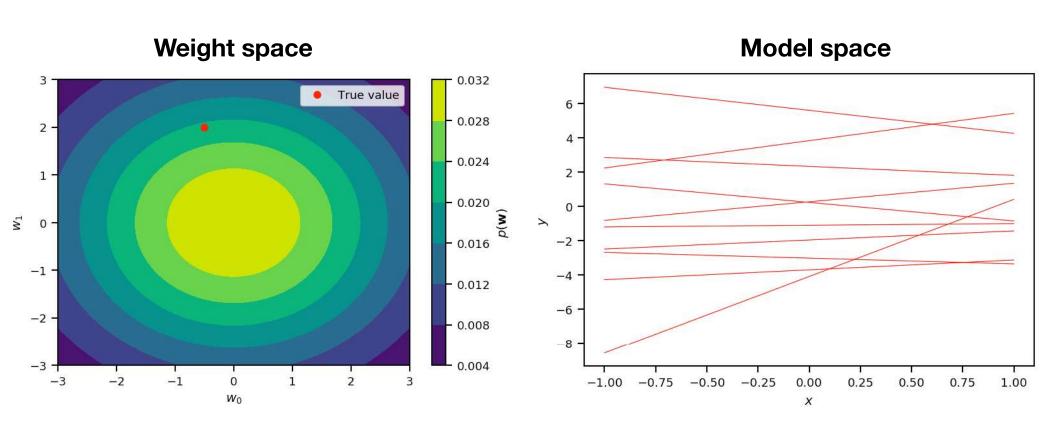
Open questions

- How do I quantify the measurement noise?
- How do we avoid overfitting?
- How do I quantify epistemic uncertainty induced by limited data?
- How do I choose any remaining parameters?
- How do I choose which basis functions to keep?



Weight prior (linear regression)





Weight posterior

posterior a likelihood × prior $p(\underline{w} \mid x_{1:N}, y_{1:N}, \delta) \propto p(y_{1:N} \mid x_{1:N}, \delta, \underline{w}) \cdot p(\underline{w})$ $= \mathcal{N}(y_{1:N} \mid \underline{\Phi} \underline{w}, \delta^2 \underline{I}_N) \times \mathcal{N}(\underline{w} \mid D, \sigma^{-1} \underline{I}_M)$ $= \frac{y^n(x_1) \underline{w}}{y^n(x_N) \underline{w}}$

$$= \mathcal{N}(\mathcal{U}, \mathcal{Y}, \mathcal{Y})$$

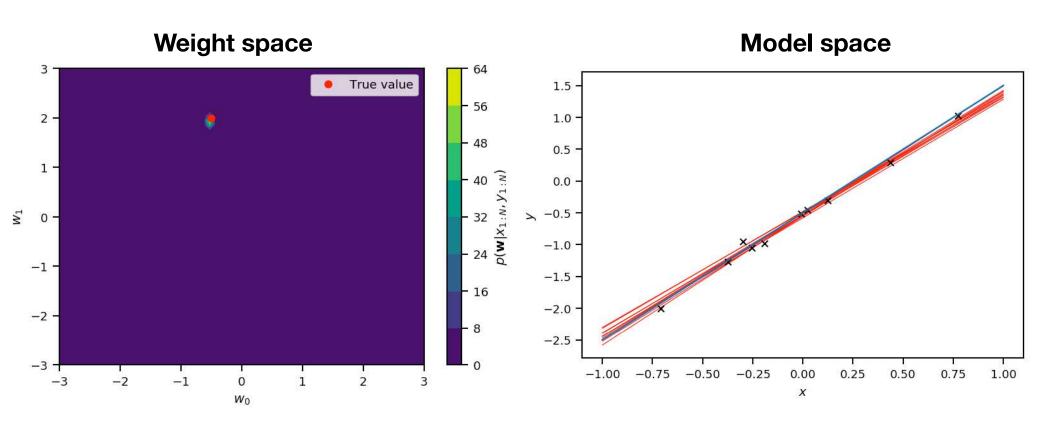
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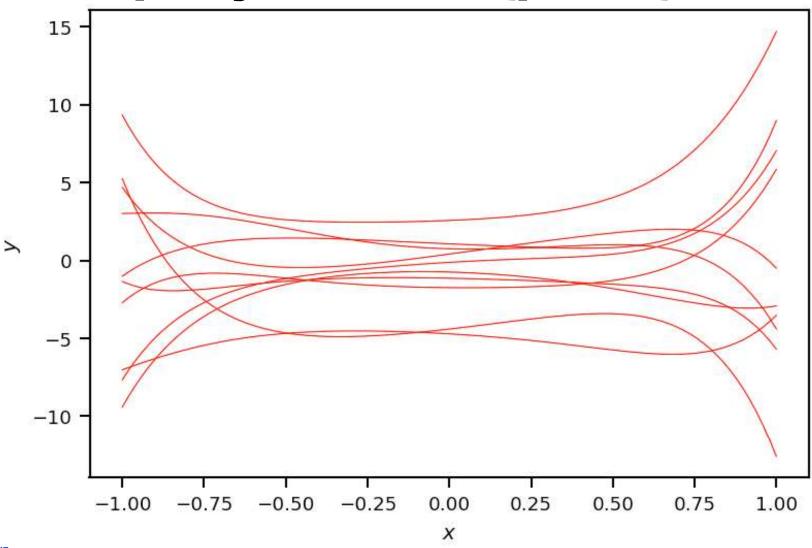


Weight posterior (linear regression)





Example: 7th degree polynomial (prior)





Example: 7th degree polynomial (posterior)

