

# Theoretical Transit Area Model

Given:

$R_s$  = stellar radius,  $R_p$  = planetary radius,  $\tau$  = transit duration,  $t_0$  = mid-transit time.

Define the **radius ratio**:

$$k = \frac{R_p}{R_s}.$$

The **transit chord length** is:

$$C = 2(1 + k).$$

The **relative velocity** (in stellar-radius units per second) is:

$$v_R = \frac{C}{\tau} = \frac{2(1 + k)}{\tau}.$$

At time  $t$ , the projected center-to-center separation is:

$$z(t) = |v_R(t - t_0)|.$$

## Planet–Star Overlap Function

$$\lambda(z, k) = \begin{cases} 0, & z \geq 1 + k, \\ k^2, & z \leq 1 - k, \\ \frac{1}{\pi} \left[ \cos^{-1} \left( \frac{z^2 + 1 - k^2}{2z} \right) + k^2 \cos^{-1} \left( \frac{z^2 + k^2 - 1}{2zk} \right) \right. \\ \quad \left. - \frac{1}{2} \sqrt{(-z + 1 + k)(z + 1 - k)(z - 1 + k)(z + 1 + k)} \right], & \text{otherwise.} \end{cases}$$

## Transit Area (Integrated Flux Deficit)

$$A_{\text{theoretical}} = \int_{t_0 - \frac{\tau}{2}}^{t_0 + \frac{\tau}{2}} \lambda(z(t), k) dt.$$

Numerical midpoint approximation:

$$A_{\text{theoretical}} \approx \sum_i \frac{\lambda(t_{i+1}) + \lambda(t_i)}{2} \Delta t_i.$$

## Model Comparison with Neural Network Output

$$\Delta A = A_{\text{NN}} - A_{\text{theoretical}}, \quad \delta_{\%} = \frac{\Delta A}{A_{\text{theoretical}}} \times 100, \quad \text{Agreement Score} = 100 - |\delta_{\%}|.$$

Classification rule:

$$\text{Final Label} = \begin{cases} \text{CONFIRMED EXOPLANET}, & \text{if Agreement Score} \geq 50 \text{ and disposition} \neq \text{FP}, \\ \text{CONFIRMED FALSE POSITIVE}, & \text{if Agreement Score} \geq 50 \text{ and disposition} = \text{FP}, \\ \text{POTENTIAL EXOPLANET}, & \text{if Agreement Score} < 50 \text{ and disposition} = \text{FP}, \\ \text{POTENTIAL FALSE POSITIVE}, & \text{otherwise.} \end{cases}$$