

ALEX TACESCU

☎ (559) 301-6222

✉ alextac98@gmail.com

🌐 www.alextac.com

QUALIFICATION SUMMARY

Robotics engineer with extensive knowledge of multiple programming languages and significant experience in 3D CAD design in multidisciplinary applications

TECHNICAL SKILLS

Robotics: Software Development, Mechanical Design, Electrical Design, Agile Project Management (SCRUM)

Programming: C++ [4 years], Python [5 years], Robot Operating System [4 years], Java [9 years], SQL [2 year], PointCloudLibrary [2 years], Docker [3 years], and Git [7 years]

3D CAD: Design and Simulation in Autodesk Inventor [9 years], Dassault SolidWorks [7 years], PTC Creo Parametric (ProE) [1 year]

Rapid Prototyping: FDM & SLA 3D Printers, PCB Design, Laser/WaterJet Cutting

Embedded Systems Programming: Raspberry Pi, BeagleBone Black/Blue, NVIDIA Jetson, Device Trees in Linux, ESP32 & ESP8266, Arduino

Other Software Experience: Linux (Debian, Ubuntu, RedHat, ArchLinux, etc), MATLAB, Adobe Creative Suite (Photoshop & Premiere), KiCAD

EDUCATION

M.S./B.S. in Robotics Engineering **Worcester Polytechnic Institute**

Graduation: May 2021

GPA: 3.6 (M.S.) & 3.4 (B.S.)

WORK EXPERIENCE

References Available upon Request

Advanced Robotics R&D Internship **Amazon Robotics**



📅 May 2020 - August 2020 📍 Boston, MA

- Analyzed robot arm workcell faults and collected data to SQL database to display it to dashboards using Apache Superset. Presented patterns and solutions and collaborated with leadership team in decision making.
- Designed and deployed workcell fault diagnosis and mitigation systems, reducing downtime by 60% (initial tests).
- Developed vision system + path planning system for FANUC robots to recover from workcell faults by picking up dropped products.

Advanced Robotics R&D Co-Op **Amazon Robotics**



📅 Aug 2019 - Dec 2019 📍 Boston, MA

- Automated 3D Packing using a vision-guided Universal Robotics arm in Python and C++.
- Developed perception algorithms using 3D cameras and the PointCloudLibrary

Powertrain Integration Engineering Internship **Tesla**



📅 Summer 2019 📍 Palo Alto, CA

- Designed and deployed new automated platform that reports reoccurring issues using anonymous fleet analytics for over 600,000 cars

- System was utilized by Tesla powertrain software developers to identify and debug several user-facing issues
- Developed in Python in Jupyter Lab using PySpark and SQL to pull and analyze fleet data. Created user interface and dashboards using Apache Superset, automated by Apache Airflow

Powertrain Integration Engineering Internship **Tesla**



Summer 2018

Palo Alto, CA

- Responsible for troubleshooting battery thermal system issues and developing test stands for Model S/X, Model 3, Semi-Truck, and other products
- Developed software components for testing, collecting data over CAN networks
- Discovered and fixed 3 issues in critical systems such as the battery and powertrain thermal system and the high voltage system
- Identified a problem and implemented a change in 2 assembly cells that increased Model 3 end-of-line production by 45%

Student Assistant **Worcester Polytechnic Institute**



Aug 2018 – Current

Worcester, MA

- Student Teaching Assistant for WPI's Junior year Robotics classes (RBE 3001 & 3002) focusing on robotic manipulation, dynamics, machine vision, path-planning, & other advanced concepts

PROJECTS

For more, please visit alextac.com/projects

2020-2021: WPI Exoskeleton is a research project with the goal to design an exoskeleton to help paraplegic patients' physical rehabilitation through exercise and bone loading. I developed a customizable bio-mechanical knee joint to follow the flexion and extension patterns of the human knee with the help of magnetic resonance imaging (MRI) as my Masters thesis. This project was done as a part of WPI's Automation and Interventional Medicine (AIM) robotics research laboratory. Patents and academic papers to be announced.

2018-2019: SmallKat Major Qualifying Project is a quadrupedal robotic platform designed for research and development of multipedal robotic systems. SmallKat is 3D printed, open source, and contains fully custom electronics. I developed the high-level software, including footstep planning, path planning, forward/inverse kinematics, machine vision, and networking systems for off-platform debugging for my Major Qualifying Project (MQP) with 2 other students. To learn more, please visit alextac.com/smallkat

2015-2020: Project Maverick is an award-winning omni-directional robotic system that provides mobility for people with walking disabilities. The drive system allows the user to move in any direction using 4 steering and 4 driving electronically synchronized motors, creating the same degrees of motion as an able person. It was designed, built, and programmed as a personal project, initially with Java and then converted to ROS (C++ & Python). To learn more, please visit pmaverick.com

2017-2018: Poverty Stoplight Interactive Qualifying Project is an Android application for social workers in Paraguay to better help people in poverty. The application was designed for Fundación Paraguay and Poverty Stoplight and consisted of developing a REST API and an Android Java application capable of syncing sensitive family data with a secure server. To learn more, please visit alextac.com/stoplight-iqp

2016-17: NASA Space Robotics Challenge is a competition to develop software for NASA's humanoid robot Valkyrie. Developed footstep motion planning, optimized cycle-speed, and tested in ROS, C++, and Python with Gazebo as a member of the WPI Humanoid Robotics Lab. To learn more, please visit alextac.com/src

2017: Project Drogo is a wearable embedded system accompanied by a smart-phone app designed to assist elderly people through post-hip surgery recovery. It combines 2 goals of post-surgery medicine: preventing prohibited motions and guiding the user through physical therapy and rehab. Developed on a team of 4 students as a part of the hackathon Health Hacks RI, where it received 1st place. To learn more, please visit alextac.com/drogo

2017: Project Pather is a kiosk mapping software developed to provide directions to Bringham and Women's Hospital visitors. It has contextual search as well as the capability to send directions to users via text message or email. It is written in Java and JavaFX, with a SQL backend, and was developed on an 8-person team for a school project. To learn more, please visit alextac.com/pather

2012-16: FIRST FRC Robotics Team 2761 4 cumulative seasons with the team. Designed, built, programmed, and tested 5 full-size robots. To learn more, please visit alextac.com/frc

AWARDS

For an updated list, please visit www.alextac.com/awards

2019 SmallKat Major Qualifying Project (MQP) Honorable Mention (2nd best capstone project in Robotics Engineering Department)

2018 Dean's List at WPI (Spring 2018)

2018 Inducted in Rho Beta Epsilon Robotics Engineering Honor Society

2017 1st Place at HealthHacksRI at the University of Rhode Island for Project Drogo

2017 NASA Space Robotics Challenge Team Finalist

2016 2nd Place at the Intel International Science and Engineering Fair (ISEF) in the category of Applied Mechanics

2016 Google International Science Fair Regional Finalist (top 100 in the world)

2016 International Council on Systems Engineering (INCOSE) Award for "best interdisciplinary project that can produce technologically appropriate solution that meet societal needs" at ISEF

2016 GE Fallonventions Award and participation on NBC's Tonight Show starring Jimmy Fallon (aired on April 11, 2016). [See it here](#)

2015 & 2016 Sweepstakes Award winner (1st place overall) and 1st place in Engineering at the Central California Science, Math, and Engineering Fair

2015 National Honor Society Inductee and California Scholarship Federation Member

2015 Institute of Electrical and Electronics Engineers President's Scholarship Award at Intel Science and Engineering Fair for "an outstanding project demonstrating an understanding of electrical engineering, electronics engineering, and computer science."

2015 1st place in the category of Applied Mechanics at the California State Science Fair

LEADERSHIP EXPERIENCE

2019-2020 Officer board member for the Rho Beta Epsilon Robotics Honor Society

2016 Leadership Practice at WPI: analyzed business and leadership practices for an on-campus organization with Prof. Sharon Wulf

2012-16 Lead Technical Director, Build and Pit Team Leader for FIRST FRC Robotics Team 2761

HOBBIES

Making, Woodworking, Tennis, Ultimate Frisbee, Skiing, Fishing, Camping