

Search Trees

→ use a search tree structure to efficiently implement a sorted map

→ three most fundamental methods of a map M :

1.) $M[k]$: return the value associated with key k in map M

2.) $M[k] = v$: associate value v with key k in map M

3.) $\text{del } M[k]$: remove from M the item with key k

Binary trees are an excellent data struct for storing items in a map, assuming the keys have an order relation

→ binary search tree where each position p storing a key-value pair (k, v) such that

→ keys stored in left subtree of p are less than k

→ keys stored in right subtree of p are greater than k

Navigation

→ Proposition: an inorder traversal of a binary search tree visits positions in increasing order of their keys

→ with a BST, we can support:

- $\text{first}()$: returns position containing least key

- $\text{last}()$: returns position containing greatest key

- $\text{before}(p)$: returns position containing greatest key less than position p

- $\text{after}(p)$: returns position containing least key that is greater than that at position p

↳ Algorithm $\text{after}(p)$:

if $\text{right}(p)$ is not None

// successor is leftmost position in p 's right subtree

$\text{walk} = \text{right}(p)$

 while $\text{left}(\text{walk})$ is not None

$\text{walk} = \text{left}(\text{walk})$

else

// successor is nearest ancestor having p in left subtree

$\text{walk} = p$

$\text{ancestor} = \text{parent}(\text{walk})$

 while ancestor is not None and $\text{walk} == \text{right}(\text{ancestor})$

$\text{walk} = \text{ancestor}$

$\text{ancestor} = \text{parent}(\text{walk})$

return ancestor