

SITE: **TRP**Control Equipment: **QC\_74 - DEA Performance**THOMAS REFERENCE: **HEL010/A - C1 - 07.09.2021 - 08.00**OPERATOR: **PP**DATE : **07/09/21 14:47:31**SOFTWARE: **METROLOG X4V14**

## RESULTS

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
ⓘ S10 - CERC 710 - C							
Inters. PLAN A - CYL C.							
Diam.	4.000	3.915	-0.100	0.000	-0.085		✓
ⓘ S10 - CERC 710 - B							
Inters. PLAN A - CYL B.							
Diam.	4.000	3.928	-0.100	0.000	-0.072		✓
ⓘ S07 - PLTE 450							
PLAN A C							
Val.	0.000	0.200		0.250	0.200		✓
ⓘ S04 - PLTE 455							
PLAN J C							
Val.	0.000	0.137		0.200	0.137		✓
ⓘ S15 - DIST 470 - 11.25							
DRTE B-C - POIN 470 - 11.25 / REP ABC.							
dZ	11.250	11.218	-0.075	0.075	-0.032		✓
⚠ TRUE POSITION 0.15 - S15 - DIST 470 - 11.25							
=ABS([S15 - DIST 470 - 11.25=>Z]-[S15 - DIST 470 - 11.25=>Z])*2							
Val.	0.000	0.065	0.000	0.150	0.065		✓
ⓘ S15 - DIST 470 - 33.65							
DRTE B-C - POIN 470 - 33.65 / REP ABC.							
dZ	33.650	33.661	-0.130	0.130	0.011		✓
⚠ TRUE POSITION 0.15 - S15 - DIST 470 - 33.65							
=ABS([S15 - DIST 470 - 33.65=>Z]-[S15 - DIST 470 - 33.65=>Z])*2							
Val.	0.000	0.021	0.000	0.260	0.021		✓
ⓘ S18 - DIST 550							
PLAN A - POIN 550 / REP ABC.							
D	6.100	6.144	-0.100	0.100	0.044		✓
ⓘ S06 - DIST 1280							
POIN 1280 - 1 - POIN 1280 - 2 / REP ABC.							
D	12.700	12.721	-0.100	0.100	0.021		✓
ⓘ S16 - DIST 1300 - LEFT							
PLAN H - POIN 1300 - LEFT / REP ABC.							
dY	12.015	12.063	-0.050	0.050	0.048		✓
ⓘ S16 - DIST 1300 - RIGHT							
PLAN H - POIN 1300 - RIGHT / REP ABC.							
dY	12.015	12.037	-0.050	0.050	0.022		✓
ⓘ S19 - DIST 1400 - P6 - DOWN							
PLAN J - POIN 1400 - P6 - DOWN / REP ABC.							
dY	0.850	0.905	-0.100	0.110	0.055		✓
ⓘ S19 - DIST 1400 - P6 - UP							
PLAN J - POIN 1400 - P6 - UP / REP ABC.							
dY	0.850	0.887	-0.100	0.110	0.037		✓
ⓘ S19 - DIST 1400 - P7 - DOWN							
PLAN J - POIN 1400 - P7 - DOWN / REP ABC.							
dY	0.850	0.884	-0.100	0.110	0.034		✓
ⓘ S19 - DIST 1400 - P7 - UP							
PLAN J - POIN 1400 - P7 - UP / REP ABC.							
dY	0.850	0.876	-0.100	0.110	0.026		✓
ⓘ S05 - DIST 1410 - P6 - 12.8							
POIN 2500 - P3 - X - POIN 1410 - 1 - 12.8 / REP ABC.							
dZ	12.800	12.843	-0.150	0.150	0.043		✓
ⓘ S05 - DIST 1410 - P6 - 3.4							
POIN 2500 - P3 - Z - POIN 1410 - 1 - 3.4 / REP ABC.							
dX	3.400	3.242	-0.150	0.150	-0.158	-0.008	✗
⚠ TRUE POSITION 0.3 X^2+Y^2 - S05 - DIST 1410 - P6							
=[SQRT X^2+Y^2 - S05 - DIST 1410 - P6->Val])*2							
Val.	0.000	0.328	0.000	0.300	0.328	0.028	✗
ⓘ S05 - DIST 1410 - P7 - 9.6							
POIN 1410 - 2 - 9.6 - POIN 2500 - P3 - X / REP ABC.							
dZ	9.600	9.629	-0.150	0.150	0.029		✓
ⓘ S05 - DIST 1410 - P7 - 3.4							
POIN 2500 - P3 - Z - POIN 1410 - 2 - 3.4 / REP ABC.							
dX	3.400	3.266	-0.150	0.150	-0.134		✓
⚠ TRUE POSITION 0.3 X^2+Y^2 - S05 - DIST 1410 - P7							
=[SQRT X^2+Y^2 - S05 - DIST 1410 - P7->Val])*2							
Val.	0.000	0.274	0.000	0.300	0.274		✓
ⓘ S01 - 1690 - MP10							
POIN 109 - MP10 - 2 - POIN 109 - MP10 - 1 / REP ABC.							
dX	109.000	108.991	-0.100	0.200	-0.009		✓



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S01 - 1690 - MP11 POIN 109 - MP11 - 2 - POIN 109 - MP11 - 1 / REP ABC.							
dX	109.000	108.968	-0.100	0.200	-0.032		✓
S01 - 1690 - MP12 POIN 109 - MP12 - 2 - POIN 109 - MP12 - 1 / REP ABC.							
dX	109.000	109.038	-0.100	0.200	0.038		✓
S02 - 1730 POIN 1730 - 2 - POIN 1730 - 1 / REP ABC.							
dZ	56.700	56.847	-0.100	0.300	0.147		✓
S03 - DIST 1880 PLAN 1880 - POIN 1880 - 3 / REP ABC.							
dY	43.500	43.533	-0.100	0.150	0.033		✓
S17 - 1980 - 1 PLAN A-1 - POIN 1680 - 1 - 3 / REP ABC.							
D	7.000	6.874	-0.130	0.000	-0.126		✓
S17 - 1980 - 2 PLAN A-2 - POIN 1980 - 2 - 3 / REP ABC.							
D	7.000	6.987	-0.100	0.000	-0.013		✓
S17 - 1980 - 3 PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC.							
D	7.000	7.006	-0.050	0.075	0.006		✓
S17 - 1980 - 4 PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.							
D	7.000	6.878	-0.130	0.000	-0.122		✓
S17 - 1980 - 5 PLAN A-5 - POIN 1980 - 5 - 3 / REP ABC.							
D	7.000	6.992	-0.050	0.040	-0.008		✓
S17 - 1980 - 6 PLAN A-6 - POIN 1980 - 6 - 3 / REP ABC.							
D	7.000	6.886	-0.100	0.000	-0.114	-0.014	✗
S13 - DIST 2310 - MP1 - UP POIN 2310 - MP1 - UP - 1 - POIN 2310 - MP1 - UP - 2 / REP ABC.							
D	9.950	9.931	-0.050	0.150	-0.019		✓
S13 - DIST 2310 - MP1 - DOWN POIN 2310 - MP1 - DOWN - 1 - POIN 2310 - MP1 - DOWN - 2 / REP ABC.							
D	9.950	9.997	-0.050	0.150	0.047		✓
S13 - DIST 2310 - MP4 - UP POIN 2310 - MP4 - UP - 1 - POIN 2310 - MP4 - UP - 2 / REP ABC.							
D	9.950	10.088	-0.050	0.150	0.138		✓
S13 - DIST 2310 - MP4 - DOWN POIN 2310 - MP4 - DOWN - 1 - POIN 2310 - MP4 - DOWN - 2 / REP ABC.							
D	9.950	10.078	-0.050	0.150	0.128		✓
S08 - DIST 2420 - MP1 POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.							
D	25.900	26.027	-0.100	0.150	0.127		✓
S08 - DIST 2420 - MP2 POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.							
D	25.900	26.039	-0.100	0.150	0.139		✓
S09 - DIST 2500 - P1 - 8 POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.							
dZ	8.000	7.979	-0.100	0.100	-0.021		✓
S09 - DIST 2500 - P1 - 0 POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.							
dX	0.000	-0.007	-0.100	0.100	-0.007		✓
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P1 =[SQRT X^2+Y^2 - S09 - DIST 2500 - P1->Val]*2							
Val.	0.000	0.044	0.000	0.200	0.044		✓
S09 - DIST 2500 - P2 - 4 POIN 2500 - P3 - X - POIN 2500 - P2 - 4 / REP ABC.							
dZ	4.000	4.004	-0.100	0.100	0.004		✓
S09 - DIST 2500 - P2 - 0 POIN 2500 - P2 - 0 - POIN 2500 - P3 - Z / REP ABC.							
dX	-0.000	-0.004	-0.100	0.100	-0.004		✓
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P2 =[SQRT X^2+Y^2 - S09 - DIST 2500 - P2->Val]*2							
Val.	0.000	0.012	0.000	0.200	0.012		✓
S09 - DIST 2500 - P4 - 4 POIN 2500 - P4 - 4 - POIN 2500 - P3 - X / REP ABC.							
dZ	4.000	3.969	-0.100	0.100	-0.031		✓
S09 - DIST 2500 - P4 - 0 POIN 2500 - P4 - 0 - POIN 2500 - P3 - Z / REP ABC.							
dX	-0.000	0.099	-0.100	0.100	0.099		✓



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TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P4 =[SQRT X^2+Y^2 - S09 - DIST 2500 - P4->Val]*2 Val.	0.000	0.207	0.000	0.200	0.207	0.007	✗
S09 - DIST 2500 - P5 - 8 POIN 2500 - P5 - 8 - POIN 2500 - P3 - X / REP ABC. dZ	8.000	8.085	-0.100	0.100	0.085		✓
S09 - DIST 2500 - P5 - 0 POIN 2500 - P5 - 0 - POIN 2500 - P3 - Z / REP ABC. dX	0.000	0.111	-0.100	0.100	0.111	0.011	✗
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P5 =[SQRT X^2+Y^2 - S09 - DIST 2500 - P5->Val]*2 Val.	0.000	0.279	0.000	0.200	0.279	0.079	✗
S20 - DIST 2530 - P1 - DOWN PLAN J - POIN 2530 - P1 - DOWN / REP ABC. dY	1.150	1.136	-0.100	0.100	-0.014		✓
S20 - DIST 2530 - P1 - UP PLAN J - POIN 2530 - P1 - UP / REP ABC. dY	1.150	1.130	-0.100	0.100	-0.020		✓
S20 - DIST 2530 - P2 - DOWN PLAN J - POIN 2530 - P2 - DOWN / REP ABC. dY	1.150	1.111	-0.100	0.100	-0.039		✓
S20 - DIST 2530 - P2 - UP PLAN J - POIN 2530 - P2 - UP / REP ABC. dY	1.150	1.110	-0.100	0.100	-0.040		✓
S20 - DIST 2530 - P3 - DOWN PLAN J - POIN 2530 - P3 - DOWN / REP ABC. dY	1.150	1.119	-0.100	0.100	-0.031		✓
S20 - DIST 2530 - P3 - UP PLAN J - POIN 2530 - P3 - UP / REP ABC. dY	1.150	1.124	-0.100	0.100	-0.026		✓
S20 - DIST 2530 - P4 - DOWN PLAN J - POIN 2530 - P4 - DOWN / REP ABC. dY	1.150	1.094	-0.140	0.100	-0.056		✓
S20 - DIST 2530 - P4 - UP PLAN J - POIN 2530 - P4 - UP / REP ABC. dY	1.150	1.101	-0.120	0.100	-0.049		✓
S20 - DIST 2530 - P5 - DOWN PLAN J - POIN 2530 - P5 - DOWN / REP ABC. dY	1.150	1.096	-0.100	0.100	-0.054		✓
S20 - DIST 2530 - P5 - UP PLAN J - POIN 2530 - P5 - UP / REP ABC. dY	1.150	1.091	-0.100	0.100	-0.059		✓
S14 - 2670 - 29.5 S10 - CERC 710 - B - POIN K-5 / REP ABC. dX	29.500	29.699	-0.100	0.100	0.199	0.099	✗
S14 - 2670 - 20.85 S10 - CERC 710 - B - POIN K-6 / REP ABC. dZ	20.850	20.856	-0.100	0.100	0.006		✓
TRUE POSITION 0.2 X^2+Y^2 - S14 - 2670 - 20.8529 =[SQRT X^2+Y^2 - S14 - 2670->Val]*2 Val.	0.000	0.397	0.000	0.200	0.397	0.197	✗
S12 - DIST 2810 - P1 POIN D.69 - POIN 2810 - P1 / REP ABC. dZ	8.000	7.959	-0.075	0.075	-0.041		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P1 =ABS([S12 - DIST 2810 - P1=>Z]-[S12 - DIST 2810 - P1->Z])*2 Val.	0.000	0.081	0.000	0.150	0.081		✓
S12 - DIST 2810 - P2 POIN D.69 - POIN 2810 - P2 / REP ABC. dZ	4.000	3.977	-0.075	0.075	-0.023		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P2 =ABS([S12 - DIST 2810 - P2=>Z]-[S12 - DIST 2810 - P2->Z])*2 Val.	0.000	0.046	0.000	0.150	0.046		✓
S12 - DIST 2810 - P3 POIN D.69 - POIN 2810 - P3 / REP ABC. dZ	0.000	-0.005	-0.075	0.075	-0.005		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P3 =ABS([S12 - DIST 2810 - P3=>Z]-[S12 - DIST 2810 - P3->Z])*2 Val.	0.000	0.009	0.000	0.150	0.009		✓
S12 - DIST 2810 - P4 POIN 2810 - P4 - POIN D.69 / REP ABC. dZ	4.000	3.986	-0.075	0.075	-0.014		✓



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TRUE POSITION 0.15 - S12 - DIST 2810 - P4 =ABS([S12 - DIST 2810 - P4=>Z]-[S12 - DIST 2810 - P4->Z])*2 Val.	0.000	0.028	0.000	0.150	0.028		✓
S12 - DIST 2810 - P5 POIN 2810 - P5 - POIN D.69 / REP ABC. dZ	8.000	7.951	-0.075	0.075	-0.049		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P5 =ABS([S12 - DIST 2810 - P5=>Z]-[S12 - DIST 2810 - P5->Z])*2 Val.	0.000	0.097	0.000	0.150	0.097		✓
VAL1 Dimensiuni extra							
DIST 400 - 1 POIN 400 - 1-5 - PLAN 400 - 1 / REP ABC. dZ	2.650	4.223	-0.120	0.100	1.573	1.473	✗
DIST 400 - 2 POIN 400 - 2-5 - PLAN 400 - 2 / REP ABC. dZ	2.650	2.553	-0.090	0.090	-0.097	-0.007	✗
DIST 400 - 3 PLAN 400 - 3 - POIN 400 - 3-5 / REP ABC. dX	2.650	2.559	-0.140	0.090	-0.091		✓
DIST 400 - 4 PLAN 400 - 4 - POIN 400 - 4-5 / REP ABC. dZ	2.650	2.571	-0.120	0.090	-0.079		✓
DIST 400 - 5 PLAN 400 - 5 - POIN 400 - 5-9 / REP ABC. dZ	2.650	2.366	-0.280	0.090	-0.284	-0.004	✗
DIST 400 - 6 POIN 400 - 6-5 - PLAN 400 - 6 / REP ABC. dX	2.650	2.516	-0.120	0.090	-0.134	-0.014	✗
DIST 410 - 1 POIN 410 - 1 - POIN 410 - 1-2 / REP ABC. dY	2.600	2.410	-0.150	0.090	-0.190	-0.040	✗
DIST 410 - 2 POIN 410 - 2 - POIN 410 - 2-2 / REP ABC. dY	2.600	2.546	-0.100	0.090	-0.054		✓
DIST 410 - 3 POIN 410 - 3-1 - POIN 410 - 3-2 / REP ABC. dY	2.600	2.599	-0.090	0.090	-0.001		✓
DIST 410 - 4 POIN 410 - 4-1 - POIN 410 - 4-2 / REP ABC. dY	2.600	2.450	-0.200	0.090	-0.150		✓
DIST 410 - 5 POIN 410 - 5 - POIN 410 - 5-2 / REP ABC. dY	2.600	2.631	-0.090	0.090	0.031		✓
DIST 410 - 6 POIN 410 - 6 - POIN 1980 - 6 - 3 / REP ABC. dY	2.600	1.828	-0.090	0.090	-0.772	-0.682	✗
DIST 630 - 1 POIN 630 - 1-1 - POIN 630 - 1-2 / REP ABC. dZ	55.500	55.405	-0.270	0.100	-0.095		✓
DIST 630 - 2 POIN 630 - 2-1 - POIN 630 - 2-2 / REP ABC. dZ	55.500	55.222	-0.270	0.100	-0.278	-0.008	✗
DIST 780 - 1 POIN 780 - 1 - PLAN 780 - 1 / REP ABC. D	3.200	3.249	0.000	0.170	0.049		✓
DIST 780 - 2 POIN 780 - 2 - PLAN 780 - 2 / REP ABC. D	3.200	3.341	0.000	0.190	0.141		✓
DIST 780 - 3 POIN 780 - 3 - PLAN 780 - 3 / REP ABC. D	3.200	3.278	0.000	0.100	0.078		✓
DIST 780 - 4 POIN 780 - 4 - PLAN 780 - 4 / REP ABC. D	3.200	3.392	0.000	0.100	0.192	0.092	✗
DIST 1780 - MP10 POIN 1780 - MP10 - 2 - POIN 1780 - MP10 - 1 / REP ABC. dX	106.500	106.569	0.000	0.220	0.069		✓
DIST 1780 - MP11 POIN 1780 - MP11 - 2 - POIN 1780 - MP11 - 1 / REP ABC. dX	106.500	106.626	0.000	0.220	0.126		✓

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DIST 1780 - MP12							
POIN 1780 - MP12 - 2 - POIN 1780 - MP12 - 1 / REP ABC.							
dX	106.500	106.599	0.000	0.220	0.099		✓
DIST 2600 - P1 - F							
POIN 2600 - P1 - DRTE F / REP ABC.							
dX	-0.000	-0.069	-0.075	0.075	-0.069		✓
0.1 - DIST 2600 - P1 - F							
=ABS([DIST 2600 - P1 - F=>X]-[DIST 2600 - P1 - F->X])*2							
Val.	0.000	0.137	0.000	0.150	0.137		✓
DIST 2600 - P2 - F							
POIN 2600 - P2 - DRTE F / REP ABC.							
dX	0.000	-0.059	-0.075	0.075	-0.059		✓
0.1 - DIST 2600 - P2 - F							
=ABS([DIST 2600 - P2 - F=>X]-[DIST 2600 - P2 - F->X])*2							
Val.	0.000	0.118	0.000	0.150	0.118		✓
DIST 2600 - P3 - F							
POIN 2600 - P3 - DRTE F / REP ABC.							
dX	-0.000	-0.062	-0.075	0.075	-0.062		✓
0.1 - DIST 2600 - P3 - F							
=ABS([DIST 2600 - P3 - F=>X]-[DIST 2600 - P3 - F->X])*2							
Val.	0.000	0.124	0.000	0.150	0.124		✓
DIST 2600 - P4 - F							
POIN 2600 - P4 - DRTE F / REP ABC.							
dX	-0.000	-0.069	-0.075	0.075	-0.069		✓
0.1 - DIST 2600 - P4 - F							
=ABS([DIST 2600 - P4 - F=>X]-[DIST 2600 - P4 - F->X])*2							
Val.	0.000	0.139	0.000	0.150	0.139		✓
DIST 2600 - P5 - F							
POIN 2600 - P5 - DRTE F / REP ABC.							
dX	0.000	-0.074	-0.075	0.075	-0.074		✓
0.1 - DIST 2600 - P5 - F							
=ABS([DIST 2600 - P5 - F=>X]-[DIST 2600 - P5 - F->X])*2							
Val.	0.000	0.147	0.000	0.150	0.147		✓
DIST 2600 - P1 - L							
POIN 2600 - P1 - DRTE L / REP ABC.							
dX	0.000	-0.006	-0.075	0.075	-0.006		✓
0.1 - DIST 2600 - P1 - L							
=ABS([DIST 2600 - P1 - L=>X]-[DIST 2600 - P1 - L->X])*2							
Val.	0.000	0.012	0.000	0.150	0.012		✓
DIST 2600 - P2 - L							
POIN 2600 - P2 - DRTE L / REP ABC.							
dX	0.000	0.015	-0.075	0.075	0.015		✓
0.1 - DIST 2600 - P2 - L							
=ABS([DIST 2600 - P2 - L=>X]-[DIST 2600 - P2 - L->X])*2							
Val.	0.000	0.030	0.000	0.150	0.030		✓
DIST 2600 - P3 - L							
POIN 2600 - P3 - DRTE L / REP ABC.							
dX	0.000	0.025	-0.075	0.075	0.025		✓
0.1 - DIST 2600 - P3 - L							
=ABS([DIST 2600 - P3 - L=>X]-[DIST 2600 - P3 - L->X])*2							
Val.	0.000	0.049	0.000	0.150	0.049		✓
DIST 2600 - P4 - L							
POIN 2600 - P4 - DRTE L / REP ABC.							
dX	0.000	0.030	-0.075	0.075	0.030		✓
0.1 - DIST 2600 - P4 - L							
=ABS([DIST 2600 - P4 - L=>X]-[DIST 2600 - P4 - L->X])*2							
Val.	0.000	0.059	0.000	0.150	0.059		✓
DIST 2600 - P5 - L							
POIN 2600 - P5 - DRTE L / REP ABC.							
dX	0.000	0.037	-0.075	0.075	0.037		✓
0.1 - DIST 2600 - P5 - L							
=ABS([DIST 2600 - P5 - L=>X]-[DIST 2600 - P5 - L->X])*2							
Val.	0.000	0.075	0.000	0.150	0.075		✓
DIST 2610 - P1 - F							
POIN 2610 - P1 - DRTE F / REP ABC.							
dX	0.000	-0.097	-0.150	0.150	-0.097		✓
0.1 - DIST 2610 - P1 - F							
=ABS([DIST 2610 - P1 - F=>X]-[DIST 2610 - P1 - F->X])*2							
Val.	0.000	0.194	0.000	0.300	0.194		✓
DIST 2610 - P2 - F							
POIN 2610 - P2 - DRTE F / REP ABC.							
dX	0.000	-0.066	-0.150	0.150	-0.066		✓

SITE: **TRP**Control Equipment: **QC\_74 - DEA Performance**THOMAS REFERENCE: **HEL010/A - C1 - 07.09.2021 - 08.00**OPERATOR: **PP**DATE : **07/09/21 14:47:33**SOFTWARE: **METROLOG X4V14**

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
0.1 - DIST 2610 - P2 - F =ABS([DIST 2610 - P2 - F=>X]-[DIST 2610 - P2 - F->X])*2 Val.	0.000	0.132	0.000	0.300	0.132		✓
DIST 2610 - P3 - F POIN 2610 - P3 - DRTE F / REP ABC. dX	-0.000	-0.076	-0.150	0.150	-0.076		✓
0.1 - DIST 2610 - P3 - F =ABS([DIST 2610 - P3 - F=>X]-[DIST 2610 - P3 - F->X])*2 Val.	0.000	0.152	0.000	0.300	0.152		✓
DIST 2610 - P4 - F POIN 2610 - P4 - DRTE F / REP ABC. dX	0.000	-0.137	-0.150	0.150	-0.137		✓
0.1 - DIST 2610 - P4 - F =ABS([DIST 2610 - P4 - F=>X]-[DIST 2610 - P4 - F->X])*2 Val.	0.000	0.275	0.000	0.300	0.275		✓
DIST 2610 - P5 - F POIN 2610 - P5 - DRTE F / REP ABC. dX	-0.000	-0.152	-0.150	0.150	-0.152	-0.002	✗
0.1 - DIST 2610 - P5 - F =ABS([DIST 2610 - P5 - F=>X]-[DIST 2610 - P5 - F->X])*2 Val.	0.000	0.305	0.000	0.300	0.305	0.005	✗
DIST 2610 - P1 - L POIN 2610 - P1 - DRTE L / REP ABC. dX	0.000	-0.034	-0.150	0.150	-0.034		✓
0.1 - DIST 2610 - P1 - L =ABS([DIST 2610 - P1 - L=>X]-[DIST 2610 - P1 - L->X])*2 Val.	0.000	0.069	0.000	0.300	0.069		✓
DIST 2610 - P2 - L POIN 2610 - P2 - DRTE L / REP ABC. dX	0.000	0.008	-0.150	0.150	0.008		✓
0.1 - DIST 2610 - P2 - L =ABS([DIST 2610 - P2 - L=>X]-[DIST 2610 - P2 - L->X])*2 Val.	0.000	0.017	0.000	0.300	0.017		✓
DIST 2610 - P3 - L POIN 2610 - P3 - DRTE L / REP ABC. dX	0.000	0.011	-0.150	0.150	0.011		✓
0.1 - DIST 2610 - P3 - L =ABS([DIST 2610 - P3 - L=>X]-[DIST 2610 - P3 - L->X])*2 Val.	0.000	0.021	0.000	0.300	0.021		✓
DIST 2610 - P4 - L POIN 2610 - P4 - DRTE L / REP ABC. dX	0.000	-0.038	-0.150	0.150	-0.038		✓
0.1 - DIST 2610 - P4 - L =ABS([DIST 2610 - P4 - L=>X]-[DIST 2610 - P4 - L->X])*2 Val.	0.000	0.077	0.000	0.300	0.077		✓
DIST 2610 - P5 - L POIN 2610 - P5 - DRTE L / REP ABC. dX	-0.000	-0.041	-0.150	0.150	-0.041		✓
0.1 - DIST 2610 - P5 - L =ABS([DIST 2610 - P5 - L=>X]-[DIST 2610 - P5 - L->X])*2 Val.	0.000	0.083	0.000	0.300	0.083		✓
PERP 2620 - P1 DRTE 2620 - P1(G)/PLAN H - C-Zone Val.	0.000	0.047		0.200	0.047		✓
PERP 2620 - P2 DRTE 2620 - P2(G)/PLAN H - C-Zone Val.	0.000	0.026		0.200	0.026		✓
PERP 2620 - P3 DRTE 2620 - P3(G)/PLAN H - C-Zone Val.	0.000	0.033		0.200	0.033		✓
PERP 2620 - P4 DRTE 2620 - P4(G)/PLAN H - C-Zone Val.	0.000	0.087		0.200	0.087		✓
PERP 2620 - P5 DRTE 2620 - P5(G)/PLAN H - C-Zone Val.	0.000	0.098		0.200	0.098		✓
DIST 2630 DRTE L-1 - DRTE L-2 / REP ABC. D	7.180	7.158	-0.050	0.050	-0.022		✓
DIST 2640 DRTE 2640 - 2 - DRTE 2640 - 1 / REP ABC. D	7.150	7.154	-0.050	0.050	0.004		✓



SITE: **TRP**

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SOFTWARE: **METROLOG X4V14**



Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
✚ DIST 2650							
■ DRTE F - 1 - DRTE F-2 / REP ABC.							
D	6.950	6.940	-0.050	0.050	-0.010		✓
✚ DIST 2660 - F							
■ DRTE 2640 - MID - DRTE F / REP ABC.							
D	0.000	0.051	-0.050	0.050	0.051	0.001	✗
✚ SYMMETRY 0.1 - DIST 2660							
■ =ABS([DIST 2660 - F=>Dist1]-[DIST 2660 - F->Dist1])*2							
Val.	0.000	0.101	0.000	0.100	0.101	0.001	✗
✚ DIST 2660 - L							
■ DRTE 2640 - MID - DRTE L / REP ABC.							
D	0.000	0.036	-0.050	0.050	0.036		✓
✚ SYMMETRY 0.1 - DIST 2660 - L							
■ =ABS([DIST 2660 - L=>Dist1]-[DIST 2660 - L->Dist1])*2							
Val.	0.000	0.072	0.000	0.100	0.072		✓
✚ DIST 2710 - MP6							
■ POIN 2710 - MP6 - 1 - POIN 2710 - MP6 - 2 / REP ABC.							
dZ	54.200	54.135	-0.050	0.200	-0.065	-0.015	✗
✚ DIST 2710 - MP7							
■ POIN 2710 - MP7 - 1 - POIN 2710 - MP7 - 2 / REP ABC.							
dZ	54.200	54.290	-0.100	0.550	0.090		✓
✚ DIST 2710 - MP8							
■ POIN 2710 - MP8 - 1 - POIN 2710 - MP8 - 2 / REP ABC.							
dZ	54.200	54.201	-0.020	0.200	0.001		✓
✚ DIST 2750							
■ POIN 2780 - 3 - POIN D.69 / REP ABC.							
dZ	0.000	-0.011	-0.050	0.050	-0.011		✓
✚ SYMMETRY 0.1 - DIST 2750							
■ =ABS([DIST 2750=>Z]-[DIST 2750->Z])*2							
Val.	0.000	0.023	0.000	0.100	0.023		✓
✚ DIST 2750 - K							
■ POIN 2780 - 3 - POIN 2500 - P3 - X / REP ABC.							
dZ	-0.000	-0.023	-0.050	0.050	-0.023		✓
✚ SYMMETRY 0.1 - DIST 2750 - K							
■ =ABS([DIST 2750 - K=>Z]-[DIST 2750 - K->Z])*2							
Val.	0.000	0.047	0.000	0.100	0.047		✓
✚ DIST 2760							
■ POIN 2760 - POIN D.69 / REP ABC.							
dZ	-0.000	-0.021	-0.050	0.050	-0.021		✓
✚ SYMMETRY 0.1 - DIST 2760							
■ =ABS([DIST 2760=>Z]-[DIST 2760->Z])*2							
Val.	0.000	0.042	0.000	0.100	0.042		✓
✚ DIST 2760 - K							
■ POIN 2760 - POIN 2500 - P3 - X / REP ABC.							
dZ	0.000	-0.033	-0.050	0.050	-0.033		✓
✚ SYMMETRY 0.1 - DIST 2760 - K							
■ =ABS([DIST 2760 - K=>Z]-[DIST 2760 - K->Z])*2							
Val.	0.000	0.066	0.000	0.100	0.066		✓
✚ DIST 2770							
■ POIN 2770 - 1 - POIN 2770 - 2 / REP ABC.							
D	23.190	23.268	-0.050	0.050	0.078	0.028	✗
✚ DIST 2780							
■ POIN 2780 - 1 - POIN 2780 - 2 / REP ABC.							
D	23.150	23.174	-0.050	0.050	0.024		✓
✚ DIST 2790							
■ POIN D-2 - POIN D-1 / REP ABC.							
dZ	21.600	21.540	-0.050	0.050	-0.060	-0.010	✗
✚ DIST 2800							
■ POIN 2800 - 1 - POIN 2800 - 2 / REP ABC.							
D	23.850	24.047	-0.150	0.150	0.197	0.047	✗
✚ DIST 2820 - P1							
■ POIN D.69 - POIN 2820 - P1 / REP ABC.							
dZ	8.000	7.930	-0.150	0.150	-0.070		✓
✚ TRUE POSITION 0.3 - DIST 2820 - P1							
■ =ABS([DIST 2820 - P1=>Z]-[DIST 2820 - P1->Z])*2							
Val.	0.000	0.140	0.000	0.300	0.140		✓
✚ DIST 2820 - P2							
■ POIN D.69 - POIN 2820 - P2 / REP ABC.							
dZ	4.000	3.962	-0.150	0.150	-0.038		✓
✚ TRUE POSITION 0.3 - DIST 2820 - P2							
■ =ABS([DIST 2820 - P2=>Z]-[DIST 2820 - P2->Z])*2							
Val.	0.000	0.076	0.000	0.300	0.076		✓



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Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
DIST 2820 - P3 POIN D.69 - POIN 2820 - P3 / REP ABC. dZ	0.000	-0.011	-0.150	0.150	-0.011		✓
TRUE POSITION 0.3 - DIST 2820 - P3 =ABS([DIST 2820 - P3=>Z]-[DIST 2820 - P3->Z])*2 Val.	0.000	0.022	0.000	0.300	0.022		✓
DIST 2820 - P4 POIN 2820 - P4 - POIN D.69 / REP ABC. dZ	4.000	3.960	-0.150	0.150	-0.040		✓
TRUE POSITION 0.3 - DIST 2820 - P4 =ABS([DIST 2820 - P4=>Z]-[DIST 2820 - P4->Z])*2 Val.	0.000	0.080	0.000	0.300	0.080		✓
DIST 2820 - P5 POIN 2820 - P5 - POIN D.69 / REP ABC. dZ	8.000	7.937	-0.150	0.150	-0.063		✓
TRUE POSITION 0.3 - DIST 2820 - P5 =ABS([DIST 2820 - P5=>Z]-[DIST 2820 - P5->Z])*2 Val.	0.000	0.126	0.000	0.300	0.126		✓