

SITE: **TRP**Control Equipment: **QC\_74 - DEA Performance**THOMAS REFERENCE: **HEL010/A - C2 - 01.06.2021 - 12.00**OPERATOR: **IR**DATE : **01/06/21 15:52:08**SOFTWARE: **METROLOG X4V14**

## RESULTS

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
⊙ S10 - CERC 710 - C							
Inters. PLAN A - CYL C.							
Diam.	4.000	3.907	-0.100	0.000	-0.093		✓
⊙ S10 - CERC 710 - B							
Inters. PLAN A - CYL B.							
Diam.	4.000	3.957	-0.100	0.000	-0.043		✓
▢ S07 - PLTE 450							
PLAN A C							
Val.	0.000	0.215		0.250	0.215		✓
▢ S04 - PLTE 455							
PLAN J C							
Val.	0.000	0.136		0.200	0.136		✓
⌈ S15 - DIST 470 - 11.25							
DRTE B-C - POIN 470 - 11.25 / REP ABC.							
dZ	11.250	11.277	-0.075	0.075	0.027		✓
⚙ TRUE POSITION 0.15 - S15 - DIST 470 - 11.25							
=ABS([S15 - DIST 470 - 11.25=>Z]-[S15 - DIST 470 - 11.25->Z])*2							
Val.	0.000	0.053	0.000	0.150	0.053		✓
⌈ S15 - DIST 470 - 33.65							
DRTE B-C - POIN 470 - 33.65 / REP ABC.							
dZ	33.650	33.625	-0.130	0.130	-0.025		✓
⚙ TRUE POSITION 0.15 - S15 - DIST 470 - 33.65							
=ABS([S15 - DIST 470 - 33.65=>Z]-[S15 - DIST 470 - 33.65->Z])*2							
Val.	0.000	0.050	0.000	0.260	0.050		✓
⌈ S18 - DIST 550							
PLAN A - POIN 550 / REP ABC.							
D	6.100	6.181	-0.100	0.100	0.081		✓
⌈ S06 - DIST 1280							
POIN 1280 - 1 - POIN 1280 - 2 / REP ABC.							
D	12.700	12.641	-0.100	0.100	-0.059		✓
⌈ S16 - DIST 1300 - LEFT							
PLAN H - POIN 1300 - LEFT / REP ABC.							
dY	12.015	12.061	-0.050	0.050	0.046		✓
⌈ S16 - DIST 1300 - RIGHT							
PLAN H - POIN 1300 - RIGHT / REP ABC.							
dY	12.015	12.035	-0.050	0.050	0.020		✓
⌈ S19 - DIST 1400 - P6 - DOWN							
PLAN J - POIN 1400 - P6 - DOWN / REP ABC.							
dY	0.850	0.833	-0.100	0.110	-0.017		✓
⌈ S19 - DIST 1400 - P6 - UP							
PLAN J - POIN 1400 - P6 - UP / REP ABC.							
dY	0.850	0.788	-0.100	0.110	-0.062		✓
⌈ S19 - DIST 1400 - P7 - DOWN							
PLAN J - POIN 1400 - P7 - DOWN / REP ABC.							
dY	0.850	0.805	-0.100	0.110	-0.045		✓
⌈ S19 - DIST 1400 - P7 - UP							
PLAN J - POIN 1400 - P7 - UP / REP ABC.							
dY	0.850	0.827	-0.100	0.110	-0.023		✓
⌈ S05 - DIST 1410 - P6 - 12.8							
POIN 2500 - P3 - X - POIN 1410 - 1 - 12.8 / REP ABC.							
dZ	12.800	12.831	-0.150	0.150	0.031		✓
⌈ S05 - DIST 1410 - P6 - 3.4							
POIN 2500 - P3 - Z - POIN 1410 - 1 - 3.4 / REP ABC.							
dX	3.400	3.232	-0.150	0.150	-0.168	-0.018	✗
⚙ TRUE POSITION 0.3 X^2+Y^2 - S05 - DIST 1410 - P6							
=[SQRT X^2+Y^2 - S05 - DIST 1410 - P6->Val]*2							
Val.	0.000	0.342	0.000	0.300	0.342	0.042	✗
⌈ S05 - DIST 1410 - P7 - 9.6							
POIN 1410 - 2 - 9.6 - POIN 2500 - P3 - X / REP ABC.							
dZ	9.600	9.609	-0.150	0.150	0.009		✓
⌈ S05 - DIST 1410 - P7 - 3.4							
POIN 2500 - P3 - Z - POIN 1410 - 2 - 3.4 / REP ABC.							
dX	3.400	3.236	-0.150	0.150	-0.164	-0.014	✗
⚙ TRUE POSITION 0.3 X^2+Y^2 - S05 - DIST 1410 - P7							
=[SQRT X^2+Y^2 - S05 - DIST 1410 - P7->Val]*2							
Val.	0.000	0.329	0.000	0.300	0.329	0.029	✗
⌈ S01 - 1690 - MP10							
POIN 109 - MP10 - 2 - POIN 109 - MP10 - 1 / REP ABC.							
dX	109.000	108.987	-0.100	0.200	-0.013		✓



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S01 - 1690 - MP11 POIN 109 - MP11 - 2 - POIN 109 - MP11 - 1 / REP ABC.							
dX	109.000	108.961	-0.100	0.200	-0.039		✓
S01 - 1690 - MP12 POIN 109 - MP12 - 2 - POIN 109 - MP12 - 1 / REP ABC.							
dX	109.000	109.001	-0.100	0.200	0.001		✓
S02 - 1730 POIN 1730 - 2 - POIN 1730 - 1 / REP ABC.							
dZ	56.700	56.866	-0.100	0.300	0.166		✓
S03 - DIST 1880 PLAN 1880 - POIN 1880 - 3 / REP ABC.							
dY	43.500	43.493	-0.100	0.150	-0.007		✓
S17 - 1980 - 1 PLAN A-1 - POIN 1680 - 1 - 3 / REP ABC.							
D	7.000	6.955	-0.130	0.000	-0.045		✓
S17 - 1980 - 2 PLAN A-2 - POIN 1980 - 2 - 3 / REP ABC.							
D	7.000	6.985	-0.100	0.000	-0.015		✓
S17 - 1980 - 3 PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC.							
D	7.000	6.899	-0.100	0.000	-0.101	-0.001	✗
S17 - 1980 - 4 PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.							
D	7.000	6.881	-0.110	0.000	-0.119	-0.009	✗
S17 - 1980 - 5 PLAN A-5 - POIN 1980 - 5 - 3 / REP ABC.							
D	7.000	7.024	-0.050	0.065	0.024		✓
S17 - 1980 - 6 PLAN A-6 - POIN 1980 - 6 - 3 / REP ABC.							
D	7.000	6.911	-0.100	0.000	-0.089		✓
S13 - DIST 2310 - MP1 - UP POIN 2310 - MP1 - UP - 1 - POIN 2310 - MP1 - UP - 2 / REP ABC.							
D	9.950	9.962	-0.050	0.150	0.012		✓
S13 - DIST 2310 - MP1 - DOWN POIN 2310 - MP1 - DOWN - 1 - POIN 2310 - MP1 - DOWN - 2 / REP ABC.							
D	9.950	9.961	-0.050	0.150	0.011		✓
S13 - DIST 2310 - MP4 - UP POIN 2310 - MP4 - UP - 1 - POIN 2310 - MP4 - UP - 2 / REP ABC.							
D	9.950	10.070	-0.050	0.150	0.120		✓
S13 - DIST 2310 - MP4 - DOWN POIN 2310 - MP4 - DOWN - 1 - POIN 2310 - MP4 - DOWN - 2 / REP ABC.							
D	9.950	10.073	-0.050	0.150	0.123		✓
S08 - DIST 2420 - MP1 POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.							
D	25.900	26.026	-0.100	0.150	0.126		✓
S08 - DIST 2420 - MP2 POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.							
D	25.900	25.876	-0.100	0.150	-0.024		✓
S09 - DIST 2500 - P1 - 8 POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.							
dZ	8.000	7.988	-0.100	0.100	-0.012		✓
S09 - DIST 2500 - P1 - 0 POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.							
dX	0.000	-0.068	-0.100	0.100	-0.068		✓
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P1 =[SQRT X^2+Y^2 - S09 - DIST 2500 - P1->Val]*2							
Val.	0.000	0.137	0.000	0.200	0.137		✓
S09 - DIST 2500 - P2 - 4 POIN 2500 - P3 - X - POIN 2500 - P2 - 4 / REP ABC.							
dZ	4.000	4.002	-0.100	0.100	0.002		✓
S09 - DIST 2500 - P2 - 0 POIN 2500 - P2 - 0 - POIN 2500 - P3 - Z / REP ABC.							
dX	-0.000	0.083	-0.100	0.100	0.083		✓
TRUE POSITION 0.2 X^2+Y^2 - S09 - DIST 2500 - P2 =[SQRT X^2+Y^2 - S09 - DIST 2500 - P2->Val]*2							
Val.	0.000	0.165	0.000	0.200	0.165		✓
S09 - DIST 2500 - P4 - 4 POIN 2500 - P4 - 4 - POIN 2500 - P3 - X / REP ABC.							
dZ	4.000	3.986	-0.100	0.100	-0.014		✓
S09 - DIST 2500 - P4 - 0 POIN 2500 - P4 - 0 - POIN 2500 - P3 - Z / REP ABC.							
dX	-0.000	0.072	-0.100	0.100	0.072		✓

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Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
TRUE POSITION 0.2 X <sup>2</sup> +Y <sup>2</sup> - S09 - DIST 2500 - P4 =[SQRT X <sup>2</sup> +Y <sup>2</sup> - S09 - DIST 2500 - P4->Val]*2 Val.	0.000	0.146	0.000	0.200	0.146		✓
S09 - DIST 2500 - P5 - 8 POIN 2500 - P5 - 8 - POIN 2500 - P3 - X / REP ABC. dZ	8.000	7.992	-0.100	0.100	-0.008		✓
S09 - DIST 2500 - P5 - 0 POIN 2500 - P5 - 0 - POIN 2500 - P3 - Z / REP ABC. dX	0.000	0.056	-0.100	0.100	0.056		✓
TRUE POSITION 0.2 X <sup>2</sup> +Y <sup>2</sup> - S09 - DIST 2500 - P5 =[SQRT X <sup>2</sup> +Y <sup>2</sup> - S09 - DIST 2500 - P5->Val]*2 Val.	0.000	0.114	0.000	0.200	0.114		✓
S20 - DIST 2530 - P1 - DOWN PLAN J - POIN 2530 - P1 - DOWN / REP ABC. dY	1.150	1.120	-0.100	0.100	-0.030		✓
S20 - DIST 2530 - P1 - UP PLAN J - POIN 2530 - P1 - UP / REP ABC. dY	1.150	1.107	-0.100	0.100	-0.043		✓
S20 - DIST 2530 - P2 - DOWN PLAN J - POIN 2530 - P2 - DOWN / REP ABC. dY	1.150	1.084	-0.100	0.100	-0.066		✓
S20 - DIST 2530 - P2 - UP PLAN J - POIN 2530 - P2 - UP / REP ABC. dY	1.150	1.073	-0.100	0.100	-0.077		✓
S20 - DIST 2530 - P3 - DOWN PLAN J - POIN 2530 - P3 - DOWN / REP ABC. dY	1.150	1.076	-0.100	0.100	-0.074		✓
S20 - DIST 2530 - P3 - UP PLAN J - POIN 2530 - P3 - UP / REP ABC. dY	1.150	1.065	-0.100	0.100	-0.085		✓
S20 - DIST 2530 - P4 - DOWN PLAN J - POIN 2530 - P4 - DOWN / REP ABC. dY	1.150	1.086	-0.140	0.100	-0.064		✓
S20 - DIST 2530 - P4 - UP PLAN J - POIN 2530 - P4 - UP / REP ABC. dY	1.150	1.083	-0.120	0.100	-0.067		✓
S20 - DIST 2530 - P5 - DOWN PLAN J - POIN 2530 - P5 - DOWN / REP ABC. dY	1.150	1.113	-0.100	0.100	-0.037		✓
S20 - DIST 2530 - P5 - UP PLAN J - POIN 2500 - P5 - UP / REP ABC. dY	1.150	1.104	-0.100	0.100	-0.046		✓
S14 - 2670 - 29.5 S10 - CERC 710 - B - POIN 2500 - P3 - Z / REP ABC. dX	29.500	29.590	-0.100	0.100	0.090		✓
S14 - 2670 - 20.85 S10 - CERC 710 - B - POIN K-6 / REP ABC. dZ	20.850	20.837	-0.100	0.100	-0.013		✓
TRUE POSITION 0.2 X <sup>2</sup> +Y <sup>2</sup> - S14 - 2670 - 20.8529 =[SQRT X <sup>2</sup> +Y <sup>2</sup> - S14 - 2670->Val]*2 Val.	0.000	0.183	0.000	0.200	0.183		✓
S12 - DIST 2810 - P1 POIN D.69 - POIN 2810 - P1 / REP ABC. dZ	8.000	7.963	-0.075	0.075	-0.037		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P1 =ABS([S12 - DIST 2810 - P1=>Z]-[S12 - DIST 2810 - P1->Z])*2 Val.	0.000	0.074	0.000	0.150	0.074		✓
S12 - DIST 2810 - P2 POIN D.69 - POIN 2810 - P2 / REP ABC. dZ	4.000	4.004	-0.075	0.075	0.004		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P2 =ABS([S12 - DIST 2810 - P2=>Z]-[S12 - DIST 2810 - P2->Z])*2 Val.	0.000	0.009	0.000	0.150	0.009		✓
S12 - DIST 2810 - P3 POIN D.69 - POIN 2810 - P3 / REP ABC. dZ	-0.000	0.024	-0.075	0.075	0.024		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P3 =ABS([S12 - DIST 2810 - P3=>Z]-[S12 - DIST 2810 - P3->Z])*2 Val.	0.000	0.048	0.000	0.150	0.048		✓
S12 - DIST 2810 - P4 POIN 2810 - P4 - POIN D.69 / REP ABC. dZ	4.000	3.948	-0.075	0.075	-0.052		✓



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TRUE POSITION 0.15 - S12 - DIST 2810 - P4 =ABS([S12 - DIST 2810 - P4=>Z]-[S12 - DIST 2810 - P4->Z])*2 Val.	0.000	0.104	0.000	0.150	0.104		✓
S12 - DIST 2810 - P5 POIN 2810 - P5 - POIN D.69 / REP ABC. dZ	8.000	7.937	-0.075	0.075	-0.063		✓
TRUE POSITION 0.15 - S12 - DIST 2810 - P5 =ABS([S12 - DIST 2810 - P5=>Z]-[S12 - DIST 2810 - P5->Z])*2 Val.	0.000	0.126	0.000	0.150	0.126		✓
VAL1 Dimensiuni extra							
DIST 400 - 1 POIN 400 - 1-5 - PLAN 400 - 1 / REP ABC. dZ	2.650	2.518	-0.120	0.100	-0.132	-0.012	✗
DIST 400 - 2 POIN 400 - 2-5 - PLAN 400 - 2 / REP ABC. dZ	2.650	2.579	-0.090	0.090	-0.071		✓
DIST 400 - 3 PLAN 400 - 3 - POIN 400 - 3-5 / REP ABC. dX	2.650	2.554	-0.140	0.090	-0.096		✓
DIST 400 - 4 PLAN 400 - 4 - POIN 400 - 4-5 / REP ABC. dZ	2.650	2.581	-0.120	0.090	-0.069		✓
DIST 400 - 5 PLAN 400 - 5 - POIN 400 - 5-9 / REP ABC. dZ	2.650	2.589	-0.280	0.090	-0.061		✓
DIST 400 - 6 POIN 400 - 6-5 - PLAN 400 - 6 / REP ABC. dX	2.650	2.565	-0.120	0.090	-0.085		✓
DIST 410 - 1 POIN 410 - 1 - POIN 410 - 1-2 / REP ABC. dY	2.600	2.503	-0.150	0.090	-0.097		✓
DIST 410 - 2 POIN 410 - 2 - POIN 410 - 2-2 / REP ABC. dY	2.600	2.523	-0.100	0.090	-0.077		✓
DIST 410 - 3 POIN 410 - 3-1 - POIN 410 - 3-2 / REP ABC. dY	2.600	2.618	-0.090	0.090	0.018		✓
DIST 410 - 4 POIN 410 - 4-1 - POIN 410 - 4-2 / REP ABC. dY	2.600	2.472	-0.200	0.090	-0.128		✓
DIST 410 - 5 POIN 410 - 5 - POIN 410 - 5-2 / REP ABC. dY	2.600	2.642	-0.090	0.090	0.042		✓
DIST 410 - 6 POIN 410 - 6 - POIN 1980 - 6 - 3 / REP ABC. dY	2.600	2.541	-0.090	0.090	-0.059		✓
DIST 630 - 1 POIN 630 - 1-1 - POIN 630 - 1-2 / REP ABC. dZ	55.500	55.459	-0.270	0.100	-0.041		✓
DIST 630 - 2 POIN 630 - 2-1 - POIN 630 - 2-2 / REP ABC. dZ	55.500	55.233	-0.270	0.100	-0.267		✓
DIST 780 - 1 POIN 780 - 1 - PLAN 780 - 1 / REP ABC. D	3.200	3.374	0.000	0.170	0.174	0.004	✗
DIST 780 - 2 POIN 780 - 2 - PLAN 780 - 2 / REP ABC. D	3.200	3.307	0.000	0.190	0.107		✓
DIST 780 - 3 POIN 780 - 3 - PLAN 780 - 3 / REP ABC. D	3.200	3.281	0.000	0.100	0.081		✓
DIST 780 - 4 POIN 780 - 4 - PLAN 780 - 4 / REP ABC. D	3.200	3.341	0.000	0.100	0.141	0.041	✗
DIST 1780 - MP10 POIN 1780 - MP10 - 2 - POIN 1780 - MP10 - 1 / REP ABC. dX	106.500	106.591	0.000	0.220	0.091		✓
DIST 1780 - MP11 POIN 1780 - MP11 - 2 - POIN 1780 - MP11 - 1 / REP ABC. dX	106.500	106.647	0.000	0.220	0.147		✓



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✚ DIST 1780 - MP12 POIN 1780 - MP12 - 2 - POIN 1780 - MP12 - 1 / REP ABC. dX	106.500	106.580	0.000	0.220	0.080		✓
✚ DIST 2600 - P1 - F POIN 2600 - P1 - DRTE F / REP ABC. dX	-0.000	-0.050	-0.075	0.075	-0.050		✓
⚙ 0.1 - DIST 2600 - P1 - F =ABS([DIST 2600 - P1 - F=>X]-[DIST 2600 - P1 - F->X])*2 Val.	0.000	0.100	0.000	0.150	0.100		✓
✚ DIST 2600 - P2 - F POIN 2600 - P2 - DRTE F / REP ABC. dX	-0.000	-0.050	-0.075	0.075	-0.050		✓
⚙ 0.1 - DIST 2600 - P2 - F =ABS([DIST 2600 - P2 - F=>X]-[DIST 2600 - P2 - F->X])*2 Val.	0.000	0.100	0.000	0.150	0.100		✓
✚ DIST 2600 - P3 - F POIN 2600 - P3 - DRTE F / REP ABC. dX	0.000	-0.046	-0.075	0.075	-0.046		✓
⚙ 0.1 - DIST 2600 - P3 - F =ABS([DIST 2600 - P3 - F=>X]-[DIST 2600 - P3 - F->X])*2 Val.	0.000	0.091	0.000	0.150	0.091		✓
✚ DIST 2600 - P4 - F POIN 2600 - P4 - DRTE F / REP ABC. dX	0.000	-0.043	-0.075	0.075	-0.043		✓
⚙ 0.1 - DIST 2600 - P4 - F =ABS([DIST 2600 - P4 - F=>X]-[DIST 2600 - P4 - F->X])*2 Val.	0.000	0.087	0.000	0.150	0.087		✓
✚ DIST 2600 - P5 - F POIN 2600 - P5 - DRTE F / REP ABC. dX	-0.000	-0.029	-0.075	0.075	-0.029		✓
⚙ 0.1 - DIST 2600 - P5 - F =ABS([DIST 2600 - P5 - F=>X]-[DIST 2600 - P5 - F->X])*2 Val.	0.000	0.058	0.000	0.150	0.058		✓
✚ DIST 2600 - P1 - L POIN 2600 - P1 - DRTE L / REP ABC. dX	0.000	0.015	-0.075	0.075	0.015		✓
⚙ 0.1 - DIST 2600 - P1 - L =ABS([DIST 2600 - P1 - L=>X]-[DIST 2600 - P1 - L->X])*2 Val.	0.000	0.030	0.000	0.150	0.030		✓
✚ DIST 2600 - P2 - L POIN 2600 - P2 - DRTE L / REP ABC. dX	-0.000	0.007	-0.075	0.075	0.007		✓
⚙ 0.1 - DIST 2600 - P2 - L =ABS([DIST 2600 - P2 - L=>X]-[DIST 2600 - P2 - L->X])*2 Val.	0.000	0.015	0.000	0.150	0.015		✓
✚ DIST 2600 - P3 - L POIN 2600 - P3 - DRTE L / REP ABC. dX	0.000	0.004	-0.075	0.075	0.004		✓
⚙ 0.1 - DIST 2600 - P3 - L =ABS([DIST 2600 - P3 - L=>X]-[DIST 2600 - P3 - L->X])*2 Val.	0.000	0.009	0.000	0.150	0.009		✓
✚ DIST 2600 - P4 - L POIN 2600 - P4 - DRTE L / REP ABC. dX	0.000	-0.001	-0.075	0.075	-0.001		✓
⚙ 0.1 - DIST 2600 - P4 - L =ABS([DIST 2600 - P4 - L=>X]-[DIST 2600 - P4 - L->X])*2 Val.	0.000	0.002	0.000	0.150	0.002		✓
✚ DIST 2600 - P5 - L POIN 2600 - P5 - DRTE L / REP ABC. dX	-0.000	0.006	-0.075	0.075	0.006		✓
⚙ 0.1 - DIST 2600 - P5 - L =ABS([DIST 2600 - P5 - L=>X]-[DIST 2600 - P5 - L->X])*2 Val.	0.000	0.012	0.000	0.150	0.012		✓
✚ DIST 2610 - P1 - F POIN 2610 - P1 - DRTE F / REP ABC. dX	0.000	-0.011	-0.150	0.150	-0.011		✓
⚙ 0.1 - DIST 2610 - P1 - F =ABS([DIST 2610 - P1 - F=>X]-[DIST 2610 - P1 - F->X])*2 Val.	0.000	0.021	0.000	0.300	0.021		✓
✚ DIST 2610 - P2 - F POIN 2610 - P2 - DRTE F / REP ABC. dX	0.000	-0.017	-0.150	0.150	-0.017		✓



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THOMAS REFERENCE: **HEL010/A - C2 - 01.06.2021 - 12.00**

OPERATOR: **IR**

DATE : **01/06/21 15:52:08**

SOFTWARE: **METROLOG X4V14**



Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
0.1 - DIST 2610 - P2 - F =ABS([DIST 2610 - P2 - F=>X]-[DIST 2610 - P2 - F->X])*2 Val.	0.000	0.033	0.000	0.300	0.033		✓
DIST 2610 - P3 - F POIN 2610 - P3 - DRTE F / REP ABC. dX	0.000	0.050	-0.150	0.150	0.050		✓
0.1 - DIST 2610 - P3 - F =ABS([DIST 2610 - P3 - F=>X]-[DIST 2610 - P3 - F->X])*2 Val.	0.000	0.099	0.000	0.300	0.099		✓
DIST 2610 - P4 - F POIN 2610 - P4 - DRTE F / REP ABC. dX	0.000	-0.001	-0.150	0.150	-0.001		✓
0.1 - DIST 2610 - P4 - F =ABS([DIST 2610 - P4 - F=>X]-[DIST 2610 - P4 - F->X])*2 Val.	0.000	0.002	0.000	0.300	0.002		✓
DIST 2610 - P5 - F POIN 2610 - P5 - DRTE F / REP ABC. dX	0.000	0.061	-0.150	0.150	0.061		✓
0.1 - DIST 2610 - P5 - F =ABS([DIST 2610 - P5 - F=>X]-[DIST 2610 - P5 - F->X])*2 Val.	0.000	0.123	0.000	0.300	0.123		✓
DIST 2610 - P1 - L POIN 2610 - P1 - DRTE L / REP ABC. dX	0.000	0.054	-0.150	0.150	0.054		✓
0.1 - DIST 2610 - P1 - L =ABS([DIST 2610 - P1 - L=>X]-[DIST 2610 - P1 - L->X])*2 Val.	0.000	0.109	0.000	0.300	0.109		✓
DIST 2610 - P2 - L POIN 2610 - P2 - DRTE L / REP ABC. dX	0.000	0.041	-0.150	0.150	0.041		✓
0.1 - DIST 2610 - P2 - L =ABS([DIST 2610 - P2 - L=>X]-[DIST 2610 - P2 - L->X])*2 Val.	0.000	0.082	0.000	0.300	0.082		✓
DIST 2610 - P3 - L POIN 2610 - P3 - DRTE L / REP ABC. dX	-0.000	0.100	-0.150	0.150	0.100		✓
0.1 - DIST 2610 - P3 - L =ABS([DIST 2610 - P3 - L=>X]-[DIST 2610 - P3 - L->X])*2 Val.	0.000	0.199	0.000	0.300	0.199		✓
DIST 2610 - P4 - L POIN 2610 - P4 - DRTE L / REP ABC. dX	-0.000	0.041	-0.150	0.150	0.041		✓
0.1 - DIST 2610 - P4 - L =ABS([DIST 2610 - P4 - L=>X]-[DIST 2610 - P4 - L->X])*2 Val.	0.000	0.083	0.000	0.300	0.083		✓
DIST 2610 - P5 - L POIN 2610 - P5 - DRTE L / REP ABC. dX	0.000	0.096	-0.150	0.150	0.096		✓
0.1 - DIST 2610 - P5 - L =ABS([DIST 2610 - P5 - L=>X]-[DIST 2610 - P5 - L->X])*2 Val.	0.000	0.192	0.000	0.300	0.192		✓
PERP 2620 - P1 DRTE 2620 - P1(G)/PLAN H - C-Zone Val.	0.000	0.028		0.200	0.028		✓
PERP 2620 - P2 DRTE 2620 - P2(G)/PLAN H - C-Zone Val.	0.000	0.022		0.200	0.022		✓
PERP 2620 - P3 DRTE 2620 - P3(G)/PLAN H - C-Zone Val.	0.000	0.083		0.200	0.083		✓
PERP 2620 - P4 DRTE 2620 - P4(G)/PLAN H - C-Zone Val.	0.000	0.031		0.200	0.031		✓
PERP 2620 - P5 DRTE 2620 - P5(G)/PLAN H - C-Zone Val.	0.000	0.078		0.200	0.078		✓
DIST 2630 DRTE L-1 - DRTE L-2 / REP ABC. D	7.180	7.100	-0.050	0.050	-0.080	-0.030	✗
DIST 2640 DRTE 2640 - 2 - DRTE 2640 - 1 / REP ABC. D	7.150	7.130	-0.050	0.050	-0.020		✓



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✚ DIST 2650 ■ DRTE F - 1 - DRTE F-2 / REP ABC.							
D	6.950	6.938	-0.050	0.050	-0.012		✓
✚ DIST 2660 - F ■ DRTE 2640 - MID - DRTE F / REP ABC.							
D	0.000	0.029	-0.050	0.050	0.029		✓
⚙ SYMMETRY 0.1 - DIST 2660 ■ =ABS([DIST 2660 - F=>Dist1]-[DIST 2660 - F->Dist1])*2							
Val.	0.000	0.058	0.000	0.100	0.058		✓
✚ DIST 2660 - L ■ DRTE 2640 - MID - DRTE L / REP ABC.							
D	0.000	0.020	-0.050	0.050	0.020		✓
⚙ SYMMETRY 0.1 - DIST 2660 - L ■ =ABS([DIST 2660 - L=>Dist1]-[DIST 2660 - L->Dist1])*2							
Val.	0.000	0.039	0.000	0.100	0.039		✓
✚ DIST 2710 - MP6 ■ POIN 2710 - MP6 - 1 - POIN 2710 - MP6 - 2 / REP ABC.							
dZ	54.200	54.177	-0.050	0.200	-0.023		✓
✚ DIST 2710 - MP7 ■ POIN 2710 - MP7 - 1 - POIN 2710 - MP7 - 2 / REP ABC.							
dZ	54.200	54.384	-0.100	0.550	0.184		✓
✚ DIST 2710 - MP8 ■ POIN 2710 - MP8 - 1 - POIN 2710 - MP8 - 2 / REP ABC.							
dZ	54.200	54.256	-0.020	0.200	0.056		✓
✚ DIST 2750 ■ POIN 2780 - 3 - POIN D.69 / REP ABC.							
dZ	-0.000	-0.023	-0.050	0.050	-0.023		✓
⚙ SYMMETRY 0.1 - DIST 2750 ■ =ABS([DIST 2750=>Z]-[DIST 2750->Z])*2							
Val.	0.000	0.046	0.000	0.100	0.046		✓
✚ DIST 2750 - K ■ POIN 2780 - 3 - POIN 2500 - P3 - X / REP ABC.							
dZ	-0.000	0.010	-0.050	0.050	0.010		✓
⚙ SYMMETRY 0.1 - DIST 2750 - K ■ =ABS([DIST 2750 - K=>Z]-[DIST 2750 - K->Z])*2							
Val.	0.000	0.021	0.000	0.100	0.021		✓
✚ DIST 2760 ■ POIN 2760 - POIN D.69 / REP ABC.							
dZ	-0.000	-0.015	-0.050	0.050	-0.015		✓
⚙ SYMMETRY 0.1 - DIST 2760 ■ =ABS([DIST 2760=>Z]-[DIST 2760->Z])*2							
Val.	0.000	0.031	0.000	0.100	0.031		✓
✚ DIST 2760 - K ■ POIN 2760 - POIN 2500 - P3 - X / REP ABC.							
dZ	-0.000	0.018	-0.050	0.050	0.018		✓
⚙ SYMMETRY 0.1 - DIST 2760 - K ■ =ABS([DIST 2760 - K=>Z]-[DIST 2760 - K->Z])*2							
Val.	0.000	0.036	0.000	0.100	0.036		✓
✚ DIST 2770 ■ POIN 2770 - 1 - POIN 2770 - 2 / REP ABC.							
D	23.190	23.284	-0.050	0.050	0.094	0.044	✗
✚ DIST 2780 ■ POIN 2780 - 1 - POIN 2780 - 2 / REP ABC.							
D	23.150	23.185	-0.050	0.050	0.035		✓
✚ DIST 2790 ■ POIN D-2 - POIN D-1 / REP ABC.							
dZ	21.600	21.570	-0.050	0.050	-0.030		✓
✚ DIST 2800 ■ POIN 2800 - 1 - POIN 2800 - 2 / REP ABC.							
D	23.850	24.038	-0.150	0.150	0.188	0.038	✗
✚ DIST 2820 - P1 ■ POIN D.69 - POIN 2820 - P1 / REP ABC.							
dZ	8.000	7.937	-0.150	0.150	-0.063		✓
⚙ TRUE POSITION 0.3 - DIST 2820 - P1 ■ =ABS([DIST 2820 - P1=>Z]-[DIST 2820 - P1->Z])*2							
Val.	0.000	0.125	0.000	0.300	0.125		✓
✚ DIST 2820 - P2 ■ POIN D.69 - POIN 2820 - P2 / REP ABC.							
dZ	4.000	3.971	-0.150	0.150	-0.029		✓
⚙ TRUE POSITION 0.3 - DIST 2820 - P2 ■ =ABS([DIST 2820 - P2=>Z]-[DIST 2820 - P2->Z])*2							
Val.	0.000	0.059	0.000	0.300	0.059		✓



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DIST 2820 - P3							
POIN D.69 - POIN 2820 - P3 / REP ABC.							
dZ	0.000	0.013	-0.150	0.150	0.013	<div><div></div></div>	✓
TRUE POSITION 0.3 - DIST 2820 - P3							
=ABS([DIST 2820 - P3=>Z]-[DIST 2820 - P3->Z])*2							
Val.	0.000	0.026	0.000	0.300	0.026	<div><div></div></div>	✓
DIST 2820 - P4							
POIN 2820 - P4 - POIN D.69 / REP ABC.							
dZ	4.000	3.962	-0.150	0.150	-0.038	<div><div></div></div>	✓
TRUE POSITION 0.3 - DIST 2820 - P4							
=ABS([DIST 2820 - P4=>Z]-[DIST 2820 - P4->Z])*2							
Val.	0.000	0.075	0.000	0.300	0.075	<div><div></div></div>	✓
DIST 2820 - P5							
POIN 2820 - P5 - POIN D.69 / REP ABC.							
dZ	8.000	7.938	-0.150	0.150	-0.062	<div><div></div></div>	✓
TRUE POSITION 0.3 - DIST 2820 - P5							
=ABS([DIST 2820 - P5=>Z]-[DIST 2820 - P5->Z])*2							
Val.	0.000	0.123	0.000	0.300	0.123	<div><div></div></div>	✓