

1. A **probability space** is a measurable space  $(S, \mathcal{M}, \mu)$  with  $\mathcal{M} \subseteq \mathcal{P}(S)$  and  $\mu: \mathcal{M} \rightarrow [0, 1]$  with  $\mu(S) = 1$ . In particular, we will write  $\mathcal{M} = \mathcal{F}$ ,  $\Omega = S$  and  $\mu = \mathbb{P}$ . The sets  $E \in \mathcal{M}$  are called **events**. The  $\sigma$ -algebra  $\mathcal{F}$  must satisfy the following axioms:

- (a)  $\emptyset \in \mathcal{F}$
- (b) If  $A \in \mathcal{F}$ , then  $A^c \in \mathcal{F}$
- (c) If  $A_1, A_2, \dots \in \mathcal{F}$ , then  $\bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$ .

As well,  $\mathbb{P}$  must satisfy

- (a)  $\mathbb{P}(A) \geq 0$  for all  $A \in \mathcal{F}$ .
- (b)  $\mathbb{P}(\Omega) = 1$ .
- (c) Let  $A_1, A_2, \dots$  be disjoint. Then  $\mathbb{P}\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} \mathbb{P}(A_i)$ .

As a result, we collect some general properties here:

- (a)  $\mathbb{P}(A^c) + \mathbb{P}(A) = 1$
- (b)  $\mathbb{P}\left(\bigcup_{i=1}^n A_i\right) = \sum_{r=1}^n (-1)^{r+1} \sum_{1 \leq i_1 < \dots < i_r \leq n} \mathbb{P}(A_{i_1} \cap \dots \cap A_{i_r})$
- (c) We say  $D_1, D_2, \dots$  is a **decreasing** (resp. **increasing**) sequence of events if  $D_1 \supset D_2 \supset \dots$  (resp.  $D_1 \subset D_2 \subset \dots$ ) and define  $\lim_{n \rightarrow \infty} D_n = \bigcap_{i=1}^{\infty} D_n$  (resp.  $\lim_{n \rightarrow \infty} D_n = \bigcup_{i=1}^{\infty} D_n$ ). Then  $\mathbb{P}(\lim_{n \rightarrow \infty} D_n) = \lim_{n \rightarrow \infty} \mathbb{P}(D_n)$ .

2. Let  $E, F \in \mathcal{F}$ . Fix  $E$  with  $\mathbb{P}(E) > 0$ . Then define  $\mathbb{P}(F|E) = \frac{\mathbb{P}(F \cap E)}{\mathbb{P}(E)}$ , the **conditional probability** of  $F$  given  $E$ . In fact, the map  $\mathbb{P}(\cdot|E): \mathcal{F} \rightarrow \mathbb{R}$  is a probability measure in its own right. Conditional probability has some nice properties:

- (a)  $\mathbb{P}(A_1 \cap A_2 \cap \dots \cap A_n) = \mathbb{P}(A_1|A_2 \cap \dots \cap A_n) \cdots \mathbb{P}(A_3|A_2 \cap A_1) \mathbb{P}(A_2|A_1) \mathbb{P}(A_1)$ .
- (b) Let  $A_1, A_2, \dots, A_n \in \mathcal{F}$  be a partition of  $\Omega$ . Then for any  $B \in \mathcal{F}$ ,

$$\mathbb{P}(B) = \sum_{i=1}^n \mathbb{P}(B|A_i) \mathbb{P}(A_i)$$

and

$$\mathbb{P}(A_k|B) = \frac{\mathbb{P}(B|A_k) \mathbb{P}(A_k)}{\sum_{i=1}^n \mathbb{P}(B|A_i) \mathbb{P}(A_i)}$$

3. Let  $A_1, A_2, \dots, A_n \in \mathcal{F}$ . We say the events are **independent (as a collection)** if

$$\mathbb{P}(A_{i_1} \cap \dots \cap A_{i_k}) = \mathbb{P}(A_{i_1}) \cdots \mathbb{P}(A_{i_k})$$

We say the events are **conditionally independent** with respect to  $B$  if they are independent with respect to the conditional probability measure:

$$\mathbb{P}(A_{i_1} \cap \dots \cap A_{i_k}|B) = \mathbb{P}(A_{i_1}|B) \cdots \mathbb{P}(A_{i_k}|B)$$

4. A **random variable** is a measurable function  $f : S \rightarrow \mathbb{R}$ . We usually write random variables with capital letters, like  $X$ . We say  $X$  is **discrete** if its range is countable.

Let  $\mathcal{B}$  denote the Borel measurable subset of  $\mathbb{R}$ . The **distribution** of a measurable function is a measure  $\rho : \mathcal{B} \rightarrow \mathbb{R}$  given by  $\rho(S) = \mathbb{P}(f^{-1}(S))$ . This is indeed measurable: by definition,  $X$  is measurable if it pulls open sets in  $\mathbb{R}$  to elements of  $\mathcal{F}$ .

For some reason, probabilists dislike writing sets down properly. We say  $\mathbb{P}(X = i) = \mathbb{P}(X^{-1}(i))$ ,  $\mathbb{P}(X \leq i) = \mathbb{P}(X^{-1}(-\infty, i])$ , and other similar notations.

The **expected value** of a random variable  $X$  is given by  $\mathbb{E}(X) = \int_{\Omega} X d\mathbb{P}$ . When  $X$  is discrete and  $X(\Omega) = \{x_1, x_2, \dots\}$ , this becomes  $\mathbb{E}(X) = \sum_{k=1}^{\infty} x_k \mathbb{P}(X = x_k)$ . Note that the sum need not necessarily exist.

(a) If  $X$  is discrete and  $g : \mathbb{R} \rightarrow \mathbb{R}$ , then  $\mathbb{E}(g(X)) = \sum_{k=1}^{\infty} g(x_k) \mathbb{P}(X = x_k)$ .

(b)  $\mathbb{E}(aX + Y) = a \mathbb{E}(X) + \mathbb{E}(Y)$ .

We define the **variance**  $\text{Var}(X) = \inf_{a \in \Omega} \mathbb{E}[(X - a)^2]$ . If  $X \in L^2$ , then this value is minimized for  $a = \mathbb{E}(X)$  and  $\text{Var}(X) = \mathbb{E}[(X - \mathbb{E}(X))^2]$ .

(a)  $\text{Var}(X) = \mathbb{E}(X^2) - \mathbb{E}(X)^2$

(b)  $\text{Var}(aX + b) = a^2 \text{Var}(X)$