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COL 7/4

Machine Learning
Major Exam

①

Elliptical SVM

Aug 31, 2020

Q.2.

$$h(x) = 1 \left\{ \sum_{j=1}^n \frac{x_j^2}{a_j^2} \leq 1 \right\} \quad \Leftrightarrow \text{corresponds to elliptical decision boundary}$$

$$\left[\sum_{j=1}^n x_j^2 / a_j^2 = 1 \right]$$

 $\phi(x_j) =$

let $x_j^2 = t_j$ & $1/a_j^2 = w_j$ ($w_j \geq 0$) — (1)

$\phi(x)$ kernel fn

Then using the transformation defined in (1) we have:

$$\sum_{j=1}^n w_j t_j = 1 \quad \text{as the decision boundary.}$$

Equivalently, we have

$$\sum_{j=1}^n w_j t_j - 1 = 0 \quad \Rightarrow \text{equation of a hyperplane}$$

which can equivalently be written as:

$$\boxed{w'^T t + b = 0}$$

[using the fact that
 $t_j: -w_j' = w_j * (-b)$
 $(-b) > 0$]

There is an additional scale factor here that we can exploit

$$\Rightarrow \{ \sum w_j' t + b \geq 0 \} \Rightarrow \text{the class } h(x)$$

& $\{ \sum w_j' t + b < 0 \}$ as the class

(why we can call above as +ve class)
 [we are flipping the signs of 2 classes]

with additional constraint that

$$\|w'\| \geq 0$$

Note: - Since data is a separable w.r.t elliptical boundary, to 4 $\hat{y} \equiv x_f \geq 0$
we do not need to explicitly enforce the constraint $-b \geq 0$ (think why).

\Rightarrow converting this into SVM form we get

$$\min_{w, b} \quad \frac{1}{2} w'^T w'$$

$$y^{(i)} [w'^T t^{(i)} + b] \geq 1 \quad \forall i \quad y^{(i)} \in \{1, -1\}$$

\rightarrow Lagrange multipliers α_i

Therefore, Lagrangian multiplier can be written as -

$\square w' \geq 0$ - Lagrange multipliers $-\beta$ (β_1, \dots, β_n)

$$L(w, b, \alpha, \beta) = \frac{1}{2} w'^T w' + \sum_{i=1}^m \alpha_i [1 - y^{(i)} (w'^T t^{(i)} + b)]$$

Now, to get the dual we will equate gradient wrt primal variables to 0.

$$\nabla_w L(w, b, \alpha, \beta) = w' + \sum_{i=1}^m -\alpha_i y^{(i)} t^{(i)} + (-1) \beta$$

\square

to get dual, we equate gradient wrt primal variables to 0.

\square dual is unconstrained, main idea

Equating this to zero, we get

$$w' = \sum_{i=1}^m \alpha_i y^{(i)} t^{(i)} + \beta$$

similarly,

$$\nabla_b L(w, b, \alpha, \beta) = \sum_{i=1}^m \alpha_i y^{(i)} (-1) = 0$$

\square

$$\Rightarrow \sum_{i=1}^m \alpha_i y^{(i)} = 0$$

② substituting the value of w' in the Lagrangian, we get:-

$$L(w, b, \alpha, \beta) = \frac{1}{2} \left[\sum_{i=1}^m \alpha_i y_i (t^w + \beta) \right]^T \left[\sum_{i=1}^m \alpha_i y_i (t^w + \beta) \right] + \sum_{i=1}^m \alpha_i - \sum_{i=1}^m \alpha_i y_i \left[\sum_{i=1}^m \alpha_i y_i (t^w + \beta) \right] t^w + b - \beta^T \left[\sum_{i=1}^m \alpha_i y_i (t^w + \beta) \right]$$

$$= \frac{1}{2} \left[\sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j (t^w)^T t^w + t^w \right] + \frac{1}{2} [\beta^T \beta]$$

$$+ \cancel{\frac{1}{2} \beta^T \sum_{i=1}^m \alpha_i y_i (t^w)} + \sum_{i=1}^m \alpha_i$$

$$- \sum_{i=1}^m \alpha_i y_i \left[\sum_{j=1}^m \alpha_j y_j (t^w + \beta) \right]^T t^w + b$$

$$- \beta^T \sum_{i=1}^m \alpha_i y_i (t^w) + (-1) \beta^T \beta$$

$$= \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j (t^w)^T t^w - \frac{1}{2} \beta^T \beta$$

$$- \sum_{i=1}^m [\beta^T \alpha_i y_i (t^w)] - b \sum_{i=1}^m \alpha_i y_i$$

$D(\alpha, \beta)$

$$\equiv \sum_{i=1}^m \alpha_i - \frac{1}{2} \beta^T \beta - \frac{1}{2} \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j (t^w)^T t^w - \beta^T \sum_{i=1}^m \alpha_i y_i (t^w)$$

Dual: -

$$\max_{\alpha, \beta}$$

$$D(\alpha, \beta)$$

$$\alpha, \beta \quad \alpha \geq 0, \beta \geq 0$$

$$\sum_{i=1}^m \alpha_i y_i = 0$$

Q.2. PCA (generalized)

From standard PCA, we know that the PCA components can be obtained by solving

$$(a) \max_{u \perp \phi} u^T \left[\sum_{i=1}^m \frac{\phi(x_i) \phi(x_i)^T}{m} \right] u \equiv \sum \phi$$

in the transformed space (one component at a time).

This can be done using (finding) / solving eigen the following eigenproblem: value

$$\sum \phi u \phi = \lambda u \phi$$

with ~~subst~~ where $\sum \phi = \sum_{i=1}^m \frac{\phi(x_i) \phi(x_i)^T}{m}$

substituting this in the above equation, we get

$$\sum_{i=1}^m \frac{\phi(x_i) \phi(x_i)^T}{m} u \phi = \lambda u \phi$$

(3)

$$\sum_{i=1}^m \phi(x^{(i)}) \frac{[\phi(x^{(i)})^T u_p \phi]}{m} = \lambda u_p \phi$$

$$\Rightarrow u_p \phi = \frac{1}{\lambda m} \left[\sum_{i=1}^m \phi(x^{(i)}) [\phi(x^{(i)})^T u_p \phi] \right]$$

\Rightarrow Desired coefficients are given as:-

$$\left\{ a_p^i = \frac{\phi(x^{(i)})^T u_p \phi}{\lambda m} \right\} \text{ s.t.}$$

$$u_p \phi = \sum_{i=1}^m a_p^i \phi(x^{(i)})$$

(b) We have:-

$$u_p \phi = \frac{1}{\lambda m} \sum_{i=1}^m a_p^i \phi(x^{(i)})$$

Pre-multiplying both sides by $\phi(x^{(j)})^T$ for some j ,

we get

$$\phi(x^{(j)})^T u_p \phi = \frac{1}{\lambda m} \phi(x^{(j)})^T \sum_{i=1}^m a_p^i \phi(x^{(i)})$$

$$\Downarrow$$

$$[a_p^j \cdot \lambda m]$$

$$\Rightarrow a_p^j \cdot \lambda m = \frac{1}{\lambda m} \sum_{i=1}^m a_p^i \underbrace{\phi(x^{(j)})^T \phi(x^{(i)})}_{K(x^{(j)}, x^{(i)})}$$

$$\boxed{\lambda a_p^j = \frac{1}{m} \sum_{i=1}^m a_p^i K(x^{(j)}, x^{(i)})}$$

This equation
gives an
individual
equation for
 $\phi(x^{(j)})$

(c) Continuing further we get (using simple matrix algebra)

$$\boxed{\lambda a_p = \frac{1}{m} K^M a_p}$$

[λ is some scalar quantity]

$\Rightarrow a_p$ is eigenvector of the matrix

$$\begin{bmatrix} K^M \\ m \end{bmatrix}$$

& λ corresponding eigenvalue.

$$K^M = \begin{bmatrix} \text{---} & \text{---} & \text{---} \\ & k(x^{(1)}, x^{(1)}) & \\ & & \ddots \\ & & & k(x^{(m)}, x^{(m)}) \end{bmatrix}$$

is the kernel matrix.

Finally we have to ensure that

$$\underline{u_p^T u_p = 1}$$

$$\Rightarrow \sum_{i=1}^m a_p^i \phi(x^{(i)})^T \sum_{j=1}^m a_p^j \phi(x^{(j)}) = 1$$

$$\Rightarrow \sum_{i,j=1}^m a_p^i \phi(x^{(i)})^T \phi(x^{(j)}) a_p^j = 1$$

$$\Rightarrow \boxed{a_p^T K^M a_p = 1}$$

Putting this in equation

$$a_p = \frac{1}{\lambda m} K^M a_p \quad (\text{Pre-multiply by } a_p^T)$$

$$a_p^T a_p = \frac{1}{\lambda m} a_p^T K^M a_p$$

$$\text{we get } \boxed{a_p^T a_p = \frac{1}{\lambda m} \cdot 1} \quad \square$$

$$\begin{aligned} (d) \quad & \phi(x^{(i)})^T u_p \phi \\ &= \phi(x^{(i)})^T \sum_{j=1}^m a_p^j \phi(x^{(j)}) \\ &= \sum_{j=1}^m a_p^j \underbrace{\phi(x^{(i)})^T \phi(x^{(j)})}_{k(x^{(i)}, x^{(j)})} \\ & \text{ } a_p^j \text{ can be computed in terms of } K \text{ function} \\ & \Rightarrow \phi(x^{(i)})^T u_p \phi \text{ can be computed in terms of } K \text{ fn.} \end{aligned}$$

Q3. (a) In general. For m points. $LL(\theta) =$ for logistic regression

$$\nabla_{\theta} LL(\theta) = \nabla_{\theta} \sum_{i=1}^m y_i \log \left[\frac{1}{1 + e^{-\theta^T x_i}} \right]$$

$$\begin{aligned} LL(\theta) &= \sum_{i=1}^m y_i \left[\log \frac{1}{1 + e^{-\theta^T x_i}} \right] + \sum_{i=1}^m (1 - y_i) \left[\log \frac{e^{-\theta^T x_i}}{1 + e^{-\theta^T x_i}} \right] \\ &\Rightarrow -\nabla_{\theta} \left[\sum_{i=1}^m y_i \log [1 + e^{-\theta^T x_i}] + \sum_{i=1}^m (1 - y_i) \theta^T x_i \right] \\ &= -\nabla_{\theta} \left[\sum_{i=1}^m \log [1 + e^{-\theta^T x_i}] + \sum_{i=1}^m (1 - y_i) \theta^T x_i \right] \end{aligned}$$

$$= \sum_{i=1}^m \frac{1}{[1 + e^{-\theta^T x_i}]} [-x_i] (-1) + \nabla_{\theta} \sum_{i=1}^m \theta^T x_i (1 - y_i) (-1)$$

$$= \sum_{i=1}^m \left[\frac{e^{-\theta^T x_i} x_i}{1 + e^{-\theta^T x_i}} - (1 - y_i) x_i \right]$$

$$\boxed{\nabla_{\theta} LL(\theta) = \sum_{i=1}^m \left[y_i - \frac{1}{1 + e^{-\theta^T x_i}} \right] x_i}$$

$$\nabla_{\theta}^2 LL(\theta) = \sum_{i=1}^m \frac{e^{-\theta^T x_i} x_i x_i^T}{(1 + e^{-\theta^T x_i})^2}$$

$$\nabla_{\theta}^2 LL(\theta) = \sum_{i=1}^m \frac{1}{(1 + e^{-\theta^T x_i})^2} [x_i x_i^T]$$

This is the same as the second derivative

Since:-

$$- \sum_{l=1}^m u^T K^{(l)} x^{(l)} x^{(l)T} u$$

the number

$$= - \sum_{l=1}^m K^{(l)} [u^T x^{(l)}]^2 \leq 0$$

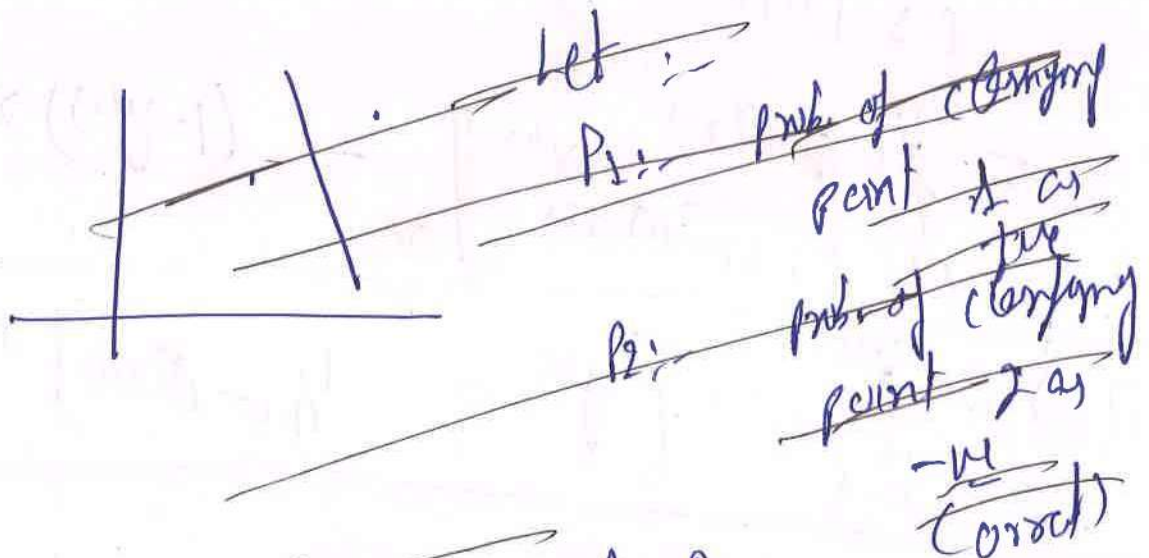
$\Rightarrow L(u)$ is concave.

$-L(u)$ is ~~convex~~ convex

Holds:- for m points

\Rightarrow holds for m=2 points.

(b)



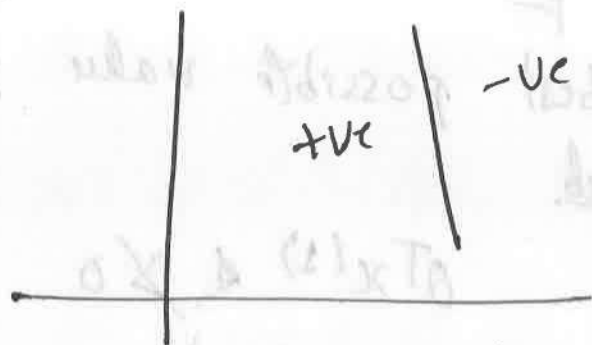
$$L(u) = \log P_1 + \log P_2$$

$$\Rightarrow \text{Dist} :- \alpha$$

$$\text{Dist} :- \gamma \epsilon$$

5)

Q.3 (b)



Two points in \mathbb{R}^2 for visualization (only).

First, we will show that optimal decision boundary must classify the 2 points correctly.

$$LL(\theta) = \log \left[\frac{1}{1 + e^{-\theta^T x^{(1)}}} \right] + \log \left[\frac{e^{-\theta^T x^{(2)}}}{1 + e^{-\theta^T x^{(2)}}} \right]$$

\rightarrow likelihood for 1st point likelihood for 2nd point

$$= \log \left[\frac{1}{1 + e^{-\theta^T x^{(1)}}} \right] + \log \left[\frac{1}{1 + e^{+\theta^T x^{(2)}}} \right]$$

To maximize this, we would need to maximize both terms

clearly if $\theta^T x^{(1)} > 0$ & $\theta^T x^{(2)} < 0$
 (i.e. decision boundary is between the two points)

we can make

$$\theta^T x^{(1)} \rightarrow \infty$$

$$1 + [\theta^T x^{(2)}] \rightarrow \infty$$

by scaling θ arbitrarily
 the decision surface

is not changing
 Replace θ by $k\theta$
 $k > 0$

as $k \rightarrow \infty$

$$L(0) \rightarrow 1 + \frac{1}{1} = 2$$

This is the best possible value that can be achieved.

Note that if $\nabla L(x(1)) \neq 0$

or $\nabla L(x(2)) \neq 0$

i.e. the points are separated by the boundary (with the +ve & -ve on correct sides): -

Then at least one of the terms will not be able to reach 1

i.e. if $\nabla L(x(i)) < 0$ then
maximum value of $\frac{1}{1 + e^{-\nabla L(x(i))}}$

$$\text{is } \frac{1}{2} = 0.5$$

\Rightarrow i.e. $L(0) \leq 1.5$ in this

$\Rightarrow Q$ can not be optimal.

~~(c) For using part (b) optimal class~~

Therefore, for the optimal boundary, it must be somewhere between the +ve & -ve points, specifically the boundary, with equal distance from the +ve & -ve points will be optimal. (one of the)

② Maximum value of $L(\theta)$ in this setting as shown in part (b) above is 2. But it is only in the limit

$$\left[\frac{1}{1+e^{-\theta^T x^{(1)}k}} + \frac{1}{1+e^{+\theta^T x^{(2)}k}} \right] = L(\theta)$$

$$\underline{k \rightarrow \infty}$$

But for any finite value of k

$$\boxed{L(\theta) \neq 2}$$

But that is not an issue since, during practical implementation, we stop learning when

$$|L(\theta^{(t+1)}) - L(\theta^{(t)})| < \epsilon$$

Alternatively, we can write $\nabla L(\theta) \rightarrow 0$

for some ϵ . Thus will

happen since $L(\theta) \rightarrow 2$ in the limit $\Rightarrow \theta^{(t)}$ & $\theta^{(t+1)}$ as we take gradient steps such that

$L(\theta^{(t)})$ is as close to 2 as possible

$$\nabla L(\theta) = \sum_{i=1}^2 \left[y^{(i)} - h_{\theta}(x^{(i)}) \right] x^{(i)}$$

$h_{\theta}(x^{(1)}) \rightarrow 1$ or 0 as the case might be
 $h_{\theta}(x^{(2)}) = \left[\frac{1}{1+e^{-\theta^T x^{(2)}}} \right]$ as $\theta \rightarrow k \rightarrow \infty$
 $h_{\theta}(x^{(2)}) \rightarrow 1$

as $k \rightarrow \infty$ $\log(1) + \log(1) = 0 + 0 = 0$
 $L(0) \rightarrow 1 + \frac{1}{1} = 2$

This is the best possible value that can be achieved.

Note that if $\partial T x(1) \neq 0$

or $\partial T x(2) \neq 0$

i.e. the points are separated by the boundary (with the +ve & -ve on correct sides): -

Then at least one of the terms will not be able to reach 1

i.e. if $\partial T x(i) < 0$ then
 maximum value of $\frac{1}{1 + e^{-\partial T x(i)}}$

is $\frac{1}{2} = 0.5$

\Rightarrow (i.e.) $L(0) \leq 2[0.5]$ in this case (other term can be at most 1)

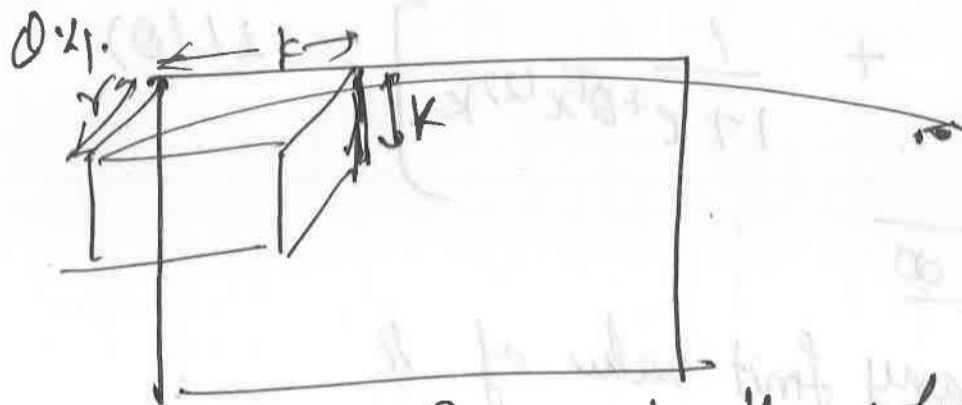
\Rightarrow Q can not be optimal.

~~For using part (b) optimal class~~

Therefore, for the optimal boundary, it must be somewhere between the two +ve & -ve points, specifically the boundary, with equal distance from the +ve & -ve points will be optimal. (One of the)

gradient goes to zero similarly for the second term

$$L_{ex} : \{ h_o(x^{(i)}) = \frac{1}{1 + e^{-\theta^T x^{(i)}}} \}$$



let us first write the relevant equations:

let the kernel be denoted by \underline{K}

i, j vary over width / height of the image

let $z_{i,j,l}^{(t)}$ denote the feature map at (i,j) position & depth l ($1 \leq i, j \leq W$)

$$1 \leq l \leq P$$

P :- kernel index

$$1 \leq P \leq \gamma$$

$x^{(t)}$:- Feature after convolution (before average pooling)

Feature map before the pooling layer

$$\left[\sum_{l=1}^P K_{u,v,l} \cdot x_{i+u, j+v, l}^{(t)} + b \right] = x_{i,j,P}^{(t)}$$

$1 \leq i, j \leq W$
 $1 \leq l \leq \gamma$
 $1 \leq P \leq \gamma$

① Average Pooling:-

$$x_{i,j,p}^{(t+1)} = \frac{\sum_{\alpha,\beta=1}^2 x'_{i+\alpha,j+\beta,p}(t)}{4}$$

Then:- we have: \downarrow
(Gradient wrt ~~pool~~ feature map going into pooling layer)

$$\textcircled{1} \quad \frac{\partial L}{\partial x'_{i,j,p}(t)} = \sum_{\alpha,\beta=1}^2 \frac{\partial L}{\partial x_{i+\alpha,j+\beta,p}^{(t+1)}} \cdot \left[\frac{\partial x_{i+\alpha,j+\beta,p}^{(t+1)}}{\partial x'_{i,j,p}(t)} \right]$$

From \downarrow ② \Downarrow

$$= \frac{1}{4} \sum_{\alpha,\beta=1}^2 \frac{\partial L}{\partial x_{i+\alpha,j+\beta,p}^{(t+1)}} \quad \text{--- (1)}$$

~~the~~ Gradient going into ~~in the layer before~~ ~~part the~~ feature map convolution ~~operation~~ layer.

$$\textcircled{2} \quad \frac{\partial L}{\partial x_{i,j,p}^{(t)}} = \sum_{u,v=1}^K \sum_{\alpha,\beta=1}^2 \left[\frac{\partial L}{\partial x_{i,j,p}^{(t)}} \right] \left[\frac{\partial x'_{i,j,p}(t)}{\partial x_{i+\alpha,j+\beta,p}(t)} \right]$$

\Downarrow ~~from~~ Eq ①

from Eq ①

When ~~t=t~~ t=t we know that

$$\left[\frac{\partial L}{\partial x^{(t)}} \right] \text{ is given to us}$$

$$\boxed{\frac{\partial x^{(t)}_{i,j,p}}{\partial x^{(t)}_{i+u,j+v,e}} = \cancel{\frac{\partial x^{(t)}_{i,j,p}}{\partial K_{u,v,e}}} \cdot K_{u,v,e}^p}$$

Finally,

$$\textcircled{3} \quad \frac{\partial L}{\partial K_{u,v,e}^p} = \sum_{t=1}^d \left[\sum_{i,j=1}^W \left[\frac{\partial L}{\partial x^{(t)}_{i,j,p}} \right] \cdot \left[\frac{\partial x^{(t)}_{i,j,p}}{\partial K_{u,v,e}^p} \right] \right] \quad \text{From } \textcircled{1}$$

$$\boxed{\frac{\partial x^{(t)}_{i,j,p}}{\partial K_{u,v,e}^p} = \cancel{\frac{\partial x^{(t)}_{i,j,p}}{\partial K_{u,v,e}^p}} \cdot x_{i+u,j+v,e}}$$

$$\textcircled{4} \quad \frac{\partial L}{\partial b^p} = \sum_{t=1}^d \left[\sum_{i,j=1}^W \frac{\partial L}{\partial x^{(t)}_{i,j,p}} \cdot \frac{\partial x^{(t)}_{i,j,p}}{\partial b^p} \right] \quad \text{From } \textcircled{1}$$

$$\boxed{\frac{\partial x^{(t)}_{i,j,p}}{\partial b^p} = 1}$$

Need to double check the computation.

⑧

0.5 - Generative Process -

$$z^{(i)} \sim \text{Multinomial}(\Phi) \quad z^{(i)} \in \{1, \dots, K\}$$

$$y^{(i)} \sim \text{Bernoulli}(p) \quad \therefore \text{does not depend on } z^{(i)} \text{ (as given in the question)}$$

$$x_j^{(i)} | y^{(i)} = t, z^{(i)} = l \quad l \in \{1, \dots, K\} \quad t \in \{1, 0\}$$

$$\equiv \text{Bernoulli}(\theta_{jl} | y = y^{(i)}, z = z^{(i)})$$

$$\equiv \text{Bernoulli}(\theta_{jl} | y = t, z = l)$$

Parameters of the Model:

$$\Phi := (\Phi_1, \dots, \Phi_K)$$

\therefore latent mixture parameters
K parameters (one redundant)

$\theta \Rightarrow$

$$\sum_l \Phi_l = 1$$

$\phi :=$ prior class probability. (one parameter)

$$\{\theta_{jl} | y = t, z = l\}_{j=1, t=0, l=1}^n, 1, K$$

$$n \times 2 \times K = 2nK \text{ parameters}$$

Log-likelihood

$$\sum_{i=1}^n \log [P(x^i, y^i; \theta)]$$

$$= \sum_{i=1}^n \log [P(x^i | y^i; \theta) P(y^i; \phi)]$$

$$= \sum_{i=1}^n \log \left[\sum_{z^i} [P(x^i | y^i, z^i; \theta)] \cdot P(z^i; \Phi) \right]$$

$$= \sum_{i=1}^n \left[\log \left[\sum_{z^i} [P(x^i | y^i, z^i; \theta)] \right] + \log P(y^i; \phi) \right]$$

[since y^i is independent of z^i]
can be expressed in terms of parameters of the model

$$= \sum_{i=1}^n \log \left[\sum_{z^i} \left[\prod_{j=1}^n P(x_j^i | y^i, z^i; \theta) \right] P(z^i; \Phi) + \log P(y^i; \phi) \right]$$

can be expressed in terms of parameters of the model

↓
can be expressed in terms of parameters

(skipping the parameters in place of corresponding one step which substitute)

$$= \sum_{i=1}^n \log \left[\sum_{z^i} \left[\prod_{j=1}^n P(x_j^i | y^i, z^i; \theta) \right] P(z^i; \Phi) + \log P(y^i; \phi) \right]$$

$\sum_{j=1}^n y_j^i = 1$
 $\sum_{j=1}^n x_j^i = 1$
 $\sum_{j=1}^n z_j^i = 1$
 $\sum_{j=1}^n \theta_j = 1$

$$+ 1\{y^{(i)}=0\} \left[1\{x_j^{(i)}=1\} \theta_j | y=0, z^{(i)}=1 \right. \\ \left. + 1\{x_j^{(i)}=0\} (1-\theta_j) | y=0, z^{(i)}=0 \right] \\ + \sum_{i=1}^n y^{(i)} \phi + (-y^{(i)}) (1-\phi)$$

(b) EM based estimation

E-step: \rightarrow

$$p(z^{(i)} | x^{(i)}, y^{(i)}; \theta)$$

$$= \frac{p(z^{(i)}, x^{(i)}, y^{(i)}; \theta)}{p(x^{(i)}, y^{(i)}; \theta)}$$

$$= \frac{p(x^{(i)} | y^{(i)}, z^{(i)}; \theta) p(y^{(i)}; \phi) p(z^{(i)}; \Phi)}{\sum_{z^{(i)}} p(x^{(i)}, y^{(i)} | z^{(i)}; \theta) p(z^{(i)}; \phi)}$$

$$= \frac{\left[\prod_{j=1}^n p(x_j^{(i)} | y^{(i)}, z^{(i)}; \theta) \right] \cdot p(y^{(i)}; \phi) p(z^{(i)}; \Phi)}{\sum_{z^{(i)}} \left[p(x^{(i)} | y^{(i)}, z^{(i)}; \theta) \right] p(y^{(i)}; \phi) p(z^{(i)}; \Phi)}$$

We know how to compute Φ for given set of parameters.

M-step - Given $p(z^{(i)}=1)$, we want to estimate the parameters of the naive Bayes model in the next step.

independent of $z^{(i)}$

$$\phi = \frac{\sum_{i=1}^m 1\{y^{(i)} = t\}}{m}$$

constant through out

$$\Phi = \frac{\sum_{i=1}^m P(z^{(i)} = t)}{m}$$

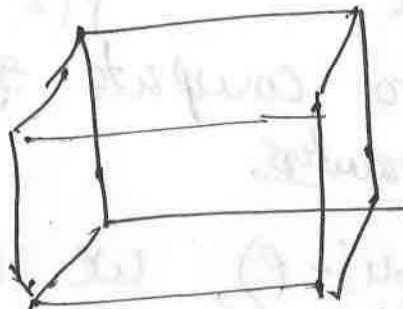
[softer version of $\frac{\sum_{i=1}^m 1\{z^{(i)} = t\}}{m}$]

M-step

$$Q_t | y=t, z^{(i)}=t = \frac{\sum_{i=1}^m P(z^{(i)}=t) 1\{y^{(i)}=t\}}{\sum_{i=1}^m 1\{y^{(i)}=t\}}$$

softer version of naive Bayes parameter estimation
[can do Laplace smoothing] by
adding 1 to the numerator
& 2 to the denominator

Q8: VC dim H_{II}^3 :-



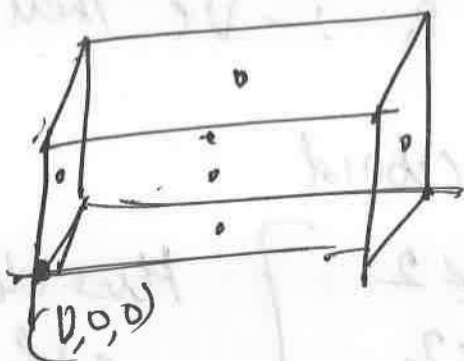
claim:-
VC-dimension of
class H_{II}^3 (axis
aligned cuboids)
= 6

Recall:- $VC(H_{II}^2) = 4$

(10) First, we will show that $VC(H_1^3) = 6$

Consider a cuboid of s length, width & height = 2 with bottom left inner corner at $(0,0,0)$

$$0 \leq x \leq 2, 0 \leq y \leq 2, 0 \leq z \leq 2$$



Now, let us place six points at the center of six faces of the cuboid i.e.,

at

$$(\frac{1}{2}, \frac{1}{2}, 0)$$

$$(0, \frac{1}{2}, 0)$$

$$(0, 0, \frac{1}{2})$$

$$(\frac{1}{2}, \frac{1}{2}, 0)$$

$$(\frac{1}{2}, 0, \frac{1}{2})$$

$$(\frac{1}{2}, \frac{1}{2}, \frac{1}{2})$$

$$P_1 (1, 1, 0)$$

$$P_2 (1, 1, 2)$$

top & bottom face

$$P_3 (1, 0, 1)$$

$$P_4 (1, 2, 1)$$

front & back face

$$P_5 (0, 1, 1)$$

$$P_6 (2, 1, 1)$$

left & right face

Then these six points can be easily shattered by moving the plane

at which the point lies by $\pm \epsilon$ ($\epsilon > 0$)
 to give the concerned point a label of
 $+ve$ or $-ve$ (or vice-versa) where ϵ is
 very small

e.g. Consider $P_1 = - (1, 1, 0)$

then if $P_2 = +ve$ then

In the cuboid,

$$-\epsilon \leq x \leq 2$$

$$0 \leq y \leq 2$$

$$0 \leq z \leq 2$$

Similarly if $P_1 = -ve$ then

In the cuboid

$$\epsilon \leq x \leq 2$$

$$0 \leq y \leq 2$$

$$0 \leq z \leq 2$$

This does not
 affect the
 label of other
 points

\Rightarrow All 96 labelings can be achieved
 by doing $\pm \epsilon$ movement of 6
 faces independently (corresponding
 to label of each point).

⑪

Next, we will show that $VC(H_{11}^3) = 6$
 i.e. no set of 7 points can be shattered.

Assume Contrary:-

3 P_1, \dots, P_7 s.t. H_{11}^3 can shatter
 them. We will show that 3 labeling
 of these 7 points that can not
 be achieved.

Let P_x^{\max} :- point with max x value

P_x^{\min} :- point with min x value

Similarly define

P_y^{\max}
 P_y^{\min}

&

P_z^{\max}
 P_z^{\min}

\exists Let b :- remaining point (at
 least one such point ~~be~~
 must be there which is
 not covered above)

Assign b :- VC label
 All other points the label

clearly:-

Let $P \in H_{11}^3$ shatter
 this labeling.

$$P_x^{\min}[x] \leq P[x] \leq P_x^{\max}[x]$$

$$P_y^{\min}[y] \leq P[y] \leq P_y^{\max}[y]$$

$$P_z^{\min}[z] \leq P[z] \leq P_z^{\max}[z]$$

Since $p_x^{\min}, p_x^{\max}, p_y^{\min}, p_y^{\max}$ are assigned the label, any point ~~without~~ lying they will be inside the aboid formed by h

$$p_x^{\min} \leq p' \leq p_x^{\max} \wedge p_y^{\min} \leq p' \leq p_y^{\max}$$

$$\wedge p_z^{\min} \leq p' \leq p_z^{\max} \text{ must also}$$

be inside. $\Rightarrow p$ must be

inside $h \in H_1^3$

$\Rightarrow p$ must have a true label contradiction.

⑥⑦ In general: $H_1^n := \lfloor VC\text{-Dim}(H_1^n) = 2n \rfloor$

A very similar argument follows

$2n$ points can be shattered by considering 2 points on two faces \parallel to each of n axes. $\&$ then making the $\&$ argument as earlier

$2n+1$ points can not be shattered by: assuming the label to a threshold points which max/min value along any dimension $\&$ assigning label to remaining point.