

CS292A Notes

* Def of Probability Spaces.

A probability distribution is ...

... a set Ω that represents an output space

... a function $\Pr: \Omega \rightarrow [0, 1]$
such that ...

... \forall events E_1, \dots, E_n where $E_i \cap E_j = \emptyset$...

... $\Pr[E_1 \cup \dots \cup E_n] = \Pr[E_1] + \dots + \Pr[E_n]$

... $\Pr[\Omega] = 1$

* Union Bound.

$$\forall E_1, \dots, E_n \quad \Pr[E_1 \cup \dots \cup E_n] \leq \sum_i \Pr[E_i]$$

* Mutual Independence.

A set of Events E_1, \dots, E_n are mutually independent if

$$\forall I \subseteq \{1, \dots, n\} \quad \Pr[\bigcap_{i \in I} E_i] = \prod_{i \in I} \Pr[E_i]$$

* Conditional Probability.

Think of this as reducing and redefining the probability spaces

$$\Pr[E_1 | E_2] = \Pr[E_1 \cap E_2] / \Pr[E_2]$$

Observe that when E_1 and E_2 are independent ...

$$\dots \Pr[E_1 | E_2] = \Pr[E_1]$$

* Law of Total Probability.

If E_1, \dots, E_n partitions Ω , then $\forall x \subseteq \Omega \dots$

$$\dots \Pr[x] = \sum_i \Pr[x | E_i] \Pr[E_i]$$

* Random Variable.

A function $X: \Omega \rightarrow \mathbb{R}$.

Note that the function doesn't need to map to \mathbb{R} but needs addition and multiplication to define expectation.

CS292A Notes

* Expectation.

$$\mathbb{E}[X] = \sum_i \Pr[X=i] \cdot i = \sum_{p \in \Omega} \Pr[p] X(p)$$

* Linearity of Expectation.

$$\mathbb{E}[X+Y] = \mathbb{E}[X] + \mathbb{E}[Y]$$

* Existence of values relating to Expectation.

$$\Pr[X \geq \mathbb{E}[X]] > 0.$$

$$\Pr[X \leq \mathbb{E}[X]] > 0.$$

* Conditional Expectation.

$$\mathbb{E}[Y | Z=z] = \sum_y \Pr[Y=y | Z=z] \cdot y$$

* Principle of Deferred Decisions.

Think about how some random variables are set for analysis and others are left random for later analysis (conditioned upon the set variables).

* Expectation and Constants.

$$\mathbb{E}[c] = c.$$

$$\mathbb{E}[cX] = c\mathbb{E}[X].$$

* Jensen's Inequality.

$$0 \leq \mathbb{E}[X^2] - (\mathbb{E}[X])^2$$

* Markov's Inequality.

For a rv $X \geq 0$, $\forall a \geq 1 \dots$

$$\dots \Pr[X \geq a \mathbb{E}[X]] \leq 1/a.$$

* Moment.

$$\mathbb{E}[X^k] = \sum_i \Pr[X=i] i^k$$

CS292A Notes

* Variance.

$$\text{Var}[X] = \mathbb{E}[X - \mathbb{E}[X]]^2 = \mathbb{E}[X^2] - (\mathbb{E}[X])^2.$$

* Bernoulli RV.

$$\Pr[X] = \begin{cases} p & \text{if success} \\ 1-p & \text{if fail} \end{cases}$$

$$\text{Var}[X] = p(1-p) \leq \min(p, 1-p)$$

$$\mathbb{E}[X] = p.$$

* Binomial RV.

$$\Pr[X=j] = \binom{n}{j} p^j (1-p)^{n-j} \quad \text{where } j \in [0, n]$$

$$\mathbb{E}[X] = np$$

$$\text{Var}[X] = np(1-p)$$

* Geometric RV.

infinite independent trials with success probability p ;

want to see number of trials until first success...

$$\dots \Pr[X=i] = (1-p)^{i-1} p$$

$$\dots \mathbb{E}[X] = 1/p$$

$$\dots \text{Var}[X] = (1-p)/p^2$$

* Memoryless Property.

~~$$\Pr[X=n+k \mid X>k] = \Pr[X=n]$$~~

* Sum of Geometric Series.

$$\sum_{i=1}^n a \cdot r^{i-1} = a(1-r^n)/(1-r)$$

* Covariance.

$$\text{Cov}(X, Y) = \mathbb{E}[X - \mathbb{E}[X]] \mathbb{E}[Y - \mathbb{E}[Y]] = \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y]$$

If X, Y are independent ...

$$\dots \text{Cov}(X, Y) = 0.$$

CS292A Notes

* Joint Variance.

$$\text{Var}[X+Y] = \text{Var}[X] + \text{Var}[Y] + 2\text{Cov}[X, Y]$$

If a set of RV are pairwise independent, then ...

$$\dots \text{Var}[\sum_i X_i] = \sum_i \text{Var}[X_i]$$

* Chebychev's Inequality.

$$\Pr[|X - \mathbb{E}[X]| \geq k\sigma(X)] \leq \frac{1}{k^2} \quad \text{where } \sigma(X) = \sqrt{\text{Var}(X)}$$

* Moment Generating Function.

$$M_X(t) = \mathbb{E}[e^{tX}] = \sum_i \Pr[X=i] \cdot e^{ti} : \mathbb{R} \rightarrow \mathbb{R}$$

For the k^{th} moment ...

$$\dots \mathbb{E}[X^k] = M_X^k(t=0).$$

$\{e^{-t}, e^t\}$ defined s.t. geometric series converges & well defined around 0.

* Joint Moment Generating Functions.

If X, Y are independent ...

$$\dots M_{X+Y}(t) = M_X(t) M_Y(t)$$

* Chernoff Bounds.

For $t > 0, \dots$

$$\dots \Pr[X \geq a] = \Pr[e^{tX} \geq e^{ta}] \leq \mathbb{E}[e^{tX}] / e^{ta}$$

... where we want to pick t s.t. $\min(\mathbb{E}[e^{tX}] / e^{ta})$

For $t < 0, \dots$

$$\dots \Pr[X \leq a] = \Pr[e^{tX} \geq e^{ta}] \leq \mathbb{E}[e^{tX}] / e^{ta}$$

... where we want to pick t s.t. $\min(\mathbb{E}[e^{tX}] / e^{ta})$

* Chernoff Bounds for Sum of Independent Bernoulli RV

For $\Pr[X_i] = p_i, X = \sum_i X_i, \mu = \mathbb{E}[X], \dots$

$$\dots \Pr[X \geq (1+\delta)\mu] \leq (e^\delta / (1+\delta))^\mu \quad \text{for any } \delta > 0$$

$$\dots \Pr[X \geq (1+\delta)\mu] \leq (e^{-\mu\delta^2/3}) \quad \text{for } \delta \in (0, 1]$$

$$\dots \Pr[X \geq R] \leq 2^{-R} \quad \text{for } R \geq 6\mu$$

CS292A Notes

* More Chernoff Bounds for Sum of Independent Bernoulli RVs

For $\Pr[X_i] = p_i$, $X = \sum_i X_i$, $\mu = \mathbb{E}[X]$, ...

$$\dots \Pr[X \leq (1-\delta)\mu] \leq e^{-\mu\delta^2/2}$$

for $\delta \in (0, 1)$

$$\dots \Pr[X \geq (1+\delta)\mu] \leq (e^\delta / (1+\delta)^{(1+\delta)})^\mu$$

for $\delta \in (0, 1)$

* Hoeffding Bounds.

For $a_i \leq X_i \leq b_i$, $X = \sum_i X_i$, $t > 0$, ...

$$\dots \Pr[|X - \mu| \geq \epsilon n] \leq 2 \exp(-2\epsilon^2 n^2 / \sum (b_i - a_i)^2)$$

* Random Graphs — $G(n, p)$ model.

$G(n, p)$ defines a graph with n vertices, and m edges, each included with probability p ...

$$\dots \Pr[G = \tilde{G}] = p^m (1-p)^{\binom{n}{2} - m}$$

$$\dots \mathbb{E}[m] = \binom{n}{2} p$$

$$\dots \mathbb{E}[\text{degree per vertex}] = (n-1) p$$

* Random Graphs — $G(n, N)$ model.

$G(n, N)$ defines a graph with n vertices and exactly N edges.

* Probabilistic Methods

If $\Pr[E] > 0$, then $E \neq \emptyset$.

~~if~~ $\forall p \in [2]$, $\Pr[p = p] \leq x \rightarrow |x| \geq 1/x$

$\forall p \in [2]$, $\Pr[p = p] \geq x \rightarrow |x| \leq 1/x$

* Stochastic Processes.

A sequence of random variables X_1, \dots, X_t .

* Markov Chain.

A stochastic process is a markov chain if it is memoryless...

$$\dots \forall t, a_1, \dots, a_t \Pr[X_t = a_t | X_{t-1} = a_{t-1}, \dots, X_1 = a_1] = \Pr[X_t = a_t | X_{t-1} = a_{t-1}]$$

~~this does not state the probability is constant w.r.t time,~~
~~but instead all information is embedded in previous state.~~

CS292A Notes

* Verifying Polynomial Identities.

Input: Polynomials $F(x), G(x)$ of max degree d

Output: 1 iff $F(x) = G(x)$, 0 otherwise

Algorithm:

- pick x' $\text{var} \in [1, 100d]$

- output 1 when $F(x') = G(x')$, 0 otherwise

- repeat to boost success; ~~only~~ output product of trials

* Verifying Matrix Multiplication

Input: $A, B \in \mathbb{R}^{m \times m}, C \in \mathbb{R}^{m \times m}$

Output: 1 iff $C = AB$, 0 otherwise

Algorithm:

- pick random $x \in \{0, 1\}^n$

- compute Cx

- compute $A(Bx)$

- output 1 when $Cx = A(Bx)$, 0 otherwise

- repeat to boost success; output product of trials

* Min Cut

Input: Graph G

Output: set X s.t. $d(X) := |\{(u, v) \in E(G) : u \in X, v \notin X\}|$ is minimized
to create 2 disjoint sets

Algorithm:

for ~~i=2 to n-1~~ $n-2$ iterations,

pick $e \in E(G)$ var

contract e (combine u, v into single vertex)

eliminate self loops (connecting u, v)

output edges connecting final 2 vertices.

* K-Approximation.

A K-approximation is no worse than the optimal solution by a factor of K .

CS292A Notes

* Generating Random Permutations.

Input: list of n elements.

Output: random permutation s.t. all choices have $\Pr[\sigma] = \frac{1}{n!}$

Algorithm:

- for n iterations, with each iteration i ,

- Choose $r = \text{random}(0, n-1)$

- Swap $a[n-i]$ with $a[r]$

- Output permuted array a

* Max Bisection.

Input: Graph G

Output: Two sets A, B that partition $V(G)$ and $| |A| - |B| | \leq 1$.

Algorithm:

- Select an arbitrary $n/2$ points to be in A

- and the other points to be in B . ($n = \#$ of vertices).

- Output A, B .

* Max Cut.

Input: Graph G .

Output: set X s.t. $\delta(X) := |\{uv \in E(G) : u \in X, v \notin X\}|$ is maximized
to create two disjoint sets in G .

Algorithm:

- Include every edge in X with independent probability αS .

- Output X .

* Coupon Collector.

Given n items, infinitely many boxes, each with equal pull rates
 $p = 1 - (i-1)/n$ of getting new item

$E[X_i] = n/(n-i+1)$ boxes until new pull

$E[\sum_i X_i] = n \sum_i 1/i$ total boxes to get one of each

CS292A Notes

* 3-SAT.

Input: set of 3-clauses, literals from choice of n booleans.

Output: an assignment that satisfies or maximizes number of clauses satisfied.. where a clause is satisfied

if an assignment assigns $T = x_i, F = \bar{x}_i \quad \forall x_i \in \text{clause } c$.

Algorithm:

- iterate through n variables

- Set $x_i = \text{True}$ if more clauses use x_i than \bar{x}_i , false otherwise

- Output assignment of x_1, \dots, x_n

* Quicksort.

- Input: $A[1], \dots, A[n]$ list of values.

- Output: Sorted list of values.

Algorithm:

- if $|A| \leq 1$, return A

- pick pivot $p \in A$ u.a.r.

- $L = \{A[i] : A[i] < p\}$

- $R = \{A[i] : A[i] > p\}$

- return $[QS(L), p, QS(R)]$

* Quickselect.

- Input: $A[1], \dots, A[n], k$

- Output: k th value in the sorted list

Algorithm:

- if $|A| = 1$, return $A[1]$

- pick pivot $p \in A$ u.a.r.

- $L = \{A[i] : A[i] < p\}$

- $R = \{A[i] : A[i] > p\}$

- if $|L| \geq k$ return $QS(L, k)$

- if $|L| = k-1$ return p

- else return $QS(R, k - |L| - 1)$