ECE 637 Deep Learning Lab Exercises

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Section 1

Exercise 1.1

- 1. Create two lists, A and B: A contains 3 arbitrary numbers and B contains 3 arbitrary strings.
- 2. Concatenate two lists into a bigger list and name that list C.
- 3. Print the first element in C.
- 4. Print the second last element in C via negative indexing.
- 5. Remove the second element of A from C.
- 6. Print C again.

```
In [ ]: # ------ YOUR CODE ------
import numpy as np

#1
    A = [1,2,3]
    B = ['Alex', 'Olive', 'Pellicer']

#2
    C = A + B

#3
    print(C[0])

#4
    print(C[-2])

#5
    rm = C.pop(1)

#6
    print(C)

1
    Olive
    [1, 3, 'Alex', 'Olive', 'Pellicer']
```

Exercise 1.2

In this exercise, you will use a low-pass IIR filter to remove noise from a sine-wave signal.

You should organize your plots in a 3x1 subplot format.

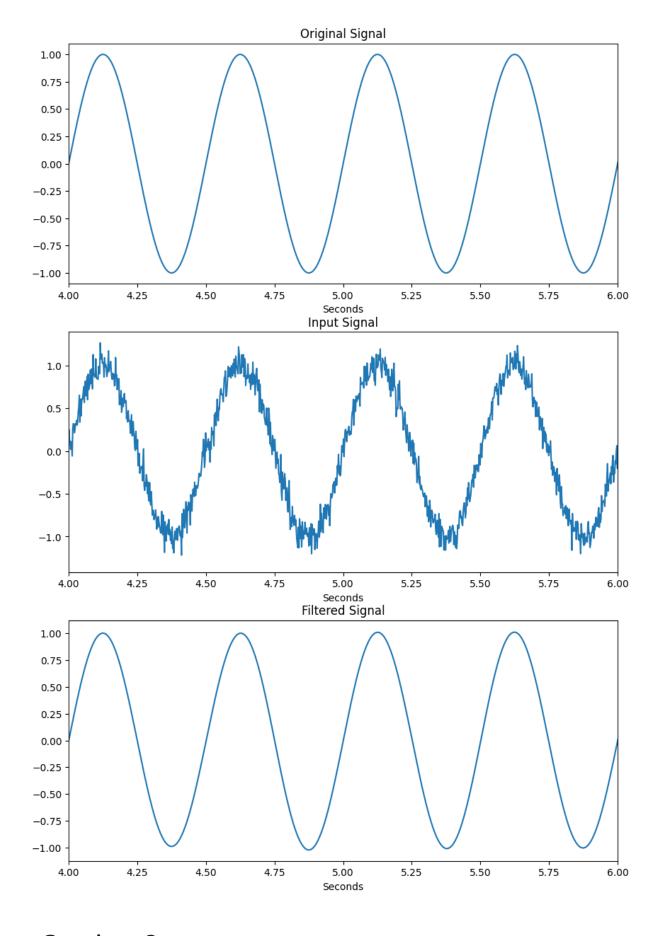
- Generate a discrete-time signal, x, by sampling a 2Hz continuous time sine wave signal with peak amplitude 1 from time 0s to 10s and at a sampling frequency of 500 Hz.
 Display the signal, x, from time 4s to 6s in the first row of a 3x1 subplot with the title "original signal".
- 2. Add Gaussian white random noise with 0 mean and standard deviation 0.1 to $\, x \,$ and call it $\, x_n \,$. Display $\, x_n \,$ from 4s to 6s on the second row of the subplot with the title "input signal".
- 3. Design a low-pass butterworth IIR filter of order 5 with a cut-off frequency of 4Hz, designed to filter out the noise. Hint: Use the signal.butter function and note that the frequencies are relative to the Nyquist frequency. Apply the IIR filter to x_n, and name the output y. Hint: Use signal.filtfilt function. Plot y from 4s to 6s on the third row of the subplot with the title "filtered signal".

```
import numpy as np
In [ ]:
                                                    # import the numpy packages and use a shorte
         import matplotlib.pyplot as plt  # again import the matplotlib's pyplot packa
from scipy import signal  # import a minor package signal from scipy
plt.figure(figsize=(10, 15))  # fix the plot size
         # ----- YOUR CODE -----
         # Part 1
         f = 2 \# Hz
         fs = 500 # sampling frequency
         t start = 0 # seconds
         t_finish = 10 # seconds
         num_samples = fs*(t_finish - t_start)
         t = np.linspace(t_start, t_finish, num_samples)
         x = np.sin(2*np.pi*f*t)
         plt.subplot(3, 1, 1)
         plt.plot(t, x)
         plt.xlim([4, 6])
         plt.title('Original Signal')
         plt.xlabel('Seconds')
         # Part 2
         length = np.size(t);
         n = np.random.randn(length)*0.1
         x_n = x+n
         plt.subplot(3, 1, 2)
         plt.plot(t, x_n)
         plt.xlim([4, 6])
         plt.title('Input Signal')
         plt.xlabel('Seconds')
         # Part 3
         cut freq = 4
         b, a = signal.butter(5, cut_freq, btype='low', fs=fs)
         y = signal.filtfilt(b, a, x_n, padlen=3)
```

```
plt.subplot(3, 1, 3)
plt.plot(t, y)
plt.xlim([4, 6])
plt.title('Filtered Signal')
plt.xlabel('Seconds')

plt.show()
```

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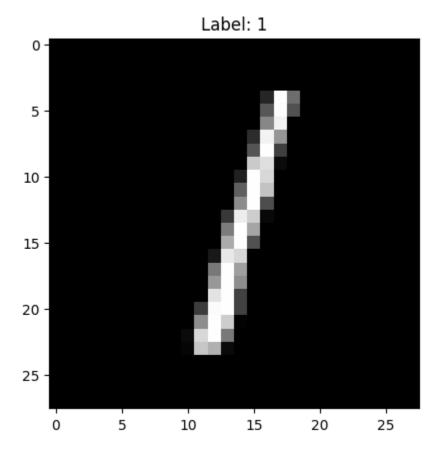


Section 2

Exercise 2.1

- Plot the third image in the test data set
- Find the correspoding label for the this image and make it the title of the figure

Out[]: Text(0.5, 1.0, 'Label: 1')



Exercise 2.2

It is usually helpful to have an accuracy plot as well as a loss value plot to get an intuitive sense of how effectively the model is being trained.

• Add code to this example for plotting two graphs with the following requirements:

- Use a 1x2 subplot with the left subplot showing the loss function and right subplot showing the accuracy.
- For each graph, plot the value with respect to epochs. Clearly label the x-axis, y-axis and the title.

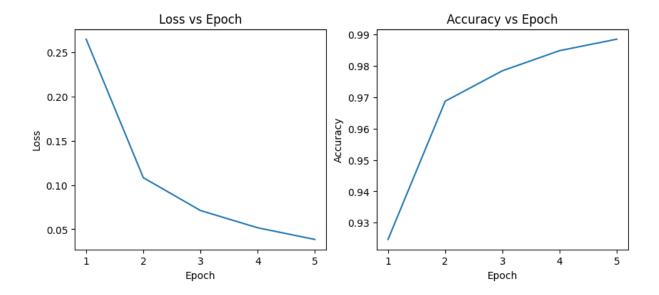
(Hint: The value of of loss and accuracy are stored in the hist variable. Try to print out hist.history and his.history.keys() .)

```
In [ ]: import keras
        from keras.datasets import mnist
        from keras import models
        from keras import layers
        from keras.utils import to_categorical
        (train_images, train_labels), (test_images, test_labels) = mnist.load_data()
        train_images = train_images.reshape((60000, 28, 28, 1))
        test_images = test_images.reshape((10000, 28, 28, 1))
        network = models.Sequential()
        network.add(layers.Flatten(input_shape=(28, 28, 1)))
        network.add(layers.Dense(512, activation='relu'))
        network.add(layers.Dense(10, activation='softmax'))
        network.summary()
        network.compile(optimizer='rmsprop', loss='categorical_crossentropy', metrics=['acc
        train_images_nor = train_images.astype('float32') / 255
        test_images_nor = test_images.astype('float32') / 255
        train_labels_cat = to_categorical(train_labels)
        test_labels_cat = to_categorical(test_labels)
        hist = network.fit(train_images_nor, train_labels_cat, epochs=5, batch_size=128)
```

Model: "sequential_27"

```
Layer (type)
                              Output Shape
                                                    Param #
      ______
      flatten_13 (Flatten)
                              (None, 784)
      dense_37 (Dense)
                              (None, 512)
                                                    401920
      dense 38 (Dense)
                              (None, 10)
                                                    5130
      _____
      Total params: 407050 (1.55 MB)
      Trainable params: 407050 (1.55 MB)
      Non-trainable params: 0 (0.00 Byte)
      Epoch 1/5
      469/469 [============= ] - 2s 3ms/step - loss: 0.2648 - accuracy: 0.
      9247
      Epoch 2/5
      469/469 [============= ] - 2s 3ms/step - loss: 0.1083 - accuracy: 0.
      9687
      Epoch 3/5
      469/469 [============= ] - 2s 3ms/step - loss: 0.0712 - accuracy: 0.
      9784
      Epoch 4/5
      469/469 [============= ] - 2s 3ms/step - loss: 0.0517 - accuracy: 0.
      9848
      Epoch 5/5
      469/469 [============= ] - 2s 3ms/step - loss: 0.0385 - accuracy: 0.
In [ ]: import matplotlib.pyplot as plt
      plt.figure(figsize=(10, 4))
       # ----- YOUR CODE -----
       epoch = [1, 2, 3, 4, 5]
      plt.subplot(1, 2, 1)
      plt.plot(epoch, hist.history['loss'])
       plt.xlabel('Epoch')
      plt.ylabel('Loss')
      plt.title('Loss vs Epoch')
      plt.subplot(1, 2, 2)
      plt.plot(epoch, hist.history['accuracy'])
      plt.xlabel('Epoch')
      plt.ylabel('Accuracy')
      plt.title('Accuracy vs Epoch')
      plt.show()
```

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Exercise 2.3

Use the dense network from Section 2 as the basis to construct of a deeper network with

• 5 dense hidden layers with dimensions [512, 256, 128, 64, 32] each of which uses a ReLU non-linearity

Question: Will the accuracy on the testing data always get better if we keep making the neural network larger?

No. Not always that we make the neural network larger the accuracy will get better. There will be a moment where the neural network will be too large so that it will overfit the training data. We say that the capacity of the neural network will be too high with respect to the training data points. As a result, the model will not generalize so it will not perform well on the testing data.

Model: "sequential_28"

Layer (type)	Output Shape	Param #
flatten_14 (Flatten)	(None, 784)	0
dense_39 (Dense)	(None, 512)	401920
dense_40 (Dense)	(None, 256)	131328
dense_41 (Dense)	(None, 128)	32896
dense_42 (Dense)	(None, 64)	8256
dense_43 (Dense)	(None, 32)	2080
dense_44 (Dense)	(None, 10)	330

Total params: 576810 (2.20 MB)
Trainable params: 576810 (2.20 MB)
Non-trainable params: 0 (0.00 Byte)

```
In []: import keras
from keras.datasets import mnist
from keras.datasets import to_categorical

    (train_images, train_labels), (test_images, test_labels) = mnist.load_data()

    train_images = train_images.reshape((60000, 28, 28, 1))

    test_images = test_images.reshape((10000, 28, 28, 1))

    network.compile(optimizer='rmsprop', loss='categorical_crossentropy', metrics=['acc
    train_images_nor = train_images.astype('float32') / 255
    test_images_nor = test_images.astype('float32') / 255

train_labels_cat = to_categorical(train_labels)
    test_labels_cat = to_categorical(test_labels)

hist = network.fit(train_images_nor, train_labels_cat, epochs=5, batch_size=128)

test_loss, test_acc = network.evaluate(test_images_nor, test_labels_cat)
    print('test_accuracy:', test_acc)
```

```
Epoch 1/5
469/469 [============== ] - 3s 4ms/step - loss: 0.3013 - accuracy: 0.
9072
Epoch 2/5
469/469 [============ ] - 2s 4ms/step - loss: 0.1016 - accuracy: 0.
9686
Epoch 3/5
469/469 [============= ] - 2s 4ms/step - loss: 0.0683 - accuracy: 0.
9789
Epoch 4/5
469/469 [============ ] - 3s 6ms/step - loss: 0.0499 - accuracy: 0.
9845
Epoch 5/5
469/469 [============= ] - 2s 4ms/step - loss: 0.0387 - accuracy: 0.
9805
test_accuracy: 0.9804999828338623
```

Section 3

Exercise 3.1

In this exercise, you will access the relationship between the feature extraction layer and classification layer. The example above uses two sets of convolutional layers and pooling layers in the feature extraction layer and two dense layers in the classification layers. The overall performance is around 98% for both training and test dataset. In this exercise, try to create a similar CNN network with the following requirements:

- Achieve the overall accuracy higher than 99% for training and testing dataset.
- Keep the total number of parameters used in the network lower than 100,000.

Model: "sequential_29"

Layer (type)	Output Shape	Param #	
conv2d_43 (Conv2D)		160	
<pre>max_pooling2d_19 (MaxPooli ng2D)</pre>	(None, 14, 14, 16)	0	
conv2d_44 (Conv2D)	(None, 14, 14, 32)	4640	
<pre>max_pooling2d_20 (MaxPooli ng2D)</pre>	(None, 7, 7, 32)	0	
conv2d_45 (Conv2D)	(None, 7, 7, 64)	18496	
<pre>max_pooling2d_21 (MaxPooli ng2D)</pre>	(None, 3, 3, 64)	0	
flatten_15 (Flatten)	(None, 576)	0	
dense_45 (Dense)	(None, 128)	73856	
dense_46 (Dense)	(None, 10)	1290	

```
train_images = train_images.reshape((60000, 28, 28, 1))
train_images_nor = train_images.astype('float32') / 255
test_images = test_images.reshape((10000, 28, 28, 1))
test_images_nor = test_images.astype('float32') / 255

train_labels_cat = to_categorical(train_labels)
test_labels_cat = to_categorical(test_labels)

network.compile(optimizer='rmsprop', loss='categorical_crossentropy', metrics=['acc network.fit(train_images_nor, train_labels_cat, epochs=5, batch_size=128)

test_loss, test_acc = network.evaluate(test_images_nor, test_labels_cat)
print('test_accuracy:', test_acc)
```

```
Epoch 1/5
9137
Epoch 2/5
469/469 [============ ] - 2s 5ms/step - loss: 0.0626 - accuracy: 0.
9803
Epoch 3/5
469/469 [============ ] - 2s 5ms/step - loss: 0.0410 - accuracy: 0.
9867
Epoch 4/5
469/469 [============ ] - 3s 6ms/step - loss: 0.0304 - accuracy: 0.
9902
Epoch 5/5
469/469 [============ ] - 2s 5ms/step - loss: 0.0239 - accuracy: 0.
9924
test accuracy: 0.9901999831199646
```

Section 4

Exercise 4.1

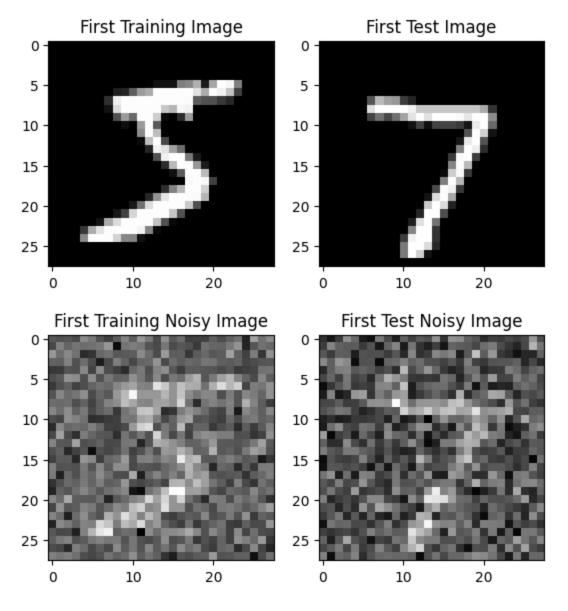
In this exercise you will need to create the entire neural network that does image denoising tasks. Try to mimic the code provided above and follow the structure as provided in the instructions below.

Task 1: Create the datasets

- 1. Import necessary packages
- 2. Load the MNIST data from Keras, and save the training dataset images as train_images, save the test dataset images as test_images
- 3. Add additive white gaussian noise to the train images as well as the test images and save the noisy images to train_images_noisy and test_images_noisy respectivly. The noise should have mean value 0, and standard deviation 0.4. (Hint: Use np.random.normal)

4. Show the first image in the training dataset as well as the test dataset (plot the images in 1×2 subplot form)

```
In [ ]: | # ------ YOUR CODE -----
        import keras
        from keras.datasets import mnist
        from keras import models
        from keras import layers
        from tensorflow.keras.utils import to_categorical
        import matplotlib.pyplot as plt
        import numpy as np
        (train_images, train_labels), (test_images, test_labels) = mnist.load_data()
        train_images = train_images.reshape((60000, 28, 28, 1))
        train_images_nor = train_images.astype('float32') / 255
        test_images = test_images.reshape((10000, 28, 28, 1))
        test images nor = test images.astype('float32') / 255
        train_noise = np.random.normal(0, 0.4, train_images.shape)
        test noise = np.random.normal(0, 0.4, test images.shape)
        train_images_noisy = train_images_nor + train_noise
        test images noisy = test images nor + test noise
        train_labels_cat = to_categorical(train_labels)
        test_labels_cat = to_categorical(test_labels)
        first_train = train_images[0,:,:,0]
        first test = test images[0,:,:,0]
        plt.subplot(1, 2, 1)
        plt.imshow(first train, cmap='gray')
        plt.title('First Training Image')
        plt.subplot(1, 2, 2)
        plt.imshow(first test, cmap='gray')
        plt.title('First Test Image')
        plt.show()
        first_noisy_train = train_images_noisy[0,:,:,0]
        first noisy test = test images noisy[0,:,:,0]
        plt.subplot(1, 2, 1)
        plt.imshow(first_noisy_train, cmap='gray')
        plt.title('First Training Noisy Image')
        plt.subplot(1, 2, 2)
        plt.imshow(first_noisy_test, cmap='gray')
        plt.title('First Test Noisy Image')
        plt.show()
```



Task 2: Create the neural network model

- 1. Create a sequential model called encoder with the following layers sequentially:
- convolutional layer with 32 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activition function.
- max pooling layer with 2x2 kernel size
- convolutional layer with 16 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activition function.
- max pooling layer with 2x2 kernel size
- convolutional layer with 8 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activition function and name the layer as 'convOutput'.
- flatten layer
- dense layer with output dimension as encoding_dim with 'relu' activition function.
- 2. Create a sequential model called decoder with the following layers sequentially:

- dense layer with the input dimension as encoding_dim and the output dimension as the product of the output dimensions of the 'convOutput' layer.
- reshape layer that convert the tensor into the same shape as 'convOutput'
- convolutional layer with 8 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activition function.
- upsampling layer with 2x2 kernel size
- convolutional layer with 16 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activition function.
- upsampling layer with 2x2 kernel size
- convolutional layer with 32 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activition function
- convolutional layer with 1 output channels, 3x3 kernel size, and the padding convention 'same' with 'sigmoid' activition function
- 3. Create a sequential model called autoencoder with the following layers sequentially:
- encoder model
- decoder model

In []: # ------ YOUR CODE -----

```
encoding_dim = 32
        # 1
        encoder = models.Sequential()
        encoder.add(layers.Conv2D(32, (3, 3), activation='relu', padding = 'same', input_sh
        encoder.add(layers.MaxPooling2D((2, 2)))
        encoder.add(layers.Conv2D(16, (3, 3), activation='relu', padding = 'same'))
        encoder.add(layers.MaxPooling2D((2, 2)))
        encoder.add(layers.Conv2D(8, (3, 3), activation='relu', padding = 'same', name = 'c
        encoder.add(layers.Flatten())
        encoder.add(layers.Dense(encoding_dim, activation='relu'))
        # 2
        conv_output_shape = encoder.get_layer('convOutput').output_shape[1:]
        dense_output_shape = conv_output_shape[0]*conv_output_shape[1]*conv_output_shape[2]
        decoder = models.Sequential()
        decoder.add(layers.Dense(dense output shape, input shape=(encoding dim,)))
        decoder.add(layers.Reshape(conv_output_shape))
        decoder.add(layers.Conv2D(8, (3, 3), activation='relu', padding = 'same'))
        decoder.add(layers.UpSampling2D((2, 2)))
        decoder.add(layers.Conv2D(16, (3, 3), activation='relu', padding = 'same'))
        decoder.add(layers.UpSampling2D((2, 2)))
        decoder.add(layers.Conv2D(32, (3, 3), activation='relu', padding = 'same'))
        decoder.add(layers.Conv2D(1, (3, 3), activation='sigmoid', padding = 'same'))
        # 3
        autoencoder = models.Sequential()
        autoencoder.add(encoder)
        autoencoder.add(decoder)
        encoder.summary()
In [ ]:
        decoder.summary()
        autoencoder.summary()
```

Model: "sequential_30"

Layer (type)	Output Shape	Param #
conv2d_46 (Conv2D)	(None, 28, 28, 32)	320
<pre>max_pooling2d_22 (MaxPooli ng2D)</pre>	(None, 14, 14, 32)	0
conv2d_47 (Conv2D)	(None, 14, 14, 16)	4624
<pre>max_pooling2d_23 (MaxPooli ng2D)</pre>	(None, 7, 7, 16)	0
convOutput (Conv2D)	(None, 7, 7, 8)	1160
flatten_16 (Flatten)	(None, 392)	0
dense_47 (Dense)	(None, 32)	12576

Total params: 18680 (72.97 KB)
Trainable params: 18680 (72.97 KB)
Non-trainable params: 0 (0.00 Byte)

Model: "sequential_31"

Layer (type)	Output Shape	Param #
dense_48 (Dense)	(None, 392)	12936
reshape_6 (Reshape)	(None, 7, 7, 8)	0
conv2d_48 (Conv2D)	(None, 7, 7, 8)	584
up_sampling2d_12 (UpSampli ng2D)	(None, 14, 14, 8)	0
conv2d_49 (Conv2D)	(None, 14, 14, 16)	1168
up_sampling2d_13 (UpSampli ng2D)	(None, 28, 28, 16)	0
conv2d_50 (Conv2D)	(None, 28, 28, 32)	4640
conv2d_51 (Conv2D)	(None, 28, 28, 1)	289

Total params: 19617 (76.63 KB)
Trainable params: 19617 (76.63 KB)
Non-trainable params: 0 (0.00 Byte)

Model: "sequential_32"

Layer (type)	Output Shape	Param #	

Task 3: Create the neural network model

Fit the model to the training data using the following hyper-parameters:

- adam optimizer
- binary_crossentropy loss function
- 20 training epochs
- batch size as 256
- set shuffle as True

Compile the model and fit ...

```
Epoch 1/20
Epoch 2/20
Epoch 3/20
Epoch 4/20
Epoch 5/20
235/235 [=============== ] - 3s 11ms/step - loss: 0.1137
Epoch 6/20
Epoch 7/20
Epoch 8/20
Epoch 9/20
Epoch 10/20
Epoch 11/20
235/235 [============== ] - 3s 11ms/step - loss: 0.1029
Epoch 12/20
Epoch 13/20
Epoch 14/20
235/235 [============] - 3s 11ms/step - loss: 0.1008
Epoch 15/20
235/235 [============= ] - 3s 11ms/step - loss: 0.1001
Epoch 16/20
235/235 [================ ] - 3s 11ms/step - loss: 0.0998
Epoch 17/20
235/235 [========== ] - 3s 11ms/step - loss: 0.0992
Epoch 18/20
Epoch 19/20
235/235 [============= ] - 3s 11ms/step - loss: 0.0985
Epoch 20/20
```

Task 4: Create the neural network model (No need to write code, just run the following commands)

```
In [ ]: def showImages(input_imgs, encoded_imgs, output_imgs, size=1.5, groundTruth=None):
    numCols = 3 if groundTruth is None else 4
    num_images = input_imgs.shape[0]
    encoded_imgs = encoded_imgs.reshape((num_images, 1, -1))

    plt.figure(figsize=((numCols+encoded_imgs.shape[2]/input_imgs.shape[2])*size, num
```

```
pltIdx = 0
col = 0
for i in range(0, num_images):
  col += 1
  # plot input image
  pltIdx += 1
  ax = plt.subplot(num_images, numCols, pltIdx)
  plt.imshow(input_imgs[i].reshape(28, 28))
  plt.gray()
  ax.get_xaxis().set_visible(False)
  ax.get_yaxis().set_visible(False)
  if col == 1:
    plt.title('Input Image')
  # plot encoding
  pltIdx += 1
  ax = plt.subplot(num_images, numCols, pltIdx)
  plt.imshow(encoded_imgs[i])
  plt.gray()
  ax.get_xaxis().set_visible(False)
  ax.get_yaxis().set_visible(False)
  if col == 1:
    plt.title('Encoded Image')
  # plot reconstructed image
  pltIdx += 1
  ax = plt.subplot(num_images, numCols, pltIdx)
  plt.imshow(output_imgs[i].reshape(28, 28))
  plt.gray()
  ax.get_xaxis().set_visible(False)
  ax.get_yaxis().set_visible(False)
  if col == 1:
    plt.title('Reconstructed Image')
  if numCols == 4:
    # plot ground truth image
    pltIdx += 1
    ax = plt.subplot(num_images, numCols, pltIdx)
    plt.imshow(groundTruth[i].reshape(28, 28))
    plt.gray()
    ax.get_xaxis().set_visible(False)
    ax.get_yaxis().set_visible(False)
    if col == 1:
      plt.title('Ground Truth')
plt.show()
```

```
in [ ]: num_images = 10

input_labels = test_labels[0:num_images]
I = np.argsort(input_labels)

input_imgs = test_images_noisy[I]
```

