x}, \mathbf{y})} [\log q_{\delta}(\mathbf{y} | \mathbf{z})] . \end{aligned}$$

CSVAE architecture

Idea: minimize MI between label and subspace

Can find features correlated with labels for manipulation

Encoders: $x \rightarrow z$, $xy \rightarrow w$

Decoders: $zw \rightarrow x$, $w \rightarrow y$ (unusual)

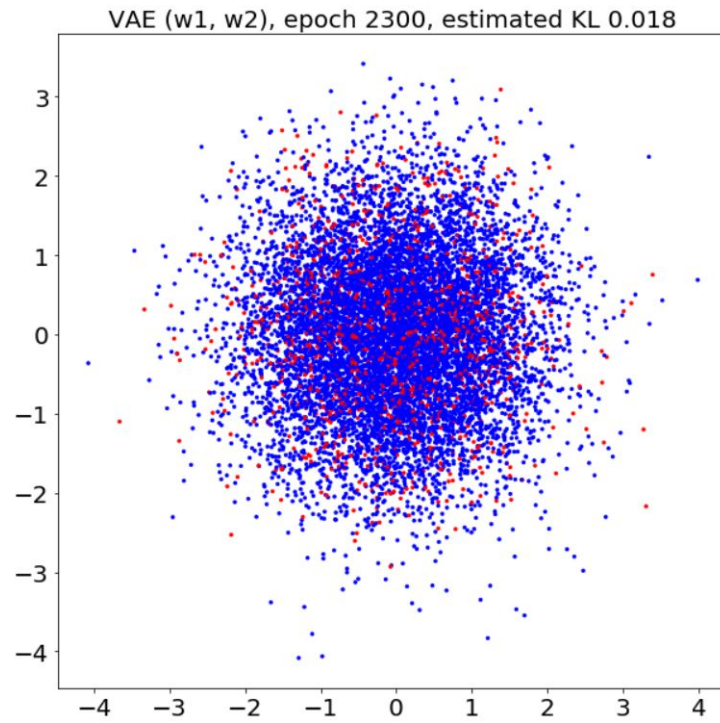
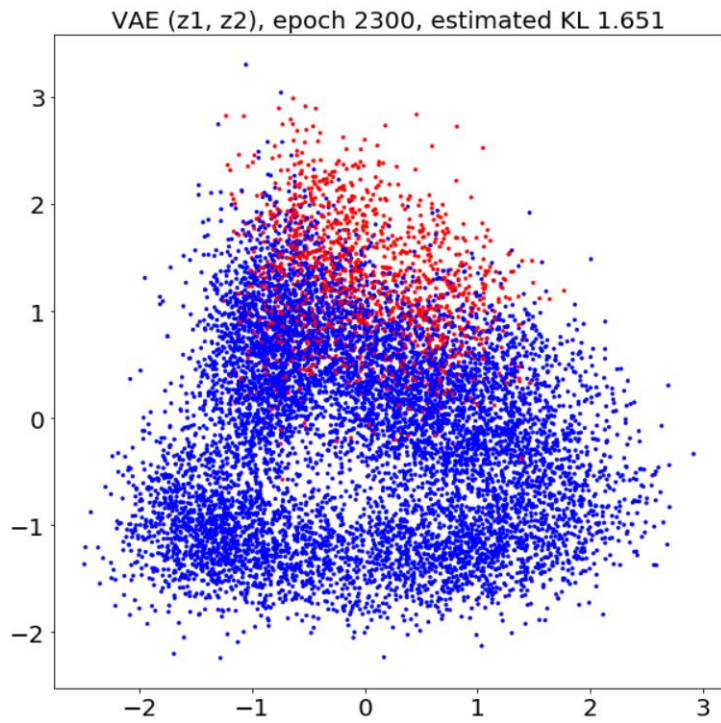
Optimizer 1: for decoder $w \rightarrow y$

Optimizer 2: for all other encoders/decoders

Label $Y = 0/1$. Latent space is $z1, z2, w1, w2$.

$w1, w2$ shouldn't have information about Y , but $z1, z2$ shouldn't have it.

Vanilla VAE

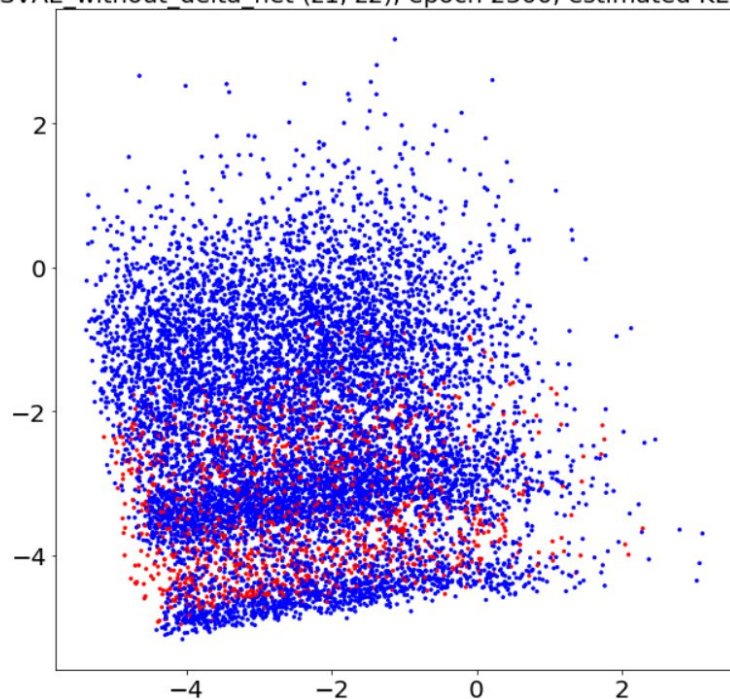


Label $Y = 0/1$. Latent space is $z1, z2, w1, w2$.

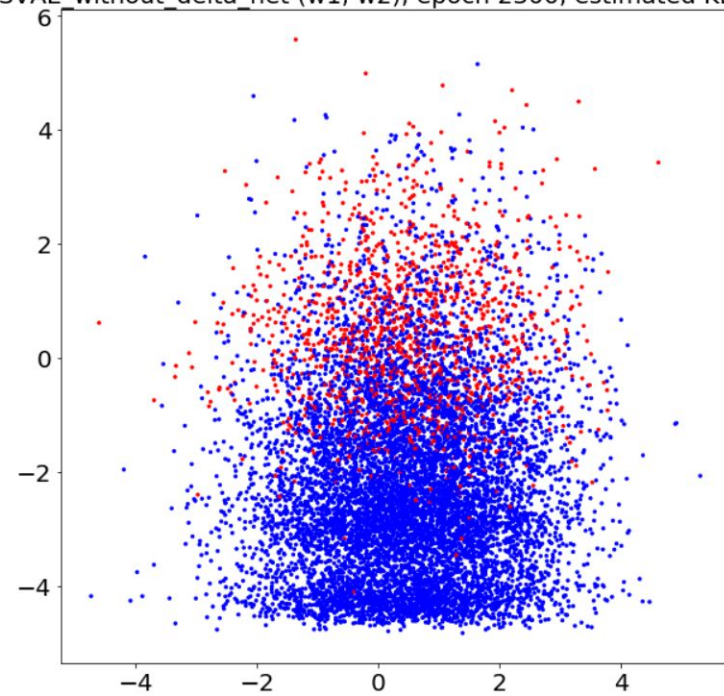
$w1, w2$ shouldn't have information about Y , but $z1, z2$ shouldn't have it.

CSVAE without adversarial component

CSVAE without_delta_net ($z1, z2$), epoch 2300, estimated KL 0.716



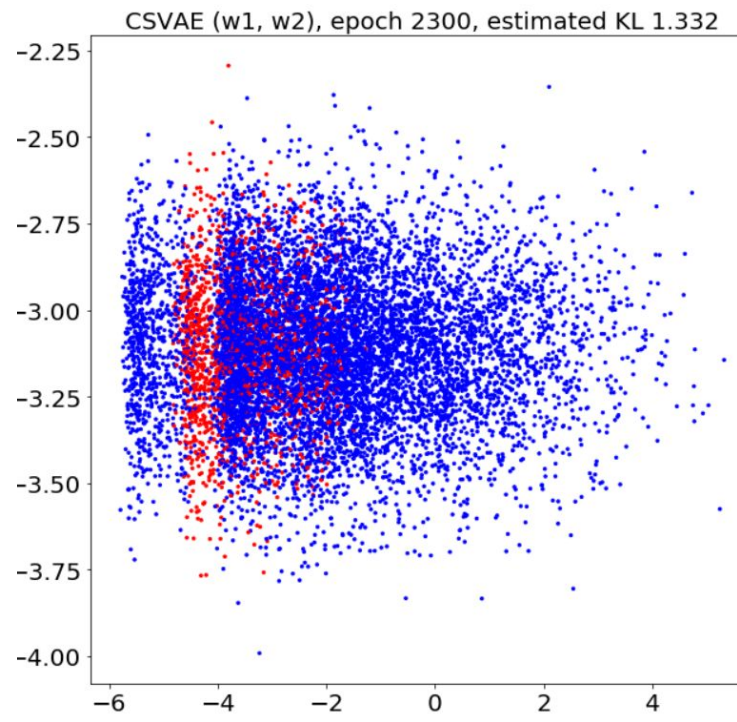
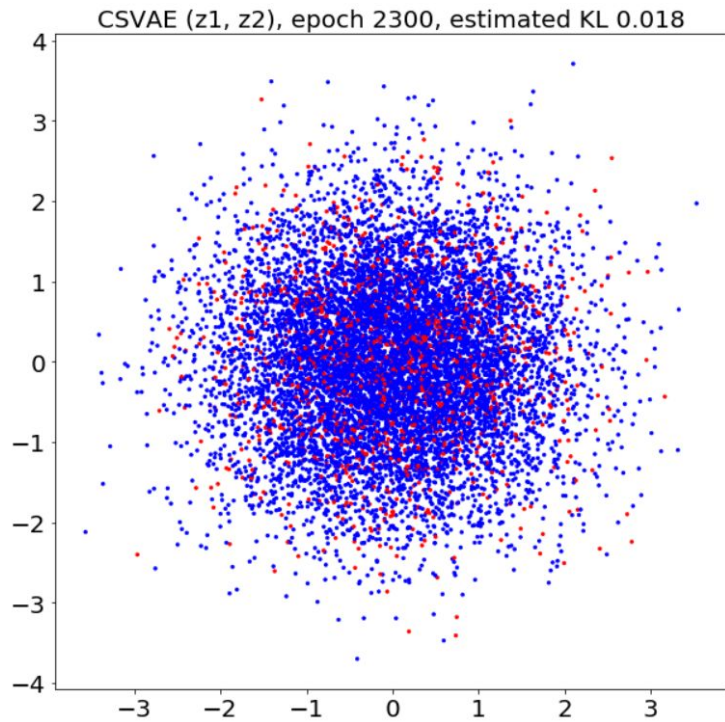
CSVAE without_delta_net ($w1, w2$), epoch 2300, estimated KL 1.315



Label $Y = 0/1$. Latent space is z_1, z_2, w_1, w_2 .

w_1, w_2 should have information about Y , but z_1, z_2 shouldn't have it.

CSVAE



CelebA

- **200,000** images of celebrity faces
- **40** labelled attributes

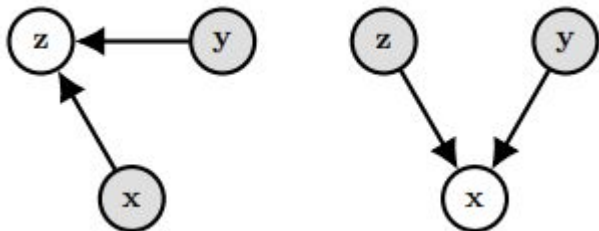
Experiments details

- First trained basic VAE architecture
- Used **same encoder-decoder architecture** and **pretrained weights** for conv layers in all experiments

CelebA

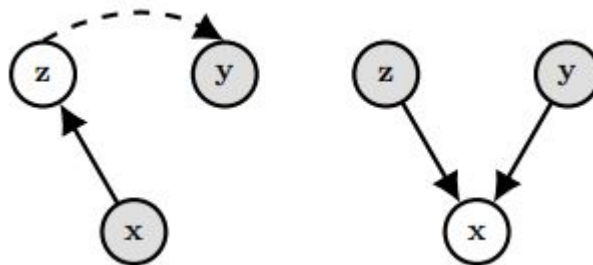
Comparison of CondVAE with other approaches:

CondVAE



- Generated samples are conditioned on label y

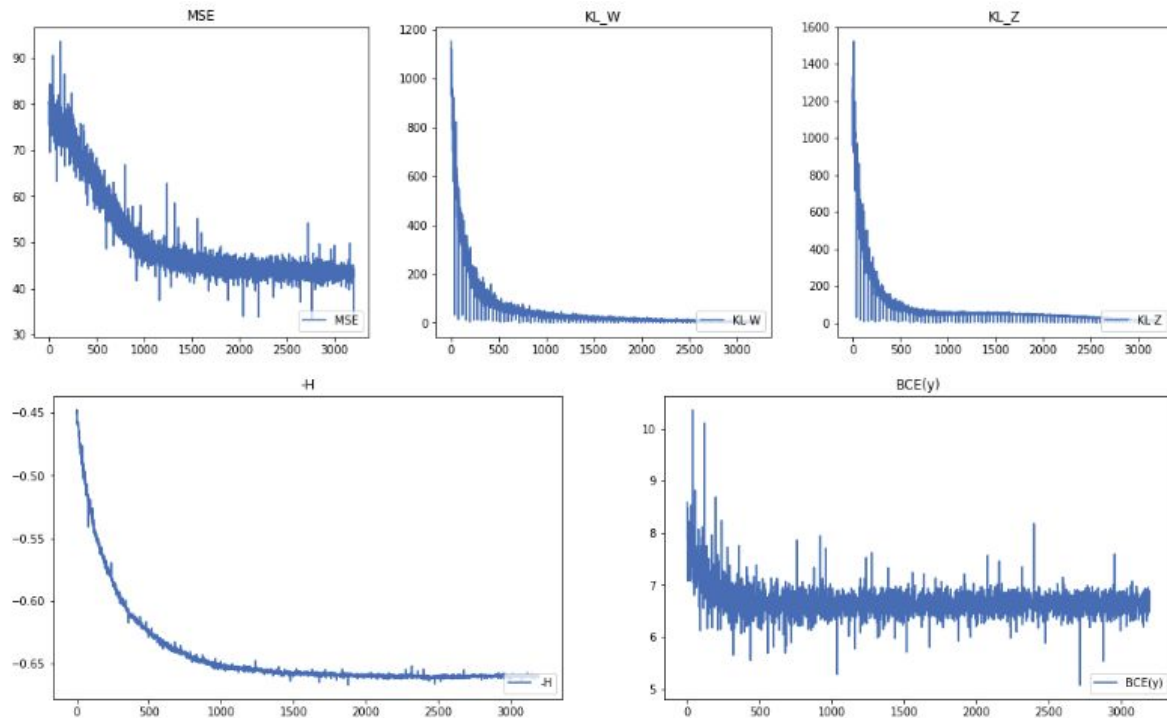
CondVAE-info



- Additional network predicts label y from latent vector
- Adversarially trained to make latent representation z independent from label

CelebA

- 200,000 images of celebrity faces
- 40 labelled attributes
- First trained base VAE architecture
- Used same architecture and pretrained weights for CSVAE and All other experiments



CSVAE loss components

Attributes: "Eyeglasses"

CSVAE

vs.

CondVAE

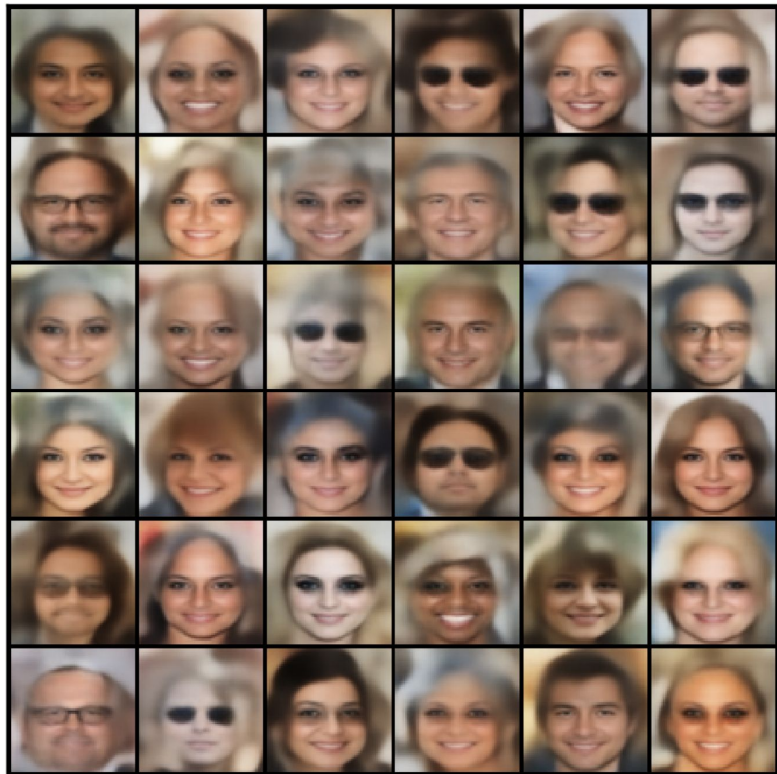


Attributes: “Eyeglasses” and “Smiling”

CSVAE

vs.

CondVAE



Attributes: "Male" without "Heavy Makeup", "Wearing Lipstick"

CSVAE

vs.

CondVAE



Attributes: "Heavy Makeup" without 'Male', 'Receding_Hairline', 'Eyeglasses',
'Mustache'

CSVAE

vs.

CondVAE



Interpolation: No eyeglasses → Eyeglasses

CondVAE



vs.



CSVAE



Conclusions

CondVAE

- More accurate samples
- Simpler and easier to train model

CSVAE:

- Many networks including competing components
- Many hyperparameters to tune
=> more difficult to train properly on complex tasks (CelebA)
- Richer controllable attributes and structured latent space