

SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 01.06.2021 - 12.00

OPERATOR: IR

DATE: 01/06/21 15:52:08 SOFTWARE: METROLOG X4V14



RESULTS

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
⊙ S10 - CERC 710 -	C						
Inters. PLAN A							
Diam.		3.907	-0.100	0.000	-0.093		✓
● S10 - CERC 710 -							
Inters. PLAN A		0.057	0.400	0.000	0.040		
Diam. 7 S07 - PLTE 450	4.000	3.957	-0.100	0.000	-0.043		✓
PLAN A C							
Val.	0.000	0.215		0.250	0.215		~
✓ S04 - PLTE 455	0.000	0.2.10		0.200	0.2.0		
PLAN J C							
Val.	0.000	0.136		0.200	0.136		✓
് S15 - DIST 470 - 1							
_	OIN 470 - 11.25 / REP		1	1	1		
dZ			-0.075	0.075	0.027		✓
r =).15 - S15 - DIST 470 -		. 71*0				
Val.		S15 - DIST 470 - 11.25-: 0.053	0.000	0.150	0.053		~
S15 - DIST 470 - 3		0.033	0.000	0.130	0.033		V
	OIN 470 - 33.65 / REP	ABC.					
dZ			-0.130	0.130	-0.025		✓
TRUE POSITION O).15 - S15 - DIST 470 -						
		S15 - DIST 470 - 33.65-					
Val.	0.000	0.050	0.000	0.260	0.050		✓
S18 - DIST 550	1.550 / DED ADO						
PLAN A - POIN	N 550 / REP ABC. 6.100	6 101	0.100	0.100	0.004		
S06 - DIST 1280	6.100	6.181	-0.100	0.100	0.081		✓
l' '	- POIN 1280 - 2 / REP	ABC.					
D		12.641	-0.100	0.100	-0.059		~
് S16 - DIST 1300 -		12.011	0.100	31700	0.000		·
PLAN H - POII	N 1300 - LEFT / REP A	ABC.					
dY	12.015	12.061	-0.050	0.050	0.046		✓
് S16 - DIST 1300 -							
_	N 1300 - RIGHT / REP		0.050	0.050	0.000		
dY		12.035	-0.050	0.050	0.020		✓
S19 - DIST 1400 -	P6 - DOWN 1400 - P6 - DOWN / I	REP ARC					
dY		0.833	-0.100	0.110	-0.017		~
് S19 - DIST 1400 -		0.000	0.100	00	0.011		•
	N 1400 - P6 - UP / REP	ABC.					
dY	0.850	0.788	-0.100	0.110	-0.062		✓
r∸ S19 - DIST 1400 -	P7 - DOWN	1					
-	N 1400 - P7 - DOWN / I	-					
dY		0.805	-0.100	0.110	-0.045		✓
S19 - DIST 1400 -		ADC					
dY	N 1400 - P7 - UP / REP 0.850	0.827	-0.100	0.110	-0.023		
× S05 - DIST 1410 -		0.027	-0.100	0.110	-0.023	L	✓
	3 - X - POIN 1410 - 1 -	12.8 / REP ABC.					
dZ			-0.150	0.150	0.031		✓
× S05 - DIST 1410 -	P6 - 3.4						
POIN 2500 - P	3 - Z - POIN 1410 - 1 -						
dX			-0.150	0.150	-0.168	-0.018	×
	0.3 X^2+Y^2 - S05 - DIS						
-	/^2 - S05 - DIST 1410 -		0.000	0.000	0.040	0.040	
Val. → S05 - DIST 1410 -		0.342	0.000	0.300	0.342	0.042	X
	- 9.6 - POIN 2500 - P3	3 - X / REP ABC					
dZ			-0.150	0.150	0.009		✓
S05 - DIST 1410 -							
POIN 2500 - P	3 - Z - POIN 1410 - 2 -	3.4 / REP ABC.					
dX			-0.150	0.150	-0.164	-0.014	×
r =	0.3 X^2+Y^2 - S05 - DIS					·	
_	/^2 - S05 - DIST 1410 -			2.25-1	0.05-1		
Val.		0.329	0.000	0.300	0.329	0.029	×
S01 - 1690 - MP10	P10 - 2 - POIN 109 - MI	D10 - 1 / DED ADC					
dX			-0.100	0.200	-0.013		~
ux.	100.000	100.007	0.100	0.200	0.010		



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Actual

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State

[≚] ₁ S01 - 1690 - MP11							
POIN 109 - MP11 -	2 - POIN 109 - MP11	- 1 / REP ABC.					
dX	109.000	108.961	-0.100	0.200	-0.039		✓
S01 - 1690 - MP12	<u> </u>	•		•	<u> </u>		
POIN 109 - MP12 -							
	109.000	109.001	-0.100	0.200	0.001		~
1 S02 - 1730							
POIN 1730 - 2 - PC							
dZ	56.700	56.866	-0.100	0.300	0.166		✓
S03 - DIST 1880	1000 0 / DED 100						
PLAN 1880 - POIN			0.100	0.150	0.007		
dY ↑ S17 - 1980 - 1	43.500	43.493	-0.100	0.150	-0.007		✓
PLAN A-1 - POIN 1	680 - 1 - 3 / REP ARC	•					
D	7.000	6.955	-0.130	0.000	-0.045		~
1 S17 - 1980 - 2	7.000	0.000	0.100	0.000	0.0.0		•
PLAN A-2 - POIN 1	980 - 2 - 3 / REP ABO	S .					
	7.000	6.985	-0.100	0.000	-0.015		~
↑ S17 - 1980 - 3		I		l .			·
PLAN A-3 - POIN 1	980 - 3 - 3 / REP ABO	Э.					
D	7.000	6.899	-0.100	0.000	-0.101	-0.001	×
↑ S17 - 1980 - 4				•			
PLAN A-4 - POIN 1							
D	7.000	6.881	-0.110	0.000	-0.119	-0.009	×
S17 - 1980 - 5	000 5 0/555	2					
PLAN A-5 - POIN 1			0.050	0.005	0.004		
D D	7.000	7.024	-0.050	0.065	0.024		✓
[→] S17 - 1980 - 6 ■ PLAN A-6 - POIN 1	000 6 2/050 400	•					
D PLAN A-6 - POIN 1	7.000	5. 6.911	-0.100	0.000	-0.089		
↑ S13 - DIST 2310 - MP1		0.311	-0.100	0.000	-0.009		✓
		- MP1 - UP - 2 / REP ABC	<u>:</u>				
D D		9.962	-0.050	0.150	0.012		~
1 S13 - DIST 2310 - MP1		0.002	0.000	0.100	0.0.2		•
		310 - MP1 - DOWN - 2 / F	REP ABC.				
D	9.950	9.961	-0.050	0.150	0.011		~
🔄 S13 - DIST 2310 - MP4	- UP						
[≚] 1 S13 - DIST 2310 - MP4 ■ POIN 2310 - MP4 -		- MP4 - UP - 2 / REP ABC).				
POIN 2310 - MP4 -	UP - 1 - POIN 2310 - 9.950	- MP4 - UP - 2 / REP ABC 10.070	-0.050	0.150	0.120		~
POIN 2310 - MP4 - D S13 - DIST 2310 - MP4	UP - 1 - POIN 2310 - 9.950 - DOWN	10.070	-0.050				
POIN 2310 - MP4 - D S13 - DIST 2310 - MP4 - POIN 2310 - MP4 -	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23	10.070 310 - MP4 - DOWN - 2 / F	-0.050	0.150	0.120		~
POIN 2310 - MP4 - D 7 S13 - DIST 2310 - MP4 - POIN 2310 - MP4 - D	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 9.950	10.070	-0.050				
POIN 2310 - MP4 - D T S13 - DIST 2310 - MP4 POIN 2310 - MP4 - D T S08 - DIST 2420 - MP1	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 9.950	10.070 310 - MP4 - DOWN - 2 / F 10.073	-0.050	0.150	0.120		~
POIN 2310 - MP4 - D 7 S13 - DIST 2310 - MP4 - POIN 2310 - MP4 - D 7 S08 - DIST 2420 - MP1 - POIN 2420 - MP1 -	UP - 1 - POIN 2310 - 9.950 - - DOWN DOWN - 1 - POIN 23 9.950 - 1 - POIN 2420 - MP1	10.070 B10 - MP4 - DOWN - 2 / F 10.073 I - 2 / REP ABC.	-0.050 REP ABC0.050	0.150	0.120		~
POIN 2310 - MP4 - D D T S13 - DIST 2310 - MP4 - D T S08 - DIST 2420 - MP1 - D D D D D D D D D D	UP - 1 - POIN 2310 - 9.950 - - DOWN DOWN - 1 - POIN 23 9.950 - 1 - POIN 2420 - MP1 25.900 -	10.070 310 - MP4 - DOWN - 2 / F 10.073	-0.050	0.150	0.120		~
POIN 2310 - MP4 - D T S13 - DIST 2310 - MP4 - D T S08 - DIST 2420 - MP1 - D T S08 - DIST 2420 - MP1 - D T S08 - DIST 2420 - MP2	UP - 1 - POIN 2310 - 9.950 - - DOWN DOWN - 1 - POIN 23 9.950 - 1 - POIN 2420 - MP1 25.900 -	10.070 310 - MP4 - DOWN - 2 / F 10.073 1 - 2 / REP ABC. 26.026	-0.050 REP ABC0.050	0.150	0.120		~
POIN 2310 - MP4 - D T S13 - DIST 2310 - MP4 - D T S08 - DIST 2420 - MP1 - D T S08 - DIST 2420 - MP1 - D T S08 - DIST 2420 - MP2 - D T S08 - DIST 2420 - MP2 - D T S08 - DIST 2420 - MP2 - D T S08 - DIST 2420 - MP2 - D T S08 - DIST 2420 - MP2 - D T S08 - DIST 2420 - MP2 - D T S08 - DIST 2420 - MP2 - D T S08 - DIST 2420 - MP2 - D T S08 - DIST 2420 - MP2 - D T S08 - DIST 2420 - MP2 - D T S08 - DIST 2420 - MP2 - D T S08 -	UP - 1 - POIN 2310 - 9.950 - - DOWN DOWN - 1 - POIN 23 9.950 - 1 - POIN 2420 - MP1 25.900 - 1 - POIN 2420 - MP2	10.070 310 - MP4 - DOWN - 2 / F 10.073 1 - 2 / REP ABC. 26.026 2 - 2 / REP ABC.	-0.050 REP ABC. -0.050 -0.100	0.150 0.150 0.150	0.120 0.123 0.126		
POIN 2310 - MP4 - D 7 S13 - DIST 2310 - MP4 - D 7 S08 - DIST 2420 - MP1 - D 7 S08 - DIST 2420 - MP1 - D 7 S08 - DIST 2420 - MP2 - D 8 POIN 2420 - MP2 - D	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900	10.070 310 - MP4 - DOWN - 2 / F 10.073 1 - 2 / REP ABC. 26.026	-0.050 REP ABC0.050	0.150	0.120		~
POIN 2310 - MP4 - D S13 - DIST 2310 - MP4 - D POIN 2310 - MP4 - D S08 - DIST 2420 - MP1 - D S08 - DIST 2420 - MP1 - D S08 - DIST 2420 - MP2 - D POIN 2420 - MP2 - D S09 - DIST 2500 - P1 -	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900	10.070 10.073 1 - 2 / REP ABC. 26.026 2 - 2 / REP ABC. 25.876	-0.050 REP ABC. -0.050 -0.100	0.150 0.150 0.150	0.120 0.123 0.126		
POIN 2310 - MP4 - D This state of the stat	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8	10.070 10.073 1-2/REP ABC. 26.026 2-2/REP ABC. 25.876 8/REP ABC.	-0.050 REP ABC.	0.150 0.150 0.150 0.150	0.120 0.123 0.126 -0.024		
POIN 2310 - MP4 - D This state of the stat	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000	10.070 10.073 1 - 2 / REP ABC. 26.026 2 - 2 / REP ABC. 25.876	-0.050 REP ABC. -0.050 -0.100	0.150 0.150 0.150	0.120 0.123 0.126		
POIN 2310 - MP4 - D This state of the stat	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0	10.070 B10 - MP4 - DOWN - 2 / F 10.073 1 - 2 / REP ABC. 26.026 2 - 2 / REP ABC. 25.876 3 / REP ABC. 7.988	-0.050 REP ABC.	0.150 0.150 0.150 0.150	0.120 0.123 0.126 -0.024		
POIN 2310 - MP4 - D The state of the state	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0	10.070 B10 - MP4 - DOWN - 2 / F 10.073 1 - 2 / REP ABC. 26.026 2 - 2 / REP ABC. 25.876 3 / REP ABC. 7.988	-0.050 REP ABC.	0.150 0.150 0.150 0.150	0.120 0.123 0.126 -0.024		
POIN 2310 - MP4 - D T S13 - DIST 2310 - MP4 - D T S08 - DIST 2420 - MP1 - D T S08 - DIST 2420 - MP1 - D T S08 - DIST 2420 - MP2 - D T S09 - DIST 2500 - P1 - D T S09 - D	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 - 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000	10.070 310 - MP4 - DOWN - 2 / F	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100	0.120 0.123 0.126 -0.024 -0.012		
POIN 2310 - MP4 - D S13 - DIST 2310 - MP4 - D S13 - DIST 2310 - MP4 - D S08 - DIST 2420 - MP1 - D S08 - DIST 2420 - MP2 - D S09 - DIST 2500 - P1 - D S09 - D	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 - 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 "2+Y^2 - S09 - DIST 2	10.070 310 - MP4 - DOWN - 2 / F	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100	0.120 0.123 0.126 -0.024 -0.012		
POIN 2310 - MP4 - D This state of the stat	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23	10.070 310 - MP4 - DOWN - 2 / F	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100	0.120 0.123 0.126 -0.024 -0.012		
POIN 2310 - MP4 - D This state of the sta	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 V2+Y^2 - S09 - DIST 2509 - P1 0.000	10.070 10.070 10.073 1 - 2 / REP ABC.	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100	0.120 0.123 0.126 -0.024 -0.012 -0.068		
POIN 2310 - MP4 - D 3 S13 - DIST 2310 - MP4 - D 3 S13 - DIST 2310 - MP4 - D 3 S08 - DIST 2420 - MP1 - D 3 S08 - DIST 2420 - MP1 - D 3 S08 - DIST 2420 - MP2 - D 4 POIN 2420 - MP2 - D 5 POIN 2420 - P1 - D 6 POIN 2500 - P1 - D 7 S09 - DIST 2500 - P1 - D 8 POIN 2500 - P3 - Z 4 X 5 TRUE POSITION 0.2 X 6 = [SQRT X*2+Y*2 - Val. 7 S09 - DIST 2500 - P2 - D 8 POIN 2500 - P3 - X 9 S09 - DIST 2500 - P3 - X 9 S09 - DIST 2500 - P3 - X 9 S09 - DIST 2500 - P3 - X	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23	10.070 810 - MP4 - DOWN - 2 / F	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100 0.100 0.200	0.120 0.123 0.126 -0.024 -0.012 -0.068		
POIN 2310 - MP4 - D S13 - DIST 2310 - MP4 - D S13 - DIST 2310 - MP4 - D POIN 2310 - MP1 - D S08 - DIST 2420 - MP1 - D S08 - DIST 2420 - MP2 - D POIN 2420 - MP2 - D POIN 2420 - MP2 - D S09 - DIST 2500 - P1 - D POIN 2500 - P3 - Z X TRUE POSITION 0.2 X SQRT X'2+Y'2 - Val. S09 - DIST 2500 - P2 - D POIN 2500 - P3 - X SQRT X'2+YO - Val. S09 - DIST 2500 - P3 - X S09 - DIST 2500 - P3 - X SQRT X'2+YO - Val. S09 - DIST 2500 - P3 - X	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 12+Y^2 - S09 - DIST 2 S09 - DIST 2500 - P1 0.000 4 - POIN 2500 - P2 - 4 4.000	10.070 10.070 10.073 1 - 2 / REP ABC.	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100	0.120 0.123 0.126 -0.024 -0.012 -0.068		
POIN 2310 - MP4 - D S13 - DIST 2310 - MP4 - POIN 2310 - MP4 - POIN 2310 - MP4 - D S08 - DIST 2420 - MP1 - POIN 2420 - MP2 - POIN 2420 - MP2 - D S09 - DIST 2500 - P1 - POIN 2500 - P3 - Z dX TRUE POSITION 0.2 X SIGNATURE PO	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 - 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 12+Y^2 - S09 - DIST 2500 - P1 0.000 4 - POIN 2500 - P2 - 24 4.000 0	10.070 310 - MP4 - DOWN - 2 / F	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100 0.100 0.200	0.120 0.123 0.126 -0.024 -0.012 -0.068		
POIN 2310 - MP4 - D 3 S13 - DIST 2310 - MP4 - D 3 S13 - DIST 2310 - MP4 - D 3 S08 - DIST 2420 - MP1 - D 3 S08 - DIST 2420 - MP2 - D 3 S08 - DIST 2420 - MP2 - D 4 POIN 2420 - MP2 - D 5 S09 - DIST 2500 - P1 - D 6 POIN 2500 - P3 - Z 6 X 5 TRUE POSITION 0.2 X 6 = [SQRT X^2+Y^2 - Val. 7 S09 - DIST 2500 - P2 - D 6 POIN 2500 - P3 - X 6 TRUE POSITION 0.2 X 7 S09 - DIST 2500 - P2 - D 8 POIN 2500 - P2 - D 9 POIN 2500 - P2 - D 9 POIN 2500 - P2 - D	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 - 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 12+Y^2 - S09 - DIST 2509 - P1 0.000 4 - POIN 2500 - P2 - 4.000 0 - POIN 2500 - P3 - Z	10.070 310 - MP4 - DOWN - 2 / F 10.073 1 - 2 / REP ABC. 26.026 2 - 2 / REP ABC. 25.876 3 / REP ABC. 7.988 0 / REP ABC0.068 2500 - P1 1->Val]*2 0.137 4 / REP ABC. 4.002	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100 0.200	0.120 0.123 0.126 -0.024 -0.012 -0.068 0.137		
POIN 2310 - MP4 - D The state of the state	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 12+Y^2 - S09 - DIST 2509 - P1 0.000 4 - POIN 2500 - P2 - 4 4.000 0 - POIN 2500 - P3 - Z -0.000	10.070 310 - MP4 - DOWN - 2 / F 10.073 1 - 2 / REP ABC. 26.026 2 - 2 / REP ABC. 25.876 3 / REP ABC. 7.988 0 / REP ABC0.068 2500 - P1 1->Val]*2 0.137 4 / REP ABC. 4.002	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100 0.100 0.200	0.120 0.123 0.126 -0.024 -0.012 -0.068		
POIN 2310 - MP4 - D This state of the sta	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 12+Y^2 - S09 - DIST 2 509 - DIST 2500 - P1 0.000 4 - POIN 2500 - P2 - 2 4.000 0 - POIN 2500 - P3 - Z -0.000 12+Y^2 - S09 - DIST 2	10.070 310 - MP4 - DOWN - 2 / F 10.073 1 - 2 / REP ABC. 26.026 2 - 2 / REP ABC. 25.876 3 / REP ABC0.068 2500 - P1 1->Val]*2 0.137 4 / REP ABC. 4.002 2 / REP ABC. 0.083	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100 0.200	0.120 0.123 0.126 -0.024 -0.012 -0.068 0.137		
POIN 2310 - MP4 - D This state of the sta	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 - 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 1 - POIN 2500 - P1 - 0 0.000 1 - POIN 2500 - P1 - 0 0.000 1 - POIN 2500 - P2 - 2.000 1 - POIN 2500 - P2 - 2.000 1 - POIN 2500 - P3 - Z - 0.000 1 - POIN 2500 - P3 - Z - 0.000 1 - POIN 2500 - P3 - Z - 0.000 1 - POIN 2500 - P3 - Z - 0.000 1 - POIN 2500 - P3 - Z - 0.000 1 - POIN 2500 - P3 - Z - 0.000 1 - POIN 2500 - P3 - Z - 0.000 1 - POIN 2500 - P3 - Z - 0.000 1 - POIN 2500 - P3 - Z - 0.000 1 - POIN 2500 - P3 - Z - 0.000 1 - POIN 2500 - P3 - Z - 0.000 1 - POIN 2500 - P3 - Z - 0.000 1 - POIN 2500 - P3 - Z - 0.000	10.070 310 - MP4 - DOWN - 2 / F 10.073 1 - 2 / REP ABC. 26.026 2 - 2 / REP ABC. 25.876 3 / REP ABC0.068 2500 - P1 1->Val]*2 0.137 4 / REP ABC. 4.002 2 / REP ABC. 0.083 2500 - P2 2->Val]*2	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100 0.100 0.100 0.100 0.100	0.120 0.123 0.126 -0.024 -0.012 -0.068 0.137 0.002 0.083		
POIN 2310 - MP4 - D S13 - DIST 2310 - MP4 - D S13 - DIST 2310 - MP4 - D S13 - DIST 2420 - MP4 - D S14 S08 - DIST 2420 - MP1 - D S15 S08 - DIST 2420 - MP2 - D S16 S08 - DIST 2500 - P1 - D S17 S09 - DIST 2500 - P1 - D S18 S09 - DIST 2500 - P1 - D S19 S09 - DIST 2500 - P1 - D S19 S09 - DIST 2500 - P2 - D S19 S09 - DIST	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 - 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 12+Y^2 - S09 - DIST 2 S09 - DIST 2500 - P2 - 4.000 0 - POIN 2500 - P3 - Z - 6.000 12+Y^2 - S09 - DIST 2 S09 - DIST	10.070 310 - MP4 - DOWN - 2 / F 10.073 1 - 2 / REP ABC. 26.026 2 - 2 / REP ABC. 25.876 3 / REP ABC0.068 2500 - P1 1->Val]*2 0.137 4 / REP ABC. 4.002 2 / REP ABC. 0.083	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100 0.200	0.120 0.123 0.126 -0.024 -0.012 -0.068 0.137		
POIN 2310 - MP4 - D S13 - DIST 2310 - MP4 - D POIN 2310 - MP4 - D S08 - DIST 2420 - MP1 - D S08 - DIST 2420 - MP1 - D S08 - DIST 2420 - MP2 - D S09 - DIST 2500 - P1 - D S09 - DIST 2500 - P1 - D POIN 2500 - P3 - Z dX TRUE POSITION 0.2 X S09 - DIST 2500 - P2 - D POIN 2500 - P3 - X TS09 - DIST 2500 - P2 - D POIN 2500 - P3 - X TS09 - DIST 2500 - P2 - D POIN 2500 - P3 - X TS09 - DIST 2500 - P2 - D POIN 2500 - P3 - X TS09 - DIST 2500 - P2 - D POIN 2500 - P3 - X TS09 - DIST 2500 - P2 - D TS09 - DIST 2500 - P2 - D TS09 - DIST 2500 - P3 - X TS09 - DIST 2500 - P4 - D TS09 - D T	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 12+Y^2 - S09 - DIST 2500 - P1 - 0.000 4 - POIN 2500 - P2 - 2 4.000 0 - POIN 2500 - P3 - Z 0.000 12+Y^2 - S09 - DIST 2509 - P3 - Z 0.000 12+Y^2 - S09 - DIST 2500 - P2 0.000 12+Y^2 - S09 - DIST 2500 - P2 0.000	10.070 10.070 10.073 1 - 2 / REP ABC.	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100 0.100 0.100 0.100 0.100	0.120 0.123 0.126 -0.024 -0.012 -0.068 0.137 0.002 0.083		
POIN 2310 - MP4 - D S13 - DIST 2310 - MP4 - D S13 - DIST 2310 - MP4 - D S13 - DIST 2310 - MP4 - D S08 - DIST 2420 - MP1 - D S08 - DIST 2420 - MP2 - D S09 - DIST 2500 - P1 - D S09 - DIST 2500 - P2 - D S09 - DIST 2500 - P4 - D S09 - D S09 - D D S09 - D D S09 - D D D S09 - D D S09 - D D D S09 - D D	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 - 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 12+Y^2 - S09 - DIST 2500 - P1 0.000 4 - POIN 2500 - P2 - 4 4.000 0 - POIN 2500 - P3 - Z 0.000 12+Y^2 - S09 - DIST 2500 - P3 - Z 0.000 12+Y^2 - S09 - DIST 2500 - P3 - Z 0.000 14 - POIN 2500 - P3 - Z 0.000 15 - P0 - DIST 2500 - P3 - Z 0.000 16 - POIN 2500 - P3 - Z 0.000 17 - POIN 2500 - P3 - Z 0.000 18 - POIN 2500 - P3 - Z 0.000	10.070 310 - MP4 - DOWN - 2 / F 10.073 1 - 2 / REP ABC. 26.026 2 - 2 / REP ABC. 25.876 3 / REP ABC0.068 2500 - P1 1->Val]*2 0.137 4 / REP ABC. 4.002 2 / REP ABC. 0.083 2 / REP ABC. 0.083 2 / REP ABC. 0.085 X / REP ABC.	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100 0.100 0.100 0.100 0.200 0.100 0.200	0.120 0.123 0.126 -0.024 -0.012 -0.068 0.137 0.002 0.083		
POIN 2310 - MP4 - D S13 - DIST 2310 - MP4 - D S13 - DIST 2310 - MP4 - D S08 - DIST 2420 - MP1 - D S08 - DIST 2420 - MP2 - D S09 - DIST 2500 - P1 - D S09 - DIST 2500 - P1 - D POIN 2500 - P3 - Z X TRUE POSITION 0.2 X S09 - DIST 2500 - P2 - D POIN 2500 - P3 - X X TRUE POSITION 0.2 X S09 - DIST 2500 - P2 - D R0 S09 - DIST 2500 - P2 - D R0 S09 - DIST 2500 - P2 - D R0 S09 - DIST 2500 - P2 - D R0 S09 - DIST 2500 - P2 - D R0 S09 - DIST 2500 - P2 - D R0 S09 - DIST 2500 - P4 - D S09 - D	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 - 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 12+Y^2 - S09 - DIST 2500 - P1 0.000 4 - POIN 2500 - P2 - 2 - 2 0.000 12+Y^2 - S09 - DIST 2500 - P3 - 2 0.000 12+Y^2 - S09 - DIST 2500 - P3 - 2 0.000 12+Y^2 - S09 - DIST 2500 - P3 - 2 0.000 12+Y^2 - S09 - DIST 2500 - P3 - 2 0.000 14 - POIN 2500 - P3 - 2 0.000 15 - POIN 2500 - P3 - 2 0.000 16 - POIN 2500 - P3 - 2 0.000 17 - POIN 2500 - P3 - 2 0.000 18 - POIN 2500 - P3 - 2 0.000 19 - POIN 2500 - P3 - 2 0.000	10.070 10.070 10.073 1 - 2 / REP ABC.	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100 0.100 0.100 0.100 0.100	0.120 0.123 0.126 -0.024 -0.012 -0.068 0.137 0.002 0.083		
POIN 2310 - MP4 - D S13 - DIST 2310 - MP4 - POIN 2310 - MP4 - POIN 2310 - MP4 - POIN 2310 - MP4 - D S08 - DIST 2420 - MP1 - POIN 2420 - MP2 - POIN 2420 - MP2 - D S09 - DIST 2500 - P1 - POIN 2500 - P3 - X dZ S09 - DIST 2500 - P1 - POIN 2500 - P3 - X dZ S09 - DIST 2500 - P2 - POIN 2500 - P4 - S09 - DIST 2500 - P4 - S09 - DIST 2500 - P4 - POIN 2500 - P4 - S09 - DIST 2500 - P4 -	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 - 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 12+Y^2 - S09 - DIST 2509 - P1 0.000 4 - POIN 2500 - P2 - 4.000 0 - POIN 2500 - P3 - Z - 0.000 12+Y^2 - S09 - DIST 2500 - P3 - Z - 0.000 14 - POIN 2500 - P3 - Z - 0.000 15 - POIN 2500 - P3 - Z - 0.000 16 - POIN 2500 - P3 - Z - 0.000 17 - POIN 2500 - P3 - Z - 0.000 18 - POIN 2500 - P3 - Z - 0.000 19 - POIN 2500 - P3 - Z - 0.000 10 - POIN 2500 - P3 - Z - 0.000 11 - POIN 2500 - P3 - Z - 0.000 12 - POIN 2500 - P3 - Z - 0.000 14 - POIN 2500 - P3 - Z - 0.000	10.070 310 - MP4 - DOWN - 2 / F 10.073 1 - 2 / REP ABC. 26.026 2 - 2 / REP ABC. 25.876 3 / REP ABC. 7.988 0 / REP ABC0.068 2500 - P1 1->Val]*2 0.137 4 / REP ABC. 4.002 2 / REP ABC. 0.083 2500 - P2 2->Val]*2 0.165 X / REP ABC. 3.986	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100 0.100 0.100 0.100 0.200 0.100 0.200	0.120 0.123 0.126 -0.024 -0.012 -0.068 0.137 0.002 0.083		
POIN 2310 - MP4 - D S13 - DIST 2310 - MP4 - D S13 - DIST 2310 - MP4 - D S08 - DIST 2420 - MP1 - D S08 - DIST 2420 - MP1 - D S08 - DIST 2420 - MP2 - D S09 - DIST 2500 - P1 - D S09 - DIST 2500 - P1 - D S09 - DIST 2500 - P1 - D S09 - DIST 2500 - P2 - D S09 - DIST 2500 - P4 - D	UP - 1 - POIN 2310 - 9.950 - DOWN DOWN - 1 - POIN 23 - 9.950 1 - POIN 2420 - MP1 25.900 1 - POIN 2420 - MP2 25.900 8 - POIN 2500 - P1 - 8 8.000 0 - POIN 2500 - P1 - 0 0.000 12+Y^2 - S09 - DIST 2509 - P1 0.000 4 - POIN 2500 - P2 - 4.000 0 - POIN 2500 - P3 - Z - 0.000 12+Y^2 - S09 - DIST 2500 - P3 - Z - 0.000 14 - POIN 2500 - P3 - Z - 0.000 15 - POIN 2500 - P3 - Z - 0.000 16 - POIN 2500 - P3 - Z - 0.000 17 - POIN 2500 - P3 - Z - 0.000 18 - POIN 2500 - P3 - Z - 0.000 19 - POIN 2500 - P3 - Z - 0.000 10 - POIN 2500 - P3 - Z - 0.000 11 - POIN 2500 - P3 - Z - 0.000 12 - POIN 2500 - P3 - Z - 0.000 14 - POIN 2500 - P3 - Z - 0.000	10.070 310 - MP4 - DOWN - 2 / F 10.073 1 - 2 / REP ABC. 26.026 2 - 2 / REP ABC. 25.876 3 / REP ABC. 7.988 0 / REP ABC0.068 2500 - P1 1->Val]*2 0.137 4 / REP ABC. 4.002 2 / REP ABC. 0.083 2500 - P2 2->Val]*2 0.165 X / REP ABC. 3.986	-0.050 REP ABC.	0.150 0.150 0.150 0.150 0.100 0.100 0.100 0.100 0.200 0.100 0.200	0.120 0.123 0.126 -0.024 -0.012 -0.068 0.137 0.002 0.083		



SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 01.06.2021 - 12.00

OPERATOR: IR

DATE: 01/06/21 15:52:08 SOFTWARE: METROLOG X4V14



TRUE POSITION 12 YEAR YOUNG TO THE POSITION TO	D: (D.			-				
### SPET YEAR PRO SPET 2000 0.146	Dim/Pos	Nominal No. NO. DIST 2500	Actual	Tol-	Tol+	Dev.	Tend.	State
Mail								
S95 - DST 2300 - Fs - 8				0.000	0.200	0.146		,
■ PON 2500 P5 - S - PON 2500 P3 - X REP ABC			0.140	0.000	0.200	0.146		V
### Septiments			D ARC					
S05 DBST 2500 - PS - 0				-0.100	0.100	-0.008		
■ PON 2500 - P5 - 0 - PON 2500 - P3 - 27 REP ABC ***OFTICER POSITION 0.2 X 22 x 22 - 500 - DIST 2500 - P5 ***SEP-DIST 2500 - P1 - DOWN ***OFTICER POSITION 0.2 X 22 x 22 - 500 - DIST 2500 - P5 - Vall** ***SEP-DIST 2500 - P1 - DOWN ***OFTICER POSITION 0.2 X 22 x		0.000	7.552	0.100	0.100	0.000		V
### TRUE POSITION 0.2 XY2-YY2 - 5090 - DIST 2500 - PS - SUBJECT ON 1		POIN 2500 - P3 - 7 / REF	PARC					
FIGURE POSITION 02 XY2+VP: S09 - DIST 2500 - P5				-0.100	0.100	0.056		./
■ SOOT X24.Y2 - 399 - DIST 2500 - PS - X99 X91 X9				0.100	0.100	0.000		V
S20 - DIST 2530 - P1 - DOWN REP ABC.	-							
\$38.0 PST 2830. P1 - DOWN FEP ABC.				0.000	0.200	0 114		
PLAN J - PON 250. P1 - DOWN REP ABC. PLAN J - PON 250. P1 - UP REP ABC. PLAN J - PON 250. P1 - UP REP ABC. PLAN J - PON 250. P2 - UP 1.150 1.107 -0.100 0.100 -0.043			0.111	0.000	0.200	0.111		V
SSO - DIST 2930 - P1 - UP / REP ABC. 1.150 1.107 -0.100 0.100 -0.043								
\$20 - DIST 2350 - P1 - UP / REP ABC. P PLAN J - POIN 250 - P2 - DOWN / REP ABC. \$20 - DIST 2350 - P2 - DOWN P PLAN J - POIN 250 - P2 - DOWN / REP ABC. \$21 - DIST 2350 - P3 - DOWN P PLAN J - POIN 250 - P2 - DOWN / REP ABC. \$22 - DIST 2350 - P3 - DOWN P PLAN J - POIN 250 - P3 - DOWN / REP ABC. \$24 - DIST 2350 - P3 - DOWN P PLAN J - POIN 250 - P3 - DOWN / REP ABC. \$25 - DIST 2350 - P3 - DOWN P PLAN J - POIN 250 - P3 - DOWN / REP ABC. \$26 - DIST 2350 - P3 - DOWN P PLAN J - POIN 250 - P3 - DOWN / REP ABC. \$27 - DIST 2350 - P4 - DOWN P PLAN J - POIN 250 - P3 - DOWN / REP ABC. \$28 - DIST 2350 - P4 - DOWN P PLAN J - POIN 250 - P3 - DOWN / REP ABC. \$28 - DIST 2350 - P4 - DOWN P PLAN J - POIN 250 - P3 - UP / REP ABC. \$28 - DIST 2350 - P4 - DOWN P PLAN J - POIN 250 - P4 - DOWN / REP ABC. \$29 - DIST 2350 - P4 - DOWN P PLAN J - POIN 250 - P4 - DOWN / REP ABC. \$20 - DIST 2350 - P4 - DOWN P PLAN J - POIN 250 - P4 - DOWN / REP ABC. \$20 - DIST 2350 - P4 - DOWN P PLAN J - POIN 250 - P4 - DOWN / REP ABC. \$20 - DIST 2350 - P5 - DOWN P PLAN J - POIN 250 - P4 - DOWN / REP ABC. \$20 - DIST 2350 - P5 - DOWN P PLAN J - POIN 250 - P4 - DOWN / REP ABC. \$21 - DIST 2350 - P5 - DOWN P PLAN J - POIN 250 - P4 - DOWN / REP ABC. \$25 - DIST 2350 - P5 - DOWN P PLAN J - POIN 250 - P4 - DOWN / REP ABC. \$25 - DIST 2350 - P5 - DOWN / REP ABC. \$25 - DIST 2350 - P5 - DOWN / REP ABC. \$25 - DIST 2350 - P5 - DOWN / REP ABC. \$25 - DIST 2350 - P5 - DOWN / REP ABC. \$25 - DIST 2350 - P5 - DOWN / REP ABC. \$25 - DIST 2350 - P5 - DOWN / REP ABC. \$25 - DIST 2350 - P5 - DOWN / REP ABC. \$25 - DIST 2350 - P5 - DOWN / REP ABC. \$25 - DIST 2350 - P5 - DOWN / REP ABC. \$25 - DIST 2350 - P5 - DOWN / REP ABC. \$25 - DIST 2350 - P1 - REP ABC. \$25 - DIST 2350 - P1 - REP ABC. \$25 - DIST 2350 - P1 - REP ABC. \$25 - DIST 2350 - P1 - REP ABC. \$25 - DIST 2350 - P1 - REP ABC. \$25 - DIST 2350 - P1 - REP ABC. \$25 - DIST 2350 - P2 - REP ABC. \$25 - DIST 2350 - P2 - REP ABC. \$25 - DIST 2350 - P2 - REP ABC. \$25 - DIST 2350 - P2 - REP A				-0.100	0.100	-0.030		V
■ PLAN J - PON 2530 - P1 - UP / REP ABC. 1				555	0.1,00			
↑ \$20 - DIST 2530 - P2 - DOWN PLAN J - POIN 2530 - P2 - DOWN REP ABC.								
S20 - DIST 2550 - P2 - DOWN REP ABC.			1.107	-0.100	0.100	-0.043		V
■ PLAN J - POIN 2530 - P2 - DOWN / REP ABC. 9				555	0.1,00	0.0.0		
S20 - DIST 250 - P2 - UP REP ABC.								
S20 - DIST 2530 - P2 - UP REP ABC.				-0.100	0.100	-0.066		
PLAN J - POIN 2530 - P2 - DOWN				*****	*****			
1.150								
S20 - DIST 2530 - P3 - DOWN T.150			1.073	-0.100	0.100	-0.077		_
PLAN J - POIN 2530 - P3 - DOWN / REP ABC.								
S20 - DIST 2530 - P3 - UP RP ABC.	l' '							
SS20 - DIST 2530 - P3 - UP PLAN J - POIN 2530 - P4 - DOWN PLAN J - POIN 2530 - P4 - DOWN PLAN J - POIN 2530 - P4 - DOWN PLAN J - POIN 2530 - P4 - DOWN PLAN J - POIN 2530 - P4 - UP PLAN J - POIN 2530 - P4 - UP PLAN J - POIN 2530 - P4 - UP PLAN J - POIN 2530 - P4 - UP PLAN J - POIN 2530 - P4 - UP PLAN J - POIN 2530 - P4 - UP PLAN J - POIN 2530 - P5 - DOWN PLAN J - POIN 2530 - P5 - DOWN PLAN J - POIN 2530 - P5 - DOWN REP ABC. Of				-0.100	0.100	-0.074		
PLAN J - POIN 2530 - P3 - UP / REP ABC. dY								
AS20 - DIST 2530 - P4 - DOWN								
SS0 - DIST 2530 - P4 - DOWN PEP ABC.	dY	1.150	1.065	-0.100	0.100	-0.085		✓
A		OWN				l e		·
S20 - DIST 2530 - P4 - UP FEP ABC. AV	PLAN J - POIN 2530	- P4 - DOWN / REP ABO						
S20 - DIST 2530 - P4 - UP FEP ABC. AV	dY	1.150	1.086	-0.140	0.100	-0.064		✓
AY 1.150 1.083 -0.120 0.100 -0.067	S20 - DIST 2530 - P4 - U	P						
S20 - DIST 2530 - P5 - DOWN REP ABC.	PLAN J - POIN 2530	- P4 - UP / REP ABC.						
S20 - DIST 2530 - P5 - DOWN REP ABC. PLAN J - POIN 2530 - P5 - UP REP ABC.	dY	1.150	1.083	-0.120	0.100	-0.067		✓
S20 - DIST 2530 - P5 - UP REP ABC.	S20 - DIST 2530 - P5 - D	OWN						
S20 - DIST 2530 - P5 - UP PLAN J - POIN 2500 - P5 - UP / REP ABC.	PLAN J - POIN 2530	- P5 - DOWN / REP ABO						
■ PLAN J - POIN 2500 - P5 - UP / REP ABC. dY 1.150 1.104 -0.100 0.100 -0.046	dY	1.150	1.113	-0.100	0.100	-0.037		✓
S14 - 2670 - 29.5 S10 - CERC 710 - B - POIN 2500 - P3 - Z / REP ABC. S14 - 2670 - 20.85 S10 - CERC 710 - B - POIN K-6 / REP ABC. S14 - 2670 - 20.85 S10 - CERC 710 - B - POIN K-6 / REP ABC. S14 - 2670 - 20.85 S10 - CERC 710 - B - POIN K-6 / REP ABC. S12 - DIST 2810 - P1 POIN D.69 - POIN 2810 - P1 - P2 S12 - DIST 2810 - P1 S12 - DIST 2810 - P2 S12 - DIST 2810 - P3 S12 - DIST 2810 - P4	🖰 S20 - DIST 2530 - P5 - U	P	•					
\$14 - 2670 - 29.5 \$10 - CERC 710 - B - POIN 2500 - P3 - Z / REP ABC.	PLAN J - POIN 2500	- P5 - UP / REP ABC.						
■ \$10 - CERC 710 - B - POIN 2500 - P3 - Z / REP ABC.	dY	1.150	1.104	-0.100	0.100	-0.046		✓
S14 - 2670 - 20.85	r S14 - 2670 - 29.5	·	•	·		·		
S14 - 2670 - 20.85 ■ S10 - CERC 710 - B - POIN K-6 / REP ABC. dZ	S10 - CERC 710 - B	- POIN 2500 - P3 - Z / RE	P ABC.					
■ \$10 - CERC 710 - B - POIN K-6 / REP ABC. d2		29.500	29.590	-0.100	0.100	0.090		✓
AZ 20.850 20.837 -0.100 0.100 -0.013	l' '					.		
TRUE POSITION 0.2 X"2+Y"2 - S14 - 2670 - 20.8529 ■ SQRT X"2+Y"2 - S14 - 2670-y\a 2 Val.				,				
= SQRT X*2+Y*2 - S14 - 2670->Val *2				-0.100	0.100	-0.013		✓
Val. 0.000 0.183 0.000 0.200 0.183 ✓ ↑ S12 - DIST 2810 - P1 P1 / REP ABC. O.075 0.075 0.075 -0.037 ✓ ♣ TRUE POSITION 0.15 - S12 - DIST 2810 - P1 P1 - S2I - DIST 2810 - P1 - S2I - [S12 - DIST 2810 - P1 - S2I)*2 ✓ ✓ ♣ Val. 0.000 0.074 0.000 0.150 0.074 ✓ ♣ S12 - DIST 2810 - P2 POIN D.69 - POIN 2810 - P2 / REP ABC. 0.075 0.075 0.004 ✓ ♣ TRUE POSITION 0.15 - S12 - DIST 2810 - P2 P2 - S2I - PIST 2810 - P2 P3 - S2I - PIST 2810 - P2 - S2I - [S12 - DIST 2810 - P2 - S2I)*2 Val. 0.000 0.009 0.000 0.150 0.009 ✓ ♣ S12 - DIST 2810 - P3 POIN D.69 - POIN 2810 - P3 / REP ABC. 0.005 0.075 0.075 0.024 ✓ ♣ TRUE POSITION 0.15 - S12 - DIST 2810 - P3 P3 - S2I - PIST 2810 - P3 P3 - S2I - PIST 2810 - P3 0.000 0.0150 0.048 ✓ ♣ S12 - DIST 2810 - P4 P0IN 2810 - P4 - POIN D.69 / REP ABC. 0.000 0.000 0.0150 0.048 ✓ ♣ S12 - DIST 2810 - P4 P0IN 2810 - P4 - POIN D.69 / REP ABC. 0.000 0.0			529					
S12 - DIST 2810 - P1								
■ POIN D.69 - POIN 2810 - P1 / REP ABC.		0.000	0.183	0.000	0.200	0.183		✓
dZ								
TRUE POSITION 0.15 - S12 - DIST 2810 - P1 ■ ABS([S12 - DIST 2810 - P1=>Z]-[S12 - DIST 2810 - P1->Z])*2 Val.								
■ ABS([S12 - DIST 2810 - P1=>Z]-[S12 - DIST 2810 - P1->Z])*2 Val. 0.000 0.074 0.000 0.150 0.074 ✓ S12 - DIST 2810 - P2 ■ POIN D.69 - POIN 2810 - P2 / REP ABC. dZ 4.000 4.004 -0.075 0.075 0.004 ✓ **TRUE POSITION 0.15 - S12 - DIST 2810 - P2 ■ ABS([S12 - DIST 2810 - P2=>Z]-[S12 - DIST 2810 - P2->Z])*2 Val. 0.000 0.009 0.000 0.150 0.009 ✓ **S12 - DIST 2810 - P3 ■ POIN D.69 - POIN 2810 - P3 / REP ABC. dZ -0.000 0.024 -0.075 0.075 0.024 ✓ **TRUE POSITION 0.15 - S12 - DIST 2810 - P3 ■ ABS([S12 - DIST 2810 - P3 = ABS([S12 - DIST 2810 - P3->Z])*2 Val. 0.000 0.048 0.000 0.150 0.048 ✓ **S12 - DIST 2810 - P4 ■ POIN 2810 - P4 - POIN D.69 / REP ABC.			7.963	-0.075	0.075	-0.037		✓
Val. 0.000 0.074 0.000 0.150 0.074 S12 - DIST 2810 - P2 POIN D.69 - POIN 2810 - P2 / REP ABC. 0.005 0.005 0.004 TRUE POSITION 0.15 - S12 - DIST 2810 - P2 = ABS([S12 - DIST 2810 - P2=>Z]-[S12 - DIST 2810 - P2->Z])*2 0.000 0.009 0.000 0.009 S12 - DIST 2810 - P3 POIN D.69 - POIN 2810 - P3 / REP ABC. 0.005 0.075 0.075 0.024 TRUE POSITION 0.15 - S12 - DIST 2810 - P3 = ABS([S12 - DIST 2810 - P3 - Z]-[S12 - DIST 2810 - P3 - Z])*2 0.000 0.048 0.000 0.150 0.048 S12 - DIST 2810 - P4 POIN 2810 - P4 - POIN D.69 / REP ABC. 0.000 0.0150 0.048 0.004 0.004								
S12 - DIST 2810 - P2 ■ POIN D.69 - POIN 2810 - P2 / REP ABC. dZ	·-							
■ POIN D.69 - POIN 2810 - P2 / REP ABC. dZ		0.000	0.074	0.000	0.150	0.074		✓
dZ	l' '							
TRUE POSITION 0.15 - S12 - DIST 2810 - P2 ■ =ABS([S12 - DIST 2810 - P2=>Z]-[S12 - DIST 2810 - P2->Z])*2 Val.			1	/	!			
■ =ABS([S12 - DIST 2810 - P2=>Z]-[S12 - DIST 2810 - P2->Z])*2 Val. 0.000 0.009 0.000 0.150 0.009 S12 - DIST 2810 - P3 ■ POIN D.69 - POIN 2810 - P3 / REP ABC. dZ -0.000 0.024 -0.075 0.075 0.024 TRUE POSITION 0.15 - S12 - DIST 2810 - P3 ■ =ABS([S12 - DIST 2810 - P3=>Z]-[S12 - DIST 2810 - P3->Z])*2 Val. 0.000 0.048 0.000 0.150 0.048 ■ POIN 2810 - P4 - POIN D.69 / REP ABC.			4.004	-0.075	0.075	0.004		✓
Val. 0.000 0.009 0.000 0.150 0.009 S12 - DIST 2810 - P3 ■ POIN D.69 - POIN 2810 - P3 / REP ABC. dZ -0.000 0.024 -0.075 0.075 0.024 ★ TRUE POSITION 0.15 - S12 - DIST 2810 - P3 ■ ABS([S12 - DIST 2810 - P3=>Z]-[S12 - DIST 2810 - P3->Z])*2 Val. 0.000 0.048 0.000 0.150 0.048 ★ S12 - DIST 2810 - P4 ■ POIN 2810 - P4 - POIN D.69 / REP ABC.			0040 80 70:-					
S12 - DIST 2810 - P3		••.			1			
■ POIN D.69 - POIN 2810 - P3 / REP ABC. dZ		0.000	0.009	0.000	0.150	0.009		✓
dZ		Da / = = = :						
★ TRUE POSITION 0.15 - S12 - DIST 2810 - P3 ■ =ABS([S12 - DIST 2810 - P3=>Z]-[S12 - DIST 2810 - P3->Z])*2 Val. 0.000 0.048 0.000 0.150 0.048 ➡ S12 - DIST 2810 - P4 POIN 2810 - P4 - POIN D.69 / REP ABC. POIN 2810 - P4 - POIN D.69 / REP ABC.			0.05.1		0.000			
■ =ABS([S12 - DIST 2810 - P3=>Z]-[S12 - DIST 2810 - P3->Z])*2 Val.			0.024	-0.075	0.075	0.024		✓
Val. 0.000 0.048 0.000 0.150 0.048								
S12 - DIST 2810 - P4 POIN 2810 - P4 - POIN D.69 / REP ABC.				0.000	0.450	0.010		
POIN 2810 - P4 - POIN D.69 / REP ABC.		0.000	0.048	0.000	0.150	0.048		✓
		WIND 00 / 555 / 55						
g∠ 4.000 3.948 -0.075 0.075 -0.052			0.010	6 6==1	6 6==1			
	dZ	4.000	3.948	-0.075	0.075	-0.052		✓



SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 01.06.2021 - 12.00

Tol-

OPERATOR: IR

Actual

Nominal

DATE: 01/06/21 15:52:08 SOFTWARE: METROLOG X4V14

Tol+



State

Dim/Pos	Nominal	Actual	IOI-	IOI+	Dev.	lend.	State
TRUE POSITION 0.15							
		DIST 2810 - P4->Z])*2	0.000	0.150	0.104		
Val.	0.000	0.104	0.000	0.150	0.104		~
S12 - DIST 2810 - P5							
	POIN D.69 / REP ABC		0.075	0.075	0.000		
dZ TRUE POSITION 0.15	8.000	7.937	-0.075	0.075	-0.063		✓
	,	DIST 2810 - P5->Z])*2	0.000	0.150	0.100		
Val.	0.000	0.126	0.000	0.150	0.126		✓
VAL1							
Dimensiuni extra							
DIST 400 - 1							
	LAN 400 - 1 / REP AE			1	1		
dZ	2.650	2.518	-0.120	0.100	-0.132	-0.012	×
DIST 400 - 2		_					
	LAN 400 - 2 / REP AE						
dZ	2.650	2.579	-0.090	0.090	-0.071		~
7 DIST 400 - 3							
PLAN 400 - 3 - PC	OIN 400 - 3-5 / REP AE						
dX	2.650	2.554	-0.140	0.090	-0.096		~
DIST 400 - 4							
PLAN 400 - 4 - PC	IN 400 - 4-5 / REP AE	BC.					
dZ	2.650	2.581	-0.120	0.090	-0.069		~
DIST 400 - 5		'			,		
	IN 400 - 5-9 / REP AE	BC.					
dZ	2.650	2.589	-0.280	0.090	-0.061		~
DIST 400 - 6							
	LAN 400 - 6 / REP AE	BC.					
dX	2.650	2.565	-0.120	0.090	-0.085		~
DIST 410 - 1					,,,,,,		
	IN 410 - 1-2 / REP AB	C.					
dY	2.600	2.503	-0.150	0.090	-0.097		~
DIST 410 - 2	2.000	2.000	0.100	0.000	3.037		
	IN 410 - 2-2 / REP AB	r.					
dY	2.600	2.523	-0.100	0.090	-0.077		
DIST 410 - 3	2.000	2.020	-0.100	0.050	-0.077		~
	OIN 410 00/DED	NPC					
	OIN 410 - 3-2 / REP A		0.000	0.000	0.040		
dY dY	2.600	2.618	-0.090	0.090	0.018		~
DIST 410 - 4	101N 446 4 5 : = = :	100					
	OIN 410 - 4-2 / REP A			1			
dY	2.600	2.472	-0.200	0.090	-0.128		~
7 DIST 410 - 5							
	IN 410 - 5-2 / REP AB					<u> </u>	
dY	2.600	2.642	-0.090	0.090	0.042		~
DIST 410 - 6							
POIN 410 - 6 - PO	IN 1980 - 6 - 3 / REP	ABC.					
dY	2.600	2.541	-0.090	0.090	-0.059		~
DIST 630 - 1							
	OIN 630 - 1-2 / REP A	ABC.					
dZ	55.500	55.459	-0.270	0.100	-0.041		~
DIST 630 - 2	00.000	23.100			3.0		
	OIN 630 - 2-2 / REP A	ABC					
dZ	55.500	55.233	-0.270	0.100	-0.267		
DIST 780 - 1	55.500	JJ.233	-0.270	0.100	-0.207		✓
	AN 700 4 / DED 400						
	AN 780 - 1 / REP ABC		0.000	0.470	0.474	0.004	
D D	3.200	3.374	0.000	0.170	0.174	0.004	X
DIST 780 - 2							
	AN 780 - 2 / REP ABC						
D	3.200	3.307	0.000	0.190	0.107		✓
DIST 780 - 3						· · · · · · · · · · · · · · · · · · ·	
POIN 780 - 3 - PL	AN 780 - 3 / REP ABC	i.					
D	3.200	3.281	0.000	0.100	0.081		~
DIST 780 - 4							
	AN 780 - 4 / REP ABC	·.					
	3.200	3.341	0.000	0.100	0.141	0.041	X
	0.200	3.011	0.000	300	3.111	0.011	
D							
D ↑ DIST 1780 - MP10) - 2 - POIN 1780 . ME	210 - 1 / REP ARC					
D DIST 1780 - MP10 POIN 1780 - MP10) - 2 - POIN 1780 - MF		0.000	0.330	0.001		
D ↑ DIST 1780 - MP10 ■ POIN 1780 - MP10 dX	0 - 2 - POIN 1780 - MF 106.500	P10 - 1 / REP ABC. 106.591	0.000	0.220	0.091		✓
D D D D D D D D D D D D D D D D D D D	106.500	106.591	0.000	0.220	0.091		~
D D D D D D D D D D D D D D D D D D D		106.591	0.000	0.220	0.091		✓



SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 01.06.2021 - 12.00

Tol-

OPERATOR: IR

Actual

Nominal

DATE: 01/06/21 15:52:08 SOFTWARE: METROLOG X4V14

Tol+



State

				101+		
DIST 1780 - MP12	0 DOIN 1700 MD:	10 1/DED ADC				
POIN 1780 - MP12 -			0.000	0.000	0.000	
dX	106.500	106.580	0.000	0.220	0.080	 ✓
ri DIST 2600 - P1 - F						
POIN 2600 - P1 - DF	RTE F / REP ABC.					
dX	-0.000	-0.050	-0.075	0.075	-0.050	 ✓
						 _
=ABS([DIST 2600 - F	01 E VI IDIGE 260	00 D1 E VI*0				
1.5			0.000	0.450	0.400	
Val.	0.000	0.100	0.000	0.150	0.100	 ✓
in DIST 2600 - P2 - F						
POIN 2600 - P2 - DF	RTE F / REP ABC.					
dX	-0.000	-0.050	-0.075	0.075	-0.050	 ✓
	0.000	0.000	0.07.0	0.07.0	0.000	·
	00 E VI (DIOT 000	00 D0 E VI*0				
= ABS([DIST 2600 - F			1			
Val.	0.000	0.100	0.000	0.150	0.100	 ✓
r DIST 2600 - P3 - F	•		·			
POIN 2600 - P3 - DF	RTE F / REP ABC.					
dX	0.000	-0.046	-0.075	0.075	-0.046	 ~
	0.000	-0.040	-0.075	0.075	-0.040	 ~
♦ 0.1 - DIST 2600 - P3 - F						
■ =ABS([DIST 2600 - F	ソ3 - F=>X]-[DIST 260)U - P3 - F->X])*2				
Val.	0.000	0.091	0.000	0.150	0.091	 ✓
→ DIST 2600 - P4 - F						
POIN 2600 - P4 - DF	RTE E / REP ARC					
		0.040	0.075	0.075	0.040	
dX	0.000	-0.043	-0.075	0.075	-0.043	 ✓
★ 0.1 - DIST 2600 - P4 - F						
= ABS([DIST 2600 - F	P4 - F=>X]-[DIST 260	00 - P4 - F->X])*2				
Val.	0.000	0.087	0.000	0.150	0.087	 ✓
→ DIST 2600 - P5 - F	3.300	0.007	0.000	300	3.307	
	TE E / DED 400					
POIN 2600 - P5 - DF						
dX	-0.000	-0.029	-0.075	0.075	-0.029	 ✓
♦ 0.1 - DIST 2600 - P5 - F	•		·			
=ABS([DIST 2600 - F	P5 - F=>X1-IDIST 260	00 - P5 - F->X1)*2				
Val.	0.000	0.058	0.000	0.150	0.058	
	0.000	0.038	0.000	0.130	0.036	 ✓
→ DIST 2600 - P1 - L						
POIN 2600 - P1 - DF	RTE L / REP ABC.					
dX	0.000	0.015	-0.075	0.075	0.015	 ✓
					1	
PA						
= ABS(IDIST 2600 - F	21 - I =>X]-[DIST 260	\n - P1 - I ->X*2				
= ABS([DIST 2600 - F			0.000	0.150	0.020	
Val.	P1 - L=>X]-[DIST 260 0.000	00 - P1 - L->X])*2 0.030	0.000	0.150	0.030	 ✓
Val. r∸ DIST 2600 - P2 - L	0.000		0.000	0.150	0.030	 ~
Val.	0.000		0.000	0.150	0.030	 ✓
Val. → DIST 2600 - P2 - L	0.000		0.000	0.150	0.030	 ✓
Val. ↑↑ DIST 2600 - P2 - L POIN 2600 - P2 - DF dX	0.000 RTE L / REP ABC.	0.030				
Val. ↑↑ DIST 2600 - P2 - L ■ POIN 2600 - P2 - DF dX ♪ 0.1 - DIST 2600 - P2 - L	0.000 RTE L / REP ABC. -0.000	0.030				
Val. ↑↑ DIST 2600 - P2 - L ■ POIN 2600 - P2 - DF dX ♣ 0.1 - DIST 2600 - P2 - L ■ =ABS([DIST 2600 - F	0.000 RTE L / REP ABC. -0.000 P2 - L=>X]-[DIST 260	0.030 0.007 00 - P2 - L->X])*2	-0.075	0.075	0.007	 →
Val. ↑↑ DIST 2600 - P2 - L ■ POIN 2600 - P2 - DF dX ♣ 0.1 - DIST 2600 - P2 - L ■ =ABS([DIST 2600 - F Val.	0.000 RTE L / REP ABC. -0.000	0.030				
Val. ↑ ↑ DIST 2600 - P2 - L POIN 2600 - P2 - DF dX 0.1 - DIST 2600 - P2 - L = ABS([DIST 2600 - F2 - L Val. ↑ ↑ DIST 2600 - P3 - L	0.000 RTE L / REP ABC. -0.000 P2 - L=>X]-[DIST 260 0.000	0.030 0.007 00 - P2 - L->X])*2	-0.075	0.075	0.007	 →
Val. ↑↑ DIST 2600 - P2 - L ■ POIN 2600 - P2 - DF dX ♣ 0.1 - DIST 2600 - P2 - L ■ =ABS([DIST 2600 - F Val.	0.000 RTE L / REP ABC. -0.000 P2 - L=>X]-[DIST 260 0.000	0.030 0.007 00 - P2 - L->X])*2	-0.075	0.075	0.007	 →
Val. POIN 2600 - P2 - L POIN 2600 - P2 - DF dX 0.1 - DIST 2600 - P2 - L = ABS([DIST 2600 - F Val. Val. POIN 2600 - P3 - DF	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC.	0.030 0.007 00 - P2 - L->X])*2 0.015	-0.075 0.000	0.075	0.007	 ✓ ✓
Val. ↑ ↑ DIST 2600 - P2 - L ■ POIN 2600 - P2 - DF dX ↑ ↑ 0.1 - DIST 2600 - P2 - L ■ =ABS([DIST 2600 - F Val. ↑ ↑ DIST 2600 - P3 - L ■ POIN 2600 - P3 - DF dX	0.000 RTE L / REP ABC. -0.000 P2 - L=>X]-[DIST 260 0.000	0.030 0.007 00 - P2 - L->X])*2	-0.075	0.075	0.007	 →
Val. ↑ ↑ DIST 2600 - P2 - L ■ POIN 2600 - P2 - DF dX ▲ 0.1 - DIST 2600 - P2 - L ■ =ABS([DIST 2600 - F2 - L ■ POIN 2600 - P3 - L ■ POIN 2600 - P3 - DF dX ▲ 0.1 - DIST 2600 - P3 - L	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004	-0.075 0.000	0.075	0.007	 ✓ ✓
Val. POIN 2600 - P2 - L POIN 2600 - P2 - DF dX 0.1 - DIST 2600 - P2 - L = ABS([DIST 2600 - F3 - L POIN 2600 - P3 - DF dX 0.1 - DIST 2600 - P3 - L = ABS([DIST 2600 - P3 - L POIN 2600 - P3 - L = ABS([DIST 2600 - P3 - L	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2	-0.075 0.000 -0.075	0.075 0.150 0.075	0.007 0.015 0.004	✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓
Val. ↑ DIST 2600 - P2 - L POIN 2600 - P2 - DF dX 0.1 - DIST 2600 - P2 - L = ABS([DIST 2600 - F2 - L POIN 2600 - P3 - L POIN 2600 - P3 - DF dX 0.1 - DIST 2600 - P3 - L = ABS([DIST 2600 - F3 - L	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004	-0.075 0.000	0.075	0.007	 ✓ ✓
Val. POIN 2600 - P2 - L POIN 2600 - P2 - DF dX 0.1 - DIST 2600 - P2 - L = ABS([DIST 2600 - F3 - L POIN 2600 - P3 - DF dX 0.1 - DIST 2600 - P3 - L = ABS([DIST 2600 - P3 - L POIN 2600 - P3 - L = ABS([DIST 2600 - P3 - L	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2	-0.075 0.000 -0.075	0.075 0.150 0.075	0.007 0.015 0.004	✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓
Val. ↑ ↑ DIST 2600 - P2 - L POIN 2600 - P2 - DF dX 0.1 - DIST 2600 - P2 - L = ABS([DIST 2600 - F] Val. ↑ ↑ DIST 2600 - P3 - L POIN 2600 - P3 - DF dX 0.1 - DIST 2600 - P3 - L = ABS([DIST 2600 - F] Val. ↑ ↑ DIST 2600 - P4 - L	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2	-0.075 0.000 -0.075	0.075 0.150 0.075	0.007 0.015 0.004	✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓
Val. ↑ ↑ DIST 2600 - P2 - L POIN 2600 - P2 - DE dX 0.1 - DIST 2600 - P2 - L = ABS([DIST 2600 - F2 - L POIN 2600 - F3 - L POIN 2600 - P3 - DE dX 0.1 - DIST 2600 - P3 - L = ABS([DIST 2600 - F3 - L POIN 2600 - P4 - DE	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC.	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2 0.009	-0.075 0.000 -0.075 0.000	0.075 0.150 0.075 0.150	0.007 0.015 0.004 0.009	
Val. POIST 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - DF dX 0.1 - DIST 2600 - P2 - L POIN 2600 - P3 - L POIN 2600 - P3 - DF dX 0.1 - DIST 2600 - P3 - L POIN 2600 - P3 - L POIN 2600 - P4 - DF DIST 2600 - P4 - DF dX	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2	-0.075 0.000	0.075 0.150 0.075	0.007 0.015 0.004	✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓
Val. ↑↑ DIST 2600 - P2 - L ■ POIN 2600 - P2 - DF dX ↑↑ 0.1 - DIST 2600 - P2 - L ■ = ABS([DIST 2600 - P Val. ↑↑ DIST 2600 - P3 - L ■ POIN 2600 - P3 - DF dX ↑↑ 0.1 - DIST 2600 - P3 - L ■ = ABS([DIST 2600 - P3 - L ■ POIN 2600 - P4 - DF dX ↑↑ DIST 2600 - P4 - DF dX ↑↑ 0.1 - DIST 2600 - P4 - DF	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2 0.009	-0.075 0.000 -0.075 0.000	0.075 0.150 0.075 0.150	0.007 0.015 0.004 0.009	
Val. POIST 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - DF dX 0.1 - DIST 2600 - P2 - L POIN 2600 - P3 - L POIN 2600 - P3 - DF dX 0.1 - DIST 2600 - P3 - L POIN 2600 - P3 - L POIN 2600 - P4 - DF DIST 2600 - P4 - DF dX	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2 0.009	-0.075 0.000 -0.075 0.000	0.075 0.150 0.075 0.150	0.007 0.015 0.004 0.009	
Val. → DIST 2600 - P2 - L → POIN 2600 - P2 - DF dX → 0.1 - DIST 2600 - P2 - L → ABS([DIST 2600 - P Val. → DIST 2600 - P3 - L → POIN 2600 - P3 - DF dX → 0.1 - DIST 2600 - P3 - L → BS([DIST 2600 - P3 - L → DIST 2600 - P4 - DF dX → DIST 2600 - P4 - DF dX → O.1 - DIST 2600 - P4 - DF dX → 0.1 - DIST 2600 - P4 - DF	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2 0.009	-0.075 0.000 -0.075 0.000	0.075 0.150 0.075 0.150	0.007 0.015 0.004 0.009	
Val. → DIST 2600 - P2 - L → POIN 2600 - P2 - L → POIN 2600 - P2 - L → ABS([DIST 2600 - P2 - L → DIST 2600 - P3 - L → POIN 2600 - P3 - L → POIN 2600 - P3 - L → POIN 2600 - P3 - L → DIST 2600 - P4 - L → POIN 2600 - P4 - DF → DIST 2600 - P4 - DF →	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000 P4 - L=>X]-[DIST 260 0.000	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2 0.009 -0.001 00 - P4 - L->X])*2	-0.075 0.000 -0.075 0.000	0.075 0.150 0.075 0.150	0.007 0.015 0.004 0.009	
Val. ↑ DIST 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - L ABS([DIST 2600 - P2 - L POIN 2600 - P3 - L POIN 2600 - P4 - L POIN 2600 - P5 - L	0.000 RTE L / REP ABC0.000 RTE L / REP ABC. 0.000	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2 0.009 -0.001 00 - P4 - L->X])*2	-0.075 0.000 -0.075 0.000	0.075 0.150 0.075 0.150	0.007 0.015 0.004 0.009	
Val. POINT 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - L POINT 2600 - P2 - L POINT 2600 - P3 - L POINT 2600 - P4 - L POINT 2600 - P4 - L POINT 2600 - P4 - L POINT 2600 - P5 - L POINT 2600 - P5 - L POINT 2600 - P5 - DF	0.000 RTE L / REP ABC0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC.	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2 0.009 -0.001 00 - P4 - L->X])*2 0.002	-0.075 0.000 -0.075 0.000 -0.075	0.075 0.150 0.075 0.150 0.075	0.007 0.015 0.004 0.009 -0.001 0.002	
Val. POIN 2600 - P2 - L POIN 2600 - P2 - DF dX 0.1 - DIST 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P3 - L POIN 2600 - P4 - DF dX O.1 - DIST 2600 - P4 - L POIN 2600 - P5 - DF Val. POIN 2600 - P5 - DF DIST 2600 - P5 - DF DIST 2600 - P5 - DF DIST 2600 - P5 - DF	0.000 RTE L / REP ABC0.000 RTE L / REP ABC. 0.000	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2 0.009 -0.001 00 - P4 - L->X])*2	-0.075 0.000 -0.075 0.000	0.075 0.150 0.075 0.150	0.007 0.015 0.004 0.009	
Val. POINT 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - L POINT 2600 - P2 - L POINT 2600 - P3 - L POINT 2600 - P4 - L POINT 2600 - P4 - L POINT 2600 - P4 - L POINT 2600 - P5 - L POINT 2600 - P5 - L POINT 2600 - P5 - DF	0.000 RTE L / REP ABC0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC.	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2 0.009 -0.001 00 - P4 - L->X])*2 0.002	-0.075 0.000 -0.075 0.000 -0.075	0.075 0.150 0.075 0.150 0.075	0.007 0.015 0.004 0.009 -0.001 0.002	
Val. POIN 2600 - P2 - L POIN 2600 - P2 - DF dX 0.1 - DIST 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P3 - L POIN 2600 - P3 - DF dX 0.1 - DIST 2600 - P3 - L POIN 2600 - P3 - L POIN 2600 - P4 - L POIN 2600 - P4 - L POIN 2600 - P4 - DF dX 0.1 - DIST 2600 - P4 - L POIN 2600 - P5 - DF dX O.1 - DIST 2600 - P5 - DF dX O.1 - DIST 2600 - P5 - DF dX DIST 2600 - P5 - DF dX DIST 2600 - P5 - DF dX O.1 - DIST 2600 - P5 - DF	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P4 - L=>X]-[DIST 260 0.000 RTE L / REP ABC0.000 RTE L / REP ABC0.000	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2 0.009 -0.001 00 - P4 - L->X])*2 0.002	-0.075 0.000 -0.075 0.000 -0.075	0.075 0.150 0.075 0.150 0.075	0.007 0.015 0.004 0.009 -0.001 0.002	
Val. POIST 2600 - P2 - L POIN 2600 - P3 - L POIN 2600 - P4 - L POIN 2600 - P5 - L POIN 2600 - P5 - L POIN 2600 - P5 - DF dX	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000 P4 - L=>X]-[DIST 260 0.000 RTE L / REP ABC0.000 RTE L / REP ABC0.000 P5 - L=>X]-[DIST 260 0.000	0.030 0.007 0.007 0.007 0.001 0.004 0.004 0.009 0.009 0.001 0.002 0.006 0.006 0.006 0.006 0.006 0.006 0.006 0.007 0.007 0.008 0.007	-0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075	0.075 0.150 0.075 0.150 0.075 0.150 0.075	0.007 0.015 0.004 0.009 -0.001 0.002	
Val. POIST 2600 - P2 - L POIN 2600 - P3 - L POIN 2600 - P4 - L POIN 2600 - P5 - L POIN 2600 - P5 - L POIN 2600 - P5 - DF CALL POIN 2600	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P4 - L=>X]-[DIST 260 0.000 RTE L / REP ABC0.000 RTE L / REP ABC0.000	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2 0.009 -0.001 00 - P4 - L->X])*2 0.002	-0.075 0.000 -0.075 0.000 -0.075 0.000	0.075 0.150 0.075 0.150 0.075	0.007 0.015 0.004 0.009 -0.001 0.002	
Val. → DIST 2600 - P2 - L → POIN 2600 - P2 - L → POIN 2600 - P2 - L → ABS([DIST 2600 - P2 - L → DIST 2600 - P3 - L → POIN 2600 - P3 - L → POIN 2600 - P3 - L → ABS([DIST 2600 - P3 - L → ABS([DIST 2600 - P3 - L → POIN 2600 - P4 - L → POIN 2600 - P4 - L → POIN 2600 - P4 - L → DIST 2600 - P5 - L → POIN 2600 - P5 - L → POIN 2600 - P5 - DF dX → DIST 2600 - P5 - DF DIST 2600 - P5 - DF DIST 2600 - P5 - DF → DIST 2600 - P5 - DF	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000 P4 - L=>X]-[DIST 260 0.000 RTE L / REP ABC0.000 P5 - L=>X]-[DIST 260 0.000 P5 - L=>X]-[DIST 260 0.000	0.030 0.007 0.007 0.007 0.001 0.004 0.004 0.009 0.009 0.001 0.002 0.006 0.006 0.006 0.006 0.006 0.006 0.006 0.007 0.007 0.008 0.007	-0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075	0.075 0.150 0.075 0.150 0.075 0.150 0.075	0.007 0.015 0.004 0.009 -0.001 0.002	
Val. → DIST 2600 - P2 - L → POIN 2600 - P2 - L → POIN 2600 - P2 - L → ABS([DIST 2600 - P2 - L → DIST 2600 - P3 - L → POIN 2600 - P3 - L → POIN 2600 - P3 - L → POIN 2600 - P3 - L → ABS([DIST 2600 - P3 - L → DIST 2600 - P4 - L → POIN 2600 - P4 - DF → DIST 2600 - P4 - L → POIN 2600 - P5 - L → POIN 2600 - P5 - DF → DIST 2600 - P5 - DF → CASS DIST 2600 - P5 - DF → CASS DIST 2600 - P5 - DF → CASS DIST 2600 - P5 - DF → DIST 2600 - P1 - F → DOIN 2610 - P1 - DF	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC0.000 RTE F / REP ABC.	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2 0.009 -0.001 00 - P4 - L->X])*2 0.006 00 - P5 - L->X])*2	-0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.000	0.075 0.150 0.075 0.150 0.075 0.150 0.150 0.150	0.007 0.015 0.004 0.009 -0.001 0.002 0.006 0.012	
Val. → DIST 2600 - P2 - L → POIN 2600 - P2 - L → POIN 2600 - P2 - L → ABS([DIST 2600 - P2 - L → POIN 2600 - P3 - L → ABS([DIST 2600 - P3 - L → POIN 2600 - P4 - L → POIN 2600 - P4 - L → POIN 2600 - P4 - L → POIN 2600 - P5 - L → POIN 2600 - P5 - DF dX → DIST 2600 - P5 - DF dX	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000 P4 - L=>X]-[DIST 260 0.000 RTE L / REP ABC0.000 P5 - L=>X]-[DIST 260 0.000 P5 - L=>X]-[DIST 260 0.000	0.030 0.007 0.007 0.007 0.001 0.004 0.004 0.009 0.009 0.001 0.002 0.006 0.006 0.006 0.006 0.006 0.006 0.006 0.007 0.007 0.008 0.007	-0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075	0.075 0.150 0.075 0.150 0.075 0.150 0.075	0.007 0.015 0.004 0.009 -0.001 0.002	
Val. POIST 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - L AND	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC0.000 RTE F / REP ABC.	0.030 0.007 00 - P2 - L->X])*2 0.015 0.004 00 - P3 - L->X])*2 0.009 -0.001 00 - P4 - L->X])*2 0.006 00 - P5 - L->X])*2	-0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.000	0.075 0.150 0.075 0.150 0.075 0.150 0.150 0.150	0.007 0.015 0.004 0.009 -0.001 0.002 0.006 0.012	
Val. POINT 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - L AND	0.000 RTE L / REP ABC0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC0.000 RTE F / REP ABC. 0.000	0.030 0.007 0.007 0.007 0.0015 0.004 0.004 0.009 0.009 0.001 0.006 0.006 0.006 0.001	-0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.000	0.075 0.150 0.075 0.150 0.075 0.150 0.150 0.150	0.007 0.015 0.004 0.009 -0.001 0.002 0.006 0.012	
Val. POIN 2600 - P2 - L POIN 2600 - P2 - DF dX 0.1 - DIST 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P3 - L POIN 2600 - P4 - L POIN 2600 - P5 - L POIN 2610 - P1 - F	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P4 - L=>X]-[DIST 260 0.000 RTE L / REP ABC0.000 RTE L / REP ABC0.000 RTE L / REP ABC0.000 P5 - L=>X]-[DIST 260 0.000 RTE F / REP ABC0.000 RTE F / REP ABC0.000 P1 - F=>X]-[DIST 261	0.030 0.007 0.007 0.007 0.007 0.001 0.004 0.004 0.009 0.009 0.006 0.006 0.006 0.006 0.006 0.001	-0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.150 -0.150 0.000	0.075 0.150 0.075 0.150 0.075 0.150 0.150 0.150	0.007 0.015 0.004 0.009 -0.001 0.002 0.006 0.012	
Val. DIST 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - L ABS([DIST 2600 - P2 - L POIN 2600 - P3 - L POIN 2600 - P4 - L POIN 2600 - P5 - DF Val. DIST 2600 - P5 - L POIN 2600 - P5 - DF Val. DIST 2600 - P1 - F POIN 2610 - P1 - F	0.000 RTE L / REP ABC0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC0.000 RTE F / REP ABC. 0.000	0.030 0.007 0.007 0.007 0.0015 0.004 0.004 0.009 0.009 0.001 0.006 0.006 0.006 0.001	-0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.000	0.075 0.150 0.075 0.150 0.075 0.150 0.150 0.150	0.007 0.015 0.004 0.009 -0.001 0.002 0.006 0.012	
Val. POIST 2600 - P2 - L POIN 2600 - P2 - DF dX 0.1 - DIST 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P3 - L POIN 2600 - P4 - L POIN 2600 - P5 - DF dX O.1 - DIST 2600 - P5 - L POIN 2600 - P5 - L POIN 2600 - P5 - DF dX O.1 - DIST 2600 - P1 - F POIN 2610 - P1 - F	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P4 - L=>X]-[DIST 260 0.000 RTE L / REP ABC0.000 RTE L / REP ABC0.000 RTE L / REP ABC0.000 P5 - L=>X]-[DIST 260 0.000 RTE F / REP ABC0.000 RTE F / REP ABC0.000 P1 - F=>X]-[DIST 261	0.030 0.007 0.007 0.007 0.007 0.001 0.004 0.004 0.009 0.009 0.006 0.006 0.006 0.006 0.006 0.001	-0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.150 -0.150 0.000	0.075 0.150 0.075 0.150 0.075 0.150 0.150 0.150	0.007 0.015 0.004 0.009 -0.001 0.002 0.006 0.012	
Val. DIST 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - L POIN 2600 - P2 - L ABS([DIST 2600 - P2 - L POIN 2600 - P3 - L POIN 2600 - P4 - L POIN 2600 - P5 - L POIN 2600 - P5 - L POIN 2600 - P5 - DF Val. DIST 2610 - P1 - F POIN 2610 - P2 - F	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000 P4 - L=>X]-[DIST 260 0.000 RTE L / REP ABC0.000 RTE L / REP ABC. 0.000 P5 - L=>X]-[DIST 260 0.000 RTE F / REP ABC. 0.000 RTE F / REP ABC. 0.000 P1 - F=>X]-[DIST 261 0.000	0.030 0.007 0.007 0.007 0.007 0.001 0.004 0.004 0.009 0.009 0.006 0.006 0.006 0.006 0.006 0.001	-0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.150 -0.150 0.000	0.075 0.150 0.075 0.150 0.075 0.150 0.150 0.150	0.007 0.015 0.004 0.009 -0.001 0.002 0.006 0.012	
Val. DIST 2600 - P2 - L POIN 2600 - P3 - L POIN 2600 - P4 - L POIN 2600 - P5 - L POIN 2600 - P5 - L POIN 2600 - P5 - DF Val. DIST 2600 - P1 - F POIN 2610 - P2 - F	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000 P4 - L=>X]-[DIST 260 0.000 RTE L / REP ABC0.000 RTE F / REP ABC. 0.000 RTE F / REP ABC. 0.000 RTE F / REP ABC. RTE F / REP ABC. 0.000 RTE F / REP ABC.	0.030 0.007 0.007 0.007 0.007 0.0015 0.004 0.004 0.009 0.009 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.001 0.001 0.001 0.001 0.001 0.001 0.001 0.001 0.001 0.001 0.001 0.001 0.001 0.001 0.002 0.002 0.002 0.002 0.001 0.002	-0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.150 0.000	0.075 0.150 0.075 0.150 0.075 0.150 0.150 0.150 0.150 0.150	0.007 0.015 0.004 0.009 -0.001 0.002 0.006 0.012 -0.011	
Val. POIN 2600 - P2 - L POIN 2600 - P3 - L POIN 2600 - P4 - L POIN 2600 - P5 - L POIN 2600 - P5 - L POIN 2600 - P5 - DF CALL POIN 2600 - P5 - DF CALL POIN 2610 - P1 - F POIN 2610 - P2 - F	0.000 RTE L / REP ABC0.000 P2 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 P3 - L=>X]-[DIST 260 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000 RTE L / REP ABC. 0.000 P4 - L=>X]-[DIST 260 0.000 RTE L / REP ABC0.000 RTE L / REP ABC. 0.000 P5 - L=>X]-[DIST 260 0.000 RTE F / REP ABC. 0.000 RTE F / REP ABC. 0.000 P1 - F=>X]-[DIST 261 0.000	0.030 0.007 0.007 0.007 0.007 0.001 0.004 0.004 0.009 0.009 0.006 0.006 0.006 0.006 0.006 0.001	-0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.075 0.000 -0.150 -0.150 0.000	0.075 0.150 0.075 0.150 0.075 0.150 0.150 0.150	0.007 0.015 0.004 0.009 -0.001 0.002 0.006 0.012	



SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 01.06.2021 - 12.00

Tol-

OPERATOR: IR

Actual

Nominal

DATE: 01/06/21 15:52:08 SOFTWARE: METROLOG X4V14

Tol+



State

Dill/F03	Nonnia	Actual	101-	101+	Dev.	ieilu.	State
=ABS([DIST 2610 - F	'2 - F=>X]-[DIST 2610	0 - P2 - F->X])*2					
Val.	0.000	0.033	0.000	0.300	0.033		✓
₼ DIST 2610 - P3 - F		'	-	'			
POIN 2610 - P3 - DR	TE E / REP ARC						
_		0.050	0.450	0.450	0.050		
dX	0.000	0.050	-0.150	0.150	0.050		✓
太 0.1 - DIST 2610 - P3 - F							
=ABS([DIST 2610 - F	3 - F=>X]-[DIST 2610	0 - P3 - F->X])*2					
_ \`\ Val.	0.000	0.099	0.000	0.300	0.099		~
	0.000	0.033	0.000	0.000	0.000		<u> </u>
POIN 2610 - P4 - DR	TE F / REP ABC.						
dX	0.000	-0.001	-0.150	0.150	-0.001		✓
♦ 0.1 - DIST 2610 - P4 - F		-	'	'	<u>'</u>	<u> </u>	
= ABS([DIST 2610 - F	4 E-> VI IDIST 2610	D4 E VI*9					
			0.000	0.000	0.000		
Val.	0.000	0.002	0.000	0.300	0.002		✓
∸ DIST 2610 - P5 - F							
POIN 2610 - P5 - DR	TE F / REP ABC.						
dX	0.000	0.061	-0.150	0.150	0.061		~
	0.000	0.001	-0.130	0.150	0.001		<u> </u>
🗴 0.1 - DIST 2610 - P5 - F							
= ABS([DIST 2610 - F	5 - F=>X]-[DIST 2610	0 - P5 - F->X])*2					
Val.	0.000	0.123	0.000	0.300	0.123		✓
× DIST 2610 - P1 - L							
	TEL/DED ADO						
POIN 2610 - P1 - DR							
dX	0.000	0.054	-0.150	0.150	0.054		✓
🗴 0.1 - DIST 2610 - P1 - L					,		
=ABS([DIST 2610 - F	1 - I =>X]-[DIST 2610) - P1 - I ->X1*2					
			0.000	0.200	0.400		
Val.	0.000	0.109	0.000	0.300	0.109		✓
≚ DIST 2610 - P2 - L							
POIN 2610 - P2 - DR	TE L / REP ABC.						
dX	0.000	0.041	-0.150	0.150	0.041		~
• 0.1 - DIST 2610 - P2 - L	3.000	0.071	0.700	0.100	3.071		
=ABS([DIST 2610 - F	'2 - L=>X]-[DIST 2610	0 - P2 - L->X])*2					
Val.	0.000	0.082	0.000	0.300	0.082		✓
→ DIST 2610 - P3 - L							
POIN 2610 - P3 - DR	TEL / DED ADC						
		1			1		
dX	-0.000	0.100	-0.150	0.150	0.100		\checkmark
🗴 0.1 - DIST 2610 - P3 - L							
= ABS([DIST 2610 - F	3 - L=>X1-IDIST 2610) - P3 - L->X1)*2					
Val.	0.000	0.199	0.000	0.300	0.199		
	0.000	0.199	0.000	0.300	0.199		✓
∸ DIST 2610 - P4 - L							
POIN 2610 - P4 - DR	TE L / REP ABC.						
dX	-0.000	0.041	-0.150	0.150	0.041		✓
	A I VIDIOTOGIC	D4 L V1*0					
= ABS([DIST 2610 - F							
Val.	0.000	0.083	0.000	0.300	0.083		✓
→ DIST 2610 - P5 - L							
POIN 2610 - P5 - DR	TE L / REP ARC						
		0.000	0.450	0.150	0.000		
dX	0.000	0.096	-0.150	0.150	0.096		✓
🗴 0.1 - DIST 2610 - P5 - L							
=ABS([DIST 2610 - F	5 - L=>X]-[DIST 2610) - P5 - L->X])*2					
Val.	0.000	0.192	0.000	0.300	0.192		~
⊥ PERP 2620 - P1	0.000	0.102	0.000	3.000	0.102		
	N ANI II C 7						
DRTE 2620 - P1(G)/I	LAN H - C-Zone						
Val.	0.000	0.028		0.200	0.028		✓
L PERP 2620 - P2							
■ DRTE 2620 - P2(G)/F	DIANILI C Zana						
				0.01			
Val.	0.000	0.022		0.200	0.022		✓
L PERP 2620 - P3							
L L 2020 - 3							
	PLAN H - C-7one						
■ DRTE 2620 - P3(G)/F		0.000		0.200	0.000		
■ DRTE 2620 - P3(G)/F Val.	PLAN H - C-Zone 0.000	0.083		0.200	0.083		~
■ DRTE 2620 - P3(G)/F Val. L PERP 2620 - P4	0.000	0.083		0.200	0.083		~
■ DRTE 2620 - P3(G)/F Val. L PERP 2620 - P4	0.000	0.083		0.200	0.083		~
■ DRTE 2620 - P3(G)/I Val. L PERP 2620 - P4 ■ DRTE 2620 - P4(G)/I	0.000 PLAN H - C-Zone						
■ DRTE 2620 - P3(G)/f Val. L PERP 2620 - P4 ■ DRTE 2620 - P4(G)/f Val.	0.000	0.083		0.200	0.083		✓ ✓
■ DRTE 2620 - P3(G)/f Val. L PERP 2620 - P4 ■ DRTE 2620 - P4(G)/f Val. L PERP 2620 - P5	0.000 PLAN H - C-Zone 0.000						
■ DRTE 2620 - P3(G)/f Val. L PERP 2620 - P4 ■ DRTE 2620 - P4(G)/f Val.	0.000 PLAN H - C-Zone 0.000						
DRTE 2620 - P3(G)/f Val. PERP 2620 - P4 DRTE 2620 - P4(G)/f Val. PERP 2620 - P5 DRTE 2620 - P5(G)/f	0.000 PLAN H - C-Zone	0.031		0.200	0.031		~
■ DRTE 2620 - P3(G)/f Val. PERP 2620 - P4 ■ DRTE 2620 - P4(G)/f Val. PERP 2620 - P5 ■ DRTE 2620 - P5(G)/f Val.	0.000 PLAN H - C-Zone 0.000						
■ DRTE 2620 - P3(G)/f Val. PERP 2620 - P4 ■ DRTE 2620 - P4(G)/f Val. PERP 2620 - P5 ■ DRTE 2620 - P5(G)/f Val. Val.	0.000 PLAN H - C-Zone 0.000 PLAN H - C-Zone 0.000	0.031		0.200	0.031		~
■ DRTE 2620 - P3(G)/f Val. PERP 2620 - P4 ■ DRTE 2620 - P4(G)/f Val. PERP 2620 - P5 ■ DRTE 2620 - P5(G)/f Val.	0.000 PLAN H - C-Zone 0.000 PLAN H - C-Zone 0.000	0.031		0.200	0.031		✓
■ DRTE 2620 - P3(G)/f Val. PERP 2620 - P4 ■ DRTE 2620 - P4(G)/f Val. PERP 2620 - P5 ■ DRTE 2620 - P5(G)/f Val. Val.	0.000 PLAN H - C-Zone 0.000 PLAN H - C-Zone 0.000	0.031	-0.050	0.200	0.031		~
■ DRTE 2620 - P3(G)/f Val. DRTE 2620 - P4 DRTE 2620 - P4(G)/f Val. PERP 2620 - P5 DRTE 2620 - P5(G)/f Val. DIST 2630 DRTE L-1 - DRTE L-1	0.000 PLAN H - C-Zone 0.000 PLAN H - C-Zone 0.000 2 / REP ABC.	0.031	-0.050	0.200	0.031		✓
■ DRTE 2620 - P3(G)/f Val. DRTE 2620 - P4 DRTE 2620 - P4(G)/f Val. PERP 2620 - P5 DRTE 2620 - P5(G)/f Val. DRTE 2630 DRTE L-1 - DRTE L-1 D DIST 2640	0.000 PLAN H - C-Zone 0.000 PLAN H - C-Zone 0.000 2 / REP ABC. 7.180	0.031 0.078 7.100	-0.050	0.200	0.031		✓
■ DRTE 2620 - P3(G)/f Val. DRTE 2620 - P4 DRTE 2620 - P4(G)/f Val. PERP 2620 - P5 DRTE 2620 - P5(G)/f Val. DIST 2630 DRTE L-1 - DRTE L-2 D DRTE 2640 - 2 - DRTE	0.000 PLAN H - C-Zone 0.000 PLAN H - C-Zone 0.000 2 / REP ABC. 7.180 TE 2640 - 1 / REP AB	0.031 0.078 7.100 C.		0.200	0.031	-0.030	×
■ DRTE 2620 - P3(G)/f Val. PERP 2620 - P4 ■ DRTE 2620 - P4(G)/f Val. PERP 2620 - P5 ■ DRTE 2620 - P5(G)/f Val. NOTE 2630 ■ DRTE L-1 - DRTE L-1 D DIST 2640	0.000 PLAN H - C-Zone 0.000 PLAN H - C-Zone 0.000 2 / REP ABC. 7.180	0.031 0.078 7.100	-0.050	0.200	0.031		✓



SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 01.06.2021 - 12.00

Tol-

OPERATOR: IR

Actual

Nominal

DATE: 01/06/21 15:52:08 SOFTWARE: METROLOG X4V14

Tol+



State

DITT 2600 - F	*) DIST 2650	iai Actuai	101-	101+	Dev.	Teriu.	State
DIST 2800 - F. DIST 2		c.					
DIST 2800 - F 0.000			-0.050	0.050	-0.012		. /
■ DRTE 2940-MID. DRTE F, REPABC. Oxon 0.009 0.		5.000	0.000	0.000	0.012		
DIST 2270 - MPP - 1 - POIN 2270 - MPP - 2 / REP ABC. POIN 270 - SPOIN 259 - POIN 259		ARC .					
SYMMETRY 0.1 - DIST 2860			0.050	0.050	0.020		,
BASSIDIST 2800 - F-DRITI/DIST 2800 - F-DRITI/PS 2800 - F-DRITI/P		0.029	-0.030	0.030	0.029		<u> </u>
Val		OT 0000 F B' (41)**0					
DIST 2660 - L DIST 2760 - MID - DRITE L / REP ABC. 0.000			0.000	0.400	0.050		
■ ORITE 2840 - MID - DRITE L / REP ABC.		0.058	0.000	0.100	0.058		✓
D 0.000							
SYMMETRY 0.1 - DIST 2560 - L-SDIST 1/DIST 2560 - L-SDIST 2760	DRTE 2640 - MID - DRTE L / REP	ABC.				_	
	D 0.0	0.020	-0.050	0.050	0.020		✓
Val. 0.000 0.039 0.000 0.100 0.039	SYMMETRY 0.1 - DIST 2660 - L		·		•		
DIST 2710 - MP6	=ABS([DIST 2660 - L=>Dist1]-[DIST 2660 - Dist1]-[DIST 2660 - D	ST 2660 - L->Dist1])*2					
DIST 2710 - MP6	Val. 0.0	0.039	0.000	0.100	0.039		/
■ PON 2710 - MP6 - 1 - PON 2710 - MP6 - 27 REP ABC. 22 \$4.200 \$4.201 \$5.4201							<u> </u>
DIST 2710 - MP - 1 - PCNN 2710 - MP - 2 REP ABC.		- MP6 - 2 / REP ARC					
DIST 2710 - MP7 POIN 2710 - MP7 - 1 - POIN 2710 - MP7 - 2 / REP ABC. dZ			0.050	0.200	0.033		,
■ POIN 2710 - MP7 - 1 - POIN 2710 - MP7 - 2 / REP ABC. d2		34.177	-0.030	0.200	-0.023		<u> </u>
DIST 2710 - MPS							
DIST 2710 - MPP				1			
■ PON 2710 - MP8 - 1 - PON 2710 - MP8 - 2 / REP ABC. 0Z 54.200 54.256 -0.020 0.050 -0.023 -0.050 DIST 2750 -0.000 -0.023 -0.050 -0.023 -0.0		00 54.384	-0.100	0.550	0.184		✓
DIST 2750 S4.200 S4.256 -0.020 0.050 -0.023							
DIST 2750	POIN 2710 - MP8 - 1 - POIN 2710	- MP8 - 2 / REP ABC.					
DIST 2750	dZ 54.2	00 54.256	-0.020	0.200	0.056		
■ POIN 2780 - 3 - POIN 0.69 / REP ABC.	DIST 2750						
SYMMETRY O. 10ST 2750 - VALUE O. 10ST 2750 - VAL		ABC.					
SYMMETRY 0.1 - DIST 2750 Val. 0.000 0.046 0.000 0.100 0.046			-0.050	0.050	-0 023		
■ ABS(DIST 2750 - X - Z - Z - DIST 2750 - X - Z - Z - Z - Z - Z - Z - Z		-0.023	-0.000	0.000	-0.023		<u> </u>
DIST 2750 - K	•	2 . 71*0					
DIST 2750 - K POIN 2780 - POIN 2500 - P3 - X / REP ABC. 0.000 0.010 -0.050 0.050 0.010	_	. =-	9.995	0.100		<u> </u>	
■ POIN 2780 - 3 - POIN 2500 - P3 - X / REP ABC. dZ 0.000 0.010 0.021 0.000 0.010 0.021 0.000 0.021 0.022 0.000 0.021 0.022 0.000 0.021 0.022 0.022 0.000 0.022 0.02		0.046	0.000	0.100	0.046		✓
OZ O.000 O.010 O.050 O.050 O.010 O.010 O.021 O.000 O.021 O.020 O.025	↑ DIST 2750 - K						
SYMMETRY 0.1 - DIST 2750 - K =>ZI-[DIST 2750 - K >Z])*2	POIN 2780 - 3 - POIN 2500 - P3 -	X / REP ABC.					
BABS(DIST 2750 - K=>Z - DIST 2750 - K>Z)*2 Val. 0.000 0.021 0.000 0.100 0.021	dZ -0.0	0.010	-0.050	0.050	0.010		✓
BABS(DIST 2750 - K=>Z - DIST 2750 - K>Z)*2 Val. 0.000 0.021 0.000 0.001	SYMMETRY 0.1 - DIST 2750 - K						
Val. 0.000 0.021 0.000 0.100 0.021	•	2750 - K->71)*2					
DIST 2780			0.000	0.100	0.021		. /
POIN 2760 - POIN D.69 / REP ABC. dZ		0.021	0.000	0.100	0.021		
ACZ		0					
SYMMETRY 0.1 - DIST 2760 ■ ABS([DIST 2760-Z]-[DIST 2760-Z])*2			0.050	0.050			
■ ABS([DIST 2760->Z]-[DIST 2760->Z]-)2 Val.		0.015	-0.050	0.050	-0.015		<u> </u>
Val. 0.000 0.031 0.000 0.100 0.031	-						
DIST 2760 - K POIN 2500 - POIN 2500	=ABS([DIST 2760=>Z]-[DIST 2760)->Z])*2					
POIN 2760 - POIN 2500 - P3 - X / REP ABC. dZ	Val. 0.0	0.031	0.000	0.100	0.031		✓
Company	¹₁ DIST 2760 - K				•		
SYMMETRY 0.1 - DIST 2760 - K ■ ABS([DIST 2760 - K=>Z]-[DIST 2760 - K->Z])*2	POIN 2760 - POIN 2500 - P3 - X /	REP ABC.					
SYMMETRY 0.1 - DIST 2760 - K ■ ABS([DIST 2760 - K=>Z]-[DIST 2760 - K->Z])*2	dZ -0.0	0.018	-0.050	0.050	0.018		/
■ ABS([DIST 2760 - K=>Z]-[DIST 2760 - K->Z])*2 Val	l l	3.0.0		*****			·
Val. 0.000 0.036 0.000 0.100 0.036		2760 - K-\71)*2					
DIST 2770 POIN 2770 - 1 - POIN 2770 - 2 / REP ABC.	_		0.000	0.100	0.026		
□ POIN 2770 - 1 - POIN 2770 - 2 / REP ABC. □ D 23.190 23.284 -0.050 0.050 0.094 0.044 ★ □ DIST 2780 □ POIN 2780 - 1 - POIN 2780 - 2 / REP ABC. □ D 23.150 23.185 -0.050 0.050 0.035 ★ □ POIN D-2 - POIN D-1 / REP ABC. □ POIN D-2 - POIN D-1 / REP ABC. □ POIN 2800 - 1 - POIN 2800 - 2 / REP ABC. □ D 23.850 24.038 -0.150 0.150 0.150 0.188 0.038 ★ □ DIST 2820 - P1 □ POIN D-9 POIN 2820 - P1 / REP ABC. □ D 23.850 24.038 -0.150 0.150 0.150 0.163 ★ □ TRUE POSITION 0.3 - DIST 2820 - P1 -> Z], "2 □ Val. 0.000 0.125 0.000 0.300 0.125 ★ □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC.		0.036	0.000	0.100	0.036		
DIST 2780 ■ POIN 2780 - 1 - POIN 2780 - 2 / REP ABC. D							
DIST 2780 POIN 2780 - 1 - POIN 2780 - 2 / REP ABC. D							
■ POIN 2780 - 1 - POIN 2780 - 2 / REP ABC. D 23.150 23.185 -0.050 0.050 0.035 ✓ DIST 2790 ■ POIN D-2 - POIN D-1 / REP ABC. dZ 21.600 21.570 -0.050 0.050 -0.030 ✓ DIST 2800 ■ POIN 2800 - 1 - POIN 2800 - 2 / REP ABC. D 23.850 24.038 -0.150 0.150 0.188 0.038 ✓ DIST 2820 - P1 ■ POIN D.69 - POIN 2820 - P1 / REP ABC. dZ 8.000 7.937 -0.150 0.150 -0.063 ✓ TRUE POSITION 0.3 - DIST 2820 - P1 ■ ABS([DIST 2820 - P1 =>Z]-[DIST 2820 - P1->Z])*2 Val. 0.000 0.125 0.000 0.300 0.125 ✓ TRUE POSITION 0.3 - DIST 2820 - P2 / REP ABC. dZ 4.000 3.971 -0.150 0.150 -0.029 ✓ TRUE POSITION 0.3 - DIST 2820 - P2 ■ ABS([DIST 2820 - P2=>Z]-[DIST 2820 - P2->Z])*2	D 23.1	90 23.284	-0.050	0.050	0.094	0.044	X
D 23.150 23.185 -0.050 0.050 0.055	1 DIST 2780	•					
D 23.150 23.185 -0.050 0.050 0.055	POIN 2780 - 1 - POIN 2780 - 2 / R	EP ABC.					
□ POIN D-2 - POIN D-1 / REP ABC. □ DIST 2800 □ POIN 2800 - 1 - POIN 2800 - 2 / REP ABC. □ D 23.850 24.038 -0.150 0.150 0.150 0.188 0.038 ★ □ DIST 2820 - P1 □ POIN D.69 - POIN 2820 - P1 / REP ABC. □ DIST 2820 - P1 □ POIN D.69 - POIN 2820 - P1 / REP ABC. □ DIST 2820 - P1 □ POIN D.69 - POIN 2820 - P1 REP ABC. □ DIST 2820 - P1 □ = ABS([DIST 2820 - P1 = >Z]-[DIST 2820 - P1 ->Z])*2 □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC. □ DIST 2820 - P2 □ POIN D.69 - POIN 2820 - P2 / REP ABC.			-0.050	0.050	0.035		V
■ POIN D-2 - POIN D-1 / REP ABC. dZ		20.100	0.000	0.000	5.000		
DIST 2800							
DIST 2800 POIN 2800 - 1 - POIN 2800 - 2 / REP ABC. D			0.050	0.050	0.000		
POIN 2800 - 1 - POIN 2800 - 2 / REP ABC. D		21.5/0	-0.050	0.050	-0.030		
D 23.850 24.038 -0.150 0.150 0.188 0.038 ★ DIST 2820 - P1 POIN D.69 - POIN 2820 - P1 / REP ABC. dZ 8.000 7.937 -0.150 0.150 -0.063							
DIST 2820 - P1 POIN D.69 - POIN 2820 - P1 / REP ABC. dZ							
■ POIN D.69 - POIN 2820 - P1 / REP ABC. AZ		50 24.038	-0.150	0.150	0.188	0.038	X
■ POIN D.69 - POIN 2820 - P1 / REP ABC. AZ	DIST 2820 - P1						
dZ 8.000 7.937 -0.150 0.150 -0.063 TRUE POSITION 0.3 - DIST 2820 - P1 ■ =ABS([DIST 2820 - P1=>Z]-[DIST 2820 - P1->Z])*2 Val. 0.000 0.125 0.000 0.300 0.125 DIST 2820 - P2 POIN D.69 - POIN 2820 - P2 / REP ABC. dZ 4.000 3.971 -0.150 0.150 -0.029 TRUE POSITION 0.3 - DIST 2820 - P2 ■ =ABS([DIST 2820 - P2=>Z]-[DIST 2820 - P2->Z])*2		P ABC.					
TRUE POSITION 0.3 - DIST 2820 - P1 = ABS([DIST 2820 - P1=>Z]-[DIST 2820 - P1->Z])*2 Val.			-0.150	0.150	-0.063		
■ =ABS([DIST 2820 - P1=>Z]-[DIST 2820 - P1->Z])*2 Val.			0.100	3.130	0.000		
Val. 0.000 0.125 0.000 0.300 0.125 ✓ DIST 2820 - P2 ■ POIN D.69 - POIN 2820 - P2 / REP ABC. ✓							
DIST 2820 - P2 POIN D.69 - POIN 2820 - P2 / REP ABC. dZ						_	
■ POIN D.69 - POIN 2820 - P2 / REP ABC. dZ		0.125	0.000	0.300	0.125		~
dZ	☐ DIST 2820 - P2						
dZ	POIN D.69 - POIN 2820 - P2 / RE	P ABC.					
N TRUE POSITION 0.3 - DIST 2820 - P2 ■ =ABS([DIST 2820 - P2=>Z]-[DIST 2820 - P2->Z])*2			-0.150	0.150	-0.029		
= ABS([DIST 2820 - P2=>Z]-[DIST 2820 - P2->Z])*2			000	500	0.020		
vai. 0.000 0.059 0.000 0.300 0.059			0.000	0.000	0.050		
	vai. 0.0	0.059	0.000	0.300	0.059		
	vai. 0.0	0.059	0.000	0.300	0.059		



SITE: TRP Control Equipment: QC_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 01.06.2021 - 12.00

OPERATOR: IR

DATE: 01/06/21 15:52:08 SOFTWARE: METROLOG X4V14



Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
r∸ DIST 2820 - P3	<u>'</u>	<u>'</u>		· ·	· · · · · · · · · · · · · · · · · · ·	<u>"</u>	
POIN D.69 - POIN 2	820 - P3 / REP ABC.						
dZ	0.000	0.013	-0.150	0.150	0.013		~
★ TRUE POSITION 0.3 - D A section 1.3 - D A	IST 2820 - P3	•					
	P3=>Z]-[DIST 2820 - P3	->Z])*2				_	
Val.	0.000	0.026	0.000	0.300	0.026		✓
r [™] DIST 2820 - P4							
POIN 2820 - P4 - P	OIN D.69 / REP ABC.						
dZ	4.000	3.962	-0.150	0.150	-0.038		~
À TRUE POSITION 0.3 - 🛭							
	P4=>Z]-[DIST 2820 - P4					_	
Val.	0.000	0.075	0.000	0.300	0.075		✓
r [≚] i DIST 2820 - P5							
POIN 2820 - P5 - P	OIN D.69 / REP ABC.					_	
dZ	8.000	7.938	-0.150	0.150	-0.062		~
À TRUE POSITION 0.3 - 🛭							
	P5=>Z]-[DIST 2820 - P5					_	
Val.	0.000	0.123	0.000	0.300	0.123		✓