

Types of smoothing

1) Adaptive Smoothing

- compute smoothed value s ; we need to specify the threshold, T
- Output = $\begin{cases} \text{computed pixel} & \text{if } \left| \text{computed pixel} - \begin{matrix} \text{middle original} \\ \text{pixel from} \\ \text{image} \end{matrix} \right| < \text{threshold} \\ \text{middle original pixel from image} & \text{otherwise} \end{cases}$

• middle original pixel from image otherwise

2) Median Smoothing

- take all n nodes from the $n \times n$ matrix (e.g.

n_1	n_2	n_3
n_4	n_5	n_6
n_7	n_8	n_9

 — $n_1, n_2, n_3, n_4, n_5, n_6, n_7, n_8, n_9$)
- put them in an array, ^{sort} and take the median
- how to take the median? if (odd) $\text{array}(\frac{n}{2})$
else if (even) $\text{average} \left[\text{array}(\frac{n}{2}) + \text{array}(\frac{n+1}{2}) \right]$

- replace the

 with the median

3) Gaussian Smoothing

- used to reduce ringing

$$T(r) = k \exp - \left(\frac{r^2}{2\sigma^2} \right) \text{ where } \begin{aligned} k &= \text{normalising constant} \\ r^2 &= \text{distance of the elem. from the centre} \\ \sigma &= \text{width and size of the template} \end{aligned}$$

?

A rank filter will select one value as the smoothed value from the set of pixels in a neighbourhood that have been ranked according to their magnitudes. They are computationally expensive, however, a rank filter using a square neighbourhood may be approximated by two applications of one dimensional rank filters.