

SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C1.1 - 24.08.2021 - 10.00

OPERATOR: TP

DATE: 24/08/21 13:25:04 SOFTWARE: METROLOG X4V14



RESULTS

Dim/Pos Nor	minal	Actual	Tol-	Tol+	Dev.	Tend.	State
⊙ S10 - CERC 710 - C	ai	Actual	101-	1017	Dev.	iona.	Oldie
■ Inters. PLAN A - CYL C.							
Diam.	4.000	3.916	-0.100	0.000	-0.084		✓
⊙ S10 - CERC 710 - B							
Inters. PLAN A - CYL B.							
	4.000	3.950	-0.100	0.000	-0.050		✓
✓ S07 - PLTE 450							
PLAN A C Val.	0.000	0.170		0.200	0.170		
Val. V	0.000	0.170		0.200	0.170		✓
PLAN J C							
	0.000	0.104		0.200	0.104		✓
S15 - DIST 470 - 11.25							
■ DRTE B-C - POIN 470 - 11.25	/ REP AE	BC.					
	1.250	11.143	-0.075	0.075	-0.107	-0.032	X
★ TRUE POSITION 0.15 - S15 - DIST							
=ABS([S15 - DIST 470 - 11.25=		· · · · · · · · · · · · · · · · · · ·					
	0.000	0.214	0.000	0.150	0.214	0.064	×
S15 - DIST 470 - 33.65	/ DED 41	BC					
DRTE B-C - POIN 470 - 33.65 /	7 REP AL 3.650	33.582	-0.130	0.130	-0.068		
TRUE POSITION 0.15 - S15 - DIST			-0.130	0.130	-0.008		✓
= ABS([S15 - DIST 470 - 33.65=			·Z1)*2				
Val.		0.136	0.000	0.260			
r≛₁ S18 - DIST 550		22					
PLAN A - POIN 550 / REP ABC	.						
	6.100	6.140	-0.100	0.100	0.040		✓
r [×] ₁ S06 - DIST 1280							
POIN 1280 - 1 - POIN 1280 - 2							
	2.700	12.702	-0.100	0.100	0.002		~
S16 - DIST 1300 - LEFT	DED ARA	r					
PLAN H - POIN 1300 - LEFT / I	2.015	12.067	-0.050	0.050	0.052	0.002	×
12 r [*] S16 - DIST 1300 - RIGHT	2.010	12.007	-0.030	0.030	0.032	0.002	
PLAN H - POIN 1300 - RIGHT	/ REP AF	BC.					
	2.015	12.045	-0.050	0.050	0.030		~
r [×] S19 - DIST 1400 - P6 - DOWN						_	
PLAN J - POIN 1400 - P6 - DO	WN / RE	EP ABC.					
	0.850	0.905	-0.100	0.110	0.055		~
S19 - DIST 1400 - P6 - UP							
PLAN J - POIN 1400 - P6 - UP			2 125		2.225		
	0.850	0.885	-0.100	0.110	0.035		✓
S19 - DIST 1400 - P7 - DOWN PLAN J - POIN 1400 - P7 - DO	W/N / DE	EP ARC					
	0.850	0.886	-0.100	0.110	0.036		~
S19 - DIST 1400 - P7 - UP	2.000	0.000	-0.100	0.110	0.000		
PLAN J - POIN 1400 - P7 - UP	/ REP A	BC.					
	0.850	0.878	-0.100	0.110	0.028		~
r≚ S05 - DIST 1410 - P6 - 12.8							
POIN 2500 - P3 - X - POIN 141							
	2.800	12.823	-0.150	0.150	0.023		~
S05 - DIST 1410 - P6 - 3.4			·	·	·		
POIN 2500 - P3 - Z - POIN 141			0.4==!	0.45-1	0.47:1	0.65	
	3.400	3.226	-0.150	0.150	-0.174	-0.024	×
★ TRUE POSITION 0.3 X ² +Y ² - S0: ■ -ISORT XA2+YA2 - S0E DIST							
=[SQRT X^2+Y^2 - S05 - DIST Val.	1410 - F 0.000	0.351	0.000	0.300	0.351	0.051	
val. r× S05 - DIST 1410 - P7 - 9.6	0.000	0.331	0.000	0.300	0.331	0.051	×
POIN 1410 - 2 - 9.6 - POIN 250	00 - P3 -	X / REP ABC.					
	9.600	9.639	-0.150	0.150	0.039		~
S05 - DIST 1410 - P7 - 3.4							
POIN 2500 - P3 - Z - POIN 141	0 - 2 - 3	.4 / REP ABC.					
dX :	3.400	3.296	-0.150	0.150	-0.104		✓
TRUE POSITION 0.3 X^2+Y^2 - S0							
=[SQRT X^2+Y^2 - S05 - DIST							
	0.000	0.222	0.000	0.300	0.222		✓
S01 - 1690 - MP10	00 145	10 4/DED 450					
POIN 109 - MP10 - 2 - POIN 10			0.400	0.000	0.440	0.040	V
dX 109	9.000	108.887	-0.100	0.200	-0.113	-0.013	X



Dim/Pos

S01 - 1690 - MP11

SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C1.1 - 24.08.2021 - 10.00

OPERATOR: TP

Actual

Nominal

DATE: 24/08/21 13:25:05 SOFTWARE: METROLOG X4V14

Tol+

Tol-



State

POIN 109 - MP11 - 2 -							
	- POIN 109 - MP11 - 1 / F	REP ABC.					
dX	109.000	108.944	-0.100	0.200	-0.056	1	/
→ S01 - 1690 - MP12				l e			•
	- POIN 109 - MP12 - 1 / I	RED ARC					
			0.400	0.000	0.000		
dX	109.000	109.023	-0.100	0.200	0.023		~
້າ S02 - 1730							
POIN 1730 - 2 - POIN	l 1730 - 1 / REP ABC.						
dZ	56.700	56.825	-0.100	0.300	0.125		~
S03 - DIST 1880		*****	21.122	7.777	*****		<u> </u>
	000 0 / DED 400						
PLAN 1880 - POIN 18							
dΥ	43.500	43.433	-0.100	0.150	-0.067		\checkmark
⁵ ₁ S17 - 1980 - 1							
PLAN A-1 - POIN 168	80 - 1 - 3 / REP ABC						
_	7.000	6.886	-0.130	0.000	-0.114		,
D	7.000	0.000	-0.130	0.000	-0.114		✓
↑ S17 - 1980 - 2							
PLAN A-2 - POIN 198	i0 - 2 - 3 / REP ABC.						
D	7.000	6.995	-0.100	0.000	-0.005		/
↑ S17 - 1980 - 3							<u> </u>
	00 0 0 / DED ADO						
PLAN A-3 - POIN 198						_	
D	7.000	7.019	-0.050	0.075	0.019		✓
ր S17 - 1980 - 4							
PLAN A-4 - POIN 198	0 - 4 - 3 / REP ABC						
D D	7.000	6 970	0.120	0.000	0.422		
	7.000	6.878	-0.130	0.000	-0.122		✓
S17 - 1980 - 5							
PLAN A-5 - POIN 198	0 - 5 - 3 / REP ABC.						
D	7.000	7.005	-0.050	0.040	0.005		~
S17 - 1980 - 6			*****		3.300		
	0 6 0/050 450						
PLAN A-6 - POIN 198							
D	7.000	6.889	-0.100	0.000	-0.111	-0.011	×
3 S13 - DIST 2310 - MP1 - U	JP						
POIN 2310 - MP1 - UI		- UP - 2 / REP ARC					
				0.450	0.044		
D	9.950	9.936	-0.050	0.150	-0.014		~
ີງ S13 - DIST 2310 - MP1 - D	JOWN						
POIN 2310 - MP1 - DO	OWN - 1 - POIN 2310 - N	/IP1 - DOWN - 2 / R	EP ABC.				
D	9.950	9.976	-0.050	0.150	0.026		/
S13 - DIST 2310 - MP4 - U		0.0.0	0.000	000	0.020		<u> </u>
		UD 0/DED 400					
POIN 2310 - MP4 - UI	P - 1 - POIN 2310 - MP4	- UP - 2 / REP ABC.					
D	9.950	10.083	-0.050	0.150	0.133		✓
1 S13 - DIST 2310 - MP4 - D	JOWN			<u> </u>			
	OWN - 1 - POIN 2310 - N	MP4 - DOWN - 2 / R	EP ARC				
				0.450	0.400		
D	9.950	10.076	-0.050	0.150	0.126		~
⁵₁ S08 - DIST 2420 - MP1							
POIN 2420 - MP1 - 1	- POIN 2420 - MP1 - 2 / I	REP ABC.					
_ D	25.900	26.030	-0.100	0.150	0.130		~
	20.500	20.000	-0.100	0.100	0.100		
S08 - DIST 2420 - MP2							
POIN 2420 - MP2 - 1	- POIN 2420 - MP2 - 2 / I						
D	25.900	26.039	-0.100	0.150			
S09 - DIST 2500 - P1 - 8				0.100	0.139		~
309 - DIST 2300 - FT - A	· · · · · · · · · · · · · · · · · · ·		0.100	0.100	0.139		✓
* The state of the	DOIN 2500 D4 0 / D5) ARC	0.700	0.100	0.139		~
POIN 2500 - P3 - X - I	POIN 2500 - P1 - 8 / REF						
POIN 2500 - P3 - X - F	POIN 2500 - P1 - 8 / REF 8.000	P ABC. 7.963	-0.100	0.100	-0.037		✓
POIN 2500 - P3 - X - F							
POIN 2500 - P3 - X - F dZ S09 - DIST 2500 - P1 - 0	8.000	7.963					
POIN 2500 - P3 - X - F dZ 7 S09 - DIST 2500 - P1 - 0 POIN 2500 - P3 - Z - F	8.000 POIN 2500 - P1 - 0 / REF	7.963 P ABC.	-0.100	0.100	-0.037		~
■ POIN 2500 - P3 - X - F dZ ∩ S09 - DIST 2500 - P1 - 0 ■ POIN 2500 - P3 - Z - F dX	8.000 POIN 2500 - P1 - 0 / REF	7.963 P ABC. -0.017					
POIN 2500 - P3 - X - F dZ 309 - DIST 2500 - P1 - 0 POIN 2500 - P3 - Z - F dX TRUE POSITION 0.2 X^2+	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 -	7.963 PABC. -0.017	-0.100	0.100	-0.037		~
POIN 2500 - P3 - X - F dZ 7 S09 - DIST 2500 - P1 - 0 POIN 2500 - P3 - Z - F dX	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 -	7.963 PABC. -0.017	-0.100	0.100	-0.037		~
POIN 2500 - P3 - X - F dZ 309 - DIST 2500 - P1 - 0 POIN 2500 - P3 - Z - F dX TRUE POSITION 0.2 X^2+ SQUART = SQUART X^2+Y^2 - S0	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - 09 - DIST 2500 - P1->Val	7.963 PABC. -0.017 P1 *2	-0.100 -0.100	0.100	-0.037 -0.017		✓ ✓
■ POIN 2500 - P3 - X - I dZ 1 S09 - DIST 2500 - P1 - 0 ■ POIN 2500 - P3 - Z - I dX N TRUE POSITION 0.2 X*2+ ■ =[SQRT X*2+Y*2 - S0 Val.	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 -	7.963 PABC. -0.017	-0.100	0.100	-0.037		~
POIN 2500 - P3 - X - I dZ S09 - DIST 2500 - P1 - 0 POIN 2500 - P3 - Z - I dX TRUE POSITION 0.2 X^2+ = [SQRT X^2+Y^2 - S0 Val. S09 - DIST 2500 - P2 - 4	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - 09 - DIST 2500 - P1->Val 0.000	7.963 PABC. -0.017 P1 *2 0.080	-0.100 -0.100	0.100	-0.037 -0.017		✓ ✓
POIN 2500 - P3 - X - I dZ S09 - DIST 2500 - P1 - 0 POIN 2500 - P3 - Z - I dX TRUE POSITION 0.2 X^2+ [SQRT X^2+Y^2 - S0 Val. S09 - DIST 2500 - P2 - 4 POIN 2500 - P3 - X - I	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - 09 - DIST 2500 - P1->Val 0.000 POIN 2500 - P24 / RE	7.963 PABC. -0.017 P1 1*2 0.080 PABC.	-0.100 -0.100 0.000	0.100	-0.037 -0.017 0.080		✓ ✓
POIN 2500 - P3 - X - I dZ 3 S09 - DIST 2500 - P1 - 0 POIN 2500 - P3 - Z - I dX TRUE POSITION 0.2 X^2+ = [SQRT X^2+Y^2 - S0 Val. 3 S09 - DIST 2500 - P2 - 4	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - 09 - DIST 2500 - P1->Val 0.000	7.963 PABC. -0.017 P1 *2 0.080	-0.100 -0.100	0.100	-0.037 -0.017		✓ ✓
POIN 2500 - P3 - X - I dZ 3 S09 - DIST 2500 - P1 - 0 POIN 2500 - P3 - Z - I dX TRUE POSITION 0.2 X^2+ = [SQRT X^2+Y^2 - S0 Val. 3 S09 - DIST 2500 - P2 - 4 POIN 2500 - P3 - X - I dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - 09 - DIST 2500 - P1->Val 0.000 POIN 2500 - P24 / RE	7.963 PABC. -0.017 P1 1*2 0.080 PABC.	-0.100 -0.100 0.000	0.100	-0.037 -0.017 0.080		✓ ✓
POIN 2500 - P3 - X - dZ dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - 09 - DIST 2500 - P1->Valion 0.000 POIN 2500 - P24 / RE 4.000	7.963 PABC0.017 P1 *2 0.080 PABC. 3.994	-0.100 -0.100 0.000	0.100	-0.037 -0.017 0.080		✓ ✓
POIN 2500 - P3 - X - dZ dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - 09 - DIST 2500 - P1->Vali 0.000 POIN 2500 - P24 / RE 4.000	7.963 PABC0.017 P1 1*2 0.080 PABC. 3.994	-0.100 -0.100 0.000	0.100 0.100 0.200 0.100	-0.037 -0.017 0.080 -0.006		*
POIN 2500 - P3 - X - dZ dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - P1->Val 0.000 POIN 2500 - P24 / RE 4.000 POIN 2500 - P3 - Z / REF -0.000	7.963 PABC0.017 P1 3*2 0.080 PABC. 3.994 PABC. 0.011	-0.100 -0.100 0.000	0.100	-0.037 -0.017 0.080		✓ ✓
POIN 2500 - P3 - X - dZ dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - P1->Val 0.000 POIN 2500 - P24 / RE 4.000 POIN 2500 - P3 - Z / REF -0.000	7.963 PABC0.017 P1 3*2 0.080 PABC. 3.994 PABC. 0.011	-0.100 -0.100 0.000	0.100 0.100 0.200 0.100	-0.037 -0.017 0.080 -0.006		*
POIN 2500 - P3 - X - dZ dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - P1 - Val 0.000 POIN 2500 - P24 / RE 4.000 POIN 2500 - P3 - Z / REF -0.000 +Y^2 - S09 - DIST 2500 -	7.963 P ABC. -0.017 P1 3*2 0.080 P ABC. 3.994 P ABC. 0.011 P2	-0.100 -0.100 0.000	0.100 0.100 0.200 0.100	-0.037 -0.017 0.080 -0.006		*
POIN 2500 - P3 - X - I dZ dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - P1 -> Val 0.000 POIN 2500 - P24 / RE 4.000 POIN 2500 - P3 - Z / REF -0.000 +Y^2 - S09 - DIST 2500 - P2 -> Val 0.000	7.963 P ABC. -0.017 P1 *2 0.080 P ABC. 3.994 P ABC. 0.011 P2 *2	-0.100 -0.100 0.000 -0.100	0.100 0.100 0.200 0.100 0.100	-0.037 -0.017 0.080 -0.006		
POIN 2500 - P3 - X - dZ dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - P1 - Val 0.000 POIN 2500 - P24 / RE 4.000 POIN 2500 - P3 - Z / REF -0.000 +Y^2 - S09 - DIST 2500 -	7.963 P ABC. -0.017 P1 3*2 0.080 P ABC. 3.994 P ABC. 0.011 P2	-0.100 -0.100 0.000	0.100 0.100 0.200 0.100	-0.037 -0.017 0.080 -0.006		*
POIN 2500 - P3 - X - dZ dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - P1 -> Val 0.000 POIN 2500 - P24 / RE 4.000 POIN 2500 - P3 - Z / REF -0.000 +Y^2 - S09 - DIST 2500 - P2 -> Val 0.000	7.963 P ABC. -0.017 P1 *2 0.080 P ABC. 3.994 P ABC. 0.011 P2 *2	-0.100 -0.100 0.000 -0.100	0.100 0.100 0.200 0.100 0.100	-0.037 -0.017 0.080 -0.006		
POIN 2500 - P3 - X - I dZ dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - P1 -> Val 0.000 POIN 2500 - P24 / RE 4.000 POIN 2500 - P3 - Z / REF -0.000 +Y^2 - S09 - DIST 2500 - P2 -> Val 0.000	7.963 PABC0.017 P1 **2 0.080 PABC. 3.994 PABC. 0.011 P2 **2 0.025	-0.100 -0.100 0.000 -0.100	0.100 0.100 0.200 0.100 0.100	-0.037 -0.017 0.080 -0.006		
POIN 2500 - P3 - X - I dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - P1->Val 0.000 POIN 2500 - P24 / RE 4.000 POIN 2500 - P3 - Z / REF -0.000 +Y^2 - S09 - DIST 2500 - P2->Val 0.000 POIN 2500 - P3 - Z / REF -0.000 +Y^2 - S09 - DIST 2500 - P2->Val 0.000 POIN 2500 - P3 - X / RE	7.963 PABC0.017 P1 1*2 0.080 PABC. 3.994 PABC. 0.011 P2 1*2 0.025	-0.100 -0.100 0.000 -0.100 -0.100	0.100 0.100 0.200 0.100 0.200	-0.037 -0.017 0.080 -0.006 0.011 0.025		
POIN 2500 - P3 - X - dZ dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - P1->Val 0.000 POIN 2500 - P24 / RE 4.000 POIN 2500 - P3 - Z / REF -0.000 +Y^2 - S09 - DIST 2500 - P2->Val 0.000	7.963 PABC0.017 P1 **2 0.080 PABC. 3.994 PABC. 0.011 P2 **2 0.025	-0.100 -0.100 0.000 -0.100	0.100 0.100 0.200 0.100 0.100	-0.037 -0.017 0.080 -0.006		
POIN 2500 - P3 - X - dZ dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - P1 - Val 0.000 POIN 2500 - P24 / RE 4.000 POIN 2500 - P3 - Z / REF -0.000 +Y^2 - S09 - DIST 2500 - P2 - Val 0.000 POIN 2500 - P3 - X / RE 4.000	7.963 P ABC. -0.017 P1 *2 0.080 P ABC. 3.994 P ABC. 0.011 P2 0.025 P ABC. 3.974	-0.100 -0.100 0.000 -0.100 -0.100	0.100 0.100 0.200 0.100 0.200	-0.037 -0.017 0.080 -0.006 0.011 0.025		
POIN 2500 - P3 - X - dZ dZ	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - P1 - Val 0.000 POIN 2500 - P24 / RE 4.000 POIN 2500 - P3 - Z / REF -0.000 +Y^2 - S09 - DIST 2500 - P2 - Val 0.000 POIN 2500 - P3 - X / RE 4.000	7.963 P ABC. -0.017 P1 *2 0.080 P ABC. 3.994 P ABC. 0.011 P2 0.025 P ABC. 3.974	-0.100 -0.100 0.000 -0.100 -0.100	0.100 0.100 0.200 0.100 0.200	-0.037 -0.017 0.080 -0.006 0.011 0.025		
POIN 2500 - P3 - X - dZ S09 - DIST 2500 - P1 - 0 POIN 2500 - P3 - Z - dX TRUE POSITION 0.2 X^2+ = [SQRT X^2+Y^2 - S0 Val. S09 - DIST 2500 - P2 - 4 POIN 2500 - P3 - X - dZ S09 - DIST 2500 - P2 - 0 - dX TRUE POSITION 0.2 X^2+ = [SQRT X^2+Y^2 - S0 Val. TRUE POSITION 0.2 X^2+ = [SQRT X^2+Y^2 - S0 Val. S09 - DIST 2500 - P4 - 4 POIN 2500 - P4 - 4 - dZ S09 - DIST 2500 - P4 - 0	8.000 POIN 2500 - P1 - 0 / REF -0.000 +Y^2 - S09 - DIST 2500 - P1 - Val 0.000 POIN 2500 - P24 / RE 4.000 POIN 2500 - P3 - Z / REF -0.000 +Y^2 - S09 - DIST 2500 - P2 - Val 0.000 POIN 2500 - P3 - X / RE 4.000	7.963 P ABC. -0.017 P1 *2 0.080 P ABC. 3.994 P ABC. 0.011 P2 0.025 P ABC. 3.974	-0.100 -0.100 0.000 -0.100 -0.100	0.100 0.100 0.200 0.100 0.200	-0.037 -0.017 0.080 -0.006 0.011 0.025		



SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C1.1 - 24.08.2021 - 10.00

OPERATOR: TP

DATE: 24/08/21 13:25:05 **SOFTWARE: METROLOG X4V14**



Dim/Pos							
★ TRUE POSITION 0	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
	.2 X^2+Y^2 - S09 - DIS	ST 2500 - P4					
=[SQRT X^2+Y	'^2 - S09 - DIST 2500 -	- P4->Val]*2					
Val.	0.000		0.000	0.200	0.188		✓
r S09 - DIST 2500 - F							
l' '	5 - 8 - POIN 2500 - P3	- X / REP ARC					
dZ	8.000	8.064	-0.100	0.100	0.064		
		0.004	-0.100	0.100	0.064		~
S09 - DIST 2500 - F		7/000 400					
	5 - 0 - POIN 2500 - P3			1	1		
dX	0.000	0.081	-0.100	0.100	0.081		✓
TRUE POSITION 0	.2 X^2+Y^2 - S09 - DIS	3T 2500 - P5					
=[SQRT X^2+Y	'^2 - S09 - DIST 2500 -	- P5->Val]*2					
Val.	0.000	0.207	0.000	0.200	0.207	0.007	X
🖰 S20 - DIST 2530 - F	P1 - DOWN			•			
PLAN J - POIN	I 2530 - P1 - DOWN / I	REP ABC.					
dY		1.145	-0.100	0.100	-0.005		✓
r∸ S20 - DIST 2530 - F			000	0.100	0.000		•
I '	i - 01 I 2530 - P1 - UP / REP	ARC					
			0.400	0.400	0.040		
dY	1.150	1.131	-0.100	0.100	-0.019		✓
🖰 S20 - DIST 2530 - F							
	I 2530 - P2 - DOWN / I						
dY	1.150	1.111	-0.100	0.100	-0.039		✓
r S20 - DIST 2530 - F	P2 - UP						
PLAN J - POIN	I 2530 - P2 - UP / REP	ABC.					
dY			-0.100	0.100	-0.041		~
S20 - DIST 2530 - F							
I '	I 2530 - P3 - DOWN / I	REP ARC					
dY		1.133	-0.100	0.100	-0.017		
		1.133	-0.100	0.100	-0.017		~
S20 - DIST 2530 - F							
_	I 2530 - P3 - UP / REP						
dY	1.150	1.127	-0.100	0.100	-0.023		✓
🖰 S20 - DIST 2530 - F	P4 - DOWN						
PLAN J - POIN	I 2530 - P4 - DOWN / I	REP ABC.					
dY	1.150	1.100	-0.140	0.100	-0.050		✓
S20 - DIST 2530 - F							
I '	l 2530 - P4 - UP / REP	ABC					
dY			-0.120	0.100	-0.041		
		1.109	-0.120	0.100	-0.041		✓
S20 - DIST 2530 - F							
	I 2530 - P5 - DOWN / I		!				
dY		1.106	-0.100	0.100	-0.044		✓
S20 - DIST 2530 - F							
PLAN J - POIN	I 2500 - P5 - UP / REP	ABC.					
dY	1.150	1.111	-0.100	0.100	-0.039		✓
S14 - 2670 - 29.5						_	
l' '	10 - B - POIN K-5 / RE	P ABC.					
dX	29.500	29.590	-0.100	0.100	0.090		~
S14 - 2670 - 20.85	25.550	20.000	3.100	0.100	0.000		
li i	10 - B - POIN K-6 / RE	DARC					
			0.400	0.400			
dZ	20.850	20.782					
TRUE POSITION 0	" YAD I YAO OAA OO"		-0.100	0.100	-0.068		~
			-0.100	0.100	-0.068		~
=[SQRT X^2+Y	.2 X^2+Y^2 - S14 - 26/ '^2 - S14 - 2670->Val]*		-0.100	0.100	-0.068		✓
=[SQRT X^2+Y Val.		2	0.000	0.100	-0.068 0.226	0.026	
	'^2 - S14 - 2670->Val]* 0.000	2				0.026	
Val. ► S12 - DIST 2810 - F	′^2 - S14 - 2670->Val]* 0.000│ 	0.226				0.026	
Val. ↑ S12 - DIST 2810 - F ■ POIN D.69 - PO	/^2 - S14 - 2670->Val]* 0.000 P1 OIN 2810 - P1 / REP A	0.226 O.226	0.000	0.200	0.226		×
Val. ↑ S12 - DIST 2810 - F POIN D.69 - PO dZ	/^2 - S14 - 2670->Val]* 0.000 P1 OIN 2810 - P1 / REP A 8.000	22 0.226 NBC. 7.944				0.026	
Val. → S12 - DIST 2810 - F POIN D.69 - PO dZ TRUE POSITION 0	"2 - S14 - 2670->Val]* 0.000 P1 DIN 2810 - P1 / REP A 8.000 .15 - S12 - DIST 2810	22 0.226 ABC. 7.944	-0.075	0.200	0.226		×
Val. ↑ S12 - DIST 2810 - F POIN D.69 - PO dZ ↑ TRUE POSITION 0 = ABS([S12 - D	'^2 - S14 - 2670->Val]* 0.000 P1 OIN 2810 - P1 / REP A 8.000 .15 - S12 - DIST 2810 IST 2810 - P1=>Z]-[S1	72 0.226 NBC. 7.944 - P1 12 - DIST 2810 - P1->Z])	0.000 -0.075	0.200	0.226		×
Val.	'^2 - S14 - 2670->Val]* 0.000 P1 OIN 2810 - P1 / REP A 8.000 .15 - S12 - DIST 2810 IST 2810 - P1=>Z]-[S1 0.000	72 0.226 NBC. 7.944 - P1 12 - DIST 2810 - P1->Z])	-0.075	0.200	0.226		×
Val.	''^2 - \$14 - 2670->Val]* 0.000 P1 OIN 2810 - P1 / REP A 8.000 .15 - \$12 - DIST 2810 IST 2810 - P1=>Z]-[\$1 0.000 P2	0.226 0.226	0.000 -0.075	0.200	0.226		×
Val.	'^2 - S14 - 2670->Val]* 0.000 P1 OIN 2810 - P1 / REP A 8.000 .15 - S12 - DIST 2810 IST 2810 - P1=>Z]-[S1 0.000	22 0.226 SBC. 7.944 - P1 12 - DIST 2810 - P1->Z]) ⁴ 0.112 SBC.	0.000 -0.075 22 0.000	0.200 0.075 0.150	0.226 -0.056 0.112		×
Val.	''^2 - S14 - 2670->Val]* 0.000 P1 DIN 2810 - P1 / REP A 8.000 IST 2810 - P1=>Z]-[S1 0.000 P2 DIN 2810 - P2 / REP A	0.226 0.226	0.000 -0.075	0.200	0.226		×
Val. S12 - DIST 2810 - F POIN D.69 - P dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - P	"2 - S14 - 2670->Val]"	72 0.226 SBC. 7.944 - P1 12 - DIST 2810 - P1->Z])° 0.112 SBC. 3.969	0.000 -0.075 22 0.000	0.200 0.075 0.150	0.226 -0.056 0.112		×
Val. S12 - DIST 2810 - F POIN D.69 - P dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - P dZ TRUE POSITION 0	"2 - S14 - 2670->Val]"	22 0.226 ABC. 7.944 - P1 12 - DIST 2810 - P1->Z])* 0.112 ABC. 3.969 - P2	0.000 -0.075 *2	0.200 0.075 0.150	0.226 -0.056 0.112		×
Val. S12 - DIST 2810 - F POIN D.69 - P(GZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - P(GZ TRUE POSITION 0 = ABS([S12 - D	"2 - S14 - 2670->Val]"	72 0.226 SBC. 7.944 - P1 12 - DIST 2810 - P1->Z])* 0.112 SBC. 3.969 - P2 12 - DIST 2810 - P2->Z])*	0.000 -0.075 *2	0.200 0.075 0.150 0.075	0.226 -0.056 0.112 -0.031		×
Val. S12 - DIST 2810 - F POIN D.69 - PO dZ TRUE POSITION 0 = ABS([S12 - D Val. POIN D.69 - PO dZ TRUE POSITION 0 = ABS([S12 - D Val. Val. Val.	"2 - S14 - 2670->Val]" 0.000 P1 OIN 2810 - P1 / REP A 8.000 .15 - S12 - DIST 2810 IST 2810 - P1=>Z]-[S1 0.000 P2 OIN 2810 - P2 / REP A 4.000 .15 - S12 - DIST 2810 IST 2810 - P2=>Z]-[S1	72 0.226 SBC. 7.944 - P1 12 - DIST 2810 - P1->Z])* 0.112 SBC. 3.969 - P2 12 - DIST 2810 - P2->Z])*	0.000 -0.075 *2	0.200 0.075 0.150	0.226 -0.056 0.112		×
Val. S12 - DIST 2810 - F POIN D.69 - PO dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - PO dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F S12 - DIST 2810 - F	"2 - S14 - 2670->Val]" 0.000 P1 OIN 2810 - P1 / REP A 8.000 .15 - S12 - DIST 2810 IST 2810 - P1=>Z]-[S1 0.000] P2 OIN 2810 - P2 / REP A 4.000 .15 - S12 - DIST 2810 IST 2810 - P2=>Z]-[S1 0.000]	ABC. 7.944 - P1 0.112 0.	0.000 -0.075 *2	0.200 0.075 0.150 0.075	0.226 -0.056 0.112 -0.031		×
Val. S12 - DIST 2810 - F POIN D.69 - PO dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - PO Val. TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - PO	"2 - S14 - 2670->Val]" 0.000 P1 OIN 2810 - P1 / REP A 8.000 ST 2810 - P1=>Z]-[S1 0.000] P2 OIN 2810 - P2 / REP A 4.000 ST 2810 - P2 / REP A 0.000] OIST 2810 - P2=>Z]-[S1 0.000] OIST 2810 - P3 / REP A	22 0.226 ABC. 7.944 P1	0.000 -0.075 -0.075 -0.075 -0.075 -0.000	0.200 0.075 0.150 0.075	0.226 -0.056 0.112 -0.031		×
Val. S12 - DIST 2810 - F POIN D.69 - PO dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - PO dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - PO dZ	"2 - S14 - 2670->Val]" 0.000 P1 OIN 2810 - P1 / REP A 8.000 IST 2810 - P1=>Z]-[S1 0.000] P2 OIN 2810 - P2 / REP A 4.000 IST 2810 - P2=>Z]-[S1 0.000] P3 OIN 2810 - P3 / REP A 0.000	(2 0.226 NBC. 7.944 P1	0.000 -0.075 *2	0.200 0.075 0.150 0.075	0.226 -0.056 0.112 -0.031		×
Val. S12 - DIST 2810 - F POIN D.69 - P(dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - P(dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - P(CAN BE POIN D.69 -	"2 - S14 - 2670->Val]" 0.000 P1 OIN 2810 - P1 / REP A 8.000 IST 2810 - P1=>Z]-[S1 0.000 P2 OIN 2810 - P2 / REP A 4.000 IST 2810 - P2=>Z]-[S1 0.000] OIN 2810 - P2=>Z]-[S1 0.000] OIN 2810 - P3 / REP A 0.000] OIN 2810 - P3 / REP A 0.000]	(2 0.226 NBC. 7.944 P1	0.000 -0.075 -0.0	0.200 0.075 0.150 0.075	0.226 -0.056 0.112 -0.031		×
Val. S12 - DIST 2810 - F POIN D.69 - P(dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - P(dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - P(CZ TRUE POSITION 0 TRUE POSITION 0	"2 - S14 - 2670->Val]" 0.000 P1 OIN 2810 - P1 / REP A 8.000 IST 2810 - P1=>Z]-[S1 0.000 P2 OIN 2810 - P2 / REP A 4.000 IST 2810 - P2=>Z]-[S1 0.000] OIN 2810 - P2=>Z]-[S1 0.000] OIN 2810 - P3 / REP A 0.000] OIN 2810 - P3 / REP A 0.000]	(2 0.226 NBC. 7.944 P1	0.000 -0.075 -0.0	0.200 0.075 0.150 0.075	0.226 -0.056 0.112 -0.031		×
Val. S12 - DIST 2810 - F POIN D.69 - P(dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - P(dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - P(CZ TRUE POSITION 0 TRUE POSITION 0	"2 - S14 - 2670->Val]" 0.000 P1 OIN 2810 - P1 / REP A 8.000 IST 2810 - P1=>Z]-[S1 0.000 P2 OIN 2810 - P2 / REP A 4.000 IST 2810 - P2=>Z]-[S1 0.000] OIN 2810 - P2=>Z]-[S1 0.000] OIN 2810 - P3 / REP A 0.000] OIN 2810 - P3 / REP A 0.000]	(2 0.226 1.25	0.000 -0.075 -0.0	0.200 0.075 0.150 0.075	0.226 -0.056 0.112 -0.031		×
Val. S12 - DIST 2810 - F POIN D.69 - PC dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - PC dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - PC CZ TRUE POSITION 0 = ABS([S12 - D CZ TRUE POSITION 0 = ABS([S12 - D	"2 - S14 - 2670->Val]"	(2 0.226 1.25	0.000 -0.075 -0.0	0.200 0.075 0.150 0.075 0.150	0.226 -0.056 0.112 -0.031 0.061 -0.005		× × × × × × × × × × × × × × × × × × ×
Val. S12 - DIST 2810 - F POIN D.69 - PC dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - PC dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - PC dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - PC Val. S12 - DIST 2810 - F S12 - DIST 2810 - F	"2 - S14 - 2670->Val]" 0.000 P1 OIN 2810 - P1 / REP A 8.000 .15 - S12 - DIST 2810 P1 OIN 2810 - P1 - P2 / REP A 4.000 P2 OIN 2810 - P2 / REP A 4.000 IST 2810 - P2=>Z]-[S1 0.000 P3 OIN 2810 - P3 / REP A 0.000 03 OIN 2810 - P3 / REP A 0.000 015 - S12 - DIST 2810 0.000 015 - S12 - DIST 2810	(2 0.226 1.25	0.000 -0.075 -0.0	0.200 0.075 0.150 0.075 0.150	0.226 -0.056 0.112 -0.031 0.061 -0.005		× × × × × × × × × × × × × × × × × × ×
Val. S12 - DIST 2810 - F POIN D.69 - PC dZ TRUE POSITION 0 = ABS([S12 - D Val.] S12 - DIST 2810 - F POIN D.69 - PC AZ TRUE POSITION 0 = ABS([S12 - D Val.] S12 - DIST 2810 - F POIN D.69 - PC AZ TRUE POSITION 0 = ABS([S12 - D Val.] S12 - DIST 2810 - F POIN D.69 - PC AZ TRUE POSITION 0 = ABS([S12 - D Val.] S12 - DIST 2810 - F POIN 2810 - PC	"2 - S14 - 2670->Val]" 0.000 1 OIN 2810 - P1 / REP A 8.000 .15 - S12 - DIST 2810 .15 - S12 - DIST 2810 P2 OIN 2810 - P2 / REP A 4.000 .15 - S12 - DIST 2810 IST 2810 - P2=>Z]-[S1 0.000 P3 OIN 2810 - P3 / REP A 0.000 .15 - S12 - DIST 2810 15T 2810 - P3 / REP A 0.000 .15 - S12 - DIST 2810 0.000 -15 - S12 - DIST 2810 0.000 -15 - S12 - DIST 2810 0.000 -14 - POIN D.69 / REP A	22	0.000 -0.075 -0.075 -0.075 -0.075 -0.075 -0.075 -0.075 -0.075 -0.000 -0.0	0.200 0.075 0.150 0.075 0.150 0.075	0.226 -0.056 0.112 -0.031 0.061 -0.005		×
Val. S12 - DIST 2810 - F POIN D.69 - PC dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - PC dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - PC dZ TRUE POSITION 0 = ABS([S12 - D Val. S12 - DIST 2810 - F POIN D.69 - PC Val. S12 - DIST 2810 - F S12 - DIST 2810 - F	"2 - S14 - 2670->Val]" 0.000 P1 OIN 2810 - P1 / REP A 8.000 .15 - S12 - DIST 2810 P1 OIN 2810 - P1 - P2 / REP A 4.000 P2 OIN 2810 - P2 / REP A 4.000 IST 2810 - P2=>Z]-[S1 0.000 P3 OIN 2810 - P3 / REP A 0.000 03 OIN 2810 - P3 / REP A 0.000 015 - S12 - DIST 2810 0.000 015 - S12 - DIST 2810	22 0.226 ABC. 7.944 - P1 12 - DIST 2810 - P1->Z])* 0.112 ABC. 3.969 - P2 12 - DIST 2810 - P2->Z])* 0.061 ABC0.005 - P3 12 - DIST 2810 - P3->Z])* 0.011 ABC0.011	0.000 -0.075 -0.0	0.200 0.075 0.150 0.075 0.150	0.226 -0.056 0.112 -0.031 0.061 -0.005		× × × × × × × × × × × × × × × × × × ×



Dim/Pos

SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C1.1 - 24.08.2021 - 10.00

OPERATOR: TP

Actual

Nominal

DATE: 24/08/21 13:25:05 SOFTWARE: METROLOG X4V14

Tol+

Tol-



State

TRUE POSITION 0.15 - S12 - DIST		Actual	101-	101+	Dev.	iena.	State
= ABS([S12 - DIST 2810 - P4=>		- D1->71*2					
	0.000		0.000	0.150	0.054		,
	J.000	0.054	0.000	0.150	0.054		~
r S12 - DIST 2810 - P5							
POIN 2810 - P5 - POIN D.69 / I	REP ABC.						
dZ 8	8.000	7.939	-0.075	0.075	-0.061		✓
TRUE POSITION 0.15 - S12 - DIST	2810 - P5		-	<u>'</u>			
=ABS([S12 - DIST 2810 - P5=>		- P5->71)*2					
	0.000	0.122	0.000	0.150	0.122		
	3.000	0.122	0.000	0.130	0.122		✓
NAL1 NAL1							
Dimensiuni extra							
r∸ DIST 400 - 1							
POIN 400 - 1-5 - PLAN 400 - 1	/ REP ABC.						
	2.650	2.548	-0.120	0.100	-0.102		~
	2.000	2.040	-0.120	0.100	-0.102		<u> </u>
DIST 400 - 2							
POIN 400 - 2-5 - PLAN 400 - 2	/ REP ABC.						
dZ 2	2.650	2.572	-0.090	0.090	-0.078		✓
r∸ DIST 400 - 3							
PLAN 400 - 3 - POIN 400 - 3-5	/ REP ABC						
	2.650	2.575	-0.140	0.090	-0.075		,
	2.000	2.373	-0.140	0.090	-0.073		~
DIST 400 - 4							
PLAN 400 - 4 - POIN 400 - 4-5	/ REP ABC.						
dZ 2	2.650	2.587	-0.120	0.090	-0.063		~
r [≚] DIST 400 - 5							
PLAN 400 - 5 - POIN 400 - 5-9	/ REP ARC						
		2 207	0.200	0.000	0.262		
	2.650	2.387	-0.280	0.090	-0.263		✓
r [×] DIST 400 - 6							
POIN 400 - 6-5 - PLAN 400 - 6	/ REP ABC.						
dX 2	2.650	2.517	-0.120	0.090	-0.133	-0.013	X
r* DIST 410 - 1							
· ·	/ DED ADC						
POIN 410 - 1 - POIN 410 - 1-2		0.440	0.450	0.000	0.400	0.040	
	2.600	2.440	-0.150	0.090	-0.160	-0.010	X
r∸ DIST 410 - 2							
POIN 410 - 2 - POIN 410 - 2-2	/ REP ABC.						
	2.600	2.544	-0.100	0.090	-0.056		~
DIST 410 - 3	2.000	2.011	0.100	0.000	0.000		
	0 / DED ADO						
POIN 410 - 3-1 - POIN 410 - 3-							
dY 2	2.600	2.621	-0.090	0.090	0.021		\checkmark
് DIST 410 - 4							
POIN 410 - 4-1 - POIN 410 - 4-	2 / REP ABC.						
	2.600	2.450	-0.200	0.090	-0.150		~
	2.000	2.430	-0.200	0.030	-0.130		<u> </u>
r [™] DIST 410 - 5							
POIN 410 - 5 - POIN 410 - 5-2	/ REP ABC.						
dY 2	2.600	2.629	-0.090	0.090	0.029		✓
് DIST 410 - 6							
POIN 410 - 6 - POIN 1980 - 6 -	3 / REP ARC						
	2.600	2.430	-0.090	0.090	0.161	-0.071	V
	2.000	2.439	-0.090	0.090	-0.161	-0.071	×
r്∸ DIST 630 - 1							
POIN 630 - 1-1 - POIN 630 - 1-							
dZ 55	5.500	55.335	-0.270	0.100	-0.165		/
r [≚] DIST 630 - 2							
				•			
l' '	2 / DED ADC			<u>.</u>			
POIN 630 - 2-1 - POIN 630 - 2-			0.070		<u>'</u>	0.071	
POIN 630 - 2-1 - POIN 630 - 2- dZ 55		55.179	-0.270	0.100	-0.321	-0.051	X
POIN 630 - 2-1 - POIN 630 - 2-		55.179	-0.270		<u>'</u>	-0.051	X
POIN 630 - 2-1 - POIN 630 - 2- dZ 55	5.500	55.179	-0.270		<u>'</u>	-0.051	X
■ POIN 630 - 2-1 - POIN 630 - 2- dZ 55 DIST 780 - 1 ■ POIN 780 - 1 - PLAN 780 - 1 / F	5.500 S			0.100	-0.321		·
■ POIN 630 - 2-1 - POIN 630 - 2- dZ 55 DIST 780 - 1 ■ POIN 780 - 1 - PLAN 780 - 1 / F	5.500	3.300	-0.270 0.000		<u>'</u>	-0.051	×
POIN 630 - 2-1 - POIN 630 - 2- dZ 55 DIST 780 - 1 POIN 780 - 1 - PLAN 780 - 1 / F D 55	5.500 5 REP ABC. 3.200			0.100	-0.321		·
■ POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500	3.300	0.000	0.100	-0.321		· ✓
■ POIN 630 - 2-1 - POIN 630 - 2- dZ 58 DIST 780 - 1 POIN 780 - 1 - PLAN 780 - 1 / F DIST 780 - 2 POIN 780 - 2 - PLAN 780 - 2 / F DIST 780 - 2 POIN 780 - 2 / F	5.500 5 REP ABC. 3.200			0.100	-0.321		·
■ POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500	3.300	0.000	0.100	-0.321		✓
■ POIN 630 - 2-1 - POIN 630 - 2- dZ 58 DIST 780 - 1 POIN 780 - 1 - PLAN 780 - 1 / F DIST 780 - 2 POIN 780 - 2 - PLAN 780 - 2 / F DIST 780 - 2 PLAN 780 - 2 / F	5.500	3.300	0.000	0.100	-0.321		✓
■ POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500	3.300	0.000	0.100 0.170 0.190	-0.321 0.100 0.145		· ✓
■ POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500	3.300	0.000	0.100	-0.321		· ✓
■ POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500 5 REP ABC. 3.200 REP ABC. 3.200 REP ABC. 3.200 REP ABC.	3.300	0.000	0.100 0.170 0.190	-0.321 0.100 0.145		· ✓
■ POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500 5 REP ABC. 3.200 REP ABC. 3.200 REP ABC. 3.200 REP ABC.	3.300 3.345 3.274	0.000	0.100	-0.321 0.100 0.145 0.074		· ✓
■ POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500 5 REP ABC. 3.200 REP ABC. 3.200 REP ABC. 3.200 REP ABC.	3.300	0.000	0.100 0.170 0.190	-0.321 0.100 0.145		· ✓
POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500 5 REP ABC. 3.200 REP ABC. 3.200 REP ABC. 3.200 REP ABC.	3.300 3.345 3.274	0.000	0.100	-0.321 0.100 0.145 0.074		·
■ POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500 5 REP ABC. 3.200	3.300 3.345 3.274 3.378	0.000	0.100	-0.321 0.100 0.145 0.074		·
■ POIN 630 - 2-1 - POIN 630 - 2- dZ 58 58 DIST 780 - 1 POIN 780 - 1 - PLAN 780 - 1 / F DIST 780 - 2 POIN 780 - 2 - PLAN 780 - 2 / F DIST 780 - 3 POIN 780 - 3 - PLAN 780 - 3 / F DIST 780 - 4 POIN 780 - 4 - PLAN 780 - 4 / F DIST 780 - 4 PLAN 780 - 4 / F DIST 780 - MP10 POIN 1780 - MP10 POIN 1780 - MP10 - 2 - POIN 1	5.500 5 REP ABC. 3.200	3.300 3.345 3.274 3.378 PABC.	0.000 0.000 0.000	0.100 0.170 0.190 0.100 0.100	-0.321 0.100 0.145 0.074 0.178	0.078	· · · · · · · · · · · · · · · · · · ·
■ POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500 5 REP ABC. 3.200	3.300 3.345 3.274 3.378	0.000	0.100	-0.321 0.100 0.145 0.074		· · · · · · · · · · · · · · · · · · ·
■ POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500 5 REP ABC. 3.200 1780 - MP10 - 1 / REF 6.500 10	3.345 3.274 3.378 PABC. 06.577	0.000 0.000 0.000	0.100 0.170 0.190 0.100 0.100	-0.321 0.100 0.145 0.074 0.178	0.078	· · · · · · · · · · · · · · · · · · ·
■ POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500 5 REP ABC. 3.200 1780 - MP10 - 1 / REF 6.500 10	3.345 3.274 3.378 PABC. 06.577	0.000 0.000 0.000	0.100 0.170 0.190 0.100 0.100	-0.321 0.100 0.145 0.074 0.178	0.078	· · · · · · · · · · · · · · · · · · ·
■ POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500 5 REP ABC. 3.200 8 REP ABC. 3.200 8 REP ABC. 3.200 8 REP ABC. 3.200 1780 - MP10 - 1 / REF 6.500 10 REP ABC. 1 / REF	3.300 3.345 3.274 3.378 PABC. 06.577 PABC.	0.000 0.000 0.000 0.000	0.100	-0.321 0.100 0.145 0.074 0.178 0.077	0.078	· · · · · · · · · · · · · · · · · · ·
POIN 630 - 2-1 - POIN 630 - 2- dZ	5.500 5 REP ABC. 3.200 8 REP ABC. 3.200 8 REP ABC. 3.200 8 REP ABC. 3.200 1780 - MP10 - 1 / REF 6.500 10 REP ABC. 1 / REF	3.345 3.274 3.378 PABC. 06.577	0.000 0.000 0.000	0.100 0.170 0.190 0.100 0.100	-0.321 0.100 0.145 0.074 0.178	0.078	· · · · · · · · · · · · · · · · · · ·



SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C1.1 - 24.08.2021 - 10.00

OPERATOR: TP

DATE: 24/08/21 13:25:05 SOFTWARE: METROLOG X4V14



Dim/Pos Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
r* DIST 1780 - MP12	Actual	101-	101.	DCV.	TCHU.	Otato
POIN 1780 - MP12 - 2 - POIN 1780 - MP1	2 - 1 / REP ABC.					
dX 106.500	106.550	0.000	0.220	0.050		✓
DIST 2600 - P1 - F						
POIN 2600 - P1 - DRTE F / REP ABC.	-0.071	-0.075	0.075	-0.071		,
dX 0.000 0.	-0.071	-0.075	0.075	-0.071		✓
= ABS([DIST 2600 - P1 - F=>X]-[DIST 260	0 - P1 - F->X1)*2					
Val. 0.000	0.141	0.000	0.150	0.141		✓
r DIST 2600 - P2 - F	<u> </u>	' ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' '	1	'		
POIN 2600 - P2 - DRTE F / REP ABC.						
dX -0.000	-0.061	-0.075	0.075	-0.061		✓
	0 D2 E \V1*2					
Val. 0.000	0.122	0.000	0.150	0.122		✓
r DIST 2600 - P3 - F	0.122	0.000	0.100	0.122		V
POIN 2600 - P3 - DRTE F / REP ABC.						
dX 0.000	-0.060	-0.075	0.075	-0.060		✓
		·				
=ABS([DIST 2600 - P3 - F=>X]-[DIST 260		0.000	0.450	0.440		
Val. 0.000	0.119	0.000	0.150	0.119		✓
POIN 2600 - P4 - P - DRTE F / REP ABC.						
dX 0.000	-0.064	-0.075	0.075	-0.064		✓
=ABS([DIST 2600 - P4 - F=>X]-[DIST 260	0 - P4 - F->X])*2					
Val. 0.000	0.129	0.000	0.150	0.129		✓
DIST 2600 - P5 - F						
POIN 2600 - P5 - DRTE F / REP ABC.	-0.067	-0.075	0.075	-0.067		✓
d∧	-0.007	-0.075	0.075	-0.007		~
= ABS([DIST 2600 - P5 - F=>X]-[DIST 260	0 - P5 - F->X1)*2					
Val. 0.000	0.135	0.000	0.150	0.135		✓
r [™] DIST 2600 - P1 - L	<u>'</u>	<u> </u>	,	'		
POIN 2600 - P1 - DRTE L / REP ABC.						
dX 0.000	0.016	-0.075	0.075	0.016		✓
	0 D1 L \VI*2					
Val. 0.000	0.032	0.000	0.150	0.032		/
r DIST 2600 - P2 - L	0.002	0.000	0.100	0.002		·
POIN 2600 - P2 - DRTE L / REP ABC.						
dX -0.000	0.034	-0.075	0.075	0.034		✓
№ 0.1 - DIST 2600 - P2 - L	0 D0 I \000		<u> </u>			
=ABS([DIST 2600 - P2 - L=>X]-[DIST 2600		0.000	0.150	0.067		
Val. 0.000	0.067	0.000	0.150	0.067		✓
POIN 2600 - P3 - DRTE L / REP ABC.						
dX 0.000	0.043	-0.075	0.075	0.043		✓
	<u> </u>					
= ABS([DIST 2600 - P3 - L=>X]-[DIST 2600	*/					
Val. 0.000	0.086	0.000	0.150	0.086		✓
DIST 2600 - P4 - L						
POIN 2600 - P4 - DRTE L / REP ABC.	0.047	-0.075	0.075	0.047		✓
Ø.000 0.000	0.041	-0.070	3.070	0.047		V
= ABS([DIST 2600 - P4 - L=>X]-[DIST 2600	0 - P4 - L->X])*2					
Val. 0.000	0.094	0.000	0.150	0.094		✓
r≛₁ DIST 2600 - P5 - L						
POIN 2600 - P5 - DRTE L / REP ABC.	0.070	0.6==1	0.0==	0.070		
dX	0.052	-0.075	0.075	0.052		✓
= ABS([DIST 2600 - P5 - L =>X]-[DIST 2600	0 - P5 - I ->X1*2					
Val. 0.000	0.103	0.000	0.150	0.103		✓
r DIST 2610 - P1 - F	300	2.300	200	500		
POIN 2610 - P1 - DRTE F / REP ABC.						
dX -0.000	-0.088	-0.150	0.150	-0.088		✓
№ 0.1 - DIST 2610 - P1 - F						
= ABS([DIST 2610 - P1 - F=>X]-[DIST 2610		0.000	0.200	0.477		
Val. 0.000 □ Xη DIST 2610 - P2 - F	0.177	0.000	0.300	0.177		✓
POIN 2610 - P2 - PTE F / REP ABC.						
dX -0.000	-0.071	-0.150	0.150	-0.071		✓
3.300	2.2.1					_



SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C1.1 - 24.08.2021 - 10.00

OPERATOR: TP

DATE: 24/08/21 13:25:06 SOFTWARE: METROLOG X4V14



Dim/Pos Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
№ 0.1 - DIST 2610 - P2 - F	Actual	101-	1011	Dev.	iena.	State
= ABS([DIST 2610 - P2 - F=>X]-[DIST	T 2610 - P2 - F->X])*2					
Val. 0.000	0.143	0.000	0.300	0.143		✓
r [≿] ₁ DIST 2610 - P3 - F		·				
POIN 2610 - P3 - DRTE F / REP ABO		0.450	0.450	0.074		
dX -0.000	-0.074	-0.150	0.150	-0.074		✓
	T 2610 - D3 - F->Y1*2					
Val. 0.000		0.000	0.300	0.148		~
DIST 2610 - P4 - F	0.110	0.000	0.000	0.110		V
POIN 2610 - P4 - DRTE F / REP ABO	C.					
dX -0.000	-0.134	-0.150	0.150	-0.134		✓
= ABS([DIST 2610 - P4 - F=>X]-[DIST						
Val. 0.000	0.268	0.000	0.300	0.268		✓
DIST 2610 - P5 - F	0					
POIN 2610 - P5 - DRTE F / REP ABO		-0.150	0.150	-0.152	-0.002	2 X
∴ 0.1 - DIST 2610 - P5 - F	-0.132	-0.130	0.130	-0.132	-0.002	^
= ABS([DIST 2610 - P5 - F=>X]-[DIST	T 2610 - P5 - F->X1)*2					
Val. 0.000		0.000	0.300	0.304	0.004	X
DIST 2610 - P1 - L						
POIN 2610 - P1 - DRTE L / REP ABO						
dX 0.000	-0.002	-0.150	0.150	-0.002		✓
♦ 0.1 - DIST 2610 - P1 - L	F0040 D4 1 : \0*0					
=ABS([DIST 2610 - P1 - L=>X]-[DIST		0.000	0.200	0.004		
Val. 0.000 ∸ DIST 2610 - P2 - L	0.004	0.000	0.300	0.004		✓
POIN 2610 - P2 - DRTE L / REP ABO	C.					
dX -0.000		-0.150	0.150	0.023		~
						•
= ABS([DIST 2610 - P2 - L=>X]-[DIST	Γ 2610 - P2 - L->X])*2					
Val. 0.000	0.046	0.000	0.300	0.046		✓
r [™] DIST 2610 - P3 - L	_					
POIN 2610 - P3 - DRTE L / REP ABO		0.450	0.450	0.000		
dX -0.000	0.029	-0.150	0.150	0.029		✓
	T 2610 - D3 - L->YI*2					
Val. 0.000		0.000	0.300	0.058		/
DIST 2610 - P4 - L	0.000	0.000	0.000	0.000		V
POIN 2610 - P4 - DRTE L / REP ABO	O.					
dX 0.000	-0.023	-0.150	0.150	-0.023		✓
						_
= ABS([DIST 2610 - P4 - L=>X]-[DIST						
Val. 0.000	0.046	0.000	0.300	0.046		✓
DIST 2610 - P5 - L	^					
POIN 2610 - P5 - DRTE L / REP ABO dX 0.000		-0.150	0.150	-0.033		
0.000	-0.033	-0.130	0.100	-0.033		✓
= ABS([DIST 2610 - P5 - L=>X]-[DIST	Γ 2610 - P5 - L->X1)*2					
Val. 0.000		0.000	0.300	0.066		~
⊥ PERP 2620 - P1						
■ DRTE 2620 - P1(G)/PLAN H - C-Zon						
Val. 0.000	0.045		0.200	0.045		✓
⊥ PERP 2620 - P2						
DRTE 2620 - P2(G)/PLAN H - C-Zon			0.000	0.000		
Val. 0.000 ⊥ PERP 2620 - P3	0.038		0.200	0.038		✓
DRTE 2620 - P3(G)/PLAN H - C-Zon	ne					
Val. 0.000			0.200	0.041		~
⊥ PERP 2620 - P4	0.071		5.250	0.011		
■ DRTE 2620 - P4(G)/PLAN H - C-Zon	ne					
Val. 0.000			0.200	0.097		~
⊥ PERP 2620 - P5						
■ DRTE 2620 - P5(G)/PLAN H - C-Zon						
Val. 0.000	0.111		0.200	0.111		✓
DIST 2630						
■ DRTE L-1 - DRTE L-2 / REP ABC. D 7.180	7.140	-0.050	0.050	-0.040		
	7.140	-0.050	0.050	-0.040		✓
→ DIST 2640						
DIST 2640 ■ DRTE 2640 - 2 - DRTE 2640 - 1 / RE	EP ABC.					
DIST 2640 ■ DRTE 2640 - 2 - DRTE 2640 - 1 / RE D 7.150		-0.050	0.050	-0.014		~



SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C1.1 - 24.08.2021 - 10.00

OPERATOR: TP

DATE: 24/08/21 13:25:06 SOFTWARE: METROLOG X4V14



Dim/Pos r → DIST 2650	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
DRTE F - 1 - DRTE	F-2 / REP ABC. 6.950	6.941	-0.050	0.050	-0.009		✓
DIST 2660 - F DRTE 2640 - MID -				51553			
D D SYMMETRY 0.1 - DIST 2	0.000	0.057	-0.050	0.050	0.057	0.007	X
=ABS([DIST 2660 - Val.	F=>Dist1]-[DIST 2660 0.000	- F->Dist1])*2 0.115	0.000	0.100	0.115	0.015	X
	DRTE L / REP ABC. 0.000	0.046	-0.050	0.050	0.046		
SYMMETRY 0.1 - DIST 2 = ABS([DIST 2660 -	2660 - L		-0.030	0.030	0.040		✓
Val. r [™] DIST 2710 - MP6	0.000	0.091	0.000	0.100	0.091		✓
POIN 2710 - MP6 - dZ	1 - POIN 2710 - MP6 - 54.200	2 / REP ABC. 54.101	-0.050	0.200	-0.099	-0.049	X
N DIST 2710 - MP7	1 - POIN 2710 - MP7 - 54.200	2 / REP ABC. 54.189	-0.100	0.550	-0.011		✓
DIST 2710 - MP8		1	-0.100	0.000	-0.011	<u> </u>	<u> </u>
dZ dZ dZ dZ dZ	54.200	54.161	-0.020	0.200	-0.039	-0.019	X
POIN 2780 - 3 - POI	0.000	-0.026	-0.050	0.050	-0.026	11	✓
SYMMETRY 0.1 - DIST 2 = ABS([DIST 2750=> Val.		0.053	0.000	0.100	0.053		✓
POIN 2780 - 3 - POI							
dZ		-0.017	-0.050	0.050	-0.017		✓
Val.	0.000	0.034	0.000	0.100	0.034		~
POIN 2760 - POIN E	0.000	-0.038	-0.050	0.050	-0.038		✓
SYMMETRY 0.1 - DIST 2 = ABS([DIST 2760=>	Z]-[DIST 2760->Z])*2	0.076	0.000	0.100	0.076		
Val. → DIST 2760 - K POIN 2760 - POIN 2	0.000 2500 - P3 - X / REP AB	0.076	0.000	0.100	0.076		✓
dZ d	0.000	-0.028	-0.050	0.050	-0.028		✓
=ABS([DIST 2760 - Val.	K=>Z]-[DIST 2760 - K- 0.000	>Z])*2 0.057	0.000	0.100	0.057		✓
→ DIST 2770	N 2770 - 2 / REP ABC 23.190	. 23.273	-0.050	0.050	0.083	0.033	×
→ DIST 2780 ■ POIN 2780 - 1 - POI			-0.030	0.030	0.003	0.000	^
D r∸₁ DIST 2790	23.150	23.176	-0.050	0.050	0.026		✓
POIN D-2 - POIN D-dZ	1 / REP ABC. 21.600	21.550	-0.050	0.050	-0.050		✓
	N 2800 - 2 / REP ABC 23.850	. 24.059	-0.150	0.150	0.209	0.059	×
⊢ DIST 2820 - P1 POIN D.69 - POIN 2	820 - P1 / REP ABC.					3.330	
dZ A TRUE POSITION 0.3 - D		7.917	-0.150	0.150	-0.083		✓
■ =ABS([DIST 2820 - Val.	0.000 0.000	71->2])^2 0.165	0.000	0.300	0.165		✓
POIN D.69 - POIN 2	4.000	3.962	-0.150	0.150	-0.038		✓
TRUE POSITION 0.3 - D ■ =ABS([DIST 2820 -	P2=>Z]-[DIST 2820 - F		0.000	0.300	0.077		
Val.	0.000	0.077	0.000	0.300	0.077		✓



SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C1.1 - 24.08.2021 - 10.00

OPERATOR: TP

DATE: 24/08/21 13:25:06 SOFTWARE: METROLOG X4V14



Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
DIST 2820 - P3		·	I.	"			
POIN D.69 - POIN 2	820 - P3 / REP ABC.						
dZ	-0.000	-0.004	-0.150	0.150	-0.004		~
TRUE POSITION 0.3 - D			•	·			
= =ABS([DIST 2820 - F		->Z])*2					
Val.	0.000	0.009	0.000	0.300	0.009		~
DIST 2820 - P4							
POIN 2820 - P4 - PC	DIN D.69 / REP ABC.						
dZ	4.000	3.954	-0.150	0.150	-0.046		~
TRUE POSITION 0.3 - D							
= =ABS([DIST 2820 - I		->Z])*2				_	
Val.	0.000	0.092	0.000	0.300	0.092		~
DIST 2820 - P5							
POIN 2820 - P5 - PC						_	
dZ	8.000	7.910	-0.150	0.150	-0.090		~
TRUE POSITION 0.3 - D							
= =ABS([DIST 2820 - I		->Z])*2				_	
Val.	0.000	0.179	0.000	0.300	0.179		✓