

# A5-Q3: Jacobi and Gauss-Seidel

## Prelims

```
In [1]: import numpy as np
        from scipy.linalg import solve_triangular
        import matplotlib.pyplot as plt
```

```
In [2]: def split_diag(A):
        D = np.zeros_like(A)
        L_plus_U = A.copy()

        for i in range(len(A)):
            for j in range(len(A)):
                if i == j:
                    D[i, j] = L_plus_U[i, j]
                    L_plus_U[i, j] = 0

        return D, L_plus_U

def decomposition(A):

    D, L_plus_U = split_diag(A)

    U_indices = np.triu_indices(n = A.shape[0], m = A.shape[1])
    U = np.zeros_like(A)

    L = L_plus_U.copy()
    L[U_indices] = U[U_indices]
    U[U_indices] = L_plus_U[U_indices]

    return D, L, U
```

## (a): Jacobi\_step

```
In [3]: def Jacobi_step(A, f, u0):
        """
        u = Jacobi_step(A, f, u0)
        Performs one Jacobi iteration on
        A u = f using the initial guess of u0.
        """

        D, L, U = decomposition(A)

        results = np.zeros_like(u0, dtype = 'float64')
        unscaled_product = (f - (np.dot((L + U), u0)))

        for i in range(D.shape[0]):
            results[i] = unscaled_product[i] / D[i, i]

        return results
```

## (b): GS\_step

```
In [4]: def GS_step(A, f, u0):
        """
        u = GS_step(A, f, u0)
        Performs one Gauss-Seidel iteration on
        A u = f using the initial guess of u0.
        """

        D, L, U = decomposition(A)
        return solve_triangular((L + D), f - (np.dot(U, u0)), lower = True)
```

## (c): iterative\_solve

```
In [13]: def iterative_solve(StepFcn, A, f, u0, maxIters=50, tol=1.e-5):
        """
        u = iterative_solve(StepFcn, A, f, u0, maxIters=50, tol=1e-5)

        Iteratively solves A u = f, taking steps specified by the
        function StepFcn.
```

```

Inputs:
StepFcn  function that takes a single step. Its calling signature
         must be
         u = StepFcn(A, f, u0)
A        (N,N) array holding the system matrix
f        (N,) vector, RHS vector of the system
u0       (N,) vector, initial guess at the solution
maxIters maximum number of iterations
tol      tolerance for stopping criterion. Convergence is considered
         successful if the 2-norm of the residual is less than tol.

         If the maxIter is reached and the tolerance is still not
         satisfied, then the function should print a message stating
         that the method did not successfully converge.

Outputs:
u        (N,) vector approximation of the solution
...
N = len(f)
u = u0.copy()
r = np.ones_like(f)
count = 0

while (np.linalg.norm(r) > tol):

    v = StepFcn(A, f, u)
    r = f - (np.dot(A, v))

    count += 1
    u = v.copy()

    # If any of the elements of r to NaN, then it has blown up to cause an overflow
    if (np.isnan(r).any() or count > maxIters):
        print("Fails to converge")
        return None

return v

```

```

In [6]: def diagonally_dominant(A):

        diags = np.zeros(A.shape[0])
        off_diags = np.zeros(A.shape[0])

        for i in range(A.shape[0]):
            off_diagonal_sum = 0
            diag = A[i, i]
            for j in range(A.shape[1]):
                if i != j:
                    off_diagonal_sum += abs(A[i, j])

            if off_diagonal_sum > diag:
                return False, (i, off_diagonal_sum, diag)

        return True, _

```

(d)

```

In [7]: def will_converge(A):
        diag_dominant, _ = diagonally_dominant(A)
        if diag_dominant:
            return "Matrix is diagonally dominant, can use J or GS, both are guaranteed to converge"

        pd = np.all(np.linalg.eigvals(A) > 0)
        sym = np.allclose(A, A.T, atol=1e-12)

        if pd and sym:
            return "Matrix is positive definite and symmetric, but not diagonally dominant. Gauss-Seidel will converge"

        return "May or may not converge"

```

## System 1

```

In [8]: # Load the system from the file system1.npz
        data1 = np.load('system1.npz')
        A1 = data1['A']
        f1 = data1['f']

```

```

In [9]: # Determine if any of the convergence theorems apply.
        v1_J = iterative_solve(Jacobi_step, A1, f1, np.ones_like(f1), maxIters = 1000, tol = 10e-4)
        v1_GS = iterative_solve(GS_step, A1, f1, np.ones_like(f1), maxIters = 1000, tol = 10e-4)

        print("A1 " + will_converge(A1))

```

A1 Matrix is diagonally dominant, can use J or GS, both are guaranteed to converge

```
In [14]: #np.zeros_like(f1)
print("Jacobi Residual Solution: ")
print(v1_J)
print()
print("Gauss-Seidel Solution: ")
print(v1_GS)
```

Jacobi Residual Solution:

```
[ 0.18626077 -0.29574517  0.18334608  0.24363594  0.10050612  0.11484692
 -0.24841585  0.13456753 -0.18453202 -0.01292882  0.12313881  0.10982869
  0.30751189  0.06963749 -0.01483954 -0.31279143 -0.28498091  0.16762298
 -0.12399915  0.16439319 -0.05634716 -0.12282899  0.0074121  0.32324275
  0.1360699  -0.25812647 -0.16149191  0.25964131 -0.30784832 -0.31384631
 -0.01107099  0.27448764 -0.06647953 -0.30068649  0.02742924  0.13359014
 -0.29013877  0.07675133 -0.18676857  0.08094235 -0.22579644 -0.23352478
 -0.00375997 -0.17073687  0.2877989  -0.26416977  0.3187099  -0.25343944
 -0.07887928  0.19313376 -0.06770649 -0.16295874 -0.25992555  0.23410182
  0.2675301  -0.24503237  0.14884089 -0.0106379  0.1294775  0.32061091
  0.00957128  0.30499456  0.32135518  0.17668147 -0.23259707 -0.13461717
 -0.08865314  0.13906174  0.19389769 -0.23647357 -0.24721324  0.1518979
 -0.25950526 -0.2867984  -0.20071661 -0.05960143  0.16070971 -0.00880309
  0.14317258  0.23402334 -0.04521983  0.0422134  -0.0857719  -0.15669817
 -0.04108675  0.2479919  -0.31298434 -0.1653307  0.02340361  0.16317899
  0.05672658  0.06732578  0.30371574 -0.13163296  0.19054328  0.03121067
  0.14823578  0.22117674  0.01918888 -0.23980464]
```

Gauss-Seidel Solution:

```
[ 0.18626076 -0.29574523  0.1833447  0.24363625  0.10050564  0.11484667
 -0.24841748  0.13456873 -0.18453127 -0.01292812  0.12313865  0.10982829
  0.30751226  0.06963823 -0.01483958 -0.31279271 -0.28498278  0.16762201
 -0.12399695  0.16439394 -0.05634629 -0.1228292  0.00741185  0.32324268
  0.13607113 -0.25812619 -0.16149246  0.25963929 -0.3078479  -0.31384691
 -0.01107182  0.27448858 -0.06647885 -0.3006874  0.02742857  0.13359002
 -0.29013864  0.07675068 -0.18676937  0.08094323 -0.22579589 -0.2335252
 -0.00375959 -0.1707374  0.28779797 -0.26416965  0.31871014 -0.25343939
 -0.07887838  0.19313355 -0.06770755 -0.16295831 -0.25992576  0.23410209
  0.26752951 -0.24503316  0.14883918 -0.01063783  0.12947716  0.32061224
  0.00956992  0.30499398  0.32135384  0.17668014 -0.23259639 -0.13461818
 -0.08865443  0.13906101  0.19389742 -0.23647335 -0.24721343  0.15189763
 -0.25950617 -0.28679822 -0.20071657 -0.05960123  0.16070884 -0.0088024
  0.14317273  0.23402364 -0.04522008  0.04221354 -0.08577102 -0.15669756
 -0.04108755  0.24799269 -0.3129845  -0.16533065  0.02340489  0.16317912
  0.05672558  0.06732573  0.30371606 -0.13163147  0.1905425  0.03121014
  0.14823577  0.22117642  0.01918812 -0.23980361]
```

## System 2

```
In [11]: # Load the system from the file system2.npz
data2 = np.load('system2.npz')
A2 = data2['A']
f2 = data2['f']

print("A2 " + will_converge(A2))
```

A2 Matrix is positive definite and symmetric, but not diagonally dominant. Gauss-Seidel will converge, Jacobi may or may not

```
In [12]: # Determine if any of the convergence theorems apply.

print("Jacobi Solution: ")
v2_J = iterative_solve(Jacobi_step, A2, f2, np.ones_like(f2), maxIters = 1000, tol = 10e-4)

print()
print("Gauss-Seidel Solution: ")
v2_GS = iterative_solve(GS_step, A2, f2, np.ones_like(f2), maxIters = 1000, tol = 10e-4)
print(v2_GS)
```

Jacobi Solution:  
Fails to converge

Gauss-Seidel Solution:

```
[ 0.1731696 10.98640521 23.6189771 1.95344247 -43.65139767
 5.59811439 16.45570036 35.2086366 38.75276783 3.50752706
22.52374877 13.92071161 -10.93794218 -27.68185818 25.0568833
16.33403932 -28.86864363 1.48727979 -0.8657803 10.21570819
23.97059917 3.61065372 26.97137878 12.67527954 7.40420886
21.94632824 -2.62305615 -11.57373843 7.07059185 -4.15880915
-28.8711918 -12.30607452 12.10580992 -22.05571482 15.88597387
-14.28549582 15.80777293 -14.44355126 6.79712468 34.20076013
23.90330789 -0.40884063 -8.01393852 19.52147715 28.47746912
-15.26490604 8.06301365 14.07748777 -3.37276567 -23.20402621
19.58102246 -14.92904276 22.8077017 -37.48150127 16.5001963
-0.62921321 7.74244401 -5.18591774 3.25575792 3.41043358
6.42927558 1.20309054 -1.77919057 15.48259687 7.24355538
-2.07956949 7.32327812 -6.47574818 26.01237698 -6.02358927
-1.65911132 -7.56743388 35.70696881 2.38929952 -17.00985487
1.20833237 38.31626778 11.47289511 7.4478205 4.11094251
7.54483876 8.99096718 -14.2171024 13.8770118 -3.40327075
-5.75098524 19.8479811 -4.23591779 -3.68414131 -4.54104244
21.74834637 -9.58283816 7.14588306 -8.3222187 -7.2482662
41.01734001 -15.92469823 12.82502165 -25.01596066 26.31608077
-7.68124244 -14.21142907 -17.86541181 -13.42442472 5.28395235
6.07990554 19.94118316 34.18107509 19.69906771 -25.49018539]
```

The Jacobi method does not converge in this example. This is because  $A_2$  is not diagonally dominant it cannot be guaranteed to converge. However even in the non diagonally dominant case, the Gauss-Seidel method still converges to a solution, this is because the matrix  $A_2$  is positive definite and symmetric. As I increase the `maxIters` parameter, the norm of the residual of the GS methods goes to 0, while the norm of the residual for the Jacobi method goes to inf.