Pipelined Processors Data and Control Hazards

Good luck on quiz 2!

Reminder: Processor Performance

"Iron Law" of performance:

$$\frac{\text{Time}}{\text{Program}} = \frac{\text{Instructions}}{\text{Program}} \cdot \frac{\text{Cycles}}{\text{Instruction}} \cdot \frac{\text{Time}}{\text{Cycle}}$$

$$Perf = \frac{1}{Time}$$

- Pipelining Goals:
 - Lower CPI: Keep CPI as close to 1 as possible
 - Lower cycle time since each pipeline stage does less work than a single cycle processor.

Reminder: Pipelining with Data Hazards

- Strategy 1: Stall. Wait for the result to be available by freezing earlier pipeline stages
 - Simple, wastes cycles, higher CPI
- Strategy 2: Bypass. Route data to the earlier pipeline stage as soon as it is calculated
 - More expensive, lower CPI
 - Still needs stalls when result is produced after EXE stage
 - Can trade off having fewer bypasses with stalling more often

Resolving Data Hazards by Stalling

 Strategy 1: Stall. Wait for the result to be available by freezing earlier pipeline stages

addi	k x11,	x10, x11,	2
xor	x13,	x11,	x12
sub	x17,	x15,	x16
xori	k x19,	x18,	0xF

	1	2	3	4	5	6	7	8
IF	addi	xor	sub	sub	sub	sub	xori	
DEC		addi	xor	xor	xor	xor	sub	xori
EXE			addi	NOP	NOP	NOP	xor	sub
MEM				addi	NOP	NOP	NOP	xor
WB					addi	NOP	NOP	NOP

Stall

↑ x11 updated

Stalls increase CPI!

Resolving Data Hazards by Bypassing

 Strategy 2: Bypass. Route data to the earlier pipeline stage as soon as it is calculated

```
addi x11, x10, 2
xor x13, x11, x12
sub x17, x15, x16
xori x19, x18, 0xF
```

 addi writes to x11 at the end of cycle 5... but the result is produced during cycle 3, at the EXE stage!

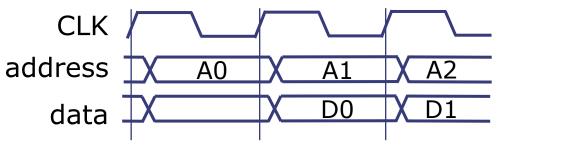
	1	2	3	4	5
IF	addi	xor	sub	xori	
DEC		addi	xor 🛕	sub	xori
EXE			addi	xor	sub
MEM				addi	xor
WB					addi

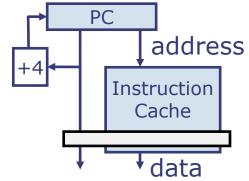
addi result computed

x11 updated

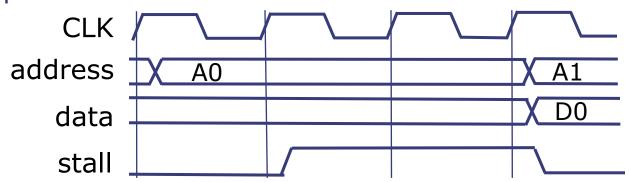
Variable Memory Response Time

 Timing of clocked read assuming cache hit (returns data by next clock cycle)





 Timing of clocked read on cache miss. The cache will produce a stall signal, telling the pipeline to wait until the memory responds.



Handling Instruction Cache Miss by Stalling

 Strategy 1: Stall. Wait for the result to be available by freezing earlier pipeline stages

addi x9,	x10,	2
xor x13,	x11,	x12
sub x17,	x15,	x1 6
xori x19	, x18,	0xF

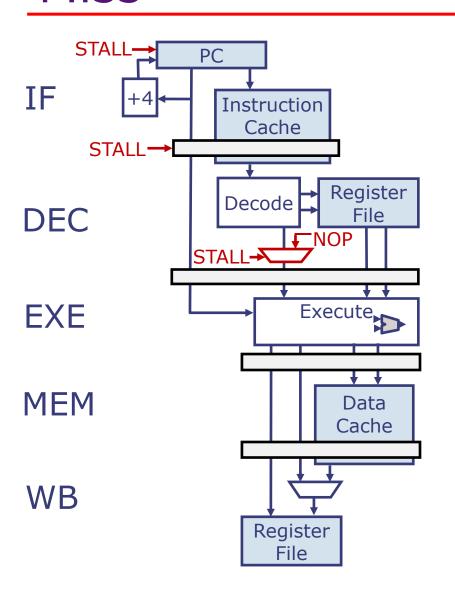
				- T				
	1	2	3	4	5	6	7	8
IF	addi	xor	sub	sub	sub	sub	xori	
DEC		addi	xor	xor	xor	xor	sub	xori
EXE			addi	NOP	NOP	NOP	xor	sub
MEM				addi	NOP	NOP	NOP	xor
WB					addi	NOP	NOP	NOP

Stall

Instruction cache hasn't responded to fetch of xor

Instruction cache returns xor instruction Begins fetch of sub

Stall Logic for Instruction Cache Miss



- STALL==1
 - Disables PC and IF pipeline register
 - Instruction cache keeps working to fetch data from memory
 - Injects NOP instruction into EXE stage
- Control logic sets STALL=1 if instruction cache misses (in addition to setting it when a data hazard exists.)

Resolving Data Cache Miss by Stalling

 Strategy 1: Stall. Wait for the result to be available by freezing earlier pipeline stages addi x9, x10, 2 lw x13, 0(x11) sub x17, x15, x16 xori x19, x18, 0xF ori x2, x1, 0x3 Stall

	1	2	3	4	5	6	7	8
IF	addi	lw	sub	xori	ori	nextI	nextI	nextI
DEC		addi	Iw	sub	xori	ori	ori	ori
EXE			addi	lw	sub	xori	xori	xori
MEM				addi	lw	sub	sub	sub
WB					addi	/w	/w	Iw

Data cache miss on lw request of cycle 5

Iw completes

Control Hazards

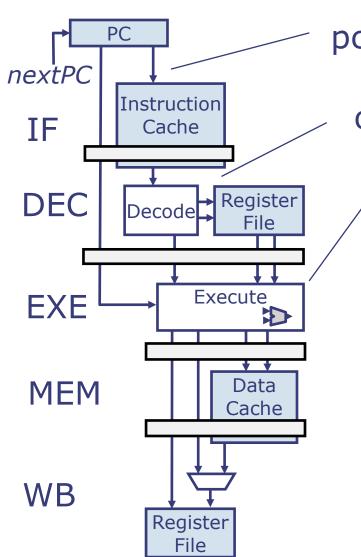
Which instruction to fetch next?

- So far, we have only considered sequential execution where nextPC = PC + 4.
- Now, we will add support for branch and jump instructions.

Control Hazards

- What do we need to compute nextPC?
 - We always need opcode to know how to compute nextPC
 - JAL: nextPC = pc + immJ
 - JALR: nextPC = {(reg[rs1] + immI)[31:1], 1'b0}
 - Branches: nextPC = brFun(reg[rs1], reg[rs2])? pc + immB
 : pc + 4
 - All other instructions: nextPC = PC + 4
- In what stage is nextPC available?
 - Depends on the pipeline and instruction type

Resolving Control Hazards



pc available in IF

opcode, imm available in DEC

operations on pc, imm, reg[rs1], reg[rs2] available in EXE

In what stage is nextPC available?

JAL	EXE
JALR	EXE
Branches	EXE
Others	DEC

Resolving Hazards

- Strategy 1: Stall. Wait for the result to be available by freezing earlier pipeline stages
- Strategy 2: Bypass (aka Forward). Route data to the earlier pipeline stage as soon as it is calculated
- Strategy 3: Speculate
 - Guess a value and continue executing anyway
 - When actual value is available, two cases
 - Guessed correctly → do nothing
 - Guessed incorrectly → kill & restart with correct value

Resolving Control Hazards By Stalling

 Assume bne is taken in this example

loop:	add	i x12	, x11	, -1
	sub	x14,	x15,	x1 6
	bne	x13,	x0,	loop

	1	2	3	4	5	6	7	8	9
IF	addi	NOP	sub	NOP	bne	NOP	NOP	addi	NOP
DEC		addi	NOP	sub	NOP	bne	NOP	NOP	addi
EXE			addi	NOP	sub	NOP	bne	NOP	NOP
MEM				addi	NOP	sub	NOP	bne	NOP
WB					addi	NOP	sub	NOP	bne

Opcode = addi nextPC = PC + 4

Opcode = bne nextPC unknown (branch outcome in EXE) → Stall once more

Opcode not known yet nextPC unknown → Stall

CPI = 7 cycles / 3 instructions ! Might as well not pipeline...

Resolving Hazards

- Strategy 1: Stall. Wait for the result to be available by freezing earlier pipeline stages
- Strategy 2: Bypass (aka Forward). Route data to the earlier pipeline stage as soon as it is calculated
- Strategy 3: Speculate
 - Guess a value and continue executing anyway
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 - Guessed correctly → do nothing
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Resolving Control Hazards with Speculation

What's a good guess for nextPC? PC+4

addi x12, x11, -1 loop: sub x14, x15, x16 bne x13, x0, loop and x16, x17, x18 xor x19, x20, x21

 Assume bne is not taken in example

	1	2	3	4	5	6	7	8	9
IF	addi	sub	bne	and	xor				
DEC		addi	sub	bne	and	xor			
EXE			addi	sub	bne	and	xor		
MEM				addi	sub	bne	and	xor	
WB					addi	sub	bne	and	xor

Start fetching at PC+4 (and) but Guessed right, keep going bne not resolved yet...

Resolving Control Hazards with Speculation

- What's a good guess for nextPC? PC+4
- Assume bne is taken in example

loop: addi x12, x11, -1 sub x14, x15, x16 bne x13, x0, loop and x16, x17, x18 xor x19, x20, x21

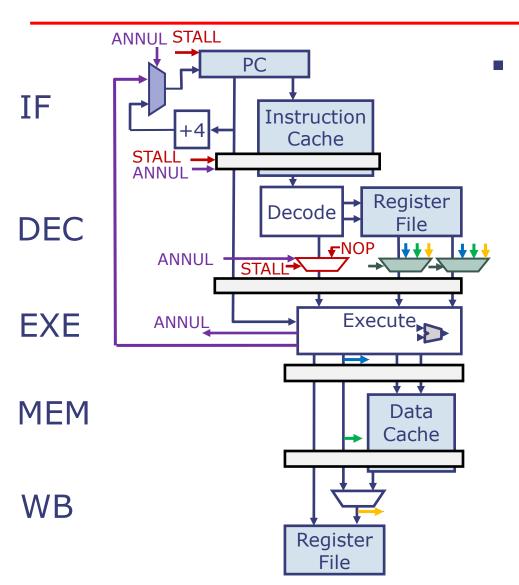
	1	2	3	4	5	6	7	8	9
IF	addi	sub	bne	and	xor	addi	sub	bne	and
DEC		addi	sub	bne	and	NOP	addi	sub	bne
EXE			addi	sub	bne	NOP	NOP	addi	sub
MEM				addi	sub	bne	NOP	NOP	addi
WB					addi	sub	bne	NOP	NOP

bne not resolved yet ...

Start fetching at PC+4 (and) but Guessed wrong, annul and & xor and restart fetching at loop

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Speculation Logic



- When EXE finds a jump or taken branch, it supplies nextPC and sets ANNUL==1
 - Writes NOPs in IF/DEC and DEC/EXE pipeline registers, annulling instructions currently in IF and DEC stages (called branch annulment)
 - Loads the branch or jump target into PC register

Interaction Between Stalling and Speculation

- Suppose that, on the same cycle,
 - EXE wants to annul DEC and IF due to a control hazard
 - DEC wants to stall due to a data hazard
- Example: Assume bne is taken

loop:	addi x12, x11, -1
	lw x14, 0(x15)
	bne x13, x0, loop
	and x16, x14, x18
	xor x19, x20, x21

5 taken								
	1	2	3	4	5			
IF	addi	lw	bne	and	xor			
DEC		addi	lw	bne	and			
EXE			addi	lw	bne			
MEM				addi	lw			
WB					addi			

bne wants to annul; and wants to stall

Which should take precedence, ANNUL or STALL?
 ANNUL, because it comes from an earlier instruction

Putting It All Together

- Let's see an example with stalls, bypassing, and (mis)speculation
- Assume bne is taken once, then not taken

loop:	addi x12, x11, -	1
	lw x14, 0(x15)	
	bne x13, x0, loo	p
	and x16, x14, x1	8
	xor x19, x20, x2	1

	1	2	3	4	5	6	7	8	9	10	11	12
IF	addi	lw	bne	and	xor	addi	lw	bne	and	xor	xor	
DEC		addi	lw	bne	and	NOP	addi	lw	bne	and	and	xor
EXE			addi	lw	bne	NOP	NOP	addi	lw	bne	NOF	and
MEM				addi	lw	bne	NOP	NOP	addi	lw	bne	NOP
WB					addi	lw	bne	NOP	NOP	addi	lw	bne

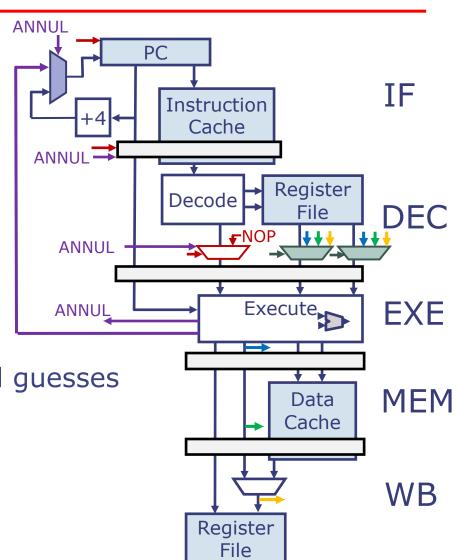
bne taken, annuls and and xor /

and stalls on x14

lw value bypassed

Summary

- Stalling can address all pipeline hazards
 - Simple, but hurts CPI
- Bypassing improves CPI on data hazards
- Speculation improvesCPI on control hazards
 - Speculation works only when it's easy to make good guesses



Thank you!

Next lecture: Synchronization