

## General Form for System of Equations

Say: products  $N_1, \dots, N_n$ , resources  $R_1, \dots, R_m$  to produce unit  $N_j$ ;  $a_{ij}$  of resources  $R_i$  are needed where  $i=1, \dots, m$  and  $j=1, \dots, n$ .

Find optimal production plan to create  $x_j$  units of product  $N_j$  if  $b_i$  units of resource and ideally none is left over.

$x_1, \dots, x_n$  units of product  $\rightarrow$  'unknowns'

$a_{i1}x_1 + \dots + a_{in}x_n$  units of resource

$(x_1, \dots, x_n)$

an element of set  $\mathbb{R}^n$

$$\left. \begin{array}{l} (x_1, \dots, x_n) \\ \text{an element of set } \mathbb{R}^n \end{array} \right\} \begin{array}{l} a_{11}x_1 + \dots + a_{1n}x_n = b_1 \\ a_{m1}x_1 + \dots + a_{mn}x_n = b_m \end{array}$$

where  $a_{ij} \in \mathbb{R}$  and  $b_i \in \mathbb{R}$

$\rightarrow$  every  $n$ -tuple  $(x_1, \dots, x_n) \in \mathbb{R}^n$  that satisfies the above set of equations is a solution of the system.

## Example of infinite solutions

$$\left. \begin{array}{l} x_1 + x_2 + x_3 = 3 \\ x_1 - x_2 + 2x_3 = 2 \\ 2x_1 + 3x_3 = 5 \end{array} \right\} \begin{array}{l} 2x_1 = 5 - 3x_3 \\ 2x_2 = 1 + x_3 \end{array}$$

$\rightarrow$  we define  $x_3 = a \in \mathbb{R}$  as a free variable, such that

$$\left( \frac{5}{2} - \frac{3}{2}a, \frac{1}{2} + \frac{1}{2}a, a \right), a \in \mathbb{R}$$

$\rightarrow$  for any system of linear equations, the solution will either be none, one, or infinitely many

$\rightarrow$  when we intersect these planes (satisfy all linear equations at once), we obtain a solution that is a plane, line, point, or empty (they have no common intersection).

$$\begin{bmatrix} a_{11} \\ \vdots \\ a_{m1} \end{bmatrix} x_1 + \begin{bmatrix} a_{12} \\ \vdots \\ a_{m2} \end{bmatrix} x_2 + \dots + \begin{bmatrix} a_{1n} \\ \vdots \\ a_{mn} \end{bmatrix} x_n = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix} \leftarrow$$

$$\Rightarrow \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix}$$