Exercise # 2. Iterative Methods For Linear Systems.

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Question 1

Using as a test the example usage, with $tol=1\times 10^{-8}$ and limiting the iterations to $maxit=250~\mathrm{I}$ got the following results.

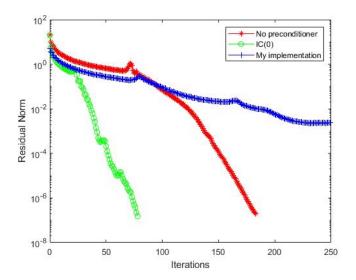


Figure 1: Residual norm vs iteration number for PCG methods, maxit = 250

Method	Iterations	Final Residual	Computational Time
Matlab PCG without preconditioning	183	1.9591×10^{-7}	0.077s
Matlab PCG IC(0)	78	1.5293×10^{-7}	0.068s
My PCG implementation	250	2.3×10^{-3}	0.151s

Table 1: Results of PCG methods, maxit = 250

When maxit is large enough to guarantee convergence in all implementations we get the following results:

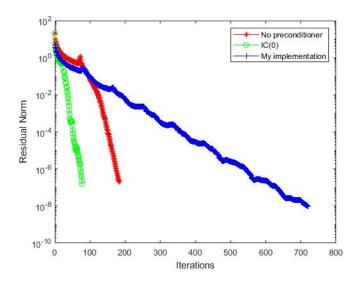


Figure 2: Residual norm vs iteration number for PCG methods, maxit = 750

Method	Iterations	Final Residual	Computational Time
Matlab PCG without preconditioning	183	1.9591×10^{-7}	0.054s
Matlab PCG IC(0)	78	1.5293×10^{-7}	0.063s
My PCG implementation	720	9.6833×10^{-9}	0.351s

Table 2: Results of PCG methods, maxit = 750

My implementation is slower to converge but produces better final residual values.

Question 2

The spectral condition number of A is

$$\kappa(A) = \frac{\lambda_{max}(A)}{\lambda_{min}(A)}. (1)$$

In Matlab I used the condest(A) function to estimate the condition number of a sparse matrix A.

n_x	h	$\kappa(A)$	$\sqrt{\kappa(A)}$	CG	PCG(0)	$PCG(10^{-2})$	$PCG(10^{-3})$
102	1.0000×10^{-4}	6.0107×10^3	77.5288	283	87	45	17
202	2.5000×10^{-5}	2.3810×10^4	154.3039	532	159	78	30
402	6.2500×10^{-6}	9.4770×10^4	307.8473	948	282	137	53
802	1.5625×10^{-6}	3.7814×10^5	614.9304	1792	533	258	97

Table 3: Iterations of PCG methods for each value of n_x and respective values of h and $\kappa(A)$

One can note from the table the dependence of the number of iterations on $h = \frac{1}{N} = \frac{1}{(nx-2)^2}$. The number of iterations is halved when n_x approximately doubles.

Question 3

show theoretically ??

When using the Choledsky precontionier with no fill in, I did'nt get the expected results. Both Matlab's and my implementation converged in only one iteration.

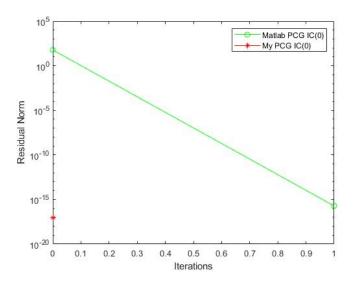


Figure 3: Residual norm vs iteration number for PCG methods with IC(0) preconditioner

Due to the bad results, I tried to remove preconditioning form my implementation by setting L as the identity matrix, L = speye(size(L)).

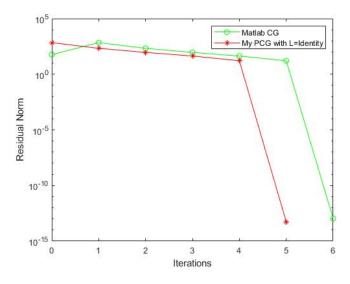


Figure 4: Residual norm vs iteration number for PCG methods without preconditioning

Method	Iterations	Final Residual	Computational Time
Matlab PCG	6	9.2128×10^{-14}	0.021s
My PCG	5	1.2744×10^{-13}	0.012s

Table 4: Results for each value of implementation, no preconditioning

These results show the theoretical calculations, my implementation is still better than expected.

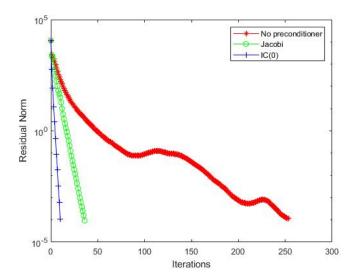


Figure 5: Residual norm vs iteration number for PCG methods without preconditioning

Preconditioner	Iterations	Final Residual	Computational Time
None	253	1.1367×10^{-4}	0.254s
Jacobi	36	9.3198×10^{-5}	0.053s
$\overline{\mathrm{IC}(0)}$	10	1.1155×10^{-4}	0.046s

Table 5: Results for each preconditioner

There is a very clear improvement when using preconditioning. It is also noticeable the superior characteristics of the incomplete Choledsky preconditioner relative to Jacobi.

Question 6

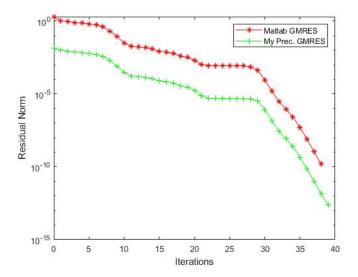


Figure 6: semilogy plot $\exp 6$

 $\begin{array}{c} 4.5350 \text{e-} 13 \\ 7.1893 \text{e-} 14 \\ \text{With L} \end{array}$

Method	Iterations		Computational Time
GMRES	1	3.8481×10^{-16}	0.027s
My PCG	1	1.7554×10^{-17}	0.003s

Table 6: Iterations for each value of nx

GMRES without preconditioning, My PCG with L as identity matrix

Method	Iterations	Final Residual	Computational Time
GMRES	6	3.0413×10^{-14}	0.102s
My PCG	5	1.0468×10^{-13}	0.012s

Table 7: Iterations for each value of nx, no preconditioning

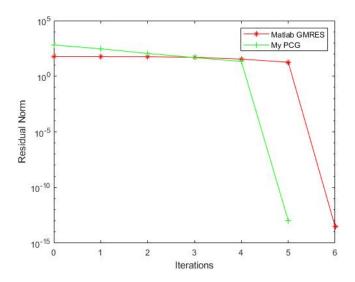


Figure 7: semilogy plot ex6, GMRES without preconditioning, My PCG with L as identity matrix

Restart	Iterations	Final Residual	Computational Time
10	1149	9.6915×10^{-13}	2.235s
20	739	9.6140×10^{-13}	1.443s
30	88	6.7203×10^{-13}	0.242s
50	41	4.8414×10^{-13}	0.135s

Table 8: Iterations for each value of nx, no preconditioning

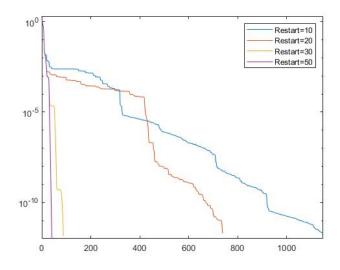


Figure 8: semilogy plot ex7

Tolerance	Iterations	Tprec	Tsol	Ttotal	Final Residual	\mathbf{rho}
2×10^{-2}	1983	39.59s	77.65s	117.24s	9.9053×10^{-13}	0.4537
1×10^{-2}	691	36.46s	26.63s	63.09s	9.7254×10^{-13}	0.5807
3×10^{-3}	247	40.67s	11.04s	51.71s	9.1709×10^{-13}	0.9401
1×10^{-3}	102	37.61s	5.63s	43.24s	8.7501×10^{-13}	1.4544
1×10^{-4}	34	42.44s	2.93s	45.37s	4.5169×10^{-13}	3.5140
1×10^{-5}	16	76.50s	2.49s	78.99s	4.9947×10^{-13}	9.0720

Table 9: Iterations for each value of nx, no preconditioning

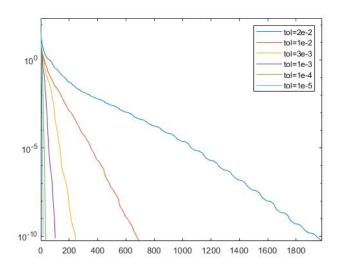


Figure 9: semilogy plot ex8