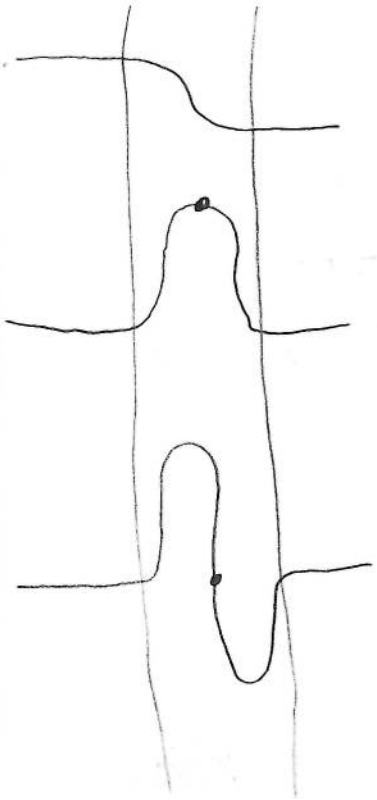
Marr-Hildreth operator

- included a double differential operator
- more accurate localisation of an edge pixel



a) - profile across a real step edge

b) - profile is differentiated - constant grey values = 0
- region where the grey value changes = edge region
- the max of that region = location of the edge

c) - double differentiated - uniform regions = 0
- edge region = finite result
- location of edge = where the profile crosses the 0
= zero crossing