RESULTS

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
⊙ S10 - CERC 710 - C							
▪ Inters. PLAN A - CYL C.							
Diam.	4.000	3.907	-0.100	0.000	-0.093		✓
⊙ S10 - CERC 710 - B							
▪ Inters. PLAN A - CYL B.							
Diam.	4.000	3.955	-0.100	0.000	-0.045		✓
▱ S07 - PLTE 450							
▪ PLAN A C							
Val.	0.000	0.197		0.250	0.197		✓
▱ S04 - PLTE 455							
▪ PLAN J C							
Val.	0.000	0.109		0.200	0.109		✓
S15 - DIST 470 - 11.25							
▪ DRTE B-C - POIN 470 - 11.25 / REP ABC.							
dZ	11.250	11.274	-0.075	0.075	0.024		✓
⚹ TRUE POSITION 0.15 - S15 - DIST 470 - 11.25							
▪ =ABS([S15 - DIST 470 - 11.25=>Z]-[S15 - DIST 470 - 11.25->Z])*2							
Val.	0.000	0.047	0.000	0.150	0.047		✓
S15 - DIST 470 - 33.65							
▪ DRTE B-C - POIN 470 - 33.65 / REP ABC.							
dZ	33.650	33.659	-0.130	0.130	0.009		✓
⚹ TRUE POSITION 0.15 - S15 - DIST 470 - 33.65							
▪ =ABS([S15 - DIST 470 - 33.65=>Z]-[S15 - DIST 470 - 33.65->Z])*2							
Val.	0.000	0.018	0.000	0.260	0.018		✓
S18 - DIST 550							
▪ PLAN A - POIN 550 / REP ABC.							
D	6.100	6.208	-0.100	0.100	0.108	0.008	✗
S06 - DIST 1280							
▪ POIN 1280 - 1 - POIN 1280 - 2 / REP ABC.							
D	12.700	12.654	-0.100	0.100	-0.046		✓
S16 - DIST 1300 - LEFT							
▪ PLAN H - POIN 1300 - LEFT / REP ABC.							
dY	12.015	12.063	-0.050	0.050	0.048		✓
S16 - DIST 1300 - RIGHT							
▪ PLAN H - POIN 1300 - RIGHT / REP ABC.							
dY	12.015	12.029	-0.050	0.050	0.014		✓
S19 - DIST 1400 - P6 - DOWN							
▪ PLAN J - POIN 1400 - P6 - DOWN / REP ABC.							
dY	0.850	0.830	-0.100	0.110	-0.020		✓
S19 - DIST 1400 - P6 - UP							
▪ PLAN J - POIN 1400 - P6 - UP / REP ABC.							
dY	0.850	0.790	-0.100	0.110	-0.060		✓
S19 - DIST 1400 - P7 - DOWN							
▪ PLAN J - POIN 1400 - P7 - DOWN / REP ABC.							
dY	0.850	0.799	-0.100	0.110	-0.051		✓
S19 - DIST 1400 - P7 - UP							
▪ PLAN J - POIN 1400 - P7 - UP / REP ABC.							
dY	0.850	0.823	-0.100	0.110	-0.027		✓
S05 - DIST 1410 - P6 - 12.8							
▪ POIN 2500 - P3 - X - POIN 1410 - 1 - 12.8 / REP ABC.							
dZ	12.800	12.795	-0.150	0.150	-0.005		✓
S05 - DIST 1410 - P6 - 3.4							
▪ POIN 2500 - P3 - Z - POIN 1410 - 1 - 3.4 / REP ABC.							
dX	3.400	3.297	-0.150	0.150	-0.103		✓
⚹ TRUE POSITION 0.3 X^2+Y^2 - S05 - DIST 1410 - P6							
▪ =[SQRT X^2+Y^2 - S05 - DIST 1410 - P6->Val]*2							
Val.	0.000	0.205	0.000	0.300	0.205		✓
S05 - DIST 1410 - P7 - 9.6							
▪ POIN 1410 - 2 - 9.6 - POIN 2500 - P3 - X / REP ABC.							
dZ	9.600	9.660	-0.150	0.150	0.060		✓
S05 - DIST 1410 - P7 - 3.4							
▪ POIN 2500 - P3 - Z - POIN 1410 - 2 - 3.4 / REP ABC.							
dX	3.400	3.300	-0.150	0.150	-0.100		✓
⚹ TRUE POSITION 0.3 X^2+Y^2 - S05 - DIST 1410 - P7							
▪ =[SQRT X^2+Y^2 - S05 - DIST 1410 - P7->Val]*2							
Val.	0.000	0.234	0.000	0.300	0.234		✓
S01 - 1690 - MP10							
▪ POIN 109 - MP10 - 2 - POIN 109 - MP10 - 1 / REP ABC.							
dX	109.000	109.009	-0.100	0.200	0.009		✓

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
S01 - 1690 - MP11							
POIN 109 - MP11 - 2 - POIN 109 - MP11 - 1 / REP ABC.							
dX	109.000	108.943	-0.100	0.200	-0.057		✓
S01 - 1690 - MP12							
POIN 109 - MP12 - 2 - POIN 109 - MP12 - 1 / REP ABC.							
dX	109.000	108.922	-0.100	0.200	-0.078		✓
S02 - 1730							
POIN 1730 - 2 - POIN 1730 - 1 / REP ABC.							
dZ	56.700	56.843	-0.100	0.300	0.143		✓
S03 - DIST 1880							
PLAN 1880 - POIN 1880 - 3 / REP ABC.							
dY	43.500	43.509	-0.100	0.150	0.009		✓
S17 - 1980 - 1							
PLAN A-1 - POIN 1680 - 1 - 3 / REP ABC.							
D	7.000	6.945	-0.130	0.000	-0.055		✓
S17 - 1980 - 2							
PLAN A-2 - POIN 1980 - 2 - 3 / REP ABC.							
D	7.000	6.997	-0.100	0.000	-0.003		✓
S17 - 1980 - 3							
PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC.							
D	7.000	6.918	-0.100	0.000	-0.082		✓
S17 - 1980 - 4							
PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.							
D	7.000	6.889	-0.110	0.000	-0.111	-0.001	✗
S17 - 1980 - 5							
PLAN A-5 - POIN 1980 - 5 - 3 / REP ABC.							
D	7.000	7.022	-0.050	0.065	0.022		✓
S17 - 1980 - 6							
PLAN A-6 - POIN 1980 - 6 - 3 / REP ABC.							
D	7.000	6.898	-0.100	0.000	-0.102	-0.002	✗
S13 - DIST 2310 - MP1 - UP							
POIN 2310 - MP1 - UP - 1 - POIN 2310 - MP1 - UP - 2 / REP ABC.							
D	9.950	9.963	-0.050	0.150	0.013		✓
S13 - DIST 2310 - MP1 - DOWN							
POIN 2310 - MP1 - DOWN - 1 - POIN 2310 - MP1 - DOWN - 2 / REP ABC.							
D	9.950	9.951	-0.050	0.150	0.001		✓
S13 - DIST 2310 - MP4 - UP							
POIN 2310 - MP4 - UP - 1 - POIN 2310 - MP4 - UP - 2 / REP ABC.							
D	9.950	10.085	-0.050	0.150	0.135		✓
S13 - DIST 2310 - MP4 - DOWN							
POIN 2310 - MP4 - DOWN - 1 - POIN 2310 - MP4 - DOWN - 2 / REP ABC.							
D	9.950	10.077	-0.050	0.150	0.127		✓
S08 - DIST 2420 - MP1							
POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.							
D	25.900	26.032	-0.100	0.150	0.132		✓
S08 - DIST 2420 - MP2							
POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.							
D	25.900	25.885	-0.100	0.150	-0.015		✓
S09 - DIST 2500 - P1 - 8							
POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.							
dZ	8.000	7.929	-0.100	0.100	-0.071		✓
S09 - DIST 2500 - P1 - 0							
POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.							
dX	0.000	0.033	-0.100	0.100	0.033		✓
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P1							
=[SQRT X^2+Y^2 - S09 - DIST 2500 - P1->Val]*2							
Val.	0.000	0.156	0.000	0.200	0.156		✓
S09 - DIST 2500 - P2 - 4							
POIN 2500 - P3 - X - POIN 2500 - P2 - .4 / REP ABC.							
dZ	4.000	3.960	-0.100	0.100	-0.040		✓
S09 - DIST 2500 - P2 - 0							
POIN 2500 - P2 - 0 - POIN 2500 - P3 - Z / REP ABC.							
dX	0.000	-0.037	-0.100	0.100	-0.037		✓
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P2							
=[SQRT X^2+Y^2 - S09 - DIST 2500 - P2->Val]*2							
Val.	0.000	0.109	0.000	0.200	0.109		✓
S09 - DIST 2500 - P4 - 4							
POIN 2500 - P4 - .4 - POIN 2500 - P3 - X / REP ABC.							
dZ	4.000	4.056	-0.100	0.100	0.056		✓
S09 - DIST 2500 - P4 - 0							
POIN 2500 - P4 - 0 - POIN 2500 - P3 - Z / REP ABC.							
dX	-0.000	-0.047	-0.100	0.100	-0.047		✓

SITE: **TRP**	Control Equipment: **QC_74 - DEA Performance**
THOMAS REFERENCE: HEL010/A - C2 - 24.08.2021 - 10:00 - inj 2	
OPERATOR: CA	
DATE : 24/08/21 14:15:49	SOFTWARE: **METROLOG X4V14**

THOMAS TONTEC

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P4							
=[SQRT X^2+Y^2 - S09 - DIST 2500 - P4->Val]*2							
Val.	0.000	0.146	0.000	0.200	0.146		✓
S09 - DIST 2500 - P5 - 8							
POIN 2500 - P5 - 8 - POIN 2500 - P3 - X / REP ABC.							
dZ	8.000	7.952	-0.100	0.100	-0.048		✓
S09 - DIST 2500 - P5 - 0							
POIN 2500 - P5 - 0 - POIN 2500 - P3 - Z / REP ABC.							
dX	0.000	-0.001	-0.100	0.100	-0.001		✓
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P5							
=[SQRT X^2+Y^2 - S09 - DIST 2500 - P5->Val]*2							
Val.	0.000	0.095	0.000	0.200	0.095		✓
S20 - DIST 2530 - P1 - DOWN							
PLAN J - POIN 2530 - P1 - DOWN / REP ABC.							
dY	1.150	1.132	-0.100	0.100	-0.018		✓
S20 - DIST 2530 - P1 - UP							
PLAN J - POIN 2530 - P1 - UP / REP ABC.							
dY	1.150	1.116	-0.100	0.100	-0.034		✓
S20 - DIST 2530 - P2 - DOWN							
PLAN J - POIN 2530 - P2 - DOWN / REP ABC.							
dY	1.150	1.104	-0.100	0.100	-0.046		✓
S20 - DIST 2530 - P2 - UP							
PLAN J - POIN 2530 - P2 - UP / REP ABC.							
dY	1.150	1.104	-0.100	0.100	-0.046		✓
S20 - DIST 2530 - P3 - DOWN							
PLAN J - POIN 2530 - P3 - DOWN / REP ABC.							
dY	1.150	1.071	-0.100	0.100	-0.079		✓
S20 - DIST 2530 - P3 - UP							
PLAN J - POIN 2530 - P3 - UP / REP ABC.							
dY	1.150	1.075	-0.100	0.100	-0.075		✓
S20 - DIST 2530 - P4 - DOWN							
PLAN J - POIN 2530 - P4 - DOWN / REP ABC.							
dY	1.150	1.110	-0.140	0.100	-0.040		✓
S20 - DIST 2530 - P4 - UP							
PLAN J - POIN 2530 - P4 - UP / REP ABC.							
dY	1.150	1.113	-0.120	0.100	-0.037		✓
S20 - DIST 2530 - P5 - DOWN							
PLAN J - POIN 2530 - P5 - DOWN / REP ABC.							
dY	1.150	1.089	-0.100	0.100	-0.061		✓
S20 - DIST 2530 - P5 - UP							
PLAN J - POIN 2500 - P5 - UP / REP ABC.							
dY	1.150	1.101	-0.100	0.100	-0.049		✓
S14 - 2670 - 29.5							
S10 - CERC 710 - B - POIN 2500 - P3 - Z / REP ABC.							
dX	29.500	29.533	-0.100	0.100	0.033		✓
S14 - 2670 - 20.85							
S10 - CERC 710 - B - POIN K-6 / REP ABC.							
dZ	20.850	20.887	-0.100	0.100	0.037		✓
TRUE POSITION 0.2 X^2+Y^2 - S14 - 2670 - 20.8529							
=[SQRT X^2+Y^2 - S14 - 2670->Val]*2							
Val.	0.000	0.099	0.000	0.200	0.099		✓
S12 - DIST 2810 - P1							
POIN D.69 - POIN 2810 - P1 / REP ABC.							
dZ	8.000	7.962	-0.075	0.075	-0.038		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P1							
=ABS([S12 - DIST 2810 - P1=>Z]-[S12 - DIST 2810 - P1->Z])*2							
Val.	0.000	0.077	0.000	0.150	0.077		✓
S12 - DIST 2810 - P2							
POIN D.69 - POIN 2810 - P2 / REP ABC.							
dZ	4.000	4.004	-0.075	0.075	0.004		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P2							
=ABS([S12 - DIST 2810 - P2=>Z]-[S12 - DIST 2810 - P2->Z])*2							
Val.	0.000	0.009	0.000	0.150	0.009		✓
S12 - DIST 2810 - P3							
POIN D.69 - POIN 2810 - P3 / REP ABC.							
dZ	0.000	0.017	-0.075	0.075	0.017		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P3							
=ABS([S12 - DIST 2810 - P3=>Z]-[S12 - DIST 2810 - P3->Z])*2							
Val.	0.000	0.034	0.000	0.150	0.034		✓
S12 - DIST 2810 - P4							
POIN 2810 - P4 - POIN D.69 / REP ABC.							
dZ	4.000	3.958	-0.075	0.075	-0.042		✓

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
TRUE POSITION 0.15 - S12 - DIST 2810 - P4							
=ABS([S12 - DIST 2810 - P4=>Z]-[S12 - DIST 2810 - P4->Z])*2							
Val.	0.000	0.084	0.000	0.150	0.084		✓
S12 - DIST 2810 - P5							
POIN 2810 - P5 - POIN D.69 / REP ABC.							
dZ	8.000	7.923	-0.075	0.075	-0.077	-0.002	✗
TRUE POSITION 0.15 - S12 - DIST 2810 - P5							
=ABS([S12 - DIST 2810 - P5=>Z]-[S12 - DIST 2810 - P5->Z])*2							
Val.	0.000	0.154	0.000	0.150	0.154	0.004	✗
VAL1							
Dimensiuni extra							
DIST 400 - 1							
POIN 400 - 1-5 - PLAN 400 - 1 / REP ABC.							
dZ	2.650	2.528	-0.120	0.100	-0.122	-0.002	✗
DIST 400 - 2							
POIN 400 - 2-5 - PLAN 400 - 2 / REP ABC.							
dZ	2.650	2.568	-0.090	0.090	-0.082		✓
DIST 400 - 3							
PLAN 400 - 3 - POIN 400 - 3-5 / REP ABC.							
dX	2.650	2.519	-0.140	0.090	-0.131		✓
DIST 400 - 4							
PLAN 400 - 4 - POIN 400 - 4-5 / REP ABC.							
dZ	2.650	2.663	-0.120	0.090	0.013		✓
DIST 400 - 5							
PLAN 400 - 5 - POIN 400 - 5-9 / REP ABC.							
dZ	2.650	2.592	-0.280	0.090	-0.058		✓
DIST 400 - 6							
POIN 400 - 6-5 - PLAN 400 - 6 / REP ABC.							
dX	2.650	2.543	-0.120	0.090	-0.107		✓
DIST 410 - 1							
POIN 410 - 1 - POIN 410 - 1-2 / REP ABC.							
dY	2.600	2.501	-0.150	0.090	-0.099		✓
DIST 410 - 2							
POIN 410 - 2 - POIN 410 - 2-2 / REP ABC.							
dY	2.600	2.523	-0.100	0.090	-0.077		✓
DIST 410 - 3							
POIN 410 - 3-1 - POIN 410 - 3-2 / REP ABC.							
dY	2.600	2.610	-0.090	0.090	0.010		✓
DIST 410 - 4							
POIN 410 - 4-1 - POIN 410 - 4-2 / REP ABC.							
dY	2.600	2.479	-0.200	0.090	-0.121		✓
DIST 410 - 5							
POIN 410 - 5 - POIN 410 - 5-2 / REP ABC.							
dY	2.600	2.644	-0.090	0.090	0.044		✓
DIST 410 - 6							
POIN 410 - 6 - POIN 1980 - 6 - 3 / REP ABC.							
dY	2.600	2.556	-0.090	0.090	-0.044		✓
DIST 630 - 1							
POIN 630 - 1-1 - POIN 630 - 1-2 / REP ABC.							
dZ	55.500	55.400	-0.270	0.100	-0.100		✓
DIST 630 - 2							
POIN 630 - 2-1 - POIN 630 - 2-2 / REP ABC.							
dZ	55.500	55.199	-0.270	0.100	-0.301	-0.031	✗
DIST 780 - 1							
POIN 780 - 1 - PLAN 780 - 1 / REP ABC.							
D	3.200	3.339	0.000	0.170	0.139		✓
DIST 780 - 2							
POIN 780 - 2 - PLAN 780 - 2 / REP ABC.							
D	3.200	3.288	0.000	0.190	0.088		✓
DIST 780 - 3							
POIN 780 - 3 - PLAN 780 - 3 / REP ABC.							
D	3.200	3.248	0.000	0.100	0.048		✓
DIST 780 - 4							
POIN 780 - 4 - PLAN 780 - 4 / REP ABC.							
D	3.200	3.326	0.000	0.100	0.126	0.026	✗
DIST 1780 - MP10							
POIN 1780 - MP10 - 2 - POIN 1780 - MP10 - 1 / REP ABC.							
dX	106.500	106.601	0.000	0.220	0.101		✓
DIST 1780 - MP11							
POIN 1780 - MP11 - 2 - POIN 1780 - MP11 - 1 / REP ABC.							
dX	106.500	106.601	0.000	0.220	0.101		✓

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
DIST 1780 - MP12							
POIN 1780 - MP12 - 2 - POIN 1780 - MP12 - 1 / REP ABC.							
dX	106.500	106.551	0.000	0.220	0.051		✓
DIST 2600 - P1 - F							
POIN 2600 - P1 - DRTE F / REP ABC.							
dX	-0.000	-0.039	-0.075	0.075	-0.039		✓
0.1 - DIST 2600 - P1 - F							
=ABS([DIST 2600 - P1 - F=>X]-[DIST 2600 - P1 - F->X])*2							
Val.	0.000	0.078	0.000	0.150	0.078		✓
DIST 2600 - P2 - F							
POIN 2600 - P2 - DRTE F / REP ABC.							
dX	-0.000	-0.038	-0.075	0.075	-0.038		✓
0.1 - DIST 2600 - P2 - F							
=ABS([DIST 2600 - P2 - F=>X]-[DIST 2600 - P2 - F->X])*2							
Val.	0.000	0.076	0.000	0.150	0.076		✓
DIST 2600 - P3 - F							
POIN 2600 - P3 - DRTE F / REP ABC.							
dX	-0.000	-0.042	-0.075	0.075	-0.042		✓
0.1 - DIST 2600 - P3 - F							
=ABS([DIST 2600 - P3 - F=>X]-[DIST 2600 - P3 - F->X])*2							
Val.	0.000	0.084	0.000	0.150	0.084		✓
DIST 2600 - P4 - F							
POIN 2600 - P4 - DRTE F / REP ABC.							
dX	0.000	-0.043	-0.075	0.075	-0.043		✓
0.1 - DIST 2600 - P4 - F							
=ABS([DIST 2600 - P4 - F=>X]-[DIST 2600 - P4 - F->X])*2							
Val.	0.000	0.087	0.000	0.150	0.087		✓
DIST 2600 - P5 - F							
POIN 2600 - P5 - DRTE F / REP ABC.							
dX	-0.000	-0.013	-0.075	0.075	-0.013		✓
0.1 - DIST 2600 - P5 - F							
=ABS([DIST 2600 - P5 - F=>X]-[DIST 2600 - P5 - F->X])*2							
Val.	0.000	0.026	0.000	0.150	0.026		✓
DIST 2600 - P1 - L							
POIN 2600 - P1 - DRTE L / REP ABC.							
dX	-0.000	0.016	-0.075	0.075	0.016		✓
0.1 - DIST 2600 - P1 - L							
=ABS([DIST 2600 - P1 - L=>X]-[DIST 2600 - P1 - L->X])*2							
Val.	0.000	0.031	0.000	0.150	0.031		✓
DIST 2600 - P2 - L							
POIN 2600 - P2 - DRTE L / REP ABC.							
dX	-0.000	0.019	-0.075	0.075	0.019		✓
0.1 - DIST 2600 - P2 - L							
=ABS([DIST 2600 - P2 - L=>X]-[DIST 2600 - P2 - L->X])*2							
Val.	0.000	0.037	0.000	0.150	0.037		✓
DIST 2600 - P3 - L							
POIN 2600 - P3 - DRTE L / REP ABC.							
dX	-0.000	0.016	-0.075	0.075	0.016		✓
0.1 - DIST 2600 - P3 - L							
=ABS([DIST 2600 - P3 - L=>X]-[DIST 2600 - P3 - L->X])*2							
Val.	0.000	0.033	0.000	0.150	0.033		✓
DIST 2600 - P4 - L							
POIN 2600 - P4 - DRTE L / REP ABC.							
dX	0.000	0.017	-0.075	0.075	0.017		✓
0.1 - DIST 2600 - P4 - L							
=ABS([DIST 2600 - P4 - L=>X]-[DIST 2600 - P4 - L->X])*2							
Val.	0.000	0.034	0.000	0.150	0.034		✓
DIST 2600 - P5 - L							
POIN 2600 - P5 - DRTE L / REP ABC.							
dX	-0.000	0.050	-0.075	0.075	0.050		✓
0.1 - DIST 2600 - P5 - L							
=ABS([DIST 2600 - P5 - L=>X]-[DIST 2600 - P5 - L->X])*2							
Val.	0.000	0.099	0.000	0.150	0.099		✓
DIST 2610 - P1 - F							
POIN 2610 - P1 - DRTE F / REP ABC.							
dX	-0.000	0.039	-0.150	0.150	0.039		✓
0.1 - DIST 2610 - P1 - F							
=ABS([DIST 2610 - P1 - F=>X]-[DIST 2610 - P1 - F->X])*2							
Val.	0.000	0.078	0.000	0.300	0.078		✓
DIST 2610 - P2 - F							
POIN 2610 - P2 - DRTE F / REP ABC.							
dX	0.000	0.039	-0.150	0.150	0.039		✓

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
0.1 - DIST 2610 - P2 - F							
=ABS([DIST 2610 - P2 - F=>X]-[DIST 2610 - P2 - F->X])*2							
Val.	0.000	0.077	0.000	0.300	0.077		✓
DIST 2610 - P3 - F							
POIN 2610 - P3 - DRTE F / REP ABC.							
dX	-0.000	0.005	-0.150	0.150	0.005		✓
0.1 - DIST 2610 - P3 - F							
=ABS([DIST 2610 - P3 - F=>X]-[DIST 2610 - P3 - F->X])*2							
Val.	0.000	0.009	0.000	0.300	0.009		✓
DIST 2610 - P4 - F							
POIN 2610 - P4 - DRTE F / REP ABC.							
dX	-0.000	0.027	-0.150	0.150	0.027		✓
0.1 - DIST 2610 - P4 - F							
=ABS([DIST 2610 - P4 - F=>X]-[DIST 2610 - P4 - F->X])*2							
Val.	0.000	0.053	0.000	0.300	0.053		✓
DIST 2610 - P5 - F							
POIN 2610 - P5 - DRTE F / REP ABC.							
dX	-0.000	0.069	-0.150	0.150	0.069		✓
0.1 - DIST 2610 - P5 - F							
=ABS([DIST 2610 - P5 - F=>X]-[DIST 2610 - P5 - F->X])*2							
Val.	0.000	0.138	0.000	0.300	0.138		✓
DIST 2610 - P1 - L							
POIN 2610 - P1 - DRTE L / REP ABC.							
dX	-0.000	0.093	-0.150	0.150	0.093		✓
0.1 - DIST 2610 - P1 - L							
=ABS([DIST 2610 - P1 - L=>X]-[DIST 2610 - P1 - L->X])*2							
Val.	0.000	0.187	0.000	0.300	0.187		✓
DIST 2610 - P2 - L							
POIN 2610 - P2 - DRTE L / REP ABC.							
dX	-0.000	0.095	-0.150	0.150	0.095		✓
0.1 - DIST 2610 - P2 - L							
=ABS([DIST 2610 - P2 - L=>X]-[DIST 2610 - P2 - L->X])*2							
Val.	0.000	0.190	0.000	0.300	0.190		✓
DIST 2610 - P3 - L							
POIN 2610 - P3 - DRTE L / REP ABC.							
dX	-0.000	0.063	-0.150	0.150	0.063		✓
0.1 - DIST 2610 - P3 - L							
=ABS([DIST 2610 - P3 - L=>X]-[DIST 2610 - P3 - L->X])*2							
Val.	0.000	0.126	0.000	0.300	0.126		✓
DIST 2610 - P4 - L							
POIN 2610 - P4 - DRTE L / REP ABC.							
dX	-0.000	0.087	-0.150	0.150	0.087		✓
0.1 - DIST 2610 - P4 - L							
=ABS([DIST 2610 - P4 - L=>X]-[DIST 2610 - P4 - L->X])*2							
Val.	0.000	0.174	0.000	0.300	0.174		✓
DIST 2610 - P5 - L							
POIN 2610 - P5 - DRTE L / REP ABC.							
dX	-0.000	0.131	-0.150	0.150	0.131		✓
0.1 - DIST 2610 - P5 - L							
=ABS([DIST 2610 - P5 - L=>X]-[DIST 2610 - P5 - L->X])*2							
Val.	0.000	0.263	0.000	0.300	0.263		✓
⊥ PERP 2620 - P1							
DRTE 2620 - P1(G)/PLAN H - C-Zone							
Val.	0.000	0.068		0.200	0.068		✓
⊥ PERP 2620 - P2							
DRTE 2620 - P2(G)/PLAN H - C-Zone							
Val.	0.000	0.067		0.200	0.067		✓
⊥ PERP 2620 - P3							
DRTE 2620 - P3(G)/PLAN H - C-Zone							
Val.	0.000	0.037		0.200	0.037		✓
⊥ PERP 2620 - P4							
DRTE 2620 - P4(G)/PLAN H - C-Zone							
Val.	0.000	0.060		0.200	0.060		✓
⊥ PERP 2620 - P5							
DRTE 2620 - P5(G)/PLAN H - C-Zone							
Val.	0.000	0.072		0.200	0.072		✓
DIST 2630							
DRTE L-1 - DRTE L-2 / REP ABC.							
D	7.180	7.099	-0.050	0.050	-0.081	-0.031	✗
DIST 2640							
DRTE 2640 - 2 - DRTE 2640 - 1 / REP ABC.							
D	7.150	7.129	-0.050	0.050	-0.021		✓

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
DIST 2650							
DRTE F - 1 - DRTE F-2 / REP ABC.							
D	6.950	6.942	-0.050	0.050	-0.008		✓
DIST 2660 - F							
DRTE 2640 - MID - DRTE F / REP ABC.							
D	0.000	0.033	-0.050	0.050	0.033		✓
SYMMETRY 0.1 - DIST 2660							
=ABS([DIST 2660 - F=>Dist1]-[DIST 2660 - F->Dist1])*2							
Val.	0.000	0.067	0.000	0.100	0.067		✓
DIST 2660 - L							
DRTE 2640 - MID - DRTE L / REP ABC.							
D	0.000	0.025	-0.050	0.050	0.025		✓
SYMMETRY 0.1 - DIST 2660 - L							
=ABS([DIST 2660 - L=>Dist1]-[DIST 2660 - L->Dist1])*2							
Val.	0.000	0.049	0.000	0.100	0.049		✓
DIST 2710 - MP6							
POIN 2710 - MP6 - 1 - POIN 2710 - MP6 - 2 / REP ABC.							
dZ	54.200	54.115	-0.050	0.200	-0.085	-0.035	✗
DIST 2710 - MP7							
POIN 2710 - MP7 - 1 - POIN 2710 - MP7 - 2 / REP ABC.							
dZ	54.200	54.270	-0.100	0.550	0.070		✓
DIST 2710 - MP8							
POIN 2710 - MP8 - 1 - POIN 2710 - MP8 - 2 / REP ABC.							
dZ	54.200	54.217	-0.020	0.200	0.017		✓
DIST 2750							
POIN 2780 - 3 - POIN D.69 / REP ABC.							
dZ	0.000	-0.014	-0.050	0.050	-0.014		✓
SYMMETRY 0.1 - DIST 2750							
=ABS([DIST 2750=>Z]-[DIST 2750->Z])*2							
Val.	0.000	0.027	0.000	0.100	0.027		✓
DIST 2750 - K							
POIN 2780 - 3 - POIN 2500 - P3 - X / REP ABC.							
dZ	0.000	0.045	-0.050	0.050	0.045		✓
SYMMETRY 0.1 - DIST 2750 - K							
=ABS([DIST 2750 - K=>Z]-[DIST 2750 - K->Z])*2							
Val.	0.000	0.089	0.000	0.100	0.089		✓
DIST 2760							
POIN 2760 - POIN D.69 / REP ABC.							
dZ	-0.000	-0.001	-0.050	0.050	-0.001		✓
SYMMETRY 0.1 - DIST 2760							
=ABS([DIST 2760=>Z]-[DIST 2760->Z])*2							
Val.	0.000	0.002	0.000	0.100	0.002		✓
DIST 2760 - K							
POIN 2760 - POIN 2500 - P3 - X / REP ABC.							
dZ	0.000	0.057	-0.050	0.050	0.057	0.007	✗
SYMMETRY 0.1 - DIST 2760 - K							
=ABS([DIST 2760 - K=>Z]-[DIST 2760 - K->Z])*2							
Val.	0.000	0.115	0.000	0.100	0.115	0.015	✗
DIST 2770							
POIN 2770 - 1 - POIN 2770 - 2 / REP ABC.							
D	23.190	23.281	-0.050	0.050	0.091	0.041	✗
DIST 2780							
POIN 2780 - 1 - POIN 2780 - 2 / REP ABC.							
D	23.150	23.179	-0.050	0.050	0.029		✓
DIST 2790							
POIN D-2 - POIN D-1 / REP ABC.							
dZ	21.600	21.552	-0.050	0.050	-0.048		✓
DIST 2800							
POIN 2800 - 1 - POIN 2800 - 2 / REP ABC.							
D	23.850	24.036	-0.150	0.150	0.186	0.036	✗
DIST 2820 - P1							
POIN D.69 - POIN 2820 - P1 / REP ABC.							
dZ	8.000	7.922	-0.150	0.150	-0.078		✓
TRUE POSITION 0.3 - DIST 2820 - P1							
=ABS([DIST 2820 - P1=>Z]-[DIST 2820 - P1->Z])*2							
Val.	0.000	0.156	0.000	0.300	0.156		✓
DIST 2820 - P2							
POIN D.69 - POIN 2820 - P2 / REP ABC.							
dZ	4.000	3.987	-0.150	0.150	-0.013		✓
TRUE POSITION 0.3 - DIST 2820 - P2							
=ABS([DIST 2820 - P2=>Z]-[DIST 2820 - P2->Z])*2							
Val.	0.000	0.026	0.000	0.300	0.026		✓

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
⌐⌐ DIST 2820 - P3							
▪ POIN D.69 - POIN 2820 - P3 / REP ABC.							
dZ	-0.000	0.012	-0.150	0.150	0.012		✓
⩘ TRUE POSITION 0.3 - DIST 2820 - P3							
▪ =ABS([DIST 2820 - P3=>Z]-[DIST 2820 - P3->Z])*2							
Val.	0.000	0.025	0.000	0.300	0.025		✓
⌐⌐ DIST 2820 - P4							
▪ POIN 2820 - P4 - POIN D.69 / REP ABC.							
dZ	4.000	3.965	-0.150	0.150	-0.035		✓
⩘ TRUE POSITION 0.3 - DIST 2820 - P4							
▪ =ABS([DIST 2820 - P4=>Z]-[DIST 2820 - P4->Z])*2							
Val.	0.000	0.070	0.000	0.300	0.070		✓
⌐⌐ DIST 2820 - P5							
▪ POIN 2820 - P5 - POIN D.69 / REP ABC.							
dZ	8.000	7.890	-0.150	0.150	-0.110		✓
⩘ TRUE POSITION 0.3 - DIST 2820 - P5							
▪ =ABS([DIST 2820 - P5=>Z]-[DIST 2820 - P5->Z])*2							
Val.	0.000	0.220	0.000	0.300	0.220		✓