

## RBE 502 Homework 1

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### Problem 1

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```
syms m l0 l theta k t;
```

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#### Question 1

Assuming  $l_0$  is unextended length of string, and  $l$  is the extended length from  $l_0$ :

```
g = 9.81; % m/s

% Calculate Kinetic Energy:
KE = 1/2*m*diff(l, t)^2 + 1/2*m*(l0 + l)^2 *diff(theta, t)^2;

% Calculate Potential Energy:
Pspring = 1/2*k*l^2;
Pgrav = m*g*(l0+l)*(1-cos(theta))-m*g*l;

L = KE - Pspring - Pgrav
```

---

$L =$

$$(981 \cdot l \cdot m) / 100 - (k \cdot l^2) / 2 + (981 \cdot m \cdot (\cos(\theta) - 1) \cdot (l + l_0)) / 100$$

```
eq1 = diff(diff(L, diff(l,t)), t) - diff(L, l) == 0;
eq2 = diff(diff(L, diff(theta, t)), t) - diff(L, theta) == 0;
```

```
l_dotdot = (l+r)*diff(theta, t)
```

---

$l_{\text{dotdot}} =$

0

**Question 2: State Space Equation**

```
stateSpaceEq1 =[diff(l, t);
                (l0+l)*diff(theta, t)^2 + g * cos(theta) - (k/m)*l;
                diff(theta, t);
                2/(l0+l) * diff(l, t) - g/(l0+l) * sin(theta)];
```

**Question 3: Equilibrium of system**

Equilibrium will be at:

$$l = (m * g) / k$$

$$\theta = 0$$

**Question 4**

The equilibrium is stable, since the differential equations will approach 0 over time

**Problem 2**

```
syms x(t);
```

**Question 1: State Space Form**

```
x_m = [x; diff(x,t)]
x_dot_m = [x_m(2); 5*x_m(2)-10*x]
```

$$x_m(t) =$$

$$\begin{bmatrix} x(t) \\ \text{diff}(x(t), t) \end{bmatrix}$$

$$x_{\dot{m}}(t) =$$

$$\begin{bmatrix} x(2) \\ \text{subs}(\text{diff}(x(t), t), t, 2) \\ 5*x(2) - 10*x(t) \\ 5*\text{subs}(\text{diff}(x(t), t), t, 2) - 10*x(t) \end{bmatrix}$$

**Question 2: Determine the equilibrium**

The equilibrium point of this system is 0, as demonstrated below

```
ode1 = diff(x,t) == x;  
ode2 = diff(x,t) == 5*diff(x,t)-10*x;  
  
eq1 = dsolve(ode1, x(0) == 0)  
eq2 = dsolve(ode2, x(0) == 0)
```

eq1 =

0

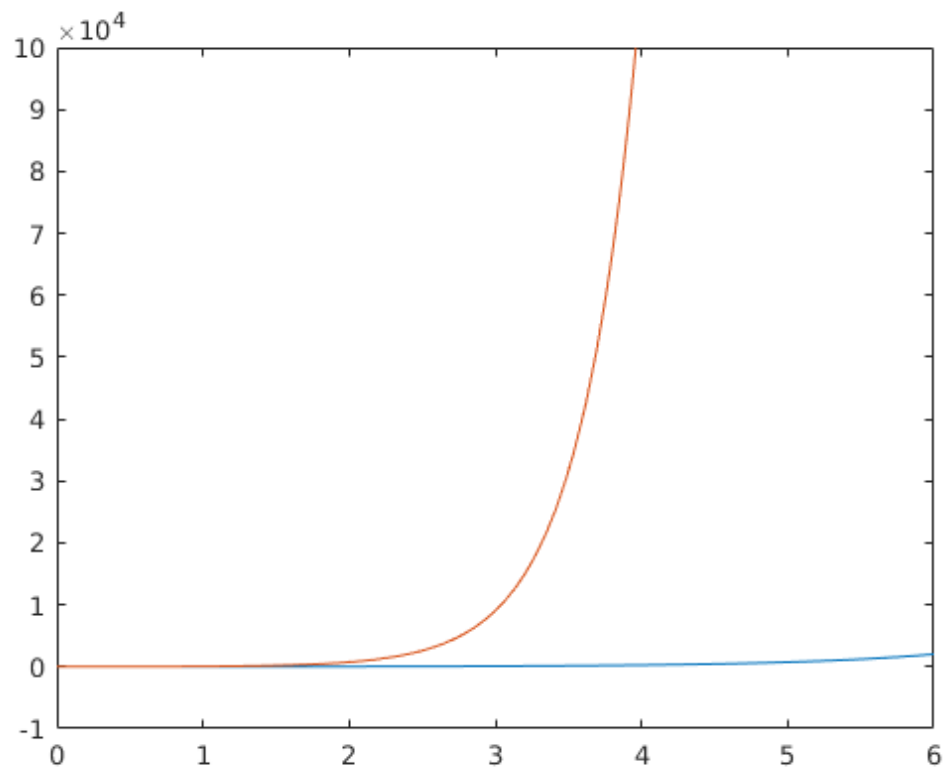
eq2 =

0

**Question 3**

As seen on the graph below, the system is unstable, because both curves separate from the equilibrium as time passes.

```
q3_1 = dsolve(ode1, x(0) == 5); % Start at non-equilibrium point  
q3_2 = dsolve(ode2, x(0) == 5); % Start at non-equilibrium point  
  
figure;  
fplot(real(q3_1(1)))  
hold on;  
fplot(real(q3_2(1)))  
  
xlim([0, 6]);  
ylim([-1*10^4, 10*10^4]);
```



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