THOMAS TONTEC

SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010_A - C1 - 28.07.2021 - 04.00

OPERATOR: CS

DATE : 28/07/21 10:54:04 SOFTWARE: METROLOG X4V14

RESULTS

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
S10 - CERC 710 - C							
Inters. PLAN A - CYL C.							
Diam.	4.000	3.905	-0.100	0.000	-0.095		✓
S10 - CERC 710 - B							
Inters. PLAN A - CYL B.							
Diam.	4.000	3.942	-0.100	0.000	-0.058		✓
S07 - PLTE 450							
PLAN A C							
Val.	0.000	0.195		0.200	0.195		✓
S04 - PLTE 455							
PLAN J C							
Val.	0.000	0.164		0.200	0.164		✓
S15 - DIST 470 - 11.25							
DRTE B-C - POIN 470 - 11.25 / REP ABC.							
dZ	11.250	11.133	-0.075	0.075	-0.117	-0.042	✗
TRUE POSITION 0.15 - S15 - DIST 470 - 11.25							
=ABS([S15 - DIST 470 - 11.25=>Z]-[S15 - DIST 470 - 11.25->Z])*2							
Val.	0.000	0.233	0.000	0.150	0.233	0.083	✗
S15 - DIST 470 - 33.65							
DRTE B-C - POIN 470 - 33.65 / REP ABC.							
dZ	33.650	33.539	-0.130	0.130	-0.111		✓
TRUE POSITION 0.15 - S15 - DIST 470 - 33.65							
=ABS([S15 - DIST 470 - 33.65=>Z]-[S15 - DIST 470 - 33.65->Z])*2							
Val.	0.000	0.222	0.000	0.260	0.222		✓
S18 - DIST 550							
PLAN A - POIN 550 / REP ABC.							
D	6.100	6.214	-0.100	0.100	0.114	0.014	✗
S06 - DIST 1280							
POIN 1280 - 1 - POIN 1280 - 2 / REP ABC.							
D	12.700	12.606	-0.100	0.100	-0.094		✓
S16 - DIST 1300 - LEFT							
PLAN H - POIN 1300 - LEFT / REP ABC.							
dY	12.015	12.079	-0.050	0.050	0.064	0.014	✗
S16 - DIST 1300 - RIGHT							
PLAN H - POIN 1300 - RIGHT / REP ABC.							
dY	12.015	12.005	-0.050	0.050	-0.010		✓
S19 - DIST 1400 - P6 - DOWN							
PLAN J - POIN 1400 - P6 - DOWN / REP ABC.							
dY	0.850	0.917	-0.100	0.110	0.067		✓
S19 - DIST 1400 - P6 - UP							
PLAN J - POIN 1400 - P6 - UP / REP ABC.							
dY	0.850	0.891	-0.100	0.110	0.041		✓
S19 - DIST 1400 - P7 - DOWN							
PLAN J - POIN 1400 - P7 - DOWN / REP ABC.							
dY	0.850	0.861	-0.100	0.110	0.011		✓
S19 - DIST 1400 - P7 - UP							
PLAN J - POIN 1400 - P7 - UP / REP ABC.							
dY	0.850	0.872	-0.100	0.110	0.022		✓
S05 - DIST 1410 - P6 - 12.8							
POIN 2500 - P3 - X - POIN 1410 - 1 - 12.8 / REP ABC.							
dZ	12.800	12.856	-0.150	0.150	0.056		✓
S05 - DIST 1410 - P6 - 3.4							
POIN 2500 - P3 - Z - POIN 1410 - 1 - 3.4 / REP ABC.							
dX	3.400	3.271	-0.150	0.150	-0.129		✓
TRUE POSITION 0.3 X^2+Y^2 - S05 - DIST 1410 - P6							
=[SQRT X^2+Y^2 - S05 - DIST 1410 - P6->Val]*2							
Val.	0.000	0.281	0.000	0.300	0.281		✓
S05 - DIST 1410 - P7 - 9.6							
POIN 1410 - 2 - 9.6 - POIN 2500 - P3 - X / REP ABC.							
dZ	9.600	9.606	-0.150	0.150	0.006		✓
S05 - DIST 1410 - P7 - 3.4							
POIN 2500 - P3 - Z - POIN 1410 - 2 - 3.4 / REP ABC.							
dX	3.400	3.335	-0.150	0.150	-0.065		✓
TRUE POSITION 0.3 X^2+Y^2 - S05 - DIST 1410 - P7							
=[SQRT X^2+Y^2 - S05 - DIST 1410 - P7->Val]*2							
Val.	0.000	0.130	0.000	0.300	0.130		✓
S01 - 1690 - MP10							
POIN 109 - MP10 - 2 - POIN 109 - MP10 - 1 / REP ABC.							
dX	109.000	109.074	-0.100	0.200	0.074		✓

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Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
S01 - 1690 - MP11							
POIN 109 - MP11 - 2 - POIN 109 - MP11 - 1 / REP ABC.							
dX	109.000	109.198	-0.100	0.200	0.198		✓
S01 - 1690 - MP12							
POIN 109 - MP12 - 2 - POIN 109 - MP12 - 1 / REP ABC.							
dX	109.000	109.033	-0.100	0.200	0.033		✓
S02 - 1730							
POIN 1730 - 2 - POIN 1730 - 1 / REP ABC.							
dZ	56.700	56.786	-0.100	0.300	0.086		✓
S03 - DIST 1880							
PLAN 1880 - POIN 1880 - 3 / REP ABC.							
dY	43.500	43.453	-0.100	0.150	-0.047		✓
S17 - 1980 - 1							
PLAN A-1 - POIN 1680 - 1 - 3 / REP ABC.							
D	7.000	6.861	-0.130	0.000	-0.139	-0.009	✗
S17 - 1980 - 2							
PLAN A-2 - POIN 1980 - 2 - 3 / REP ABC.							
D	7.000	6.981	-0.100	0.000	-0.019		✓
S17 - 1980 - 3							
PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC.							
D	7.000	7.010	-0.050	0.075	0.010		✓
S17 - 1980 - 4							
PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.							
D	7.000	6.872	-0.130	0.000	-0.128		✓
S17 - 1980 - 5							
PLAN A-5 - POIN 1980 - 5 - 3 / REP ABC.							
D	7.000	6.986	-0.050	0.040	-0.014		✓
S17 - 1980 - 6							
PLAN A-6 - POIN 1980 - 6 - 3 / REP ABC.							
D	7.000	6.867	-0.100	0.000	-0.133	-0.033	✗
S13 - DIST 2310 - MP1 - UP							
POIN 2310 - MP1 - UP - 1 - POIN 2310 - MP1 - UP - 2 / REP ABC.							
D	9.950	9.930	-0.050	0.150	-0.020		✓
S13 - DIST 2310 - MP1 - DOWN							
POIN 2310 - MP1 - DOWN - 1 - POIN 2310 - MP1 - DOWN - 2 / REP ABC.							
D	9.950	9.964	-0.050	0.150	0.014		✓
S13 - DIST 2310 - MP4 - UP							
POIN 2310 - MP4 - UP - 1 - POIN 2310 - MP4 - UP - 2 / REP ABC.							
D	9.950	10.074	-0.050	0.150	0.124		✓
S13 - DIST 2310 - MP4 - DOWN							
POIN 2310 - MP4 - DOWN - 1 - POIN 2310 - MP4 - DOWN - 2 / REP ABC.							
D	9.950	10.066	-0.050	0.150	0.116		✓
S08 - DIST 2420 - MP1							
POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.							
D	25.900	26.034	-0.100	0.150	0.134		✓
S08 - DIST 2420 - MP2							
POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.							
D	25.900	26.050	-0.100	0.150	0.150		✓
S09 - DIST 2500 - P1 - 8							
POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.							
dZ	8.000	8.001	-0.100	0.100	0.001		✓
S09 - DIST 2500 - P1 - 0							
POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.							
dX	-0.000	0.010	-0.100	0.100	0.010		✓
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P1							
=[SQRT X^2+Y^2 - S09 - DIST 2500 - P1->Val]*2							
Val.	0.000	0.020	0.000	0.200	0.020		✓
S09 - DIST 2500 - P2 - 4							
POIN 2500 - P3 - X - POIN 2500 - P2 - .4 / REP ABC.							
dZ	4.000	4.020	-0.100	0.100	0.020		✓
S09 - DIST 2500 - P2 - 0							
POIN 2500 - P2 - 0 - POIN 2500 - P3 - Z / REP ABC.							
dX	-0.000	-0.034	-0.100	0.100	-0.034		✓
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P2							
=[SQRT X^2+Y^2 - S09 - DIST 2500 - P2->Val]*2							
Val.	0.000	0.079	0.000	0.200	0.079		✓
S09 - DIST 2500 - P4 - 4							
POIN 2500 - P4 - .4 - POIN 2500 - P3 - X / REP ABC.							
dZ	4.000	3.977	-0.100	0.100	-0.023		✓
S09 - DIST 2500 - P4 - 0							
POIN 2500 - P4 - 0 - POIN 2500 - P3 - Z / REP ABC.							
dX	0.000	-0.004	-0.100	0.100	-0.004		✓

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Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P4							
=[SQRT X^2+Y^2 - S09 - DIST 2500 - P4->Val]*2							
Val.	0.000	0.047	0.000	0.200	0.047		✓
S09 - DIST 2500 - P5 - 8							
POIN 2500 - P5 - 8 - POIN 2500 - P3 - X / REP ABC.							
dZ	8.000	7.982	-0.100	0.100	-0.018		✓
S09 - DIST 2500 - P5 - 0							
POIN 2500 - P5 - 0 - POIN 2500 - P3 - Z / REP ABC.							
dX	0.000	0.056	-0.100	0.100	0.056		✓
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P5							
=[SQRT X^2+Y^2 - S09 - DIST 2500 - P5->Val]*2							
Val.	0.000	0.117	0.000	0.200	0.117		✓
S20 - DIST 2530 - P1 - DOWN							
PLAN J - POIN 2530 - P1 - DOWN / REP ABC.							
dY	1.150	1.079	-0.100	0.100	-0.071		✓
S20 - DIST 2530 - P1 - UP							
PLAN J - POIN 2530 - P1 - UP / REP ABC.							
dY	1.150	1.086	-0.100	0.100	-0.064		✓
S20 - DIST 2530 - P2 - DOWN							
PLAN J - POIN 2530 - P2 - DOWN / REP ABC.							
dY	1.150	1.082	-0.100	0.100	-0.068		✓
S20 - DIST 2530 - P2 - UP							
PLAN J - POIN 2530 - P2 - UP / REP ABC.							
dY	1.150	1.055	-0.100	0.100	-0.095		✓
S20 - DIST 2530 - P3 - DOWN							
PLAN J - POIN 2530 - P3 - DOWN / REP ABC.							
dY	1.150	1.067	-0.100	0.100	-0.083		✓
S20 - DIST 2530 - P3 - UP							
PLAN J - POIN 2530 - P3 - UP / REP ABC.							
dY	1.150	1.086	-0.100	0.100	-0.064		✓
S20 - DIST 2530 - P4 - DOWN							
PLAN J - POIN 2530 - P4 - DOWN / REP ABC.							
dY	1.150	1.052	-0.140	0.100	-0.098		✓
S20 - DIST 2530 - P4 - UP							
PLAN J - POIN 2530 - P4 - UP / REP ABC.							
dY	1.150	1.035	-0.120	0.100	-0.115		✓
S20 - DIST 2530 - P5 - DOWN							
PLAN J - POIN 2530 - P5 - DOWN / REP ABC.							
dY	1.150	1.074	-0.100	0.100	-0.076		✓
S20 - DIST 2530 - P5 - UP							
PLAN J - POIN 2500 - P5 - UP / REP ABC.							
dY	1.150	1.089	-0.100	0.100	-0.061		✓
S14 - 2670 - 29.5							
S10 - CERC 710 - B - POIN K-5 / REP ABC.							
dX	29.500	29.533	-0.100	0.100	0.033		✓
S14 - 2670 - 20.85							
S10 - CERC 710 - B - POIN K-6 / REP ABC.							
dZ	20.850	20.750	-0.100	0.100	-0.100		✓
TRUE POSITION 0.2 X^2+Y^2 - S14 - 2670 - 20.8529							
=[SQRT X^2+Y^2 - S14 - 2670->Val]*2							
Val.	0.000	0.210	0.000	0.200	0.210	0.010	✗
S12 - DIST 2810 - P1							
POIN D.69 - POIN 2810 - P1 / REP ABC.							
dZ	8.000	7.941	-0.075	0.075	-0.059		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P1							
=ABS([S12 - DIST 2810 - P1=>Z]-[S12 - DIST 2810 - P1->Z])*2							
Val.	0.000	0.117	0.000	0.150	0.117		✓
S12 - DIST 2810 - P2							
POIN D.69 - POIN 2810 - P2 / REP ABC.							
dZ	4.000	3.976	-0.075	0.075	-0.024		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P2							
=ABS([S12 - DIST 2810 - P2=>Z]-[S12 - DIST 2810 - P2->Z])*2							
Val.	0.000	0.048	0.000	0.150	0.048		✓
S12 - DIST 2810 - P3							
POIN D.69 - POIN 2810 - P3 / REP ABC.							
dZ	0.000	0.025	-0.075	0.075	0.025		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P3							
=ABS([S12 - DIST 2810 - P3=>Z]-[S12 - DIST 2810 - P3->Z])*2							
Val.	0.000	0.049	0.000	0.150	0.049		✓
S12 - DIST 2810 - P4							
POIN 2810 - P4 - POIN D.69 / REP ABC.							
dZ	4.000	3.958	-0.075	0.075	-0.042		✓

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TRUE POSITION 0.15 - S12 - DIST 2810 - P4							
=ABS([S12 - DIST 2810 - P4=>Z]-[S12 - DIST 2810 - P4->Z])*2							
Val.	0.000	0.084	0.000	0.150	0.084		✓
S12 - DIST 2810 - P5							
POIN 2810 - P5 - POIN D.69 / REP ABC.							
dZ	8.000	7.931	-0.075	0.075	-0.069		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P5							
=ABS([S12 - DIST 2810 - P5=>Z]-[S12 - DIST 2810 - P5->Z])*2							
Val.	0.000	0.139	0.000	0.150	0.139		✓
VAL1							
Dimensiuni extra							
DIST 400 - 1							
POIN 400 - 1-5 - PLAN 400 - 1 / REP ABC.							
dZ	2.650	2.544	-0.120	0.100	-0.106		✓
DIST 400 - 2							
POIN 400 - 2-5 - PLAN 400 - 2 / REP ABC.							
dZ	2.650	2.589	-0.090	0.090	-0.061		✓
DIST 400 - 3							
PLAN 400 - 3 - POIN 400 - 3-5 / REP ABC.							
dX	2.650	2.599	-0.140	0.090	-0.051		✓
DIST 400 - 4							
PLAN 400 - 4 - POIN 400 - 4-5 / REP ABC.							
dZ	2.650	2.603	-0.120	0.090	-0.047		✓
DIST 400 - 5							
PLAN 400 - 5 - POIN 400 - 5-9 / REP ABC.							
dZ	2.650	2.420	-0.280	0.090	-0.230		✓
DIST 400 - 6							
POIN 400 - 6-5 - PLAN 400 - 6 / REP ABC.							
dX	2.650	2.541	-0.120	0.090	-0.109		✓
DIST 410 - 1							
POIN 410 - 1 - POIN 410 - 1-2 / REP ABC.							
dY	2.600	2.443	-0.150	0.090	-0.157	-0.007	✗
DIST 410 - 2							
POIN 410 - 2 - POIN 410 - 2-2 / REP ABC.							
dY	2.600	2.552	-0.100	0.090	-0.048		✓
DIST 410 - 3							
POIN 410 - 3-1 - POIN 410 - 3-2 / REP ABC.							
dY	2.600	2.621	-0.090	0.090	0.021		✓
DIST 410 - 4							
POIN 410 - 4-1 - POIN 410 - 4-2 / REP ABC.							
dY	2.600	2.454	-0.200	0.090	-0.146		✓
DIST 410 - 5							
POIN 410 - 5 - POIN 410 - 5-2 / REP ABC.							
dY	2.600	2.620	-0.090	0.090	0.020		✓
DIST 410 - 6							
POIN 410 - 6 - POIN 1980 - 6 - 3 / REP ABC.							
dY	2.600	2.550	-0.090	0.090	-0.050		✓
DIST 630 - 1							
POIN 630 - 1-1 - POIN 630 - 1-2 / REP ABC.							
dZ	55.500	55.275	-0.270	0.100	-0.225		✓
DIST 630 - 2							
POIN 630 - 2-1 - POIN 630 - 2-2 / REP ABC.							
dZ	55.500	55.140	-0.270	0.100	-0.360	-0.090	✗
DIST 780 - 1							
POIN 780 - 1 - PLAN 780 - 1 / REP ABC.							
D	3.200	3.301	0.000	0.170	0.101		✓
DIST 780 - 2							
POIN 780 - 2 - PLAN 780 - 2 / REP ABC.							
D	3.200	3.333	0.000	0.190	0.133		✓
DIST 780 - 3							
POIN 780 - 3 - PLAN 780 - 3 / REP ABC.							
D	3.200	3.273	0.000	0.100	0.073		✓
DIST 780 - 4							
POIN 780 - 4 - PLAN 780 - 4 / REP ABC.							
D	3.200	3.374	0.000	0.100	0.174	0.074	✗
DIST 1780 - MP10							
POIN 1780 - MP10 - 2 - POIN 1780 - MP10 - 1 / REP ABC.							
dX	106.500	106.608	0.000	0.220	0.108		✓
DIST 1780 - MP11							
POIN 1780 - MP11 - 2 - POIN 1780 - MP11 - 1 / REP ABC.							
dX	106.500	106.591	0.000	0.220	0.091		✓

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DIST 1780 - MP12							
POIN 1780 - MP12 - 2 - POIN 1780 - MP12 - 1 / REP ABC.							
dX	106.500	106.556	0.000	0.220	0.056		✓
DIST 2600 - P1 - F							
POIN 2600 - P1 - DRTE F / REP ABC.							
dX	-0.000	-0.057	-0.075	0.075	-0.057		✓
0.1 - DIST 2600 - P1 - F							
=ABS([DIST 2600 - P1 - F=>X]-[DIST 2600 - P1 - F->X])*2							
Val.	0.000	0.115	0.000	0.150	0.115		✓
DIST 2600 - P2 - F							
POIN 2600 - P2 - DRTE F / REP ABC.							
dX	0.000	-0.055	-0.075	0.075	-0.055		✓
0.1 - DIST 2600 - P2 - F							
=ABS([DIST 2600 - P2 - F=>X]-[DIST 2600 - P2 - F->X])*2							
Val.	0.000	0.109	0.000	0.150	0.109		✓
DIST 2600 - P3 - F							
POIN 2600 - P3 - DRTE F / REP ABC.							
dX	0.000	-0.062	-0.075	0.075	-0.062		✓
0.1 - DIST 2600 - P3 - F							
=ABS([DIST 2600 - P3 - F=>X]-[DIST 2600 - P3 - F->X])*2							
Val.	0.000	0.124	0.000	0.150	0.124		✓
DIST 2600 - P4 - F							
POIN 2600 - P4 - DRTE F / REP ABC.							
dX	-0.000	-0.069	-0.075	0.075	-0.069		✓
0.1 - DIST 2600 - P4 - F							
=ABS([DIST 2600 - P4 - F=>X]-[DIST 2600 - P4 - F->X])*2							
Val.	0.000	0.138	0.000	0.150	0.138		✓
DIST 2600 - P5 - F							
POIN 2600 - P5 - DRTE F / REP ABC.							
dX	-0.000	-0.046	-0.075	0.075	-0.046		✓
0.1 - DIST 2600 - P5 - F							
=ABS([DIST 2600 - P5 - F=>X]-[DIST 2600 - P5 - F->X])*2							
Val.	0.000	0.092	0.000	0.150	0.092		✓
DIST 2600 - P1 - L							
POIN 2600 - P1 - DRTE L / REP ABC.							
dX	-0.000	0.019	-0.075	0.075	0.019		✓
0.1 - DIST 2600 - P1 - L							
=ABS([DIST 2600 - P1 - L=>X]-[DIST 2600 - P1 - L->X])*2							
Val.	0.000	0.039	0.000	0.150	0.039		✓
DIST 2600 - P2 - L							
POIN 2600 - P2 - DRTE L / REP ABC.							
dX	0.000	0.028	-0.075	0.075	0.028		✓
0.1 - DIST 2600 - P2 - L							
=ABS([DIST 2600 - P2 - L=>X]-[DIST 2600 - P2 - L->X])*2							
Val.	0.000	0.057	0.000	0.150	0.057		✓
DIST 2600 - P3 - L							
POIN 2600 - P3 - DRTE L / REP ABC.							
dX	-0.000	0.027	-0.075	0.075	0.027		✓
0.1 - DIST 2600 - P3 - L							
=ABS([DIST 2600 - P3 - L=>X]-[DIST 2600 - P3 - L->X])*2							
Val.	0.000	0.055	0.000	0.150	0.055		✓
DIST 2600 - P4 - L							
POIN 2600 - P4 - DRTE L / REP ABC.							
dX	0.000	0.027	-0.075	0.075	0.027		✓
0.1 - DIST 2600 - P4 - L							
=ABS([DIST 2600 - P4 - L=>X]-[DIST 2600 - P4 - L->X])*2							
Val.	0.000	0.054	0.000	0.150	0.054		✓
DIST 2600 - P5 - L							
POIN 2600 - P5 - DRTE L / REP ABC.							
dX	-0.000	0.057	-0.075	0.075	0.057		✓
0.1 - DIST 2600 - P5 - L							
=ABS([DIST 2600 - P5 - L=>X]-[DIST 2600 - P5 - L->X])*2							
Val.	0.000	0.113	0.000	0.150	0.113		✓
DIST 2610 - P1 - F							
POIN 2610 - P1 - DRTE F / REP ABC.							
dX	0.000	-0.062	-0.150	0.150	-0.062		✓
0.1 - DIST 2610 - P1 - F							
=ABS([DIST 2610 - P1 - F=>X]-[DIST 2610 - P1 - F->X])*2							
Val.	0.000	0.124	0.000	0.300	0.124		✓
DIST 2610 - P2 - F							
POIN 2610 - P2 - DRTE F / REP ABC.							
dX	0.000	-0.050	-0.150	0.150	-0.050		✓

THOMAS TONTEC

SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010_A - C1 - 28.07.2021 - 04.00

OPERATOR: CS

DATE : 28/07/21 10:54:06 SOFTWARE: METROLOG X4V14

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
0.1 - DIST 2610 - P2 - F							
=ABS([DIST 2610 - P2 - F=>X]-[DIST 2610 - P2 - F->X])*2							
Val.	0.000	0.099	0.000	0.300	0.099		✓
DIST 2610 - P3 - F							
POIN 2610 - P3 - DRTE F / REP ABC.							
dX	0.000	-0.111	-0.150	0.150	-0.111		✓
0.1 - DIST 2610 - P3 - F							
=ABS([DIST 2610 - P3 - F=>X]-[DIST 2610 - P3 - F->X])*2							
Val.	0.000	0.222	0.000	0.300	0.222		✓
DIST 2610 - P4 - F							
POIN 2610 - P4 - DRTE F / REP ABC.							
dX	0.000	-0.125	-0.150	0.150	-0.125		✓
0.1 - DIST 2610 - P4 - F							
=ABS([DIST 2610 - P4 - F=>X]-[DIST 2610 - P4 - F->X])*2							
Val.	0.000	0.251	0.000	0.300	0.251		✓
DIST 2610 - P5 - F							
POIN 2610 - P5 - DRTE F / REP ABC.							
dX	0.000	-0.116	-0.150	0.150	-0.116		✓
0.1 - DIST 2610 - P5 - F							
=ABS([DIST 2610 - P5 - F=>X]-[DIST 2610 - P5 - F->X])*2							
Val.	0.000	0.231	0.000	0.300	0.231		✓
DIST 2610 - P1 - L							
POIN 2610 - P1 - DRTE L / REP ABC.							
dX	0.000	0.015	-0.150	0.150	0.015		✓
0.1 - DIST 2610 - P1 - L							
=ABS([DIST 2610 - P1 - L=>X]-[DIST 2610 - P1 - L->X])*2							
Val.	0.000	0.029	0.000	0.300	0.029		✓
DIST 2610 - P2 - L							
POIN 2610 - P2 - DRTE L / REP ABC.							
dX	0.000	0.033	-0.150	0.150	0.033		✓
0.1 - DIST 2610 - P2 - L							
=ABS([DIST 2610 - P2 - L=>X]-[DIST 2610 - P2 - L->X])*2							
Val.	0.000	0.067	0.000	0.300	0.067		✓
DIST 2610 - P3 - L							
POIN 2610 - P3 - DRTE L / REP ABC.							
dX	0.000	-0.021	-0.150	0.150	-0.021		✓
0.1 - DIST 2610 - P3 - L							
=ABS([DIST 2610 - P3 - L=>X]-[DIST 2610 - P3 - L->X])*2							
Val.	0.000	0.043	0.000	0.300	0.043		✓
DIST 2610 - P4 - L							
POIN 2610 - P4 - DRTE L / REP ABC.							
dX	0.000	-0.029	-0.150	0.150	-0.029		✓
0.1 - DIST 2610 - P4 - L							
=ABS([DIST 2610 - P4 - L=>X]-[DIST 2610 - P4 - L->X])*2							
Val.	0.000	0.058	0.000	0.300	0.058		✓
DIST 2610 - P5 - L							
POIN 2610 - P5 - DRTE L / REP ABC.							
dX	-0.000	-0.013	-0.150	0.150	-0.013		✓
0.1 - DIST 2610 - P5 - L							
=ABS([DIST 2610 - P5 - L=>X]-[DIST 2610 - P5 - L->X])*2							
Val.	0.000	0.026	0.000	0.300	0.026		✓
PERP 2620 - P1							
DRTE 2620 - P1(G)/PLAN H - C-Zone							
Val.	0.000	0.030		0.200	0.030		✓
PERP 2620 - P2							
DRTE 2620 - P2(G)/PLAN H - C-Zone							
Val.	0.000	0.021		0.200	0.021		✓
PERP 2620 - P3							
DRTE 2620 - P3(G)/PLAN H - C-Zone							
Val.	0.000	0.074		0.200	0.074		✓
PERP 2620 - P4							
DRTE 2620 - P4(G)/PLAN H - C-Zone							
Val.	0.000	0.081		0.200	0.081		✓
PERP 2620 - P5							
DRTE 2620 - P5(G)/PLAN H - C-Zone							
Val.	0.000	0.095		0.200	0.095		✓
DIST 2630							
DRTE L-1 - DRTE L-2 / REP ABC.							
D	7.180	7.113	-0.050	0.050	-0.067	-0.017	✗
DIST 2640							
DRTE 2640 - 2 - DRTE 2640 - 1 / REP ABC.							
D	7.150	7.117	-0.050	0.050	-0.033		✓

THOMAS TONTEC

SITE: **TRP** Control Equipment: **QC_74 - DEA Performance**

THOMAS REFERENCE: **HEL010_A - C1 - 28.07.2021 - 04.00**

OPERATOR: **CS**

DATE : **28/07/21 10:54:06** SOFTWARE: **METROLOG X4V14**

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
DIST 2650							
DRTE F - 1 - DRTE F-2 / REP ABC.							
D	6.950	6.941	-0.050	0.050	-0.009		✓
DIST 2660 - F							
DRTE 2640 - MID - DRTE F / REP ABC.							
D	0.000	0.047	-0.050	0.050	0.047		✓
SYMMETRY 0.1 - DIST 2660							
=ABS([DIST 2660 - F=>Dist1]-[DIST 2660 - F->Dist1])*2							
Val.	0.000	0.094	0.000	0.100	0.094		✓
DIST 2660 - L							
DRTE 2640 - MID - DRTE L / REP ABC.							
D	0.000	0.042	-0.050	0.050	0.042		✓
SYMMETRY 0.1 - DIST 2660 - L							
=ABS([DIST 2660 - L=>Dist1]-[DIST 2660 - L->Dist1])*2							
Val.	0.000	0.085	0.000	0.100	0.085		✓
DIST 2710 - MP6							
POIN 2710 - MP6 - 1 - POIN 2710 - MP6 - 2 / REP ABC.							
dZ	54.200	54.049	-0.050	0.200	-0.151	-0.101	✗
DIST 2710 - MP7							
POIN 2710 - MP7 - 1 - POIN 2710 - MP7 - 2 / REP ABC.							
dZ	54.200	54.100	-0.100	0.550	-0.100	-0.000	✗
DIST 2710 - MP8							
POIN 2710 - MP8 - 1 - POIN 2710 - MP8 - 2 / REP ABC.							
dZ	54.200	54.130	-0.020	0.200	-0.070	-0.050	✗
DIST 2750							
POIN 2780 - 3 - POIN D.69 / REP ABC.							
dZ	0.000	-0.022	-0.050	0.050	-0.022		✓
SYMMETRY 0.1 - DIST 2750							
=ABS([DIST 2750=>Z]-[DIST 2750->Z])*2							
Val.	0.000	0.043	0.000	0.100	0.043		✓
DIST 2750 - K							
POIN 2780 - 3 - POIN 2500 - P3 - X / REP ABC.							
dZ	0.000	-0.042	-0.050	0.050	-0.042		✓
SYMMETRY 0.1 - DIST 2750 - K							
=ABS([DIST 2750 - K=>Z]-[DIST 2750 - K->Z])*2							
Val.	0.000	0.084	0.000	0.100	0.084		✓
DIST 2760							
POIN 2760 - POIN D.69 / REP ABC.							
dZ	0.000	-0.030	-0.050	0.050	-0.030		✓
SYMMETRY 0.1 - DIST 2760							
=ABS([DIST 2760=>Z]-[DIST 2760->Z])*2							
Val.	0.000	0.059	0.000	0.100	0.059		✓
DIST 2760 - K							
POIN 2760 - POIN 2500 - P3 - X / REP ABC.							
dZ	0.000	-0.050	-0.050	0.050	-0.050	-0.000	✗
SYMMETRY 0.1 - DIST 2760 - K							
=ABS([DIST 2760 - K=>Z]-[DIST 2760 - K->Z])*2							
Val.	0.000	0.100	0.000	0.100	0.100	0.000	✗
DIST 2770							
POIN 2770 - 1 - POIN 2770 - 2 / REP ABC.							
D	23.190	23.290	-0.050	0.050	0.100	0.050	✗
DIST 2780							
POIN 2780 - 1 - POIN 2780 - 2 / REP ABC.							
D	23.150	23.183	-0.050	0.050	0.033		✓
DIST 2790							
POIN D-2 - POIN D-1 / REP ABC.							
dZ	21.600	21.551	-0.050	0.050	-0.049		✓
DIST 2800							
POIN 2800 - 1 - POIN 2800 - 2 / REP ABC.							
D	23.850	24.077	-0.150	0.150	0.227	0.077	✗
DIST 2820 - P1							
POIN D.69 - POIN 2820 - P1 / REP ABC.							
dZ	8.000	7.924	-0.150	0.150	-0.076		✓
TRUE POSITION 0.3 - DIST 2820 - P1							
=ABS([DIST 2820 - P1=>Z]-[DIST 2820 - P1->Z])*2							
Val.	0.000	0.152	0.000	0.300	0.152		✓
DIST 2820 - P2							
POIN D.69 - POIN 2820 - P2 / REP ABC.							
dZ	4.000	3.976	-0.150	0.150	-0.024		✓
TRUE POSITION 0.3 - DIST 2820 - P2							
=ABS([DIST 2820 - P2=>Z]-[DIST 2820 - P2->Z])*2							
Val.	0.000	0.048	0.000	0.300	0.048		✓

THOMAS TONTEC

SITE: **TRP** Control Equipment: **QC_74 - DEA Performance**

THOMAS REFERENCE: **HEL010_A - C1 - 28.07.2021 - 04.00**

OPERATOR: **CS**

DATE : **28/07/21 10:54:06** SOFTWARE: **METROLOG X4V14**

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
DIST 2820 - P3							
POIN D.69 - POIN 2820 - P3 / REP ABC.							
dZ	-0.000	0.045	-0.150	0.150	0.045		✓
TRUE POSITION 0.3 - DIST 2820 - P3							
=ABS([DIST 2820 - P3=>Z]-[DIST 2820 - P3->Z])*2							
Val.	0.000	0.091	0.000	0.300	0.091		✓
DIST 2820 - P4							
POIN 2820 - P4 - POIN D.69 / REP ABC.							
dZ	4.000	3.923	-0.150	0.150	-0.077		✓
TRUE POSITION 0.3 - DIST 2820 - P4							
=ABS([DIST 2820 - P4=>Z]-[DIST 2820 - P4->Z])*2							
Val.	0.000	0.154	0.000	0.300	0.154		✓
DIST 2820 - P5							
POIN 2820 - P5 - POIN D.69 / REP ABC.							
dZ	8.000	7.882	-0.150	0.150	-0.118		✓
TRUE POSITION 0.3 - DIST 2820 - P5							
=ABS([DIST 2820 - P5=>Z]-[DIST 2820 - P5->Z])*2							
Val.	0.000	0.236	0.000	0.300	0.236		✓