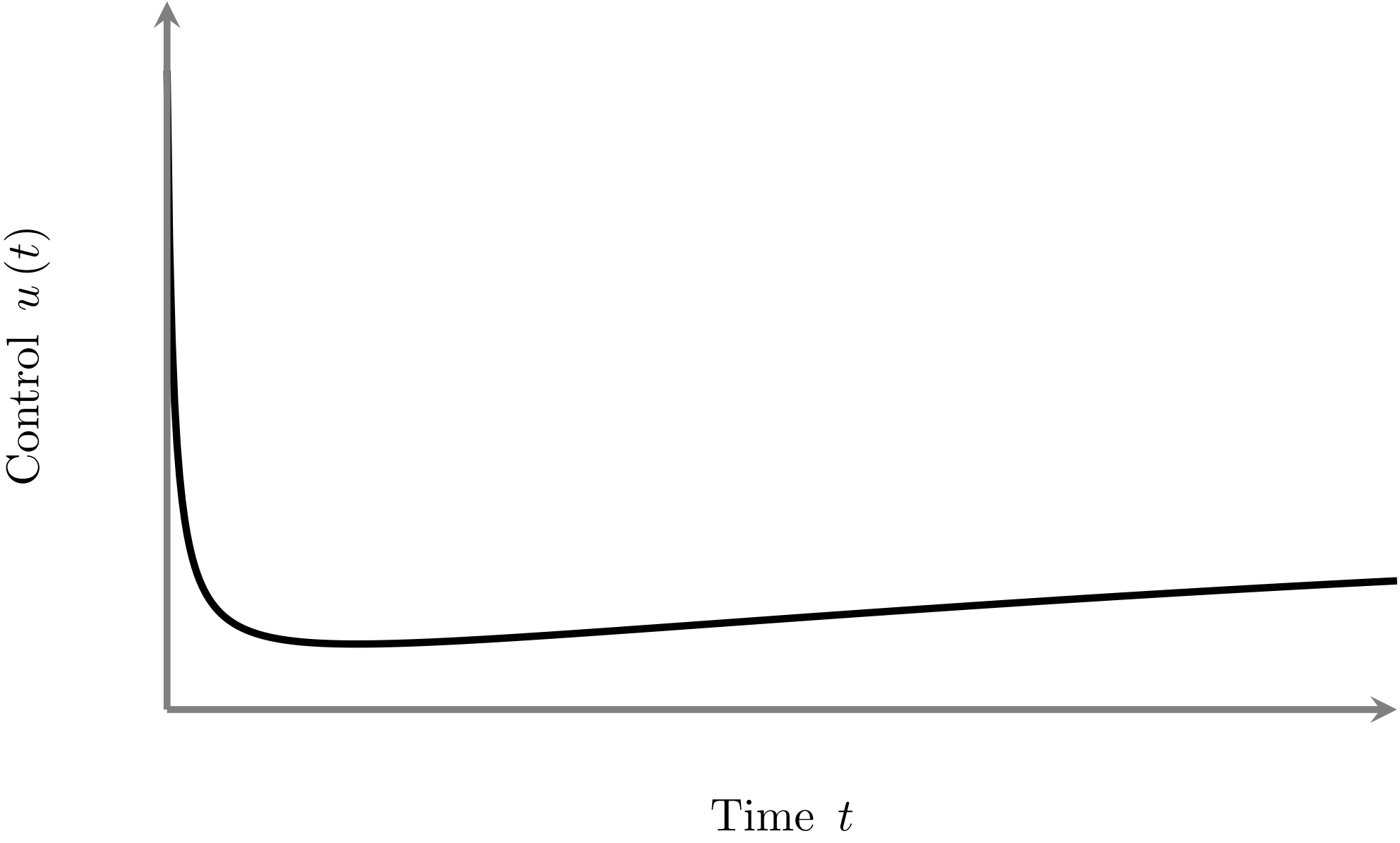
Control $u(t)$
Time t