

SITE: TRP Control Equipment: QC\_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 24.08.2021 - 10:00 - inj 2

OPERATOR: CA

DATE: 24/08/21 14:15:49 SOFTWARE: METROLOG X4V14



## **RESULTS**

Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
⊙ S10 - CERC 710 - C							
Inters. PLAN A - CYL (	C.						
Diam.	4.000	3.907	-0.100	0.000	-0.093		<b>✓</b>
⊙ S10 - CERC 710 - B	'	•	<u> </u>	<u> </u>	<u> </u>		
Inters. PLAN A - CYL I	В.						
Diam.	4.000	3.955	-0.100	0.000	-0.045		<b>✓</b>
✓ S07 - PLTE 450					*****		Y
PLAN A C							
Val.	0.000	0.197		0.250	0.197		
	0.000	0.197		0.230	0.197		<b>✓</b>
✓ S04 - PLTE 455							
PLAN J C		!		1			
Val.	0.000	0.109		0.200	0.109		<b>✓</b>
r S15 - DIST 470 - 11.25							
DRTE B-C - POIN 470	) - 11.25 / REP AB(	D.					
dZ	11.250	11.274	-0.075	0.075	0.024		<b>✓</b>
★ TRUE POSITION 0.15 - S <sup>-</sup>	15 - DIST 470 - 11.	25					
_		- DIST 470 - 11.25->Z])*2					
Val.	0.000	0.047	0.000	0.150	0.047		<b>✓</b>
	0.000	0.047	0.000	0.130	0.047		<b>V</b>
S15 - DIST 470 - 33.65	00.05 / 555	2					
DRTE B-C - POIN 470							
dZ	33.650	33.659	-0.130	0.130	0.009		<b>✓</b>
★ TRUE POSITION 0.15 - S <sup>2</sup>	15 - DIST 470 - 33.	65					
= =ABS([S15 - DIST 470	0 - 33.65=>Z]-[S15	- DIST 470 - 33.65->Z])*2	2				
Val.	0.000	0.018	0.000	0.260	0.018		<b>✓</b>
S18 - DIST 550	,,,,,,				,,,,,,		
PLAN A - POIN 550 / I	REP ARC						
_		6 200	0.400	0.400	0.400	0.00	0
D	6.100	6.208	-0.100	0.100	0.108	0.00	8 ×
× S06 - DIST 1280							
POIN 1280 - 1 - POIN	1280 - 2 / REP AB	C.					
D	12.700	12.654	-0.100	0.100	-0.046		<b>~</b>
S16 - DIST 1300 - LEFT	'	<u>'</u>	'	ļ.	'		
PLAN H - POIN 1300	- LEFT / REP ABC						
dY	12.015	12.063	-0.050	0.050	0.048		<b>✓</b>
് S16 - DIST 1300 - RIGHT	12.010	12.000	-0.000	0.000	0.040	<u> </u>	<b>V</b>
	DIOLIT / DED AD	3					
PLAN H - POIN 1300			0.050	0.070	0.044		
dY	12.015	12.029	-0.050	0.050	0.014		<b>✓</b>
S19 - DIST 1400 - P6 - DC	NWN						
PLAN J - POIN 1400 -	P6 - DOWN / REF	PABC.					
dY	0.850	0.830	-0.100	0.110	-0.020		<b>✓</b>
S19 - DIST 1400 - P6 - UP	)						
PLAN J - POIN 1400 -		C					
dY	0.850	0.790	-0.100	0.110	-0.060		<b>✓</b>
		0.790	-0.100	0.110	-0.000		<b>V</b>
S19 - DIST 1400 - P7 - DC							
■ PLAN J - POIN 1400 -							
dY	0.850	0.799	-0.100	0.110	-0.051		<b>✓</b>
🖰 S19 - DIST 1400 - P7 - UP							
PLAN J - POIN 1400 -	P7 - UP / REP AB	C.					
dY	0.850	0.823	-0.100	0.110	-0.027		<b>✓</b>
S05 - DIST 1410 - P6 - 12.							
POIN 2500 - P3 - X - F		8 / REP ABC					
dZ	12.800	12.795	-0.150	0.150	-0.005		
		12.790	-0.130	0.100	-0.003		<b>✓</b>
S05 - DIST 1410 - P6 - 3.4		/ DED 45 *					
POIN 2500 - P3 - Z - F							
dX	3.400	3.297	-0.150	0.150	-0.103		<b>✓</b>
★ TRUE POSITION 0.3 X <sup>2</sup> +	Y <sup>2</sup> - S05 - DIST 1	410 - P6					
= [SQRT X^2+Y^2 - S0							
Val.	0.000	0.205	0.000	0.300	0.205		<b>✓</b>
S05 - DIST 1410 - P7 - 9.6		5.250	0.000	0.000	0.200		
		/ DED ARC					
POIN 1410 - 2 - 9.6 - I			0.450	0.450	0.000		
dZ	9.600	9.660	-0.150	0.150	0.060		<b>✓</b>
S05 - DIST 1410 - P7 - 3.4							
POIN 2500 - P3 - Z - F	POIN 1410 - 2 - 3.4	/ REP ABC.					
dX	3.400	3.300	-0.150	0.150	-0.100		<b>✓</b>
★ TRUE POSITION 0.3 X^2+	-Y^2 - S05 - DIST 1	410 - P7					
=[SQRT X^2+Y^2 - S0							
Val.	0.000	0.234	0.000	0.300	0.234		
	0.000	0.234	0.000	0.300	0.234		<b>✓</b>
S01 - 1690 - MP10							
POIN 109 - MP10 - 2							
dX	109.000	109.009	-0.100	0.200	0.009		<b>✓</b>
-							



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OPERATOR: CA

Actual

Nominal

DATE: 24/08/21 14:15:49 SOFTWARE: METROLOG X4V14

Tol+

Tol-



State

S01 - 1690 - MP12	-0.057
dx	-0.078
S01 - 1690 - MP12	-0.078
■ POIN 109 - MP12 - 2 - POIN 109 - MP12 - 1 / REP ABC.    dX	0.143
108.922   -0.100   0.200   -0.00   -	0.143
S02 - 1730	0.143
■ POIN 1730 - 2 - POIN 1730 - 1 / REP ABC.  dZ   56.700   56.843   -0.100   0.300   0.1  S03 - DIST 1880 ■ PLAN 1880 - POIN 1880 - 3 / REP ABC.  dY   43.500   43.509   -0.100   0.150   0.0  S17 - 1980 - 1 ■ PLAN A-1 - POIN 1680 - 1 - 3 / REP ABC.  D   7.000   6.945   -0.130   0.000   -0.0  S17 - 1980 - 2 ■ PLAN A-2 - POIN 1980 - 2 - 3 / REP ABC.  D   7.000   6.997   -0.100   0.000   -0.0  S17 - 1980 - 3 ■ PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC.  D   7.000   6.918   -0.100   0.000   -0.000    S17 - 1980 - 4 ■ PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.	-0.003
■ POIN 1730 - 2 - POIN 1730 - 1 / REP ABC.  dZ   56.700   56.843   -0.100   0.300   0.1  S03 - DIST 1880 ■ PLAN 1880 - POIN 1880 - 3 / REP ABC.  dY   43.500   43.509   -0.100   0.150   0.0  S17 - 1980 - 1 ■ PLAN A-1 - POIN 1680 - 1 - 3 / REP ABC.  D   7.000   6.945   -0.130   0.000   -0.0  S17 - 1980 - 2 ■ PLAN A-2 - POIN 1980 - 2 - 3 / REP ABC.  D   7.000   6.997   -0.100   0.000   -0.0  S17 - 1980 - 3 ■ PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC.  D   7.000   6.918   -0.100   0.000   -0.000    S17 - 1980 - 4 ■ PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.	-0.003
dZ	-0.003
↑ S03 - DIST 1880 ■ PLAN 1880 - POIN 1880 - 3 / REP ABC. dY	-0.003
■ PLAN 1880 - POIN 1880 - 3 / REP ABC.    dY	-0.055
dY	-0.055
S17 - 1980 - 1 PLAN A-1 - POIN 1680 - 1 - 3 / REP ABC. D 7.000 6.945 -0.130 0.000 -0.00 S17 - 1980 - 2 PLAN A-2 - POIN 1980 - 2 - 3 / REP ABC. D 7.000 6.997 -0.100 0.000 -0.00 S17 - 1980 - 3 PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC. D 7.000 6.918 -0.100 0.000 -0.00 S17 - 1980 - 4 PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.	-0.055
■ PLAN A-1 - POIN 1680 - 1 - 3 / REP ABC.  D   7.000  6.945  -0.130  0.000  -0.000   \$17 S17 - 1980 - 2  ■ PLAN A-2 - POIN 1980 - 2 - 3 / REP ABC.  D   7.000  6.997  -0.100  0.000  -0.000   \$18 S17 - 1980 - 3  ■ PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC.  D   7.000  6.918  -0.100  0.000  -0.000   \$18 S17 - 1980 - 4  ■ PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.	-0.003
D 7.000 6.945 -0.130 0.000 -0.000 -0.000	-0.003
S17 - 1980 - 2 PLAN A-2 - POIN 1980 - 2 - 3 / REP ABC. D 7.000 6.997 -0.100 0.000 -0.00 S17 - 1980 - 3 PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC. D 7.000 6.918 -0.100 0.000 -0.00 S17 - 1980 - 4 PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.	-0.003
■ PLAN A-2 - POIN 1980 - 2 - 3 / REP ABC.  D 7.000 6.997 -0.100 0.000 -0.00  1 S17 - 1980 - 3 ■ PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC.  D 7.000 6.918 -0.100 0.000 -0.00  1 S17 - 1980 - 4 ■ PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.	
D     7.000     6.997     -0.100     0.000     -0.0       *↑ S17 - 1980 - 3     PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC.     -0.100     0.000     -0.0       D     7.000     6.918     -0.100     0.000     -0.0       *↑ S17 - 1980 - 4     PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.	
D 7.000 6.997 -0.100 0.000 -0.00  1 S17 - 1980 - 3  ■ PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC.  D 7.000 6.918 -0.100 0.000 -0.00  1 S17 - 1980 - 4  ■ PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.	
1 S17 - 1980 - 3	
■ PLAN A-3 - POIN 1980 - 3 - 3 / REP ABC.  D	-0.082
D 7.000 6.918 -0.100 0.000 -0.00	-0.082
¬ S17 - 1980 - 4 ■ PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.	-0.082
■ PLAN A-4 - POIN 1980 - 4 - 3 / REP ABC.	
DI 7,000 6,889 -0.110 0,000 0.4	
	-0.111 -0.001
<sup>4</sup> 1 S17 - 1980 - 5	
■ PLAN A-5 - POIN 1980 - 5 - 3 / REP ABC.	
	0.022
*1 S17 - 1980 - 6	
PLAN A-6 - POIN 1980 - 6 - 3 / REP ABC.	
	-0.102
	-0.102 <b>-</b> 0.002 ×
<sup>4</sup> ¬ S13 - DIST 2310 - MP1 - UP	
POIN 2310 - MP1 - UP - 1 - POIN 2310 - MP1 - UP - 2 / REP ABC.	
D 9.950 9.963 -0.050 0.150 0.0	0.013
1 S13 - DIST 2310 - MP1 - DOWN	
■ POIN 2310 - MP1 - DOWN - 1 - POIN 2310 - MP1 - DOWN - 2 / REP ABC.	
	0.001
*1 S13 - DIST 2310 - MP4 - UP	0.001
POIN 2310 - MP4 - UP - 1 - POIN 2310 - MP4 - UP - 2 / REP ABC.	
	0.425
<sup>2</sup> ₁ S13 - DIST 2310 - MP4 - DOWN	0.135
■ POIN 2310 - MP4 - DOWN - 1 - POIN 2310 - MP4 - DOWN - 2 / REP ABC.	0.135
	0.135
D 9.950 10.077 -0.050 0.150 0.1	
D 9.950 10.077 -0.050 0.150 0.1 1 S08 - DIST 2420 - MP1 ■ POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.	0.127
D      9.950      10.077      -0.050      0.150      0.1       1 S08 - DIST 2420 - MP1     POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.     D      25.900      26.032      -0.100      0.150      0.150      0.1	
D          9.950          10.077          -0.050          0.150          0.1           *1 S08 - DIST 2420 - MP1         POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.         D          25.900          26.032          -0.100          0.150          0.1           *1 S08 - DIST 2420 - MP2         -0.100          0.150          0.1         0.1	0.127
D     9.950     10.077     -0.050     0.150     0.1       1 S08 - DIST 2420 - MP1     POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.     D     25.900     26.032     -0.100     0.150     0.1       1 S08 - DIST 2420 - MP2     POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.	0.127
D         9.950         10.077         -0.050         0.150         0.1           1 S08 - DIST 2420 - MP1         POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.         D         0.150         0.150         0.1           2 S08 - DIST 2420 - MP2         POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.         0.150         0.150         -0.00         -0.00         0.150         -0.00         -0.00         0.150         -0.00         -	0.127
D         9.950         10.077         -0.050         0.150         0.1           1 S08 - DIST 2420 - MP1         POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.         0         0         0.150         0.1           2 S08 - DIST 2420 - MP2         POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.         0         0.150         0.150         -0.0           3 S09 - DIST 2500 - P1 - 8         POIN 2500 - D1 - 8         -0.100         0.150         -0.00	0.127
D 9.950 10.077 -0.050 0.150 0.1  S08 - DIST 2420 - MP1 POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC. D 25.900 26.032 -0.100 0.150 0.1  S08 - DIST 2420 - MP2 POIN 2420 - MP2 POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC. D 25.900 25.885 -0.100 0.150 -0.0  Solution Solu	0.127
D 9.950 10.077 -0.050 0.150 0.1  S08 - DIST 2420 - MP1 POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC. D 25.900 26.032 -0.100 0.150 0.1  S08 - DIST 2420 - MP2 POIN 2420 - MP2 POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC. D 25.900 25.885 -0.100 0.150 -0.00  S09 - DIST 2500 - P1 - 8 POIN 2500 - P1 - 8	0.127
D 9.950 10.077 -0.050 0.150 0.1  S08 - DIST 2420 - MP1 POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC. D 25.900 26.032 -0.100 0.150 0.1  S08 - DIST 2420 - MP2 POIN 2420 - MP2 POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC. D 25.900 25.885 -0.100 0.150 -0.0  S09 - DIST 2500 - P1 - 8 POIN 2500 - P1 - 8 POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC. dZ 8.000 7.929 -0.100 0.100 -0.00	0.127
D 9.950 10.077 -0.050 0.150 0.1  S08 - DIST 2420 - MP1 POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC. D 25.900 26.032 -0.100 0.150 0.1  S08 - DIST 2420 - MP2 POIN 2420 - MP2 POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC. D 25.900 25.885 -0.100 0.150 -0.0  S09 - DIST 2500 - P1 - 8 POIN 2500 - P1 - 8 POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC. dZ 8.000 7.929 -0.100 0.100 -0.00	0.127
D 9.950 10.077 -0.050 0.150 0.1  308 - DIST 2420 - MP1  POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.1  POIN 2420 - MP2  POIN 2420 - MP2  POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.6  S09 - DIST 2500 - P1 - 8  POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.6  S09 - DIST 2500 - P1 - 0  POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 S08 - DIST 2420 - MP1  ■ POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.1  3 S08 - DIST 2420 - MP2  ■ POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.805 -0.100 0.150 -0.60  3 S09 - DIST 2500 - P1 - 8  ■ POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.60  3 S09 - DIST 2500 - P1 - 0  ■ POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.033 -0.100 0.100 0.000	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 S08 - DIST 2420 - MP1  POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.1  3 S08 - DIST 2420 - MP2  POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.50  3 S09 - DIST 2500 - P1 - 8  POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.00  S S09 - DIST 2500 - P1 - 0  POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.003 -0.000 0.000 0.000	0.127
D 9.950 10.077 -0.050 0.150 0.1  308 - DIST 2420 - MP1  POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.1  308 - DIST 2420 - MP2  POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.50  309 - DIST 2500 - P1 - 8  POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.00  309 - DIST 2500 - P1 - 0  POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.033 -0.100 0.100 0.000  TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1  = [SQRT X*2+Y*2 - S09 - DIST 2500 - P1-> Val]*2	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 S08 - DIST 2420 - MP1  POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.1  POIN 2420 - MP2  POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.0  Solution - P1 - 8  POIN 2500 - P1 - 8  POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.00  POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.033 -0.100 0.100 0.00  TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1  = [SQRT X*2+Y*2 - S09 - DIST 2500 - P1-> Val]*2  Val. 0.000 0.156 0.000 0.200 0.1	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 S08 - DIST 2420 - MP1  POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.1  POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.0  POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.0  POIN 2500 - P1 - 8  POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.00  POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.033 -0.100 0.100 0.00  TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1  = [SQRT X*2+Y*2 - S09 - DIST 2500 - P1 -> Val]*2  Val. 0.000 0.156 0.000 0.200 0.1	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 S08 - DIST 2420 - MP1  POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.1  POIN 2420 - MP2  POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.0  POIN 2500 - P1 - 8  POIN 2500 - P1 - 8  POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.0  POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  X S09 - DIST 2500 - P1 - 0  POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1  SO9 - DIST 2500 - P3 - Z - POIN 2500 - P1 - N / REP ABC.  N TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1  SO9 - DIST 2500 - P3 - X - POIN 2500 - P1 ->Val]*2  Val. 0.000 0.156 0.000 0.200 0.156  POIN 2500 - P3 - X - POIN 2500 - P2 - 4  POIN 2500 - P3 - X - POIN 2500 - P2 - 4 / REP ABC.	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 S08 - DIST 2420 - MP1  POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.1  POIN 2420 - MP2  POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.0  POIN 2500 - P1 - 8  POIN 2500 - P1 - 8  POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.0  POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  X S09 - DIST 2500 - P1 - 0  POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1  SO9 - DIST 2500 - P3 - Z - POIN 2500 - P1 - N / REP ABC.  N TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1  SO9 - DIST 2500 - P3 - X - POIN 2500 - P1 ->Val]*2  Val. 0.000 0.156 0.000 0.200 0.156  POIN 2500 - P3 - X - POIN 2500 - P2 - 4  POIN 2500 - P3 - X - POIN 2500 - P2 - 4 / REP ABC.	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 S08 - DIST 2420 - MP1  POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.1  POIN 2420 - MP2  POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.60  POIN 2500 - P1 - 8  POIN 2500 - P1 - 8  POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.60  POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.003 -0.100 0.100 0.000  TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1  = [SQRT X*2+Y*2 - S09 - DIST 2500 - P1 - Val]*2  Val. 0.000 0.156 0.000 0.200 0.100  POIN 2500 - P3 - X - POIN 2500 - P2 - 4  POIN 2500 - P3 - X - POIN 2500 - P2 - 4  POIN 2500 - P3 - X - POIN 2500 - P2 - 4  POIN 2500 - P3 - X - POIN 2500 - P2 - 4 / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.60	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 S08 - DIST 2420 - MP1  ■ POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.1  3 S08 - DIST 2420 - MP2  ■ POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.50  □ 25.900 25.885 -0.100 0.150 -0.50  □ 25.900 25.885 -0.100 0.150 -0.50  □ 25.900 P1 - 8 / REP ABC.  □ POIN 2500 - P1 - 8   REP ABC.  □ 2 8.000 7.929 -0.100 0.100 -0.00  □ POIN 2500 - P1 - 0   ■ POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  □ X	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 S08 - DIST 2420 - MP1  ■ POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.1  3 S08 - DIST 2420 - MP2  ■ POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.0  3 S09 - DIST 2500 - P1 - 8  ■ POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.0  3 S09 - DIST 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.033 -0.100 0.100 0.00  ■ TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1  ■ [SQRT X*2+Y*2 - S09 - DIST 2500 - P1 - Val]*2  Val. 0.000 0.156 0.000 0.200 0.1  3 S09 - DIST 2500 - P2 - 4  ■ POIN 2500 - P3 - X - POIN 2500 - P24 / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.00  3 S09 - DIST 2500 - P2 - 0  ■ POIN 2500 - P2 - 0 - POIN 2500 - P3 - Z / REP ABC.	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 S08 - DIST 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.150 0.1  3 S08 - DIST 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.00  3 S09 - DIST 2500 - P1 - 8  POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.00  3 S09 - DIST 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.033 -0.100 0.100 0.00  TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1  = [SQRT X*2+Y*2 - S09 - DIST 2500 - P1 -> Val]*2  Val. 0.000 0.156 0.000 0.200 0.100  3 S09 - DIST 2500 - P2 - 4  POIN 2500 - P3 - X - POIN 2500 - P24 / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.00  3 S09 - DIST 2500 - P2 - 0  POIN 2500 - P2 - 0 - POIN 2500 - P3 - Z / REP ABC.	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 088 - DIST 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.1  3 088 - DIST 2420 - MP2  POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.150 -0.0  3 099 - DIST 2500 - P1 - 8  POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.0  3 099 - DIST 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.003 -0.100 0.100 0.100 0.00  TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1  □ POIN 2500 - P3 - X - POIN 2500 - P1 - Val]*2  Val. 0.000 0.156 0.000 0.200 0.100  3 S09 - DIST 2500 - P2 - 4  □ POIN 2500 - P3 - X - POIN 2500 - P24 / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.0  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P24 / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.0  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P3 - Z / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.000 0.10	0.127
D 9.950 10.077 -0.050 0.150 0.1  \$\text{3}\ \ 508 - \text{DIST}\ 2420 - \text{MP1} - 1 - \text{POIN}\ 2420 - \text{MP1} - 2 / \text{REP}\ ABC.  \text{D} \ 25.900 \ 26.032 \ -0.100 \ 0.150 \	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 508 - DIST 2420 - MP1  ■ POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.150 0.1  3 508 - DIST 2420 - MP2  ■ POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 0.150 -0.0  3 509 - DIST 2500 - P1 - 8  ■ POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.0  3 509 - DIST 2500 - P1 - 0  ■ POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.033 -0.100 0.100 0.00  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1 - Val]*2  Val. 0.000 0.156 0.000 0.200 0.1  ¬ S09 - DIST 2500 - P2 - 4  ■ POIN 2500 - P3 - X - POIN 2500 - P24 / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.0  ¬ TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1 - Val]*2  Val. 0.000 3.960 -0.100 0.100 0.100 -0.0  ¬ TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P24 / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.00  ¬ TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P3 - Z / REP ABC.  dX 0.000 -0.001 0.100 0.100 0.100 -0.00  ¬ TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P3 - Z / REP ABC.  dX 0.000 -0.001 0.001 0.000 0.100 0.100 -0.00  ¬ TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P24 / REP ABC.  dX 0.000 -0.001 0.001 0.000 0.1	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 08 - DIST 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.150 0.1  3 08 - DIST 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.150 -0.0  3 09 - DIST 2500 - P1 - 8   POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.00  3 09 - DIST 2500 - P1 - 0   POIN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.033 -0.100 0.100 0.100 0.00  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1 -      FOIN 2500 - P3 - X - POIN 2500 - P1 - Val]*2	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 08 - DIST 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.15  3 08 - DIST 2420 - MP2  POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 -0.150 -0.0  3 09 - DIST 2500 - P1 - 8  POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.00  3 09 - DIST 2500 - P1 - 0  POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.033 -0.100 0.100 0.00  TRUE POSITION 0.2 X'2+Y'2 - S09 - DIST 2500 - P1 - Vai]*2  Val. 0.000 0.156 0.000 0.200 0.1  3 09 - DIST 2500 - P2 - 4  POIN 2500 - P3 - X - POIN 2500 - P2 - 4 / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.0  TRUE POSITION 0.2 X'2+Y'2 - S09 - DIST 2500 - P1 - Vai]*2  Val. 0.000 3.960 -0.100 0.100 0.100 -0.00  TRUE POSITION 0.2 X'2+Y'2 - S09 - DIST 2500 - P2 - 4 / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.00  TRUE POSITION 0.2 X'2+Y'2 - S09 - DIST 2500 - P3 - Z / REP ABC.  dX 0.000 -0.000 0.100 0.100 0.100 -0.000  TRUE POSITION 0.2 X'2+Y'2 - S09 - DIST 2500 - P3 - Z / REP ABC.  dX 0.000 -0.000 0.000 0.000 0.000 0.100 0.100 0.100 -0.000  TRUE POSITION 0.2 X'2+Y'2 - S09 - DIST 2500 - P2 - Vai]*2  Val. 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.200 0.100	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 S08 - DIST 2420 - MP1  ■ POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.150 0.1  3 S08 - DIST 2420 - MP2  ■ POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 0.150 -0.0  3 S09 - DIST 2500 - P1 - 8  ■ POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 0.100 -0.0  3 S09 - DIST 2500 - P1 - 0  ■ POIN 2500 - P3 - Z - POIN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.033 -0.100 0.100 0.00  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1  ■ [SQRT X*2+Y*2 - S09 - DIST 2500 - P1 - 2 / REP ABC.  Val. 0.000 0.156 0.000 0.200 0.1  3 S09 - DIST 2500 - P2 - 4  ■ POIN 2500 - P3 - X - POIN 2500 - P2 4 / REP ABC.  dZ 4.000 3.960 -0.100 0.100 -0.0  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P2 4 / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.0  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P2 4 / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.0  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P2 4 / REP ABC.  dX 0.000 -0.037 -0.100 0.100 -0.00  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P2 -    ■ [SQRT X*2+Y*2 - S09 - DIST 2500 - P2 - VAI]*2 VAI. 0.000 0.000 0.109 0.000 0.200 0.100  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P2 - VAI]*2 VAI. 0.000 0.109 0.000 0.200 0.100	0.127
D 9.950 10.077 -0.050 0.150 0.1  3 08 - DIST 2420 - MP1  ■ POIN 2420 - MP1 - 1 - POIN 2420 - MP1 - 2 / REP ABC.  D 25.900 26.032 -0.100 0.150 0.1  3 508 - DIST 2420 - MP2  ■ POIN 2420 - MP2 - 1 - POIN 2420 - MP2 - 2 / REP ABC.  D 25.900 25.885 -0.100 0.150 0.150 -0.6  3 509 - DIST 2500 - P1 - 8  ■ POIN 2500 - P3 - X - POIN 2500 - P1 - 8 / REP ABC.  dZ 8.000 7.929 -0.100 0.100 -0.6  3 509 - DIST 2500 - P1 - 0   P0IN 2500 - P1 - 0 / REP ABC.  dX 0.000 0.033 -0.100 0.100 0.100 0.6  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P1  ■ [SQRT X*2+Y*2 - S09 - DIST 2500 - P2 - 4 / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.6  3 S09 - DIST 2500 - P2 - 0  ■ POIN 2500 - P3 - X - POIN 2500 - P3 - Z / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.6  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P2  ■ POIN 2500 - P2 - 0  ■ POIN 2500 - P2 - 0  ■ POIN 2500 - P2 - 0  ■ POIN 2500 - P3 - Z / REP ABC.  dZ 4.000 3.960 -0.100 0.100 0.100 -0.6  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P2  ■ POIN 2500 - P2 - 0  ■ POIN 2500 - P2 - 0  ■ POIN 2500 - P3 - Z / REP ABC.  dX 0.000 -0.037 -0.100 0.100 -0.6  3 TRUE POSITION 0.2 X*2+Y*2 - S09 - DIST 2500 - P2  ■ [SQRT X*2+Y*2 - S09 - DIST 2500 - P2 - Val]*2  Val. 0.000 0.100 0.100 0.000 0.200 0.100  3 S09 - DIST 2500 - P4 - 4  ■ POIN 2500 - P4 - 4 - POIN 2500 - P3 - X / REP ABC.	0.127
D 9.950 10.077 -0.050 0.150 0.150 0.15  3 08 - DIST 2420 - MP1	0.127
D 9.950 10.077 -0.050 0.150 0.150 0.15  308 - DIST 2420 - MP1	0.127



SITE: TRP Control Equipment: QC\_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 24.08.2021 - 10:00 - inj 2

OPERATOR: CA

DATE: 24/08/21 14:15:49 SOFTWARE: METROLOG X4V14



DimProc   Montana   Actual   Tol-   Dev   Tend   State								
B   SORT / X26-YP2 - SORD - DEST 2000 - PS - VPI   DOUGH   D				Tol-	Tol+	Dev.	Tend.	State
Val.   0.000  0.146    0.000  0.200  0.146    0.000    0.000    0.146    0.000	★ TRUE POSITION 0	.2 X^2+Y^2 - S09 - DIS	T 2500 - P4	'	<u>'</u>			
Val.   0.000  0.146    0.000  0.200  0.146    0.000    0.000    0.146    0.000	=[SQRT X^2+Y	'^2 - S09 - DIST 2500 -	P4->Val]*2					
SSO_DIST_2000_PS_4   PON_2000_PS_4 X   REP ABC.   0.100				0.000	0.200	0.146		<b>✓</b>
PON 2900 - PS - 3 - PON 2900 - PS - X   PEP ABC			00	2.000		30		
S00 - DIST 2900 - PS - 0 PO - 200 PS - 2 FREP ABC   -0.100   -0.001   -0.	li i		- X / REP ARC					
Sign				-0.100	0.100	-0 048		
■ PON 2500 - P9 - 0 - PON 2500 - P9 - 2 / PREP ABC.			1.902	-0.100	0.100	-0.040		
TRUE POSITION 0 X X X Y - Y - X - S0 - DIST 2500 - PS - SUB 25	l' '		7 / DED 400					
FIRE POSITION 2 X29-YP - S99 - DIST 2500 - P5					1			
■ # SOAT X24*Y*2* 280 - DIST 2200 - PS-3VIII]2  **SOB - DIST 2250 - PT - DOWN  **PLAN J - PON 2500 - PT - DOWN / REP ABC.  **PLAN J - PON 2500 - PT - PON 2500 - PT - Z / REP ABC.  **PLAN J - PON 2500 - PT - Z / REP ABC.  **PLAN J - PON 2500 - PT - Z / REP ABC.  **PLAN J - PON 2500 - PT - Z / REP ABC.  **PLAN J - PON 2500 - PT - Z / REP ABC.  **PLAN J - PON 2500 - PT - Z / REP ABC.  **PLAN J - PON 2500 - PT - Z / REP ABC.  **PLAN J - PON 2500 - PT - Z / REP ABC.  **PLAN J - PON 2500 - PT - Z / REP ABC.  **PLAN J - PON 2500 - PT - Z / REP ABC.  **PLAN J - PON 2500 - PT - Z / REP ABC.  **PLAN J - PON 2500 - PT - Z / REP ABC.  **PLAN J - PON 2500 - PT - Z / REP ABC.  **PLAN J - PON 2500 - PT - Z / REP ABC.  **PLAN J - P				-0.100	0.100	-0.001		<b>✓</b>
Value   0.000   0.095   0.000   0.005     0.	TRUE POSITION 0	.2 X^2+Y^2 - S09 - DIS	T 2500 - P5					
PLAN J - PON 250 - P1 - DOWN   REP ABC	=[SQRT X^2+Y	'^2 - S09 - DIST 2500 -	P5->Val]*2					
PLAN   - POIN 250 - P1 - DOWN   REP ABC	Val.	0.000	0.095	0.000	0.200	0.095		<b>~</b>
I	് S20 - DIST 2530 - F	P1 - DOWN						
1.150	PLAN J - POIN	I 2530 - P1 - DOWN / F	REP ABC.					
PLAN   PON 250 - P1 - UP   REP ABC				-0.100	0.100	-0.018		
			2	0.100	0.100	0.0.0		·
1.150	l' '		ARC					
S20 - DIST 2530 - P2 - DOWN REP ABC.				0.400	0.400	0.024		
			1.116	-0.100	0.100	-0.034		
S20 - DIST 2530 - P2 - UP / REP ABC.   1.150	l' '		NED 400					
S20 - DIST 2530 - P2 - UP   EPAN J - POIN 2500 - P2 - UP / REP ABC.   dY								
■ PLAN J - POIN 2530 - P3 - DOWN			1.104	-0.100	0.100	-0.046		<b>✓</b>
1.150	S20 - DIST 2530 - F	P2 - UP						
1.150	PLAN J - POIN	1 2530 - P2 - UP / REP	ABC.					
S20 - DIST 2530 - P3 - DOWN / REP ABC.	_			-0.100	0.100	-0.046		<b></b>
□ PLAN J - POIN 2530 - P3 - DOWN / REP ABC.  dy								
1.150	l' '		REP ARC					
S20_DIST 2530 - P3 - UP   I - 150   1.075   -0.100   0.100   -0.075   -0.001   -0.075   -0.001   -0.075   -0.001   -0.075   -0.001   -0.075   -0.001   -0.075   -0.001   -0.075   -0.001   -0.075   -0.001   -0.075   -0.001   -0.				-0 100	0.100	-0.070		
PLAN J - POIN 2530 - P3 - UP / REP ABC.			1.07 1	-0.100	0.100	-0.018		<u> </u>
S20 - DIST 2530 - P4 - DOWN   REP ABC.	l' '		ADO					
S20_DIST 2530_P4_DONN				0.400	0.400	0.0==1		
PLAN J - POIN 2530 - P4 - DOWN / REP ABC.   of   1.150			1.075	-0.100	0.100	-0.075		
S20 - DIST 2530 - P4 - UP   PAR J - POIN 2530 - P4 - UP / REP ABC.   S20 - DIST 2530 - P4 - UP / REP ABC.   S20 - DIST 2530 - P5 - DOWN   T. 150	l' '							
S20 - DIST 2530 - P4 - UP   REP ABC.   AP   PLAN	_							
PLAN J. POIN 2530 - P4 - UP / REP ABC.   1.150	dY	1.150	1.110	-0.140	0.100	-0.040		<b>✓</b>
A	S20 - DIST 2530 - F	P4 - UP						
A	PLAN J - POIN	1 2530 - P4 - UP / REP	ABC.					
S20 - DIST 2530 - P5 - DOWN   REP ABC.				-0.120	0.100	-0.037		<b>✓</b>
PLAN J - POIN 2530 - P5 - DOWN / REP ABC.   dY								
AY	l' '		REP ABC.					
S20_DIST 2530 - P5 - UP				-0 100	0.100	-0.061		
# PLAN J - POIN 2500 - P5 - UP / REP ABC.  dY   1.150   1.101   -0.100   0.100   -0.049    ∴ \$14 - 2670 - 29.5  ■ \$10 - CERC 710 - B - POIN 2500 - P3 - Z / REP ABC.  dX   29.500   29.533   -0.100   0.100   0.033    ∴ \$14 - 2670 - 20.85  ■ \$10 - CERC 710 - B - POIN K-6 / REP ABC.  dZ   20.850   20.887   -0.100   0.100   0.037    ∴ \$14 - 2670 - 20.85  ■ \$10 - CERC 710 - B - POIN K-6 / REP ABC.  dZ   20.850   20.887   -0.100   0.100   0.007    ∴ \$12 - DIST 2810 - P1  ■ POIN D.69 - POIN 2810 - P1 / REP ABC.  dZ   8.000   7.962   -0.075   0.075    → \$12 - DIST 2810 - P1 = 27.4 [\$12 - DIST 2810 - P1 -> Z])"2  ∀al.   0.000   0.077   0.000   0.150   0.077    ∴ \$12 - DIST 2810 - P2   REP ABC.  dZ   4.000   4.004   -0.075   0.075   0.004    ♣ TRUE POSITION 0.15 - \$12 - DIST 2810 - P2 -> Z])"2  ■ POIN D.69 - POIN 2810 - P3 / REP ABC.  dZ   4.000   4.004   -0.075   0.075   0.004    ♣ TRUE POSITION 0.15 - \$12 - DIST 2810 - P2 -> Z])"2  Val.   0.000   0.000   0.000   0.000    ♣ TRUE POSITION 0.15 - \$12 - DIST 2810 - P2 -> Z]"2  ■ POIN D.69 - POIN 2810 - P3 / REP ABC.  dZ   4.000   0.000   0.000   0.000    ♣ TRUE POSITION 0.15 - \$12 - DIST 2810 - P3 -> Z]"2  Val.   0.000   0.000   0.000   0.000    ♣ TRUE POSITION 0.15 - \$12 - DIST 2810 - P3 -> Z]"2  Val.   0.000   0.001   -0.075   0.075   0.017    ♣ TRUE POSITION 0.15 - \$12 - DIST 2810 - P3 -> Z]"2  Val.   0.000   0.001   0.001   0.005   0.001    ♣ TRUE POSITION 0.15 - \$12 - DIST 2810 - P3 -> Z]"2  Val.   0.000   0.001   0.001   0.005   0.001    ♣ TRUE POSITION 0.15 - \$12 - DIST 2810 - P3 -> Z]"2  Val.   0.000   0.004   0.000   0.004   0.000   0.005    ♣ TRUE POSITION 0.15 - \$12 - DIST 2810 - P3 -> Z]"2  Val.   0.000   0.004   0.000   0.004   0.000   0.005    ♣ TRUE POSITION 0.15 - \$12 - DIST 2810 - P3 -> Z]"2  Val.   0.000   0.004   0.000   0.004   0.000   0.005    ♣ TRUE POSITION 0.15 - \$12 - DIST 2810 - P3 -> Z]"2  Val.   0.000   0.000   0.000   0.000   0.000   0.000   0.000   0.000   0.000   0.000   0.000    ♣ TRUE POSITION 0.15 - \$12 - DIST 2810 - P3 -> Z]"2  Val.   0.0			1.009	-0.100	0.100	-0.001		
	li i		ADC					
S14 - 2670 - 29.5	_			0.400	0.400	0.010		
S10 - CERC 710 - B - POIN 2500 - P3 - Z / REP ABC.   dx		1.150	1.101	-0.100	0.100	-0.049		<b>✓</b>
dX	l' '							
\$14 - 2670 - 20.85	S10 - CERC 7	10 - B - POIN 2500 - P3	B - Z / REP ABC.					
\$10 - CERC 710 - B - POIN K-6 / REP ABC.   \$21	dX	29.500	29.533	-0.100	0.100	0.033		<u> </u>
STRUE POSITION 0.2 X°2+Y°2 - S14 - 2670 - 20.8529	S14 - 2670 - 20.85		<u> </u>	,				
STRUE POSITION 0.2 X°2+Y°2 - S14 - 2670 - 20.8529	■ S10 - CERC 7	10 - B - POIN K-6 / REF	PABC.					
TRUE POSITION 0.2 X*2+Y*2 - S14 - 2670 - 20.8529  ■ =  SQRT X*2+Y*2 - S14 - 2670-Yva *2    Val.				-0.100	0.100	0.037		<b></b>
■ =  SQRT X*2+Y*2 - S14 - 2670->Val *2  Val.				5.1.00	500	3.00.		•
Val.   0.000   0.099   0.000   0.200   0.099								
S12 - DIST 2810 - P1		*.		0.000	0.200	0.000		
■ POIN D.69 - POIN 2810 - P1 / REP ABC.  dZ			0.099	0.000	0.200	0.099		
dZ	l' '		00					
TRUE POSITION 0.15 - S12 - DIST 2810 - P1  = ABS([S12 - DIST 2810 - P1=>Z]-[S12 - DIST 2810 - P1->Z])*2  Val.				!	0.51			
■ =ABS([S12 - DIST 2810 - P1=>Z]-[S12 - DIST 2810 - P1->Z])*2  Val.   0.000   0.077   0.000   0.150   0.077    S12 - DIST 2810 - P2  ■ POIN D.69 - POIN 2810 - P2 / REP ABC.  dZ   4.000   4.004   -0.075   0.075   0.004    ■ TRUE POSITION 0.15 - S12 - DIST 2810 - P2  ■ =ABS([S12 - DIST 2810 - P2=>Z]-[S12 - DIST 2810 - P2->Z])*2  Val.   0.000   0.009   0.000   0.150   0.009    ■ S12 - DIST 2810 - P3  ■ POIN D.69 - POIN 2810 - P3 / REP ABC.  dZ   0.000   0.017   -0.075   0.075   0.017    ■ TRUE POSITION 0.15 - S12 - DIST 2810 - P3  ■ =ABS([S12 - DIST 2810 - P3   P3->Z]-[S12 - DIST 2810 - P3->Z])*2  Val.   0.000   0.034   0.000   0.150   0.034    ■ O.000   0.150   0.034   0.0034   0.000   0.150    ■ S12 - DIST 2810 - P4  ■ POIN 2810 - P4 - POIN D.69 / REP ABC.				-0.075	0.075	-0.038		<b>✓</b>
Val.       0.000       0.077       0.000       0.150       0.077         S12 - DIST 2810 - P2       POIN D.69 - POIN 2810 - P2 / REP ABC.       0.001       4.004       -0.075       0.075       0.004       0.004         ▲ TRUE POSITION 0.15 - S12 - DIST 2810 - P2       POIN 2810 - P2=>Z]-[S12 - DIST 2810 - P2->Z])*2       0.000       0.009       0.000       0.0150       0.009	-							
☐ S12 - DIST 2810 - P2 ☐ POIN D.69 - POIN 2810 - P2 / REP ABC.  dZ	= =ABS([S12 - D	IST 2810 - P1=>Z]-[S1	2 - DIST 2810 - P1->Z])*2					
☐ S12 - DIST 2810 - P2 ☐ POIN D.69 - POIN 2810 - P2 / REP ABC.  dZ	Val.	0.000	0.077	0.000	0.150	0.077		<b>/</b>
■ POIN D.69 - POIN 2810 - P2 / REP ABC.  dZ		P2						
dZ	1 1		BC.					
TRUE POSITION 0.15 - S12 - DIST 2810 - P2  ■ =ABS([S12 - DIST 2810 - P2=>Z]-[S12 - DIST 2810 - P2->Z])*2  Val.				-0.075	0.075	0.004		
■ =ABS([S12 - DIST 2810 - P2=>Z]-[S12 - DIST 2810 - P2->Z])*2  Val.   0.000   0.009   0.000   0.150   0.009    S12 - DIST 2810 - P3  ■ POIN D.69 - POIN 2810 - P3 / REP ABC.  dZ   0.000   0.017   -0.075   0.075   0.017    TRUE POSITION 0.15 - S12 - DIST 2810 - P3  ■ =ABS([S12 - DIST 2810 - P3=>Z]-[S12 - DIST 2810 - P3->Z])*2  Val.   0.000   0.034   0.000   0.150   0.034    ■ POIN 2810 - P4 - POIN D.69 / REP ABC.				-0.073	0.073	0.004		<u> </u>
Val.       0.000       0.009       0.000       0.150       0.009	· A							
S12 - DIST 2810 - P3  ■ POIN D.69 - POIN 2810 - P3 / REP ABC.  dZ				0.000	0.450	0.000		
■ POIN D.69 - POIN 2810 - P3 / REP ABC.  dZ			0.009	0.000	0.150	0.009		<b>✓</b>
dZ	l' '							
ITRUE POSITION 0.15 - S12 - DIST 2810 - P3         ■ =ABS([S12 - DIST 2810 - P3=>Z]-[S12 - DIST 2810 - P3->Z])*2         Val.       0.000       0.034       0.000       0.150       0.034         □ S12 - DIST 2810 - P4       ■ POIN 2810 - P4 - POIN D.69 / REP ABC.	POIN D.69 - PO	OIN 2810 - P3 / REP AI						
Image: ABS ([S12 - DIST 2810 - P3 - P	dZ	0.000	0.017	-0.075	0.075	0.017		<b>✓</b>
■ =ABS([S12 - DIST 2810 - P3=>Z]-[S12 - DIST 2810 - P3->Z])*2  Val.	★ TRUE POSITION 0	.15 - S12 - DIST 2810 ·	- P3					
Val.     0.000     0.034     0.000     0.150     0.034       □ P3 S12 - DIST 2810 - P4     □ P0IN 2810 - P4 - P0IN D.69 / REP ABC.	-							
↑ S12 - DIST 2810 - P4 POIN 2810 - P4 - POIN D.69 / REP ABC.			, <del>-</del> *	0 000	0.150	0.034		
POIN 2810 - P4 - POIN D.69 / REP ABC.			0.004	0.000	0.100	0.004		<b>~</b>
	l' '		BC.					
u∠ 4.000 3.958 -0.075 0.075 -0.042				0.075	0.075	0.040		
	dZ	4.000	3.958	-0.075	0.075	-0.042		



SITE: TRP Control Equipment: QC\_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 24.08.2021 - 10:00 - inj 2

OPERATOR: CA

Actual

Nominal

DATE: 24/08/21 14:15:49 SOFTWARE: METROLOG X4V14

Tol+

Tol-



State

Facility	
S12 - DIST 2810 - P5	
■ POIN 2810 - P5 - POIN D.69 / REP ABC.    dZ	
A	
TRUE POSITION 0.15 - S12 - DIST 2810 - P5	
■ =ABS([S12 - DIST 2810 - P5=>Z]-[S12 - DIST 2810 - P5=>Z])*2  Val.   0.000   0.154   0.000   0.150   0.154   0.004   ★  VAL1  □ Dimensiuni extra  □ DIST 400 - 1  □ POIN 400 - 1-5 - PLAN 400 - 1 / REP ABC.  dZ   2.650   2.528   -0.120   0.100   -0.122   -0.002   ★  □ DIST 400 - 2  □ POIN 400 - 2-5 - PLAN 400 - 2 / REP ABC.  dZ   2.650   2.568   -0.090   0.090   -0.082   →  □ DIST 400 - 3  □ PLAN 400 - 3 - POIN 400 - 3-5 / REP ABC.  dX   2.650   2.519   -0.140   0.090   -0.131   →  □ DIST 400 - 4  □ PLAN 400 - 4 - POIN 400 - 4-5 / REP ABC.  dZ   2.650   2.663   -0.120   0.090   0.013   →  □ DIST 400 - 5  □ PLAN 400 - 5 - POIN 400 - 5-9 / REP ABC.	
Val.       0.000       0.154       0.000       0.150       0.154       0.004       ★         VAL1       ■ Dimensiuni extra       □ DIST 400 - 1       □ POIN 400 - 1 / REP ABC.       □ POIN 400 - 1 / REP ABC.       □ POIN 400 - 1 / REP ABC.       □ POIN 400 - 2 / REP ABC.       □ POIN 400 - 2 / REP ABC.       □ POIN 400 - 2 / REP ABC.       □ POIN 400 - 3 - POIN 400 - 3 - 5 / REP ABC.       □ PLAN 400 - 3 - POIN 400 - 3 - 5 / REP ABC.       □ PLAN 400 - 4 - POIN 400 - 4 - 5 / REP ABC.       □ PLAN 400 - 4 - POIN 400 - 4 - 5 / REP ABC.       □ PLAN 400 - 5 - POIN 400 - 5 - 9 / REP ABC.       □	
VAL1	
□ Dimensiuni extra  □ DIST 400 - 1 □ POIN 400 - 1-5 - PLAN 400 - 1 / REP ABC.  □ DIST 400 - 2 □ POIN 400 - 2-5 - PLAN 400 - 2 / REP ABC.  □ DIST 400 - 3 □ PLAN 400 - 3 - POIN 400 - 3-5 / REP ABC.  □ DIST 400 - 4 □ PLAN 400 - 4 - POIN 400 - 4-5 / REP ABC.  □ DIST 400 - 4 □ PLAN 400 - 4 - POIN 400 - 4-5 / REP ABC.  □ DIST 400 - 5 □ PLAN 400 - 5 - POIN 400 - 5-9 / REP ABC.  □ DIST 400 - 5 □ PLAN 400 - 5 - POIN 400 - 5-9 / REP ABC.	
☐ DIST 400 - 1  ☐ POIN 400 - 1-5 - PLAN 400 - 1 / REP ABC.  ☐ dZ	
■ POIN 400 - 1-5 - PLAN 400 - 1 / REP ABC.  dZ	
dZ	
☐ DIST 400 - 2  ■ POIN 400 - 2-5 - PLAN 400 - 2 / REP ABC.  dZ	
■ POIN 400 - 2-5 - PLAN 400 - 2 / REP ABC.  dZ	
dZ	
DIST 400 - 3 PLAN 400 - 3 - POIN 400 - 3-5 / REP ABC.  dX	
■ PLAN 400 - 3 - POIN 400 - 3-5 / REP ABC.    dX	
dX	
DIST 400 - 4	
■ PLAN 400 - 4 - POIN 400 - 4-5 / REP ABC.    dZ	
dZ 2.650 2.663 -0.120 0.090 0.013	
□ DIST 400 - 5         □ PLAN 400 - 5 - POIN 400 - 5-9 / REP ABC.         dZ       2.650         2.592       -0.280         0.090       -0.058	
■ PLAN 400 - 5 - POIN 400 - 5-9 / REP ABC.  dZ 2.650 2.592 -0.280 0.090 -0.058	
dZ 2.650 2.592 -0.280 0.090 -0.058 ✓	
r <sup>a</sup> n DIST 400 - 6	
■ POIN 400 - 6-5 - PLAN 400 - 6 / REP ABC.	
dX 2.650 2.543 -0.120 0.090 -0.107	
r <sup>a</sup> n DIST 410 - 1	
■ POIN 410 - 1 - POIN 410 - 1-2 / REP ABC.	
dY 2.600 2.501 -0.150 0.090 -0.099	
凸 DIST 410 - 2	
■ POIN 410 - 2 - POIN 410 - 2-2 / REP ABC.	
dY 2.600 2.523 -0.100 0.090 -0.077	
r <sup>th</sup> DIST 410 - 3	
■ POIN 410 - 3-1 - POIN 410 - 3-2 / REP ABC.	
dY 2.600 2.610 -0.090 0.090 0.010	
r <sup>4-1</sup> DIST 410 - 4	
■ POIN 410 - 4-1 - POIN 410 - 4-2 / REP ABC.	
dY 2.600 2.479 -0.200 0.090 -0.121	
M DIST 410 - 5	
POIN 410 - 5 - POIN 410 - 5-2 / REP ABC.	
dY 2.600 2.644 -0.090 0.090 0.044	
1 DIST 410 - 6	
POIN 410 - 6 - POIN 1980 - 6 - 3 / REP ABC.	
dy 2.600 2.556 -0.090 0.090 -0.044 ✓	
↑ DIST 630 - 1 ■ POIN 630 - 1-1 - POIN 630 - 1-2 / REP ABC.	
dZ 55.500 55.400 -0.270 0.100 -0.100 √	
POIN 630 - 2-1 - POIN 630 - 2-2 / REP ABC.	
dZ 55.500 55.199 -0.270 0.100 -0.301 -0.031 ★	
POIN 780 - 1 - PLAN 780 - 1 / REP ABC.	
D 3.200 3.339 0.000 0.170 0.139	
台 DIST 780 - 2	
POIN 780 - 2 - PLAN 780 - 2 / REP ABC.	
D 3.200 3.288 0.000 0.190 0.088	
△ DIST 780 - 3	
POIN 780 - 3 - PLAN 780 - 3 / REP ABC.	
D 3.200 3.248 0.000 0.100 0.048	
△ DIST 780 - 4	
POIN 780 - 4 - PLAN 780 - 4 / REP ABC.	
D 3.200 3.326 0.000 0.100 0.126 0.026 X	
1.025   0.025   0.005	
POIN 1780 - MP10 - 2 - POIN 1780 - MP10 - 1 / REP ABC.	
dX	
100:000 0:00	
POIN 1780 - MP11 - 2 - POIN 1780 - MP11 - 1 / REP ABC.	,
dX  106.500  106.601  0.000  0.220  0.101	
3.220	



SITE: TRP Control Equipment: QC\_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 24.08.2021 - 10:00 - inj 2

OPERATOR: CA

DATE: 24/08/21 14:15:50 SOFTWARE: METROLOG X4V14



Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
r∸ DIST 1780 - MP12							
POIN 1780 - MP12 - 2							
dX	106.500	106.551	0.000	0.220	0.051		<b>✓</b>
r∸₁ DIST 2600 - P1 - F							
POIN 2600 - P1 - DR	ΓE F / REP ABC.						
dX	-0.000	-0.039	-0.075	0.075	-0.039		<b>✓</b>
			•		•		
■ =ABS([DIST 2600 - P	1 - F=>X]-[DIST 260	0 - P1 - F->X])*2					
Val.	0.000	0.078	0.000	0.150	0.078		<b>✓</b>
r≛ DIST 2600 - P2 - F	l .						
POIN 2600 - P2 - DR	ΓΕ F / REP ABC.						
dX	-0.000	-0.038	-0.075	0.075	-0.038		<b>✓</b>
		7,777		5151.5			·
= ABS([DIST 2600 - P	2 - F=>X1-IDIST 260	) - P2 - F->X1)*2					
Val.	0.000	0.076	0.000	0.150	0.076		<b>/</b>
Mai. DIST 2600 - P3 - F	0.000	0.070	0.000	0.130	0.070		<b>V</b>
ľ							
POIN 2600 - P3 - DR		0.040	0.075	0.075	0.040		
dX	-0.000	-0.042	-0.075	0.075	-0.042		<b>✓</b>
= =ABS([DIST 2600 - P		i i					
Val.	0.000	0.084	0.000	0.150	0.084		<b>✓</b>
r∸ DIST 2600 - P4 - F		<u></u>					
POIN 2600 - P4 - DR	ΓE F / REP ABC.						
dX	0.000	-0.043	-0.075	0.075	-0.043		<b>✓</b>
= ABS([DIST 2600 - P	4 - F=>X]-[DIST 260	0 - P4 - F->X1)*2					
Val.	0.000	0.087	0.000	0.150	0.087		<b>✓</b>
→ DIST 2600 - P5 - F							
POIN 2600 - P5 - DR	TE F / REP ABC						
dX	-0.000	-0.013	-0.075	0.075	-0.013		<b>/</b>
	-0.000	-0.013	-0.073	0.073	-0.013		<b>V</b>
♦ 0.1 - DIST 2600 - P5 - F	F VI (DIOT 000)	DE E - VI)+0					
= =ABS([DIST 2600 - P		i i	0.000	0.450	0.000		
Val.	0.000	0.026	0.000	0.150	0.026		<b>✓</b>
r∸₁ DIST 2600 - P1 - L							
POIN 2600 - P1 - DR	ΓΕ L / REP ABC.						
dX	-0.000	0.016	-0.075	0.075	0.016		<b>~</b>
= =ABS([DIST 2600 - P	1 - L=>X]-[DIST 2600	) - P1 - L->X])*2					
Val.	0.000	0.031	0.000	0.150	0.031		<b>~</b>
r≛ DIST 2600 - P2 - L	I		l e				
POIN 2600 - P2 - DR	ΓΕ L / REP ABC.						
dX	-0.000	0.019	-0.075	0.075	0.019		<b>✓</b>
	2.000	0.010	5.57.0	0.070	3.010		
= ABS([DIST 2600 - P:	2 - I =>X]-[DIST 260/	) _ P2 _ I _>X1\*2					
	0.000     0.000		0.000	0.150	0.027		
Val.	0.000	0.037	0.000	0.150	0.037		<b>✓</b>
DIST 2600 - P3 - L	TE 1 / DED 450						
POIN 2600 - P3 - DR		0.040	0.075	0.075	0.010		
dX	-0.000	0.016	-0.075	0.075	0.016		<b>✓</b>
♦ 0.1 - DIST 2600 - P3 - L							
= =ABS([DIST 2600 - P					_		
Val.	0.000	0.033	0.000	0.150	0.033		<b>✓</b>
r≚ DIST 2600 - P4 - L					<del></del>		
POIN 2600 - P4 - DR	ΓΕ L / REP ABC.						
dX	0.000	0.017	-0.075	0.075	0.017		<b>✓</b>
= =ABS([DIST 2600 - P	4 - L=>X1-IDIST 2600	) - P4 - L->X1)*2					
Val.	0.000	0.034	0.000	0.150	0.034		<b>~</b>
Mai. DIST 2600 - P5 - L	0.000	0.004	0.000	0.100	0.004		
POIN 2600 - P5 - DR	TE L / REP ARC						
_	-0.000	0.050	-0.075	0.075	0.050		
dX	-0.000	0.000	-0.073	0.073	0.050		<b>~</b>
♦ 0.1 - DIST 2600 - P5 - L	E I VI IDIOT 000	) DE 1 - \/1\*C					
= ABS([DIST 2600 - P			2 222	0.4=0	0.0==1		
Val.	0.000	0.099	0.000	0.150	0.099		<b>✓</b>
r∸ DIST 2610 - P1 - F							
POIN 2610 - P1 - DR							_ <u></u>
dX	-0.000	0.039	-0.150	0.150	0.039		<b>✓</b>
		<u> </u>					
= ABS([DIST 2610 - P	1 - F=>X]-[DIST 261	) - P1 - F->X])*2					
Val.	0.000	0.078	0.000	0.300	0.078		<b>✓</b>
DIST 2610 - P2 - F							
POIN 2610 - P2 - DR	TE F / REP ABC						
dX	0.000	0.039	-0.150	0.150	0.039		<b>~</b>
u/\	0.000	0.000	-0.100	0.100	0.000		



SITE: TRP Control Equipment: QC\_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 24.08.2021 - 10:00 - inj 2

OPERATOR: CA

Actual

Nominal

DATE: 24/08/21 14:15:50 SOFTWARE: METROLOG X4V14

Tol+

Dev.

Tend.

Tol-



State

♦ 0.1 - DIST 2610 - P2 - F	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
	2 F->VI (DICT 26	40 D0 E \VI\*0					
= ABS([DIST 2610 - P			0.000	0.200	0.077		
Val.	0.000	0.077	0.000	0.300	0.077		<b>✓</b>
→ DIST 2610 - P3 - F							
POIN 2610 - P3 - DR							
dX	-0.000	0.005	-0.150	0.150	0.005		>
🔊 0.1 - DIST 2610 - P3 - F							
= =ABS([DIST 2610 - P:	3 - F=>X]-[DIST 26	i10 - P3 - F->X])*2					
Val.	0.000	0.009	0.000	0.300	0.009		<b>/</b>
¹₁ DIST 2610 - P4 - F							·
POIN 2610 - P4 - DR	TE E / REP ARC						
	-0.000	0.027	-0.150	0.150	0.027		,
dX∣ <b>◊</b> 0.1 - DIST 2610 - P4 - F	-0.000	0.027	-0.130	0.150	0.027		<b>✓</b>
	. = \armsi						
= ABS([DIST 2610 - P							
Val.	0.000	0.053	0.000	0.300	0.053		<b>&gt;</b>
ካ DIST 2610 - P5 - F							
POIN 2610 - P5 - DR	TE F / REP ABC.						
dX	-0.000	0.069	-0.150	0.150	0.069		<b>/</b>
0.1 - DIST 2610 - P5 - F							<u> </u>
= ABS([DIST 2610 - P	5 - F=>Y1_IDIST 26	10 - P5 - F->YI)*2					
			0.000	0.200	0.420		,
Val.	0.000	0.138	0.000	0.300	0.138		<b>✓</b>
DIST 2610 - P1 - L	FF   / FF5 := =						
POIN 2610 - P1 - DR							
dX	-0.000	0.093	-0.150	0.150	0.093		<b>✓</b>
0.1 - DIST 2610 - P1 - L			<u> </u>				
■ =ABS([DIST 2610 - P	1 - L=>X]-[DIST 26	10 - P1 - L->X])*2					
Val.	0.000	0.187	0.000	0.300	0.187		<b>/</b>
DIST 2610 - P2 - L	2.300						·
POIN 2610 - P2 - DR	TE I / RED ARC						
_	-0.000	0.095	-0.150	0.150	0.095		
dX	-0.000	0.095	-0.150	0.150	0.095		<b>✓</b>
0.1 - DIST 2610 - P2 - L							
= ABS([DIST 2610 - P)	2 - L=>X]-[DIST 26	10 - P2 - L->X])*2					
Val.	0.000	0.190	0.000	0.300	0.190		<b>✓</b>
DIST 2610 - P3 - L				•			
POIN 2610 - P3 - DR	TE L / REP ABC.						
dX	-0.000	0.063	-0.150	0.150	0.063		<b>/</b>
0.1 - DIST 2610 - P3 - L	0.000	0.000	0.100	0.100	0.000		
= ABS([DIST 2610 - P	3 1 =>VI IDIST 26	10 D3 L \VI\*2					
			0.000	0.000	0.400		
Val.	0.000	0.126	0.000	0.300	0.126		<b>✓</b>
→ DIST 2610 - P4 - L							
POIN 2610 - P4 - DR	TE L / REP ABC.						
dX	-0.000	0.087		0.150	0.087		<b>✓</b>
ux		0.001	-0.150				
0.1 - DIST 2610 - P4 - L	1	0.001	-0.150				
0.1 - DIST 2610 - P4 - L	4 - L=>X]-[DIST 26		-0.150				
0.1 - DIST 2610 - P4 - L = ABS([DIST 2610 - P4		10 - P4 - L->X])*2					<b>V</b>
0.1 - DIST 2610 - P4 - L ■ =ABS([DIST 2610 - Pa Val.	4 - L=>X]-[DIST 26 0.000		0.000	0.300	0.174		<b>✓</b>
0.1 - DIST 2610 - P4 - L ■ =ABS([DIST 2610 - P4 Val.   ¬ DIST 2610 - P5 - L	0.000	10 - P4 - L->X])*2					<b>~</b>
0.1 - DIST 2610 - P4 - L = ABS([DIST 2610 - P4 - L Val.   DIST 2610 - P5 - L POIN 2610 - P5 - DR	0.000   TE L / REP ABC.	110 - P4 - L->X])*2 0.174	0.000	0.300	0.174		·
© 0.1 - DIST 2610 - P4 - L  ■ =ABS([DIST 2610 - P4  Val.  □ DIST 2610 - P5 - L  ■ POIN 2610 - P5 - DR  dX	0.000	10 - P4 - L->X])*2					✓ ✓
0.1 - DIST 2610 - P4 - L = ABS([DIST 2610 - P4 - L Val.   DIST 2610 - P5 - L POIN 2610 - P5 - DR dX   0.1 - DIST 2610 - P5 - L	0.000  TE L / REP ABC. -0.000	0.174 0.131	0.000	0.300	0.174		·
0.1 - DIST 2610 - P4 - L	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26	0.131 0.10 - P4 - L->X])*2 0.174	0.000	0.300	0.174		·
0.1 - DIST 2610 - P4 - L = ABS([DIST 2610 - P4 - L Val.] DIST 2610 - P5 - L POIN 2610 - P5 - DR dX 0.1 - DIST 2610 - P5 - L	0.000  TE L / REP ABC. -0.000	0.174 0.131	0.000	0.300	0.174		·
0.1 - DIST 2610 - P4 - L	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26	0.131 0.10 - P4 - L->X])*2 0.174	0.000	0.300	0.174		<b>✓</b>
0.1 - DIST 2610 - P4 - L  = ABS([DIST 2610 - P4 - L  Val.    DIST 2610 - P5 - L  POIN 2610 - P5 - DR'  dX    0.1 - DIST 2610 - P5 - L  = ABS([DIST 2610 - P5 - L  Val.    PERP 2620 - P1	0.000   TE L / REP ABC. -0.000   5 - L=>XJ-[DIST 26 0.000	0.131 0.10 - P4 - L->X])*2 0.174	0.000	0.300	0.174		<b>✓</b>
0.1 - DIST 2610 - P4 - L  = ABS([DIST 2610 - P4 - L  Val.    DIST 2610 - P5 - L  POIN 2610 - P5 - DR'  dX    0.1 - DIST 2610 - P5 - L  = ABS([DIST 2610 - P5 - L  Val.    PERP 2620 - P1  DRTE 2620 - P1(G)/P	0.000   TE L / REP ABC. -0.000   5 - L=>XJ-[DIST 26 0.000	0.174 0.174 0.131 0.263	0.000	0.300	0.174		✓ ✓
O.1 - DIST 2610 - P4 - L  = ABS([DIST 2610 - P4 - L  Val.    DIST 2610 - P5 - L  POIN 2610 - P5 - DR  dX    O.1 - DIST 2610 - P5 - L  = ABS([DIST 2610 - P5 - L  Val.    PERP 2620 - P1  DRTE 2620 - P1(G)/P  Val.	0.000   TE L / REP ABC. -0.000   5 - L=>XJ-[DIST 26 0.000	0.131 0.10 - P4 - L->X])*2 0.174	0.000	0.300	0.174		<b>✓</b>
0.1 - DIST 2610 - P4 - L  = ABS([DIST 2610 - P4 - L  Val.    DIST 2610 - P5 - L  POIN 2610 - P5 - DR  dX    0.1 - DIST 2610 - P5 - L  = ABS([DIST 2610 - P5 - L  Val.    PERP 2620 - P1  DRTE 2620 - P1(G)/P  Val.    PERP 2620 - P2	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   PLAN H - C-Zone 0.000	0.174 0.174 0.131 0.263	0.000	0.300	0.174		✓ ✓
O.1 - DIST 2610 - P4 - L	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   PLAN H - C-Zone 0.000   PLAN H - C-Zone	0.174 0.174 0.131 0.131 0.263 0.068	0.000	0.300 0.150 0.300 0.200	0.174 0.131 0.263 0.068		*
0.1 - DIST 2610 - P4 - L	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   PLAN H - C-Zone 0.000	0.174 0.174 0.131 0.263	0.000	0.300	0.174		✓ ✓
0.1 - DIST 2610 - P4 - L   = ABS([DIST 2610 - P4 - L     Val.     DIST 2610 - P5 - L   POIN 2610 - P5 - DR' dX     0.1 - DIST 2610 - P5 - L   = ABS([DIST 2610 - P5 - L     Val.     PERP 2620 - P1     DRTE 2620 - P1(G)/P     Val.     PERP 2620 - P2     DRTE 2620 - P2(G)/P     Val.     PERP 2620 - P3	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   PLAN H - C-Zone 0.000   PLAN H - C-Zone 0.000	0.174 0.174 0.131 0.131 0.263 0.068	0.000	0.300 0.150 0.300 0.200	0.174 0.131 0.263 0.068		*
0.1 - DIST 2610 - P4 - L   = ABS([DIST 2610 - P4 - L     Val.     DIST 2610 - P5 - L   POIN 2610 - P5 - DR' dX     0.1 - DIST 2610 - P5 - L   = ABS([DIST 2610 - P5 - L     = ABS([DIST 2610 - P5 - L     DRTE 2620 - P1     DRTE 2620 - P1(G)/P	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   PLAN H - C-Zone 0.000   PLAN H - C-Zone 0.000   PLAN H - C-Zone	0.174   0.174   0.174   0.131   0.131   0.263   0.068   0.067	0.000	0.300 0.150 0.300 0.200	0.174 0.131 0.263 0.068		*
No.1 - DIST 2610 - P4 - L  A SABS([DIST 2610 - P4 - Val.]  DIST 2610 - P5 - L  POIN 2610 - P5 - DR'  dX  No.1 - DIST 2610 - P5 - L  ABS([DIST 2610 - P5 - L  B SABS([DIST 2610 - P5 - L  CALL  DEFR 2620 - P1  DRTE 2620 - P1  DRTE 2620 - P2  DRTE 2620 - P2  DRTE 2620 - P3(G)/P  Val.  PERP 2620 - P3  DRTE 2620 - P3(G)/P  Val.	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   PLAN H - C-Zone 0.000   PLAN H - C-Zone 0.000	0.174 0.174 0.131 0.131 0.263 0.068	0.000	0.300 0.150 0.300 0.200	0.174 0.131 0.263 0.068		*
No.1 - DIST 2610 - P4 - L  A SABS([DIST 2610 - P4 - Val.]  DIST 2610 - P5 - L  POIN 2610 - P5 - DR'  dX  No.1 - DIST 2610 - P5 - L  ABS([DIST 2610 - P5 - L  B SABS([DIST 2610 - P5 - L  CALL  DEFR 2620 - P1  DRTE 2620 - P1  DRTE 2620 - P2  DRTE 2620 - P2  DRTE 2620 - P3(G)/P  Val.  PERP 2620 - P3  DRTE 2620 - P3(G)/P  Val.	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   PLAN H - C-Zone 0.000   PLAN H - C-Zone 0.000   PLAN H - C-Zone	0.174   0.174   0.174   0.131   0.131   0.263   0.068   0.067	0.000	0.300 0.150 0.300 0.200	0.174 0.131 0.263 0.068		*
No.1 - DIST 2610 - P4 - L  A SABS([DIST 2610 - P4 - Val.]  DIST 2610 - P5 - L  POIN 2610 - P5 - DR'  dX  No.1 - DIST 2610 - P5 - DR'  EABS([DIST 2610 - P5 - L  A SABS([DIST 2610 - P5 - L  A SABS([DIST 2610 - P6 - P4]]  DRTE 2620 - P1 DRTE 2620 - P1(G)/P1 Val.  PERP 2620 - P2  DRTE 2620 - P2  DRTE 2620 - P2(G)/P1 Val.  PERP 2620 - P3(G)/P1 Val.  PERP 2620 - P3(G)/P1 Val.  PERP 2620 - P4	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   PLAN H - C-Zone 0.000   PLAN H - C-Zone 0.000   PLAN H - C-Zone 0.000	0.174   0.174   0.174   0.131   0.131   0.263   0.068   0.067	0.000	0.300 0.150 0.300 0.200	0.174 0.131 0.263 0.068		*
O.1 - DIST 2610 - P4 - L	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   PLAN H - C-Zone 0.000   PLAN H - C-Zone 0.000   PLAN H - C-Zone	0.174   0.174   0.174   0.174   0.174   0.181   0.181   0.263   0.068   0.067   0.037	0.000	0.300 0.150 0.300 0.200 0.200	0.174 0.131 0.263 0.068 0.067		*
O.1 - DIST 2610 - P4 - L	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   PLAN H - C-Zone 0.000   PLAN H - C-Zone 0.000   PLAN H - C-Zone 0.000	0.174   0.174   0.174   0.131   0.131   0.263   0.068   0.067	0.000	0.300 0.150 0.300 0.200	0.174 0.131 0.263 0.068		*
O.1 - DIST 2610 - P4 - L	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   DLAN H - C-Zone 0.000	0.174   0.174   0.174   0.174   0.174   0.181   0.181   0.263   0.068   0.067   0.037	0.000	0.300 0.150 0.300 0.200 0.200	0.174 0.131 0.263 0.068 0.067		*
O.1 - DIST 2610 - P4 - L	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   DLAN H - C-Zone	0.174   0.174   0.174   0.131   0.131   0.263   0.068   0.067   0.037   0.060	0.000	0.300   0.150   0.300   0.200   0.200   0.200   0.200	0.174   0.131   0.263   0.068   0.067   0.037   0.060		* * * * * * *
0.1 - DIST 2610 - P4 - L	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   DLAN H - C-Zone 0.000	0.174   0.174   0.174   0.174   0.174   0.181   0.181   0.263   0.068   0.067   0.037	0.000	0.300 0.150 0.300 0.200 0.200	0.174 0.131 0.263 0.068 0.067		* * * * * *
No.1 - DIST 2610 - P4 - L    = ABS([DIST 2610 - P4 - L   Val.     POIN 2610 - P5 - L   POIN 2610 - P5 - DR' dX     No.1 - DIST 2610 - P5 - DR' dX     No.1 - DIST 2610 - P5 - L   = ABS([DIST 2610 - P5 - L   DRTE 2620 - P1     DRTE 2620 - P1     DRTE 2620 - P2     DRTE 2620 - P2     DRTE 2620 - P3     DRTE 2620 - P3     DRTE 2620 - P4     DRTE 2620 - P4     DRTE 2620 - P5     DRTE 2630 - P5	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   DLAN H - C-Zone 0.000	0.174   0.174   0.174   0.131   0.131   0.263   0.068   0.067   0.037   0.060	0.000	0.300   0.150   0.300   0.200   0.200   0.200   0.200	0.174   0.131   0.263   0.068   0.067   0.037   0.060		* * * * * * *
No.1 - DIST 2610 - P4 - L	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   DLAN H - C-Zone 0.000	0.174   0.174   0.174   0.131   0.131   0.263   0.068   0.067   0.037   0.060	0.000	0.300   0.150   0.300   0.200   0.200   0.200   0.200	0.174   0.131   0.263   0.068   0.067   0.037   0.060		* * * * * * *
No.1 - DIST 2610 - P4 - L    = ABS([DIST 2610 - P4 - L   Val.     POIN 2610 - P5 - L   POIN 2610 - P5 - DR' dX     No.1 - DIST 2610 - P5 - DR' dX     No.1 - DIST 2610 - P5 - L   = ABS([DIST 2610 - P5 - L   DRTE 2620 - P1     DRTE 2620 - P1     DRTE 2620 - P2     DRTE 2620 - P2     DRTE 2620 - P3     DRTE 2620 - P3     DRTE 2620 - P4     DRTE 2620 - P4     DRTE 2620 - P5     DRTE 2630 - P5	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   DLAN H - C-Zone 0.000	0.174   0.174   0.174   0.131   0.131   0.263   0.068   0.067   0.037   0.060	0.000	0.300   0.150   0.300   0.200   0.200   0.200   0.200	0.174   0.131   0.263   0.068   0.067   0.037   0.060		* * * * * * *
No.1 - DIST 2610 - P4 - L  = ABS([DIST 2610 - P4 - L  Val.    POIN 2610 - P5 - L  POIN 2610 - P5 - DR'  dX    No.1 - DIST 2610 - P5 - DR'  dX    No.1 - DIST 2610 - P5 - L  ABS([DIST 2610 - P5 - DR'  Val.    PERP 2620 - P1  DRTE 2620 - P1(G)/P  Val.    PERP 2620 - P2  DRTE 2620 - P2(G)/P  Val.    PERP 2620 - P3  DRTE 2620 - P4(G)/P  Val.    PERP 2620 - P4  DRTE 2620 - P4  DRTE 2620 - P5  DRTE 2620 - P5  DRTE 2620 - P5  DRTE 2620 - P5(G)/P  Val.    PERP 2620 - P5  DRTE 2620 - P5(G)/P  Val.    DRTE 2630  DRTE L-1 - DRTE L-2	0.000   TE L / REP ABC0.000   TE L / REP ABC.	0.174   0.174   0.174   0.174   0.174   0.174   0.131   0.168   0.068   0.067   0.037   0.060   0.072	0.000	0.300   0.150   0.300   0.200   0.200   0.200   0.200   0.200	0.174  0.131  0.263  0.068  0.067  0.037  0.060  0.072		
O.1 - DIST 2610 - P4 - L	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   DLAN H - C-Zone	0.174   0.174	0.000	0.300   0.150   0.300   0.200   0.200   0.200   0.200   0.200	0.174  0.131  0.263  0.068  0.067  0.037  0.060  0.072		
O.1 - DIST 2610 - P4 - L	0.000   TE L / REP ABC0.000   5 - L=>X]-[DIST 26 0.000   DLAN H - C-Zone	0.174   0.174	0.000	0.300   0.150   0.300   0.200   0.200   0.200   0.200   0.200	0.174  0.131  0.263  0.068  0.067  0.037  0.060  0.072		



SITE: TRP Control Equipment: QC\_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 24.08.2021 - 10:00 - inj 2

OPERATOR: CA

Actual

DATE: 24/08/21 14:15:50 SOFTWARE: METROLOG X4V14



Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
∸ DIST 2650	•	<u> </u>	•	<u>'</u>	•		
DRTE F - 1 - DRTE F-	2 / REP ABC.						
D	6.950	6.942	-0.050	0.050	-0.008		<b>✓</b>
∸₁ DIST 2660 - F	·						
DRTE 2640 - MID - DI	RTE F / REP ABC.						
D	0.000	0.033	-0.050	0.050	0.033		<b>~</b>
SYMMETRY 0.1 - DIST 26							•
=ABS([DIST 2660 - F=		F->Dist11)*2					
Val.	0.000	0.067	0.000	0.100	0.067		<b>/</b>
∸ DIST 2660 - L	0.000	0.007	0.000	0.100	0.007		<u> </u>
■ DRTE 2640 - MID - DF	TEI/DED ARC						
D DICTE 2040 - MID - DI	0.000	0.025	-0.050	0.050	0.025		,
		0.025	-0.030	0.030	0.025		<b>✓</b>
SYMMETRY 0.1 - DIST 26		L . D: (41)*0					
= =ABS([DIST 2660 - L=							
Val.	0.000	0.049	0.000	0.100	0.049		<b>✓</b>
∸ DIST 2710 - MP6							
POIN 2710 - MP6 - 1 -	POIN 2710 - MP6 - 2	2 / REP ABC.					
dZ	54.200	54.115	-0.050	0.200	-0.085	-0.035	X
→ DIST 2710 - MP7	•	•	•		•		
POIN 2710 - MP7 - 1	POIN 2710 - MP7 - 2	2 / REP ABC.					
dΖ	54.200	54.270	-0.100	0.550	0.070		<b>~</b>
△ DIST 2710 - MP8							· ·
POIN 2710 - MP8 - 1 -	POIN 2710 - MP8 - 1	2 / REP ABC					
dZ	54.200	54.217	-0.020	0.200	0.017		<b>~</b>
uz <sub> </sub> ∸₁ DIST 2750	J <del>1</del> .200	UT.Z 11	-0.020	0.200	0.017	Li coming a	
	D 60 / DED 4D0						
POIN 2780 - 3 - POIN		0.044	0.050	0.050	0.044		
dZ	0.000	-0.014	-0.050	0.050	-0.014		<b>✓</b>
SYMMETRY 0.1 - DIST 27							
= =ABS([DIST 2750=>Z							
Val.	0.000	0.027	0.000	0.100	0.027		<b>✓</b>
∸₁ DIST 2750 - K							
POIN 2780 - 3 - POIN	2500 - P3 - X / REP A	ABC.					
dZ	0.000	0.045	-0.050	0.050	0.045		<b>✓</b>
SYMMETRY 0.1 - DIST 27	50 - K						
= =ABS([DIST 2750 - K=		>Z1)*2					
Val.	0.000	0.089	0.000	0.100	0.089		<b>/</b>
Ŭ DIST 2760	0.000	0.000	0.000	0.100	0.000		<u> </u>
POIN 2760 - POIN D.6	O / DED ARC						
		0.001	0.050	0.050	0.001		,
dZ	-0.000	-0.001	-0.050	0.050	-0.001		<b>✓</b>
SYMMETRY 0.1 - DIST 27							
= =ABS([DIST 2760=>Z		1			1		
Val.	0.000	0.002	0.000	0.100	0.002		<b>✓</b>
≚ DIST 2760 - K							
POIN 2760 - POIN 25	00 - P3 - X / REP ABC	C					
dZ	0.000	0.057	-0.050	0.050	0.057	0.007	X
🗴 SYMMETRY 0.1 - DIST 27	60 - K						
= =ABS([DIST 2760 - K=	:>Z]-[DIST 2760 - K->	>Z])*2					
Val.	0.000	0.115	0.000	0.100	0.115	0.015	X
≚ DIST 2770							
POIN 2770 - 1 - POIN	2770 - 2 / REP ABC						
D D	23.190	23.281	-0.050	0.050	0.091	0.041	X
	20.100	20.201	0.000	3.000	0.001	J.UT 1	
POIN 2780 - 1 - POIN	2780 - 2 / RED ARC						
_			0.050	0.050	0.020		
D DIST 2700	23.150	23.179	-0.050	0.050	0.029		<b>~</b>
DIST 2790	/ DED 450						
POIN D-2 - POIN D-1		0. ===1	0.050	0.0=0	0.0:-1		
dZ	21.600	21.552	-0.050	0.050	-0.048		<b>~</b>
≚ DIST 2800							
POIN 2800 - 1 - POIN							
D	23.850	24.036	-0.150	0.150	0.186	0.036	X
× DIST 2820 - P1							
POIN D.69 - POIN 282	20 - P1 / REP ABC.			0.450	-0.078		<b>/</b>
POIN D.69 - POIN 282	20 - P1 / REP ABC. 8.000	7.922	-0.150	0.150			
dZ	8.000	7.922	-0.150	0.150	0.070		
dZ∣ ↑ TRUE POSITION 0.3 - DIS	8.000 T 2820 - P1		-0.150	0.150	0.070		
dZ  ↑ TRUE POSITION 0.3 - DIS ■ =ABS([DIST 2820 - P	8.000 T 2820 - P1 =>Z]-[DIST 2820 - P	1->Z])*2					
dZ  № TRUE POSITION 0.3 - DIS ■ =ABS([DIST 2820 - P <sup>2</sup> Val.	8.000 T 2820 - P1		-0.150	0.150	0.156		<b>~</b>
dZ    ↑ TRUE POSITION 0.3 - DIS  ■ =ABS([DIST 2820 - P'  Val.    ↑ DIST 2820 - P2	8.000 T 2820 - P1 =>Z]-[DIST 2820 - P	1->Z])*2					<b>~</b>
dZ    ↑ TRUE POSITION 0.3 - DIS  ■ =ABS([DIST 2820 - P'  Val.    ↑ DIST 2820 - P2  ■ POIN D.69 - POIN 282	8.000   T 2820 - P1 =>Z]-[DIST 2820 - P 0.000	1->Z])*2 0.156	0.000	0.300	0.156		
dZ    ↑ TRUE POSITION 0.3 - DIS  ■ =ABS([DIST 2820 - P'  Val.    ↑ DIST 2820 - P2  ■ POIN D.69 - POIN 282  dZ	8.000   T 2820 - P1   =>Z]-[DIST 2820 - P1   0.000   20 - P2 / REP ABC. 4.000	1->Z])*2					<b>✓</b>
dZ    ↑ TRUE POSITION 0.3 - DIS    ■ =ABS([DIST 2820 - P'     Val.    ↑ DIST 2820 - P2    ■ POIN D.69 - POIN 282    ↑ TRUE POSITION 0.3 - DIS	8.000   T 2820 - P1   =>Z]-[DIST 2820 - P: 0.000   20 - P2 / REP ABC. 4.000   T 2820 - P2	1->Z])*2 0.156	0.000	0.300	0.156		
dZ     TRUE POSITION 0.3 - DIS     = ABS([DIST 2820 - P' Val.     DIST 2820 - P2     POIN D.69 - POIN 282     TRUE POSITION 0.3 - DIS     = ABS([DIST 2820 - P' 282	8.000   T 2820 - P1 =>Z]-[DIST 2820 - P 0.000   20 - P2 / REP ABC. 4.000   T 2820 - P2 2=>Z]-[DIST 2820 - P2	1->Z])*2 0.156 3.987 2->Z])*2	-0.150	0.300	0.156		
dZ    ↑ TRUE POSITION 0.3 - DIS   = ABS([DIST 2820 - P' Val.    ↑ DIST 2820 - P2   POIN D.69 - POIN 282   dZ    ↑ TRUE POSITION 0.3 - DIS	8.000   T 2820 - P1   =>Z]-[DIST 2820 - P: 0.000   20 - P2 / REP ABC. 4.000   T 2820 - P2	1->Z])*2 0.156	0.000	0.300	0.156		



SITE: TRP Control Equipment: QC\_74 - DEA Performance

THOMAS REFERENCE: HEL010/A - C2 - 24.08.2021 - 10:00 - inj 2

OPERATOR: CA

DATE: 24/08/21 14:15:50 SOFTWARE: METROLOG X4V14



Dim/Pos	Nominal	Actual	Tol-	Tol+	Dev.	Tend.	State
ri DIST 2820 - P3		·		<u>'</u>			
POIN D.69 - POIN 2	820 - P3 / REP ABC.						
dZ	-0.000	0.012	-0.150	0.150	0.012		<b>~</b>
★ TRUE POSITION 0.3 - D	IST 2820 - P3			·			
■ =ABS([DIST 2820 -	P3=>Z]-[DIST 2820 - P3	->Z])*2					
Val.	0.000	0.025	0.000	0.300	0.025		<b>~</b>
r <sup>™</sup> DIST 2820 - P4				·			
POIN 2820 - P4 - P0	OIN D.69 / REP ABC.						
dZ	4.000	3.965	-0.150	0.150	-0.035		<b>~</b>
★ TRUE POSITION 0.3 - D							
■ =ABS([DIST 2820 -	P4=>Z]-[DIST 2820 - P4	->Z])*2					
Val.	0.000	0.070	0.000	0.300	0.070		<b>✓</b>
r∸i DIST 2820 - P5							
POIN 2820 - P5 - P0	OIN D.69 / REP ABC.						
dZ	8.000	7.890	-0.150	0.150	-0.110		<b>✓</b>
★ TRUE POSITION 0.3 - D	IST 2820 - P5						
■ =ABS([DIST 2820 -	P5=>Z]-[DIST 2820 - P5	->Z])*2					
Val.	0.000	0.220	0.000	0.300	0.220		<b>~</b>