

SITE: **TRP**Control Equipment: **QC_74 - DEA Performance**THOMAS REFERENCE: **HEL010/A - C2.3 - 24.08.2021 - 10.00**OPERATOR: **IR**DATE : **24/08/21 15:00:33**SOFTWARE: **METROLOG X4V14**

RESULTS

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
S10 - CERC 710 - C							
Inters. PLAN A - CYL C.							
Diam.	4.000	3.907	-0.100	0.000	-0.093		
S10 - CERC 710 - B							
Inters. PLAN A - CYL B.							
Diam.	4.000	3.958	-0.100	0.000	-0.042		
S07 - PLTE 450							
PLAN A C							
Val.	0.000	0.205		0.250	0.205		
S04 - PLTE 455							
PLAN J C							
Val.	0.000	0.116		0.200	0.116		
S15 - DIST 470 - 11.25							
DRTE B-C - POIN 470 - 11.25 / REP ABC.							
dZ	11.250	11.279	-0.075	0.075	0.029		
TRUE POSITION 0.15 - S15 - DIST 470 - 11.25							
=ABS([S15 - DIST 470 - 11.25=>Z]-[S15 - DIST 470 - 11.25->Z])*2							
Val.	0.000	0.057	0.000	0.150	0.057		
S15 - DIST 470 - 33.65							
DRTE B-C - POIN 470 - 33.65 / REP ABC.							
dZ	33.650	33.673	-0.130	0.130	0.023		
TRUE POSITION 0.15 - S15 - DIST 470 - 33.65							
=ABS([S15 - DIST 470 - 33.65=>Z]-[S15 - DIST 470 - 33.65->Z])*2							
Val.	0.000	0.046	0.000	0.260	0.046		
S18 - DIST 550							
PLAN A - POIN 550 / REP ABC.							
D	6.100	6.204	-0.100	0.100	0.104	0.004	
S06 - DIST 1280							
POIN 1280 - 1 - POIN 1280 - 2 / REP ABC.							
D	12.700	12.676	-0.100	0.100	-0.024		
S16 - DIST 1300 - LEFT							
PLAN H - POIN 1300 - LEFT / REP ABC.							
dY	12.015	12.060	-0.050	0.050	0.045		
S16 - DIST 1300 - RIGHT							
PLAN H - POIN 1300 - RIGHT / REP ABC.							
dY	12.015	12.020	-0.050	0.050	0.005		
S19 - DIST 1400 - P6 - DOWN							
PLAN J - POIN 1400 - P6 - DOWN / REP ABC.							
dY	0.850	0.832	-0.100	0.110	-0.018		
S19 - DIST 1400 - P6 - UP							
PLAN J - POIN 1400 - P6 - UP / REP ABC.							
dY	0.850	0.788	-0.100	0.110	-0.062		
S19 - DIST 1400 - P7 - DOWN							
PLAN J - POIN 1400 - P7 - DOWN / REP ABC.							
dY	0.850	0.796	-0.100	0.110	-0.054		
S19 - DIST 1400 - P7 - UP							
PLAN J - POIN 1400 - P7 - UP / REP ABC.							
dY	0.850	0.821	-0.100	0.110	-0.029		
S05 - DIST 1410 - P6 - 12.8							
POIN 2500 - P3 - X - POIN 1410 - 1 - 12.8 / REP ABC.							
dZ	12.800	12.809	-0.150	0.150	0.009		
S05 - DIST 1410 - P6 - 3.4							
POIN 2500 - P3 - Z - POIN 1410 - 1 - 3.4 / REP ABC.							
dX	3.400	3.284	-0.150	0.150	-0.116		
TRUE POSITION 0.3 X^2+Y^2 - S05 - DIST 1410 - P6							
=[SQRT X^2+Y^2 - S05 - DIST 1410 - P6->Val])*2							
Val.	0.000	0.233	0.000	0.300	0.233		
S05 - DIST 1410 - P7 - 9.6							
POIN 1410 - 2 - 9.6 - POIN 2500 - P3 - X / REP ABC.							
dZ	9.600	9.645	-0.150	0.150	0.045		
S05 - DIST 1410 - P7 - 3.4							
POIN 2500 - P3 - Z - POIN 1410 - 2 - 3.4 / REP ABC.							
dX	3.400	3.314	-0.150	0.150	-0.086		
TRUE POSITION 0.3 X^2+Y^2 - S05 - DIST 1410 - P7							
=[SQRT X^2+Y^2 - S05 - DIST 1410 - P7->Val])*2							
Val.	0.000	0.194	0.000	0.300	0.194		
S01 - 1690 - MP10							
POIN 109 - MP10 - 2 - POIN 109 - MP10 - 1 / REP ABC.							
dX	109.000	109.002	-0.100	0.200	0.002		



Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
S01 - 1690 - MP11							
POIN 109 - MP11 - 2 - POIN 109 - MP11 - 1 / REP ABC.							
dX	109.000	109.022	-0.100	0.200	0.022	<div><div></div></div>	✓
S01 - 1690 - MP12							
POIN 109 - MP12 - 2 - POIN 109 - MP12 - 1 / REP ABC.							
dX	109.000	109.024	-0.100	0.200	0.024	<div><div></div></div>	✓
S02 - 1730							
POIN 1730 - 2 - POIN 1730 - 1 / REP ABC.							
dZ	56.700	56.844	-0.100	0.300	0.144	<div><div></div></div>	✓
S03 - DIST 1880							
PLAN 1880 - POIN 1880 - 3 / REP ABC.							
dY	43.500	43.503	-0.100	0.150	0.003	<div><div></div></div>	✓
S17 - 1980 - 1							
PLAN A-1 - POIN 1680 - 1 - 3 / REP ABC.							
D	7.000	6.947	-0.130	0.000	-0.053	<div><div></div></div>	✓
S17 - 1980 - 2							
PLAN A-2 - POIN 1980 - 2 - 3 / REP ABC.							
D	7.000	6.998	-0.100	0.000	-0.002	<div><div></div></div>	✓
S17 - 1980 - 3							
PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC.							
D	7.000	6.920	-0.100	0.000	-0.080	<div><div></div></div>	✓
S17 - 1980 - 4							
PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.							
D	7.000	6.893	-0.110	0.000	-0.107	<div><div></div></div>	✓
S17 - 1980 - 5							
PLAN A-5 - POIN 1980 - 5 - 3 / REP ABC.							
D	7.000	7.024	-0.050	0.065	0.024	<div><div></div></div>	✓
S17 - 1980 - 6							
PLAN A-6 - POIN 1980 - 6 - 3 / REP ABC.							
D	7.000	6.897	-0.100	0.000	-0.103	-0.003	✗
S13 - DIST 2310 - MP1 - UP							
POIN 2310 - MP1 - UP - 1 - POIN 2310 - MP1 - UP - 2 / REP ABC.							
D	9.950	9.957	-0.050	0.150	0.007	<div><div></div></div>	✓
S13 - DIST 2310 - MP1 - DOWN							
POIN 2310 - MP1 - DOWN - 1 - POIN 2310 - MP1 - DOWN - 2 / REP ABC.							
D	9.950	9.961	-0.050	0.150	0.011	<div><div></div></div>	✓
S13 - DIST 2310 - MP4 - UP							
POIN 2310 - MP4 - UP - 1 - POIN 2310 - MP4 - UP - 2 / REP ABC.							
D	9.950	10.084	-0.050	0.150	0.134	<div><div></div></div>	✓
S13 - DIST 2310 - MP4 - DOWN							
POIN 2310 - MP4 - DOWN - 1 - POIN 2310 - MP4 - DOWN - 2 / REP ABC.							
D	9.950	10.073	-0.050	0.150	0.123	<div><div></div></div>	✓
S08 - DIST 2420 - MP1							
POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.							
D	25.900	26.031	-0.100	0.150	0.131	<div><div></div></div>	✓
S08 - DIST 2420 - MP2							
POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.							
D	25.900	25.886	-0.100	0.150	-0.014	<div><div></div></div>	✓
S09 - DIST 2500 - P1 - 8							
POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.							
dZ	8.000	7.985	-0.100	0.100	-0.015	<div><div></div></div>	✓
S09 - DIST 2500 - P1 - 0							
POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.							
dX	0.000	-0.016	-0.100	0.100	-0.016	<div><div></div></div>	✓
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P1							
=[SQRT X^2+Y^2 - S09 - DIST 2500 - P1->Val]*2							
Val.	0.000	0.044	0.000	0.200	0.044	<div><div></div></div>	✓
S09 - DIST 2500 - P2 - 4							
POIN 2500 - P3 - X - POIN 2500 - P2 - 4 / REP ABC.							
dZ	4.000	3.972	-0.100	0.100	-0.028	<div><div></div></div>	✓
S09 - DIST 2500 - P2 - 0							
POIN 2500 - P2 - 0 - POIN 2500 - P3 - Z / REP ABC.							
dX	-0.000	-0.038	-0.100	0.100	-0.038	<div><div></div></div>	✓
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P2							
=[SQRT X^2+Y^2 - S09 - DIST 2500 - P2->Val]*2							
Val.	0.000	0.095	0.000	0.200	0.095	<div><div></div></div>	✓
S09 - DIST 2500 - P4 - 4							
POIN 2500 - P4 - 4 - POIN 2500 - P3 - X / REP ABC.							
dZ	4.000	4.033	-0.100	0.100	0.033	<div><div></div></div>	✓
S09 - DIST 2500 - P4 - 0							
POIN 2500 - P4 - 0 - POIN 2500 - P3 - Z / REP ABC.							
dX	0.000	-0.058	-0.100	0.100	-0.058	<div><div></div></div>	✓

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Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P4 =[SQRT X^2+Y^2 - S09 - DIST 2500 - P4->Val]*2 Val.	0.000	0.134	0.000	0.200	0.134		✓
S09 - DIST 2500 - P5 - 8 POIN 2500 - P5 - 8 - POIN 2500 - P3 - X / REP ABC. dZ	8.000	7.948	-0.100	0.100	-0.052		✓
S09 - DIST 2500 - P5 - 0 POIN 2500 - P5 - 0 - POIN 2500 - P3 - Z / REP ABC. dX	0.000	0.022	-0.100	0.100	0.022		✓
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P5 =[SQRT X^2+Y^2 - S09 - DIST 2500 - P5->Val]*2 Val.	0.000	0.114	0.000	0.200	0.114		✓
S20 - DIST 2530 - P1 - DOWN PLAN J - POIN 2530 - P1 - DOWN / REP ABC. dY	1.150	1.113	-0.100	0.100	-0.037		✓
S20 - DIST 2530 - P1 - UP PLAN J - POIN 2530 - P1 - UP / REP ABC. dY	1.150	1.099	-0.100	0.100	-0.051		✓
S20 - DIST 2530 - P2 - DOWN PLAN J - POIN 2530 - P2 - DOWN / REP ABC. dY	1.150	1.117	-0.100	0.100	-0.033		✓
S20 - DIST 2530 - P2 - UP PLAN J - POIN 2530 - P2 - UP / REP ABC. dY	1.150	1.108	-0.100	0.100	-0.042		✓
S20 - DIST 2530 - P3 - DOWN PLAN J - POIN 2530 - P3 - DOWN / REP ABC. dY	1.150	1.073	-0.100	0.100	-0.077		✓
S20 - DIST 2530 - P3 - UP PLAN J - POIN 2530 - P3 - UP / REP ABC. dY	1.150	1.074	-0.100	0.100	-0.076		✓
S20 - DIST 2530 - P4 - DOWN PLAN J - POIN 2530 - P4 - DOWN / REP ABC. dY	1.150	1.110	-0.140	0.100	-0.040		✓
S20 - DIST 2530 - P4 - UP PLAN J - POIN 2530 - P4 - UP / REP ABC. dY	1.150	1.111	-0.120	0.100	-0.039		✓
S20 - DIST 2530 - P5 - DOWN PLAN J - POIN 2530 - P5 - DOWN / REP ABC. dY	1.150	1.091	-0.100	0.100	-0.059		✓
S20 - DIST 2530 - P5 - UP PLAN J - POIN 2500 - P5 - UP / REP ABC. dY	1.150	1.103	-0.100	0.100	-0.047		✓
S14 - 2670 - 29.5 S10 - CERC 710 - B - POIN 2500 - P3 - Z / REP ABC. dX	29.500	29.523	-0.100	0.100	0.023		✓
S14 - 2670 - 20.85 S10 - CERC 710 - B - POIN K-6 / REP ABC. dZ	20.850	20.888	-0.100	0.100	0.038		✓
TRUE POSITION 0.2 X^2+Y^2 - S14 - 2670 - 20.8529 =[SQRT X^2+Y^2 - S14 - 2670->Val]*2 Val.	0.000	0.089	0.000	0.200	0.089		✓
S12 - DIST 2810 - P1 POIN D.69 - POIN 2810 - P1 / REP ABC. dZ	8.000	7.967	-0.075	0.075	-0.033		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P1 =ABS([S12 - DIST 2810 - P1=>Z]-[S12 - DIST 2810 - P1->Z])*2 Val.	0.000	0.066	0.000	0.150	0.066		✓
S12 - DIST 2810 - P2 POIN D.69 - POIN 2810 - P2 / REP ABC. dZ	4.000	4.002	-0.075	0.075	0.002		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P2 =ABS([S12 - DIST 2810 - P2=>Z]-[S12 - DIST 2810 - P2->Z])*2 Val.	0.000	0.003	0.000	0.150	0.003		✓
S12 - DIST 2810 - P3 POIN D.69 - POIN 2810 - P3 / REP ABC. dZ	0.000	0.016	-0.075	0.075	0.016		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P3 =ABS([S12 - DIST 2810 - P3=>Z]-[S12 - DIST 2810 - P3->Z])*2 Val.	0.000	0.032	0.000	0.150	0.032		✓
S12 - DIST 2810 - P4 POIN 2810 - P4 - POIN D.69 / REP ABC. dZ	4.000	3.955	-0.075	0.075	-0.045		✓



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SOFTWARE: **METROLOG X4V14**



Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
TRUE POSITION 0.15 - S12 - DIST 2810 - P4 =ABS([S12 - DIST 2810 - P4=>Z]-[S12 - DIST 2810 - P4->Z])*2 Val.	0.000	0.090	0.000	0.150	0.090		✓
S12 - DIST 2810 - P5 POIN 2810 - P5 - POIN D.69 / REP ABC. dZ	8.000	7.925	-0.075	0.075	-0.075		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P5 =ABS([S12 - DIST 2810 - P5=>Z]-[S12 - DIST 2810 - P5->Z])*2 Val.	0.000	0.149	0.000	0.150	0.149		✓
VAL1 Dimensiuni extra							
DIST 400 - 1 POIN 400 - 1-5 - PLAN 400 - 1 / REP ABC. dZ	2.650	2.546	-0.120	0.100	-0.104		✓
DIST 400 - 2 POIN 400 - 2-5 - PLAN 400 - 2 / REP ABC. dZ	2.650	2.573	-0.090	0.090	-0.077		✓
DIST 400 - 3 PLAN 400 - 3 - POIN 400 - 3-5 / REP ABC. dX	2.650	2.513	-0.140	0.090	-0.137		✓
DIST 400 - 4 PLAN 400 - 4 - POIN 400 - 4-5 / REP ABC. dZ	2.650	2.591	-0.120	0.090	-0.059		✓
DIST 400 - 5 PLAN 400 - 5 - POIN 400 - 5-9 / REP ABC. dZ	2.650	2.597	-0.280	0.090	-0.053		✓
DIST 400 - 6 POIN 400 - 6-5 - PLAN 400 - 6 / REP ABC. dX	2.650	2.567	-0.120	0.090	-0.083		✓
DIST 410 - 1 POIN 410 - 1 - POIN 410 - 1-2 / REP ABC. dY	2.600	2.495	-0.150	0.090	-0.105		✓
DIST 410 - 2 POIN 410 - 2 - POIN 410 - 2-2 / REP ABC. dY	2.600	2.526	-0.100	0.090	-0.074		✓
DIST 410 - 3 POIN 410 - 3-1 - POIN 410 - 3-2 / REP ABC. dY	2.600	2.614	-0.090	0.090	0.014		✓
DIST 410 - 4 POIN 410 - 4-1 - POIN 410 - 4-2 / REP ABC. dY	2.600	2.476	-0.200	0.090	-0.124		✓
DIST 410 - 5 POIN 410 - 5 - POIN 410 - 5-2 / REP ABC. dY	2.600	2.645	-0.090	0.090	0.045		✓
DIST 410 - 6 POIN 410 - 6 - POIN 1980 - 6 - 3 / REP ABC. dY	2.600	2.557	-0.090	0.090	-0.043		✓
DIST 630 - 1 POIN 630 - 1-1 - POIN 630 - 1-2 / REP ABC. dZ	55.500	55.420	-0.270	0.100	-0.080		✓
DIST 630 - 2 POIN 630 - 2-1 - POIN 630 - 2-2 / REP ABC. dZ	55.500	55.193	-0.270	0.100	-0.307	-0.037	✗
DIST 780 - 1 POIN 780 - 1 - PLAN 780 - 1 / REP ABC. D	3.200	3.355	0.000	0.170	0.155		✓
DIST 780 - 2 POIN 780 - 2 - PLAN 780 - 2 / REP ABC. D	3.200	3.290	0.000	0.190	0.090		✓
DIST 780 - 3 POIN 780 - 3 - PLAN 780 - 3 / REP ABC. D	3.200	3.256	0.000	0.100	0.056		✓
DIST 780 - 4 POIN 780 - 4 - PLAN 780 - 4 / REP ABC. D	3.200	3.324	0.000	0.100	0.124	0.024	✗
DIST 1780 - MP10 POIN 1780 - MP10 - 2 - POIN 1780 - MP10 - 1 / REP ABC. dX	106.500	106.601	0.000	0.220	0.101		✓
DIST 1780 - MP11 POIN 1780 - MP11 - 2 - POIN 1780 - MP11 - 1 / REP ABC. dX	106.500	106.612	0.000	0.220	0.112		✓



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OPERATOR: **IR**























DATE : **24/08/21 15:00:34**

SOFTWARE: **METROLOG X4V14**







































































Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
DIST 1780 - MP12							
POIN 1780 - MP12 - 2 - POIN 1780 - MP12 - 1 / REP ABC.							
dX	106.500	106.558	0.000	0.220	0.058		✓
DIST 2600 - P1 - F							
POIN 2600 - P1 - DRTE F / REP ABC.							
dX	-0.000	-0.046	-0.075	0.075	-0.046		✓
0.1 - DIST 2600 - P1 - F							
=ABS([DIST 2600 - P1 - F=>X]-[DIST 2600 - P1 - F->X])*2							
Val.	0.000	0.093	0.000	0.150	0.093		✓
DIST 2600 - P2 - F							
POIN 2600 - P2 - DRTE F / REP ABC.							
dX	-0.000	-0.040	-0.075	0.075	-0.040		✓
0.1 - DIST 2600 - P2 - F							
=ABS([DIST 2600 - P2 - F=>X]-[DIST 2600 - P2 - F->X])*2							
Val.	0.000	0.081	0.000	0.150	0.081		✓
DIST 2600 - P3 - F							
POIN 2600 - P3 - DRTE F / REP ABC.							
dX	-0.000	-0.039	-0.075	0.075	-0.039		✓
0.1 - DIST 2600 - P3 - F							
=ABS([DIST 2600 - P3 - F=>X]-[DIST 2600 - P3 - F->X])*2							
Val.	0.000	0.078	0.000	0.150	0.078		✓
DIST 2600 - P4 - F							
POIN 2600 - P4 - DRTE F / REP ABC.							
dX	-0.000	-0.046	-0.075	0.075	-0.046		✓
0.1 - DIST 2600 - P4 - F							
=ABS([DIST 2600 - P4 - F=>X]-[DIST 2600 - P4 - F->X])*2							
Val.	0.000	0.092	0.000	0.150	0.092		✓
DIST 2600 - P5 - F							
POIN 2600 - P5 - DRTE F / REP ABC.							
dX	-0.000	-0.034	-0.075	0.075	-0.034		✓
0.1 - DIST 2600 - P5 - F							
=ABS([DIST 2600 - P5 - F=>X]-[DIST 2600 - P5 - F->X])*2							
Val.	0.000	0.067	0.000	0.150	0.067		✓
DIST 2600 - P1 - L							
POIN 2600 - P1 - DRTE L / REP ABC.							
dX	-0.000	0.008	-0.075	0.075	0.008		✓
0.1 - DIST 2600 - P1 - L							
=ABS([DIST 2600 - P1 - L=>X]-[DIST 2600 - P1 - L->X])*2							
Val.	0.000	0.015	0.000	0.150	0.015		✓
DIST 2600 - P2 - L							
POIN 2600 - P2 - DRTE L / REP ABC.							
dX	-0.000	0.013	-0.075	0.075	0.013		✓
0.1 - DIST 2600 - P2 - L							
=ABS([DIST 2600 - P2 - L=>X]-[DIST 2600 - P2 - L->X])*2							
Val.	0.000	0.025	0.000	0.150	0.025		✓
DIST 2600 - P3 - L							
POIN 2600 - P3 - DRTE L / REP ABC.							
dX	-0.000	0.013	-0.075	0.075	0.013		✓
0.1 - DIST 2600 - P3 - L							
=ABS([DIST 2600 - P3 - L=>X]-[DIST 2600 - P3 - L->X])*2							
Val.	0.000	0.026	0.000	0.150	0.026		✓
DIST 2600 - P4 - L							
POIN 2600 - P4 - DRTE L / REP ABC.							
dX	-0.000	0.005	-0.075	0.075	0.005		✓
0.1 - DIST 2600 - P4 - L							
=ABS([DIST 2600 - P4 - L=>X]-[DIST 2600 - P4 - L->X])*2							
Val.	0.000	0.010	0.000	0.150	0.010		✓
DIST 2600 - P5 - L							
POIN 2600 - P5 - DRTE L / REP ABC.							
dX	-0.000	0.017	-0.075	0.075	0.017		✓
0.1 - DIST 2600 - P5 - L							
=ABS([DIST 2600 - P5 - L=>X]-[DIST 2600 - P5 - L->X])*2							
Val.	0.000	0.033	0.000	0.150	0.033		✓
DIST 2610 - P1 - F							
POIN 2610 - P1 - DRTE F / REP ABC.							
dX	-0.000	-0.001	-0.150	0.150	-0.001		✓
0.1 - DIST 2610 - P1 - F							
=ABS([DIST 2610 - P1 - F=>X]-[DIST 2610 - P1 - F->X])*2							
Val.	0.000	0.002	0.000	0.300	0.002		✓
DIST 2610 - P2 - F							
POIN 2610 - P2 - DRTE F / REP ABC.							
dX	-0.000	0.041	-0.150	0.150	0.041		✓



Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
0.1 - DIST 2610 - P2 - F =ABS([DIST 2610 - P2 - F=>X]-[DIST 2610 - P2 - F->X])*2 Val.	0.000	0.083	0.000	0.300	0.083		✓
DIST 2610 - P3 - F POIN 2610 - P3 - DRTE F / REP ABC. dX	-0.000	0.010	-0.150	0.150	0.010		✓
0.1 - DIST 2610 - P3 - F =ABS([DIST 2610 - P3 - F=>X]-[DIST 2610 - P3 - F->X])*2 Val.	0.000	0.020	0.000	0.300	0.020		✓
DIST 2610 - P4 - F POIN 2610 - P4 - DRTE F / REP ABC. dX	-0.000	0.029	-0.150	0.150	0.029		✓
0.1 - DIST 2610 - P4 - F =ABS([DIST 2610 - P4 - F=>X]-[DIST 2610 - P4 - F->X])*2 Val.	0.000	0.057	0.000	0.300	0.057		✓
DIST 2610 - P5 - F POIN 2610 - P5 - DRTE F / REP ABC. dX	-0.000	0.018	-0.150	0.150	0.018		✓
0.1 - DIST 2610 - P5 - F =ABS([DIST 2610 - P5 - F=>X]-[DIST 2610 - P5 - F->X])*2 Val.	0.000	0.037	0.000	0.300	0.037		✓
DIST 2610 - P1 - L POIN 2610 - P1 - DRTE L / REP ABC. dX	-0.000	0.053	-0.150	0.150	0.053		✓
0.1 - DIST 2610 - P1 - L =ABS([DIST 2610 - P1 - L=>X]-[DIST 2610 - P1 - L->X])*2 Val.	0.000	0.106	0.000	0.300	0.106		✓
DIST 2610 - P2 - L POIN 2610 - P2 - DRTE L / REP ABC. dX	-0.000	0.095	-0.150	0.150	0.095		✓
0.1 - DIST 2610 - P2 - L =ABS([DIST 2610 - P2 - L=>X]-[DIST 2610 - P2 - L->X])*2 Val.	0.000	0.189	0.000	0.300	0.189		✓
DIST 2610 - P3 - L POIN 2610 - P3 - DRTE L / REP ABC. dX	-0.000	0.062	-0.150	0.150	0.062		✓
0.1 - DIST 2610 - P3 - L =ABS([DIST 2610 - P3 - L=>X]-[DIST 2610 - P3 - L->X])*2 Val.	0.000	0.124	0.000	0.300	0.124		✓
DIST 2610 - P4 - L POIN 2610 - P4 - DRTE L / REP ABC. dX	-0.000	0.080	-0.150	0.150	0.080		✓
0.1 - DIST 2610 - P4 - L =ABS([DIST 2610 - P4 - L=>X]-[DIST 2610 - P4 - L->X])*2 Val.	0.000	0.160	0.000	0.300	0.160		✓
DIST 2610 - P5 - L POIN 2610 - P5 - DRTE L / REP ABC. dX	-0.000	0.068	-0.150	0.150	0.068		✓
0.1 - DIST 2610 - P5 - L =ABS([DIST 2610 - P5 - L=>X]-[DIST 2610 - P5 - L->X])*2 Val.	0.000	0.137	0.000	0.300	0.137		✓
PERP 2620 - P1 DRTE 2620 - P1(G)/PLAN H - C-Zone Val.	0.000	0.036		0.200	0.036		✓
PERP 2620 - P2 DRTE 2620 - P2(G)/PLAN H - C-Zone Val.	0.000	0.073		0.200	0.073		✓
PERP 2620 - P3 DRTE 2620 - P3(G)/PLAN H - C-Zone Val.	0.000	0.040		0.200	0.040		✓
PERP 2620 - P4 DRTE 2620 - P4(G)/PLAN H - C-Zone Val.	0.000	0.066		0.200	0.066		✓
PERP 2620 - P5 DRTE 2620 - P5(G)/PLAN H - C-Zone Val.	0.000	0.043		0.200	0.043		✓
DIST 2630 DRTE L-1 - DRTE L-2 / REP ABC. D	7.180	7.110	-0.050	0.050	-0.070	-0.020	✗
DIST 2640 DRTE 2640 - 2 - DRTE 2640 - 1 / REP ABC. D	7.150	7.139	-0.050	0.050	-0.011		✓



Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
 DIST 2650							
 DRTE F - 1 - DRTE F-2 / REP ABC.							
D	6.950	6.944	-0.050	0.050	-0.006		✓
 DIST 2660 - F							
 DRTE 2640 - MID - DRTE F / REP ABC.							
D	0.000	0.031	-0.050	0.050	0.031		✓
 SYMMETRY 0.1 - DIST 2660							
 =ABS([DIST 2660 - F=>Dist1]-[DIST 2660 - F=>Dist1])*2							
Val.	0.000	0.063	0.000	0.100	0.063		✓
 DIST 2660 - L							
 DRTE 2640 - MID - DRTE L / REP ABC.							
D	0.000	0.020	-0.050	0.050	0.020		✓
 SYMMETRY 0.1 - DIST 2660 - L							
 =ABS([DIST 2660 - L=>Dist1]-[DIST 2660 - L=>Dist1])*2							
Val.	0.000	0.040	0.000	0.100	0.040		✓
 DIST 2710 - MP6							
 POIN 2710 - MP6 - 1 - POIN 2710 - MP6 - 2 / REP ABC.							
dZ	54.200	54.128	-0.050	0.200	-0.072	-0.022	✗
 DIST 2710 - MP7							
 POIN 2710 - MP7 - 1 - POIN 2710 - MP7 - 2 / REP ABC.							
dZ	54.200	54.282	-0.100	0.550	0.082		✓
 DIST 2710 - MP8							
 POIN 2710 - MP8 - 1 - POIN 2710 - MP8 - 2 / REP ABC.							
dZ	54.200	54.214	-0.020	0.200	0.014		✓
 DIST 2750							
 POIN 2780 - 3 - POIN D.69 / REP ABC.							
dZ	0.000	-0.012	-0.050	0.050	-0.012		✓
 SYMMETRY 0.1 - DIST 2750							
 =ABS([DIST 2750=>Z]-[DIST 2750->Z])*2							
Val.	0.000	0.024	0.000	0.100	0.024		✓
 DIST 2750 - K							
 POIN 2780 - 3 - POIN 2500 - P3 - X / REP ABC.							
dZ	0.000	0.032	-0.050	0.050	0.032		✓
 SYMMETRY 0.1 - DIST 2750 - K							
 =ABS([DIST 2750 - K=>Z]-[DIST 2750 - K=>Z])*2							
Val.	0.000	0.065	0.000	0.100	0.065		✓
 DIST 2760							
 POIN 2760 - POIN D.69 / REP ABC.							
dZ	0.000	0.002	-0.050	0.050	0.002		✓
 SYMMETRY 0.1 - DIST 2760							
 =ABS([DIST 2760=>Z]-[DIST 2760->Z])*2							
Val.	0.000	0.003	0.000	0.100	0.003		✓
 DIST 2760 - K							
 POIN 2760 - POIN 2500 - P3 - X / REP ABC.							
dZ	-0.000	0.046	-0.050	0.050	0.046		✓
 SYMMETRY 0.1 - DIST 2760 - K							
 =ABS([DIST 2760 - K=>Z]-[DIST 2760 - K=>Z])*2							
Val.	0.000	0.092	0.000	0.100	0.092		✓
 DIST 2770							
 POIN 2770 - 1 - POIN 2770 - 2 / REP ABC.							
D	23.190	23.283	-0.050	0.050	0.093	0.043	✗
 DIST 2780							
 POIN 2780 - 1 - POIN 2780 - 2 / REP ABC.							
D	23.150	23.179	-0.050	0.050	0.029		✓
 DIST 2790							
 POIN D-2 - POIN D-1 / REP ABC.							
dZ	21.600	21.553	-0.050	0.050	-0.047		✓
 DIST 2800							
 POIN 2800 - 1 - POIN 2800 - 2 / REP ABC.							
D	23.850	24.034	-0.150	0.150	0.184	0.034	✗
 DIST 2820 - P1							
 POIN D.69 - POIN 2820 - P1 / REP ABC.							
dZ	8.000	7.924	-0.150	0.150	-0.076		✓
 TRUE POSITION 0.3 - DIST 2820 - P1							
 =ABS([DIST 2820 - P1=>Z]-[DIST 2820 - P1->Z])*2							
Val.	0.000	0.151	0.000	0.300	0.151		✓
 DIST 2820 - P2							
 POIN D.69 - POIN 2820 - P2 / REP ABC.							
dZ	4.000	3.983	-0.150	0.150	-0.017		✓
 TRUE POSITION 0.3 - DIST 2820 - P2							
 =ABS([DIST 2820 - P2=>Z]-[DIST 2820 - P2->Z])*2							
Val.	0.000	0.034	0.000	0.300	0.034		✓



SITE: **TRP**

Control Equipment: **QC_74 - DEA Performance**

THOMAS REFERENCE: **HEL010/A - C2.3 - 24.08.2021 - 10.00**

OPERATOR: **IR**

DATE : **24/08/21 15:00:34**

SOFTWARE: **METROLOG X4V14**



Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
DIST 2820 - P3 POIN D.69 - POIN 2820 - P3 / REP ABC. dZ	-0.000	0.013	-0.150	0.150	0.013		✓
TRUE POSITION 0.3 - DIST 2820 - P3 =ABS([DIST 2820 - P3=>Z]-[DIST 2820 - P3->Z])*2 Val.	0.000	0.027	0.000	0.300	0.027		✓
DIST 2820 - P4 POIN 2820 - P4 - POIN D.69 / REP ABC. dZ	4.000	3.967	-0.150	0.150	-0.033		✓
TRUE POSITION 0.3 - DIST 2820 - P4 =ABS([DIST 2820 - P4=>Z]-[DIST 2820 - P4->Z])*2 Val.	0.000	0.067	0.000	0.300	0.067		✓
DIST 2820 - P5 POIN 2820 - P5 - POIN D.69 / REP ABC. dZ	8.000	7.896	-0.150	0.150	-0.104		✓
TRUE POSITION 0.3 - DIST 2820 - P5 =ABS([DIST 2820 - P5=>Z]-[DIST 2820 - P5->Z])*2 Val.	0.000	0.207	0.000	0.300	0.207		✓