# MATH 240 Lecture 2.2 The Inverse $A^{-1}$ of a matrix A

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Let A be an  $n \times n$  matrix. A is invertible if there is an  $n \times n$  matrix  $A^{-1}$ , called the inverse of A, such that  $AA^{-1} = A^{-1}A = I_n$ .

**Theorem 7 - C2.2** A is invertible  $\iff A \sim I_n$ .

 $(\Longrightarrow)$  If A is invertible, then  $A \sim I_n$ .

 $(\longleftarrow)$  If  $A \sim I_n$ , then A is invertible.

## Proof of Theorem 7-2.2

Suppose A is invertible. Then  $A^{-1}$  exists. Let  $A \sim B$  where B is in REF. (Th5-2.2) If A is invertible, then Ax = b has a unique solution. (Th4-1.4) B in REF has a pivot position in every row

We know 
$$A$$
 is square  $\implies B = \begin{bmatrix} p_1 & x & x \\ 0 & p_2 & x \\ 0 & 0 & p_3 \end{bmatrix}$  where  $p$  are pivots.

We can then apply row operations to B to get B' in RREF. B' in RREF =  $I_n$ 

# **Elementary Matrices**

Every elementary row operation corresponds to a multiplication of A by an  $n \times n$  elementary matrix E, i.e. if  $A \sim B$ , then B = EA. Since row operations are invertible, E is invertible.

### Example

For n = 3 and  $R_2 \leftarrow R_2 - 2R_1$ , find E and  $E^{-1}$ . Start with the  $I_n$ ,  $I_3$ .

$$I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Apply  $R_2 \leftarrow R_2 - 2R_1$  to  $I_3$ .

$$E = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Check.

$$EA = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} a & b & c \\ u & v & w \\ x & y & z \end{bmatrix}$$

$$\begin{bmatrix} a & b & c \\ -2a+u & -2b+v & -2c+w \\ x & y & z \end{bmatrix}$$

Find the inverse.

$$I_3 = egin{bmatrix} 1 & 0 & 0 \ 0 & 1 & 0 \ 0 & 0 & 1 \end{bmatrix}$$

Apply the **Inverse** of the row operation to  $I_3$ .  $R_2 \leftarrow R_2 + 2R_1$ 

$$E^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Check 
$$EE^{-1} = I_3$$
.  
Check  $E^{-1}E = I_3$ .

### Proof of Part 2 of Theorem 7-2.2

Suppose 
$$A \sim I$$
.  $A \sim A_1 \sim A_2 \dots A_{m-1} \sim I$   
=  $E_1 A_1 \dots E_m A_m = I$ 

Let  $E_1 = E_2 \dots E_m$  be the elementary matrices corresponding to the row operations in  $A \sim I$ .

So,

$$A_1 = E_1 \cdot A$$

$$A_2 = E_2 \cdot A_1$$

$$\vdots$$

$$I = E_m \cdot A_{m-1}$$

Because  $A_2 = E_2 \cdot A_1$ , we can write  $A_2 = E_2 \cdot (E_1 \cdot A)$ .

$$I = E_m(\dots(E_2 \cdot (E_1 \cdot A))) = (E_m \dots E_2 \cdot E_1) \cdot A.$$

We can call the matrix product  $E_m \dots E_2 \cdot E_1$  the equivalent matrix C.

We now have CA = I. Is AC = I?

We know that  $E_1, E_2, \ldots, E_m$  are invertible.

Theorem 6b-2.2 
$$(ABC)^{-1} = C^{-1}B^{-1}A^{-1}$$
  
 $C^{-1} = E_1^{-1} \cdot E_2^{-1} \dots E_m^{-1}$   
 $CA = I$   
 $C^{-1}(CA) = C^{-1}I$   
 $(C^{-1}C)A = C^{-1}I \implies A = C^{-1} \implies AC = C^{-1}C = I$ 

# **Invertible Linear Transformations**

Suppose  $T: \mathbb{R}^n \to \mathbb{R}^n$  is a linear transformation. T is invertible if there exists another linear transformation  $S: \mathbb{R}^n \to \mathbb{R}^n$  such that.

1. 
$$S(T(x)) = x$$

2. 
$$T(S(y)) = y$$

### Theorem 9

Let  $T: \mathbb{R}^n \to \mathbb{R}^n$  be a linear transformation with standard matrix A so T(x) = Ax.

T is invertible  $\iff A$  is invertible.

#### Proof of Theorem 9

#### Part 1

 $(\Leftarrow)$  If T is invertible, then A is invertible.

Assume A is invertible. So  $A^{-1}$  exists.

Consider  $S(y) = A^{-1}y$ . Then,

$$S(T(X)) = S(Ax) = A^{-1}(Ax) = (A^{-1}A)x = Ix = x$$
 (1)

$$T(S(X)) = T(A^{-1}x) = A(A^{-1}x) = (A^{-1}A)x = Ix = x$$
 (2)

#### Part 2

 $(\Longrightarrow)$  If A is invertible, then T is invertible.

Assume T(x) = Ax is invertible.

Let S be the inverse of T. S is a Linear Transformation. So, let S(y) = Cy, where C is the standard matrix of S.

$$S(T(x)) = x \implies C(Ax) = x \implies (CA)x = x . \forall x \in \mathbb{R}^n$$
  
 $\implies (CA)e_i = e_i$ 

$$CA = (CA) \begin{bmatrix} \vdots & \vdots & & \vdots \\ e_i & e_2 & \dots & e_n \\ \vdots & \vdots & & \vdots \end{bmatrix} = \begin{bmatrix} (CA)e_1 & (CA)e_2 & \dots & (CA)e_n \end{bmatrix}$$
$$= \begin{bmatrix} e_1 & e_2 & \dots & e_n \end{bmatrix} = I_n$$

We have  $CA = I_n$ . Is  $AC = I_n$ ? Yes, by IMT.