

Lecture 27: Physics-informed deep neural networks

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Gibbs sampling

Gibbs sampling

- Split variables in groups: $\mathcal{X} = (x_1, x_2, \dots, x_G)$
- **Initialize:** $\mathcal{X}_0 = (x_{10}, x_{20}, \dots, x_{G0})$
- For step $n = 1, 2, \dots$

$$\begin{aligned}
 \mathcal{X}_{n-1} &= (x_{1,n-1}, x_{2,n-1}, \dots, x_{G,n-1}) \\
 &\quad \downarrow \quad \downarrow \\
 &\quad (x_{1,n}, x_{2,n-1}, \dots, x_{G,n-1}) \\
 &\quad \quad \downarrow \\
 &\quad (x_{1,n}, x_{2,n}, \dots, x_{G,n-1})
 \end{aligned}$$

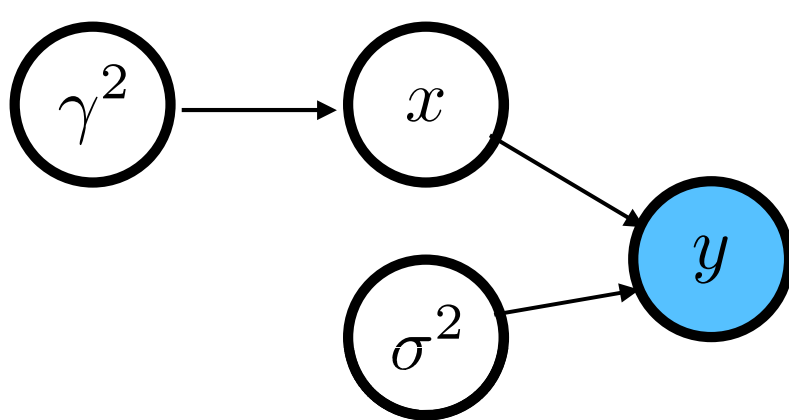
for $g = 1, \dots, G$

Sample x_{ng} from

$$p(x_g \mid x_{g'} = x_{g',n}, g' \leq g, x_{g''} = x_{g'',n-1}, g'' > g)$$



Application: Sampling from a hierarchical model



$$p(\gamma, \sigma, x | y) \propto \frac{p(y | x, \sigma) p(x | \gamma) p(\sigma)}{\pi(x, \gamma, \sigma)}$$

$$\bullet \gamma_0, x_0, \sigma_0$$

• For $n = 1, 2, \dots$

$$\gamma_n | x = x_{n-1}, \sigma = \sigma_{n-1}, y \sim p(\gamma | x = x_{n-1}, \sigma = \sigma_{n-1}, y) \propto \pi(x_{n-1}, \underline{\gamma}, \sigma_{n-1})$$

$$\underline{x}_n | \gamma = \gamma_n, \sigma = \sigma_{n-1}, y \sim p(x | \gamma = \gamma_n, \sigma = \sigma_{n-1}, y) \propto \pi(\underline{x}, \gamma_n, \sigma_{n-1})$$

$$\sigma_n | \gamma = \gamma_n, x \neq x_n, y \sim p(\sigma | \gamma = \gamma_n, x = x_n, y) \propto \pi(x_n, \gamma_n, \underline{\sigma})$$