

BioMechanical Orthotic Knee Joint for Exoskeletons Thesis

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Abstract

This is where the abstract goes [1]

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Introduction

test

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Background

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- [1] B. Jenett and K. Cheung, “Bill-e: Robotic platform for locomotion and manipulation of lightweight space structures,” in *25th AIAA/AHS Adaptive Structures Conference*. DOI: 10.2514/6.2017-1876. eprint: <https://arc.aiaa.org/doi/pdf/10.2514/6.2017-1876>. [Online]. Available: <https://arc.aiaa.org/doi/abs/10.2514/6.2017-1876>.