Quantum Mechanics and Quantum Chemistry

Part 2: Classical and quantum mechanics

by Alexey V. Akimov

Domains of dynamics



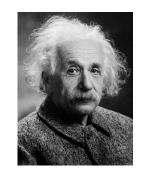
$$i\hbar \frac{\partial \Psi}{\partial t} = H\Psi$$
 but

$$H = (c\alpha \cdot p + \beta mc^2) + V$$

$$F = ma$$

but

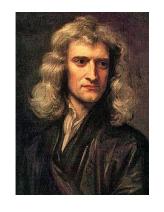
$$m = \frac{m_0}{\sqrt{1 - v^2 / c^2}}$$



$$i\hbar \frac{\partial \Psi}{\partial t} = H\Psi$$



$$F = ma$$



Basic terminology: of classical mechanics

Material point = neglect size



Coordinate system
$$f(\vec{r}, \dot{\vec{r}}, \ddot{\vec{r}}) = 0$$

$$f(\vec{r}, \dot{\vec{r}}, \ddot{\vec{r}}) = 0$$

Equations of motion (EOM)

$$\vec{r}(t) = \begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix}$$

...for all particles

Newton's (vector) Mechanics

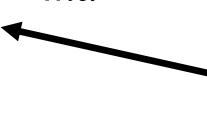
1.
$$\vec{F} = 0 \Rightarrow \vec{v} = const$$

Existence of inertial system of coordinates

mass: inertia measure

2. $\vec{F} = m\vec{a}$

This is **NOT** how to compute force



force: measure of action of one object on another

$$\vec{F}_{ij} = -\vec{F}_{ji}$$

Action - reaction

Forces: They just exist

Keeps the nucleus together

Neutron to proton (beta-decay)

Strong i	teractions:

Weak interaction:

Electromagnetic:

Gravitational:

Quarks, Leptons

Charged particles

Mass particles

Strength

$$< 10^{-15}$$

0.001

100

$$\infty$$

1

$$0 \frac{10^{-40}}{}$$

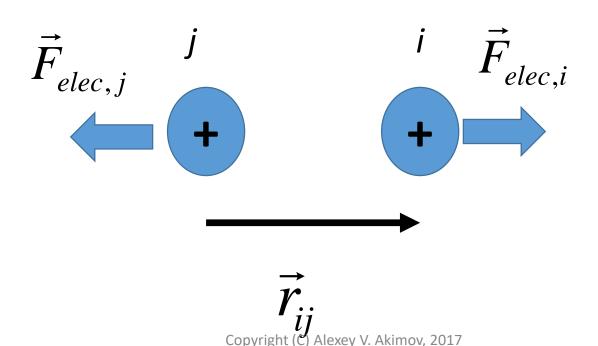
$$\vec{F}_{elec} = -C \frac{q_i q_j}{r_{ij}^2} \frac{r_{ij}}{r_{ij}}$$

$$\vec{F}_{grav} = C \frac{m_i m_j}{r_{ii}^2} \frac{\vec{r}_{ij}}{r_{ii}}$$

Closer look

$$\vec{F}_{elec,i} = C \frac{q_i q_j}{r_{ij}^2} \frac{\vec{r}_{ij}}{r_{ij}}$$

In atomic units: C = 1



Conservation laws and Integrals (invariants) of motion

$$\vec{P} = \sum_{i} \vec{p}_{i}$$

Total momentum (if no total forces) prove

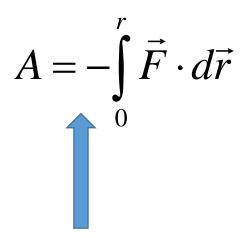
2.
$$\vec{L} = \sum_{i} \vec{l}_{i} = \sum_{i} \vec{r}_{i} \times \vec{p}_{i}$$
 lotal angular momentum (if no total torques) prove

Total angular momentum

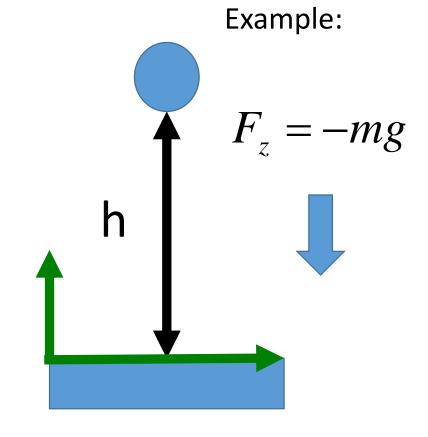
$$\begin{split} \dot{\vec{L}} &= \sum_{i} \dot{\vec{r_i}} \times \vec{p_i} + \sum_{i} \vec{r_i} \times \dot{\vec{p}_i} = \sum_{i} \frac{1}{m_i} \vec{p_i} \times \vec{p_i} + \sum_{i} \vec{r_i} \times \vec{F_i} \\ \sum_{i} \vec{r_i} \times \vec{F_i} &= \sum_{i} \vec{r_i} \times \left(\vec{F_i}^{ext} + \vec{F_i}^{int} \right) = T_{ext} + \sum_{i} \vec{r_i} \times \vec{F_i}^{int} \end{split}$$

$$\sum_{i} \vec{r_i} \times \vec{F_i}^{\text{int}} = \sum_{i} \vec{r_i} \times \sum_{j} \vec{F_{ij}} = \sum_{\substack{i,j \\ i < j}} \left(\vec{r_i} - \vec{r_j} \right) \times \vec{F_{ij}} = 0$$

Work and internal energy



Sign: the matter of convention



$$A = -\int_{0}^{h} \vec{F} \cdot d\vec{r} = -\int_{0}^{h} F_{z} \cdot dz = -F_{z}h = mgh$$

Potential forces

If:
$$U:dU=-\vec{F}\cdot d\vec{r}$$

potential

potential forces

$$A = -\int_{0}^{r} \vec{F} \cdot d\vec{r} = \int_{0}^{r} dU = U(r) - U(0)$$

$$A = -\int_{0}^{r} \vec{F} \cdot d\vec{r} = \int_{0}^{r} dU = U(r) - U(0)$$

U - function of startet (C) Alexey V. Akimov, 2017

Forces

$$\vec{F} = -\frac{\partial U}{\partial \vec{r}} \Leftrightarrow \begin{pmatrix} F_{x} \\ F_{y} \\ F_{z} \end{pmatrix} = \begin{pmatrix} -\frac{\partial U}{\partial x} \\ -\frac{\partial U}{\partial y} \\ -\frac{\partial U}{\partial z} \end{pmatrix}$$

Where to get U? Quantum Mechanics

Analysis of the dynamics

Derivative = negative

Force = positive

Result = acceleration in positive x



Derivative = positive

Force = negative

Result = deceleration in positive x

Lagrangian (analytic) mechanics

$$m\vec{a} = m\ddot{\vec{r}} = \frac{d}{dt}m\dot{\vec{r}} = \frac{d}{dt}\frac{\partial}{\partial \dot{\vec{r}}}\left(\frac{1}{2}m\dot{\vec{r}}^2\right) = \frac{d}{dt}\frac{\partial T}{\partial \dot{\vec{r}}} = \vec{F} = -\frac{\partial U}{\partial \vec{r}}$$

$$T \equiv \frac{1}{2}m\dot{\vec{r}}^2$$

$$U = U(r) \Rightarrow \frac{\partial U}{\partial \dot{r}} = 0$$
 $T = T(\dot{r}) \Rightarrow \frac{\partial T}{\partial \dot{r}} = 0$

$$T = T(\dot{\vec{r}}) \Longrightarrow \frac{CT}{\partial \vec{r}} = C$$

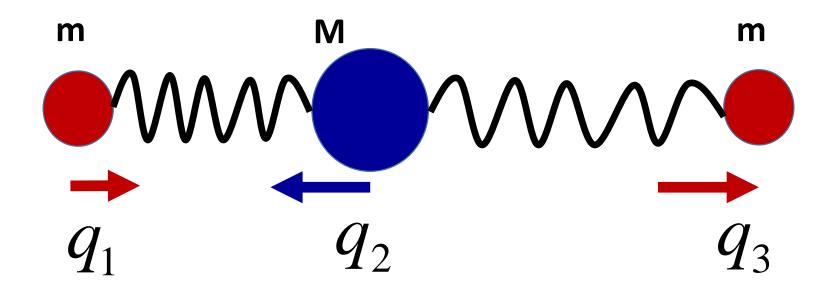
$$L(\vec{r},\dot{\vec{r}}) \equiv T - U$$

Lagrange function

$$\frac{d}{dt}\frac{\partial L}{\partial \dot{\vec{r}}} = \frac{\partial L}{\partial \vec{r}} \Longrightarrow$$

$$\frac{d}{dt} \frac{\partial L}{\partial \vec{r}} - \frac{\partial L}{\partial \vec{r}} = 0$$

Example: Normal modes



$$T = \frac{1}{2}m(\dot{q}_1^2 + \dot{q}_3^2) + \frac{1}{2}M\dot{q}_2^2$$

$$V = \frac{1}{2}k(q_1 - q_2)^2 + \frac{1}{2}k(q_3 - q_2)^2$$
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$$m\ddot{q}_{1} = k(q_{2} - q_{1})$$
 $M\ddot{q}_{2} = k(q_{1} - q_{2}) + k(q_{3} - q_{2})$
 $m\ddot{q}_{3} = k(q_{2} - q_{3})$

Search in the form:

$$q_i = A_i e^{i\omega t + \delta_i}$$

$$-m\omega^{2}q_{1} = k(q_{2} - q_{1})$$

$$-M\omega^{2}q_{2} = k(q_{1} - q_{2}) + k(q_{3} - q_{2})$$

$$-kq_{1} + (-M\omega^{2} + k)q_{1} - kq_{2} = 0$$

$$-kq_{1} + (-M\omega^{2} + 2k)q_{2} - kq_{3} = 0$$

$$-kq_{2} + (-m\omega^{2} + k)q_{3} = 0$$

$$(-m\omega^{2} + k)q_{1} - kq_{2} = 0$$

$$-kq_{1} + (-M\omega^{2} + 2k)q_{2} - kq_{3} = 0$$

$$-kq_{2} + (-m\omega^{2} + k)q_{3} = 0$$

$$(m\omega^{2} - k)q_{1} + kq_{2} = 0$$

$$kq_{1} + (M\omega^{2} - 2k)q_{2} + kq_{3} = 0$$

$$kq_{2} + (m\omega^{2} - k)q_{3} = 0$$

$$\begin{pmatrix} m\omega^2 - k & k & 0 \\ k & M\omega^2 - 2k & k \\ 0 & k & m\omega^2 - k \end{pmatrix} \begin{pmatrix} q_1 \\ q_2 \\ q_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\det\begin{pmatrix} m\omega^{2} - k & k & 0 \\ k & M\omega^{2} - 2k & k \\ 0 & k & m\omega^{2} - k \end{pmatrix} =$$

$$= (m\omega^{2} - k)[(M\omega^{2} - 2k)(m\omega^{2} - k) - k^{2}] - k[k(m\omega^{2} - k)] =$$

$$= (m\omega^{2} - k)[(M\omega^{2} - 2k)(m\omega^{2} - k) - k^{2}] - k[k(m\omega^{2} - k)] =$$

$$= (m\omega^{2} - k)[(M\omega^{2} - 2k)(m\omega^{2} - k) - k^{2}] - k[k(m\omega^{2} - k)] =$$

$$(M\omega^{2}-2k)(m\omega^{2}-k)-2k^{2} = Mm\omega^{4}-2km\omega^{2}-kM\omega^{2} =$$

$$=\omega^{2}[Mm\omega^{2}-k(2m+M)]$$

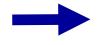
Normal modes



$$\omega_1 = 0$$

(translation)







$$(m\omega^2 - k) = 0 \Rightarrow \omega_2 = \sqrt{\frac{k}{m}}$$





$$Mm\omega^2 - k(2m+M) = 0 \Rightarrow$$

$$\omega_3 = \sqrt{\frac{k(2m+M)}{Mm}}$$





Importance

All is derived from a scalar function

Can be formulated in any variables

Can incorporate constraints

Can generalize forces





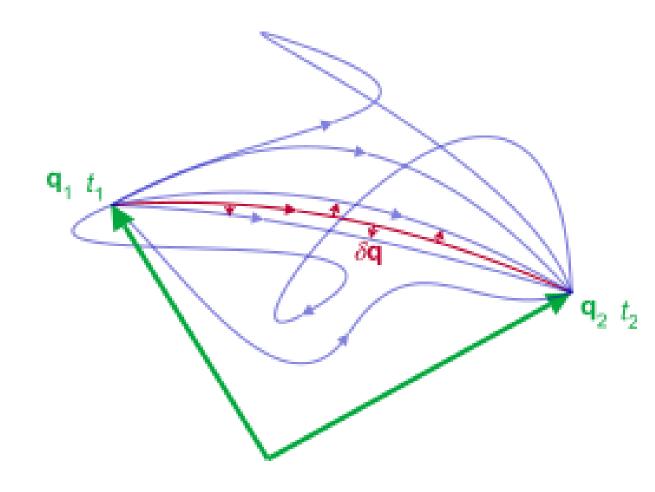




Hamilton's principle Least action principle

$$S = \int_{t_0}^{t_1} L(\vec{r}, \dot{\vec{r}}) dt$$

action



$$\delta S = \int_{t_0}^{t_1} \delta L(\vec{r}, \dot{\vec{r}}) dt = \int_{t_0}^{t_1} \left[\frac{\partial L(\vec{r}, \dot{\vec{r}})}{\partial \vec{r}} \delta \vec{r} + \frac{\partial L(\vec{r}, \dot{\vec{r}})}{\partial \dot{\vec{r}}} \delta \dot{\vec{r}} \right] dt$$

$$\int_{t_0}^{t_1} \frac{\partial L(\vec{r}, \dot{\vec{r}})}{\partial \dot{\vec{r}}} \delta \dot{\vec{r}} dt = \int_{t_0}^{t_1} \frac{\partial L(\vec{r}, \dot{\vec{r}})}{\partial \dot{\vec{r}}} d\delta \ddot{\vec{r}} = \frac{\partial L(\vec{r}, \dot{\vec{r}})}{\partial \dot{\vec{r}}} \delta \ddot{\vec{r}} \bigg|_{t_0}^{t_1} - \int_{t_0}^{t_1} \delta \ddot{\vec{r}} \frac{d}{dt} \frac{\partial L(\vec{r}, \dot{\vec{r}})}{\partial \dot{\vec{r}}} dt = -\int_{t_0}^{t_1} \delta \ddot{\vec{r}} \frac{d}{dt} \frac{\partial L(\vec{r}, \dot{\vec{r}})}{\partial \dot{\vec{r}}} dt$$

Because:

$$\delta \vec{r}(t_0) = \delta \vec{r}(t_1) = 0$$

$$\delta S = \int_{t_0}^{t_1} \delta \vec{r} \left[\frac{\partial L(\vec{r}, \dot{\vec{r}})}{\partial \vec{r}} - \frac{d}{dt} \frac{\partial L(\vec{r}, \dot{\vec{r}})}{\partial \dot{\vec{r}}} \right] dt = 0 \Rightarrow \frac{\partial L(\vec{r}, \dot{\vec{r}})}{\partial \vec{r}} - \frac{d}{dt} \frac{\partial L(\vec{r}, \dot{\vec{r}})}{\partial \dot{\vec{r}}} = 0$$

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Hamiltonian mechanics

$$H(q, p) = \dot{q}p - L(q, \dot{q})$$

Legendre transform

Hamilton's function (Hamiltonian)

also note: generalized coordinates

$$H(q,p) = \sum_{i} \dot{q}_{i} p_{i} - L(q,\dot{q}) \qquad p = \frac{\partial L}{\partial \dot{q}}$$

Example

$$L(x, y, \dot{x}, \dot{y}) = \frac{m\dot{x}^2 + m\dot{y}^2}{2} - \frac{1}{2}kx^2 - \frac{1}{2}ky^2$$



$$p_{x} = \frac{\partial L}{\partial \dot{x}} = m\dot{x} \Rightarrow \dot{x} = \frac{p_{x}}{m}$$

$$p_{y} = \frac{\partial L}{\partial \dot{y}} = m\dot{y} \Rightarrow \dot{y} = \frac{p_{y}}{m}$$



$$H(q, p) = \dot{x}p_x + \dot{y}p_y - L(x, y, \dot{x}, \dot{y}) = \frac{p_x^2}{m} + \frac{p_y^2}{m} - \frac{m\left(\frac{p_x}{m}\right)^2 + m\left(\frac{p_y}{m}\right)^2}{2} + \frac{1}{2}kx^2 + \frac{1}{2}ky^2 = \frac{p_x^2}{2m} + \frac{p_y^2}{2m} + \frac{1}{2}kx^2 + \frac{1}{2}ky^2$$

Hamiltonian

$$H(q, p) = \frac{p_x^2}{2m} + \frac{p_y^2}{2m} + \frac{1}{2}kx^2 + \frac{1}{2}ky^2$$

$$H(q, p) = T + U = \sum_{i} \frac{\vec{p}_{i}^{2}}{2m_{i}} + U(\{q\})$$

$$\frac{\partial H}{\partial p_i} = \frac{p_i}{m_i} = v_i = \dot{q}_i$$

$$-\frac{\partial H}{\partial q_i} = -\frac{\partial U}{\partial q_i} = F_i = ma_i = \frac{d}{dt}(mv_i) = \frac{d}{dt}p_i = \dot{p}_i$$
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Hamiltonian equations of motion (EOM)

$$\dot{q}_i = \frac{\partial H}{\partial p_i}$$

$$\dot{p}_i = -\frac{\partial H}{\partial q_i}$$

Momenta conjugate to coordinate

Hamiltonian equations of motion (EOM)

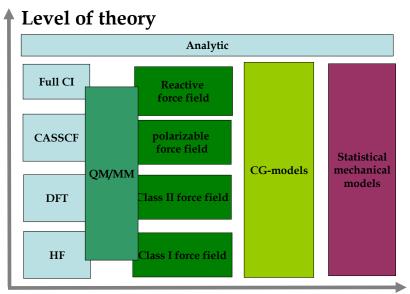
$$\begin{pmatrix} \dot{q}_i \\ \dot{p}_i \end{pmatrix} = \begin{pmatrix} \frac{\partial H}{\partial p_i} \\ -\frac{\partial H}{\partial q_i} \end{pmatrix} \qquad z_i = \begin{pmatrix} q_i \\ p_i \end{pmatrix} \qquad \text{then} \qquad \dot{z}_i = iL \cdot z_i$$

$$iL = \dot{q}_i \frac{\partial}{\partial q_i} + \dot{p}_i \frac{\partial}{\partial p_i} = \frac{\partial H}{\partial p_i} \frac{\partial}{\partial q_i} - \frac{\partial H}{\partial q_i} \frac{\partial}{\partial p_i}$$

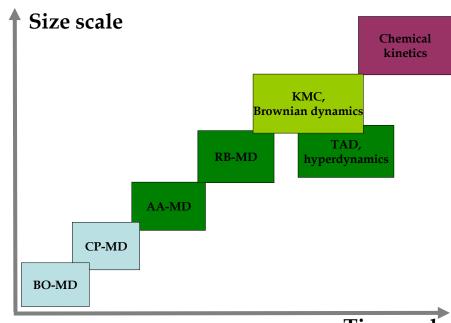
$$\dot{z}_i = \left\{ H, z_i
ight\}$$

$$\begin{split} iL \cdot q_i &= \left(\frac{\partial H}{\partial p_i} \frac{\partial}{\partial q_i} - \frac{\partial H}{\partial q_i} \frac{\partial}{\partial p_i}\right) q_i = \frac{\partial H}{\partial p_i} = \dot{q}_i \\ iL \cdot p_i &= \left(\frac{\partial H}{\partial p_i} \frac{\partial}{\partial q_i} - \frac{\partial H}{\partial q_i} \frac{\partial}{\partial p_i}\right) p_i = -\frac{\partial H}{\partial q_i} = \dot{p}_i \\ \text{Copyright (C) Alkikey V. Akimov, 2017} \end{split}$$

Classical Poisson bracket

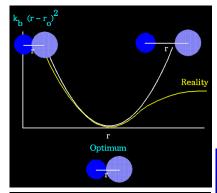


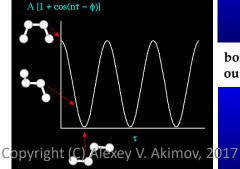
Level of coarse-graining



$$E_{tot} = E_{bonded} + E_{non-bonded}$$

$$E_{bonded} = E_{bonds} + E_{angles} + E_{dihedrals} + E_{oop}$$





bonded, 2-particle: bond stretching

$$v_R = \frac{1}{2}K_r\Delta R^2$$

 $v_R = D_e\left(e^{-2\alpha\Delta R} - 2e^{-\alpha\Delta R}\right)$

bonded, 3-particle: angle bending

$$v_{\theta} = \frac{1}{2} K_{\theta} \Delta \theta^{2}$$

$$\cos \theta = \mathbf{r}_{ij} \cdot \mathbf{r}_{ik} / |r_{ij}| |r_{ik}|$$

bonded, 4-particle: torsion/dihedral, out-of-plane/improper dihedrals

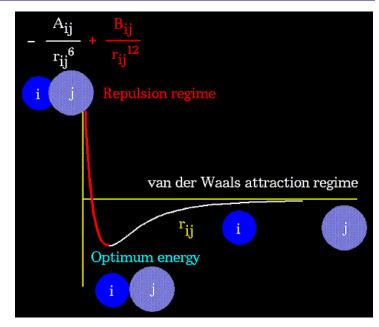
$$v_{\Phi} = K_{\Phi} \sum_{k} C_{k} \cos k\Phi$$

$$E_{non-bonded} = E_{vdW} + E_{el}$$

$$v_{disp}(r_i, r_j) = -\frac{C_6}{|\mathbf{r}_i - \mathbf{r}_j|^6}$$

$$v_{el}(r_i, r_j) = \frac{q_i q_j}{|\mathbf{r}_i - \mathbf{r}_j|}$$

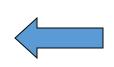
non-bonded 2-particle vdw and Coulomb interactions



Performing MD simulations: Intra-molecular potential

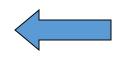
$$E_{phys,bonded} = \sum_{i \in bonds} k_i (r_i - r_{0,i})^2 + \sum_{j \in angles} \frac{k_j}{4\sin^2 \theta_{0,j}} \left[\left(2\cos^2 \theta_{0,j} + 1 \right) - 4\cos \theta_{0,j} \cos \theta_j + \cos 2\theta_j \right]$$

$$E_{phys,nonbonded} = \sum_{\substack{i > j, \\ i, j \in molecule}} D_{ij} \left[\left(\frac{\sigma_{ij}}{r_{ij}} \right)^{12} - 2 \left(\frac{\sigma_{ij}}{r_{ij}} \right)^{6} \right]$$



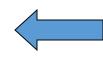
All parameters are taken from the UFF force field

$$E_{torsion} = \sum_{k \in torsions} \frac{1}{2} V_{\phi} \left[1 - \cos n \phi_{0,k} \cos n \phi \right]$$



Used only in last Parameter sets

$$E_{phys,elec} = \sum_{\substack{i>j,\\i,j \in molecule}} \frac{q_i q_j e^2}{r_{ij}}$$



Charges are calculated using charge equilibration method of Rappe et. al.

Performing MD simulations: Surface-molecule potential

Physisorption: All atoms, except S

$$E_{phys,nonbonded} = \sum_{\substack{i,j\\i \in molecule\\i \in surface}} D_{ij} \left[\left(\frac{\sigma_{ij}}{r_{ij}} \right)^{12} - 2 \left(\frac{\sigma_{ij}}{r_{ij}} \right)^{6} \right] SW(r_{ij}) \qquad E_{chem} = \sum_{\substack{i,j\\i \in molecule\\j \in surface}} D_{ij} \left[\left(e^{-\alpha \left(r_{ij} - r_{ij}^{0} \right)} - 1 \right)^{2} - 1 \right] SW(r_{ij})$$

Chemisorption: S atom

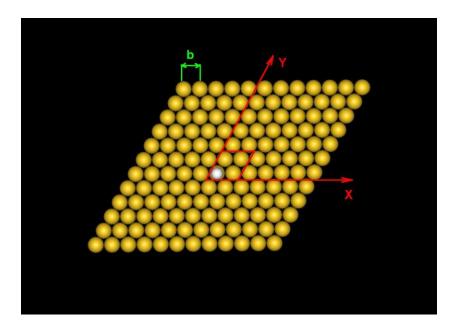
$$E_{chem} = \sum_{\substack{i,j\\i \in molecule\\j \in surface}} D_{ij} \left[\left(e^{-\alpha \left(r_{ij} - r_{ij}^{0} \right)} - 1 \right)^{2} - 1 \right] SW(r_{ij})$$

Special care about discontinuities

$$SW(R, R_{on}, R_{off}) = \begin{cases} 1, R < R_{on} \\ \frac{R_{off} - R}{R_{off} - R_{on}} \end{cases}^{3} \left[1 + 3 \left(\frac{R - R_{on}}{R_{off} - R_{on}} \right) + 6 \left(\frac{R - R_{on}}{R_{off} - R_{on}} \right)^{2} \right], R_{on} \le R \le R_{off} \\ 0.R > R_{off} \end{cases}$$

$$R_{on} = 2\sqrt{3}b$$

$$R_{off} = 5b$$



$$E(\vec{x}) = E(\vec{0}) + \sum_{i=1}^{N} \frac{\partial E}{\partial x_i} x_i + \frac{1}{2} \sum_{i,j=1}^{N} \frac{\partial^2 E}{\partial x_i \partial x_j} x_i x_j + \dots$$

Class I (diagonal), Class II (+ cross-terms)

$$E = \sum_{(i,j)} a_{ij} b o_{ij} + \sum_{\substack{(i_1,j_1),\\(i_2,j_2)}} a_{i_1j_1} a_{i_2j_2} b o_{i_1j_1} b o_{i_2j_2} + \ldots + \sum_{\substack{(i_1,j_1),\\(i_1,j_1),\\(i_2,j_2)}} a_{i_1j_1} \ldots a_{i_nj_n} b o_{i_1j_1} \ldots b o_{i_nj_n}$$

$$bo_{ij} = Ae^{-\alpha r_{ij}}$$

$$E = \sum_{(i,j)} D_{ij} [bo_{ij}^2 - 2bo_{ij}] \quad a)$$

$$\sum_{(i,j)} bo_{ij} = 1 \quad b)$$

$$\frac{d\vec{q}}{dt} = J \frac{dH(\vec{q})}{d\vec{q}} \qquad J = \begin{pmatrix} 0 & I_d \\ -I_d & 0 \end{pmatrix}$$

Canonical structure matrix

$$H = T + V(\{\vec{r}\}) = \sum_{i=1}^{N} \frac{\vec{p}_i^2}{2m_i} + V(\{\vec{r}\})$$

$$\dot{\vec{r}}_i = \frac{\vec{p}_i}{m_i}$$

$$\dot{\vec{p}}_i = -\frac{\partial V}{\partial \vec{r}_i} \equiv \vec{f}_i$$

$$\vec{r}_{i}(t+dt) = \vec{r}_{i}(t) + dt \cdot \frac{\vec{p}_{i}(t)}{m_{i}} + \frac{dt^{2}}{2!} \frac{\vec{f}_{i}(t)}{m_{i}} + O(dt^{3}) + O(dt^{4})$$

$$\vec{r}_{i}(t-dt) = \vec{r}_{i}(t) - dt \cdot \frac{\vec{p}_{i}(t)}{m_{i}} + \frac{dt^{2}}{2!} \frac{\vec{f}_{i}(t)}{m_{i}} - O(dt^{3}) + O(dt^{4})$$

$$\Rightarrow \vec{r}_{i}(t+dt) = 2 \cdot \vec{r}_{i}(t) - \vec{r}_{i}(t-dt) + dt^{2} \frac{\vec{f}_{i}(t)}{m_{i}} + O(dt^{4})$$
Verlet algorithm
$$\vec{p}_{i} \equiv \frac{\vec{r}_{i}(t+dt) - \vec{r}_{i}(t-dt)}{2 \cdot dt}$$

$$\forall i \quad \vec{p}_i(dt) = \vec{p}_i(0) + \frac{dt}{2} \left[\vec{f}_i(0) + \vec{f}_i(dt) \right]$$

$$\forall i \quad \vec{r}_i(t) = \vec{r}_i(0) + dt \vec{p}_i(0) + \frac{dt^2}{2} \vec{f}_i(0)$$
Velocity Verlet

Molecular Dynamics (MD)



Dynamical equations

$$\dot{\vec{r}}_{\!\scriptscriptstyle i} = \vec{p}_{\scriptscriptstyle i}/m_{\scriptscriptstyle i} \quad \dot{\vec{p}}_{\scriptscriptstyle i} = \vec{F}_{\!\scriptscriptstyle i}$$

$$\vec{l}_{i}^{(e)} = \vec{\tau}_{i}^{(e)} + \vec{l}_{i}^{(e)} \times \vec{I}^{-1} \vec{l}_{i}^{(e)}$$

Algorithm:

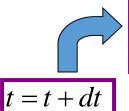
$$t = t_0$$

Initialization:

$$\vec{V}(t_0) \ll Temperature$$

$$\vec{R}(t_0) \le Geometry$$





Get forces:

$$\vec{F}(t) = -\frac{dU(\vec{R}(t))}{dR}$$





Move atoms and update velocity:

$$\vec{R}(t+dt) = \vec{R}(t) + \vec{V}(t)dt + \frac{1}{2m}\vec{F}(t)dt^2$$

$$\vec{V}(t+dt) = \vec{V}(t) + \frac{\vec{F}(t) + \vec{F}(t+dt)}{2m}dt$$

Experimental foundations of QM

Energy levels (quantization)

Wave-particle duality

- Atomic spectra
- Black body radiation

- Interference
- Photoeffect

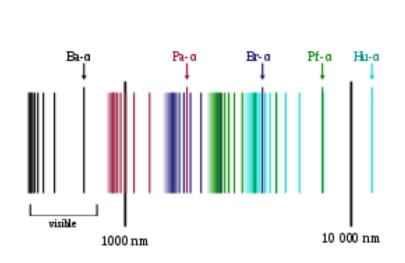
Spectral lines of H atom

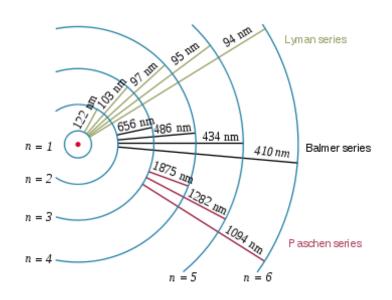
1885, Balmer
$$\lambda = B \frac{n^2}{n^2 - 4}, n = 3,4,5,...$$

$$\frac{1}{\lambda} = \frac{4}{B} \left(\frac{1}{4} - \frac{1}{n^2} \right) \Leftrightarrow v = R \left(\frac{1}{2^2} - \frac{1}{n^2} \right)$$

Lyman, Balmer, Paschen (Ritz), Bracket, Pfund, Hampfrey

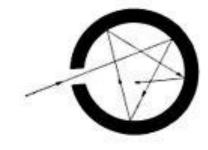






Black body (BB)

Absorbs everything (at all wavelengths)





Vantablack = vertically aligned nanotube arrays Absorbs: 99.965% of the incident light



... but can radiate (so has a color). This is determined only by T

1000K

2000K

3000K

4000K

5000K

6000K

7000K

8000K

9000K

10000K

Energy density of BB radiation

$$u = v^3 f\left(\frac{v}{T}\right)$$

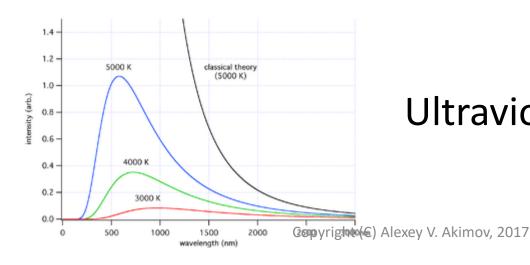
First Wien's law - general

$$u = C_1 v^3 \exp\left(-C_2 \frac{v}{T}\right)$$

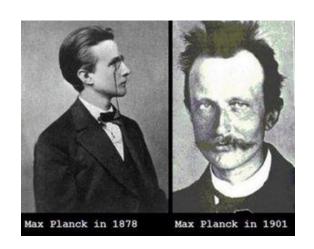
Second Wien's law (high frequency)

$$u = k_B T \frac{4v^2}{c^3}$$

Rayleigh-Jeans (low frequency)



Ultraviolet catastrophe



$$E_n = \hbar \omega \left(n + \frac{1}{2} \right)$$

Planck, 1900

$$Z = \sum_{n} \exp(-E_n / k_B T) = \sum_{n} \exp(-\hbar\omega / 2k_B T) \exp(-n\hbar\omega / k_B T)$$

$$1+x+x^2+...=\frac{1}{1-x}$$
 so:

$$Z = \frac{\exp(-\hbar\omega/2k_BT)}{1 - \exp(-\hbar\omega/k_BT)}$$

Average energy of the (equilibrium!) EM radiation:

Probability:
$$P_n = \frac{1}{Z} \exp(-E_n / k_B T)$$

Probability:
$$P_n = \frac{1}{Z} \exp(-E_n/k_B T)$$

$$\overline{E} = \sum_n E_n P_n = k_B T^2 \left(\frac{\partial \ln Z}{\partial T}\right) = \frac{\hbar \omega}{2} + \frac{\hbar \omega}{\exp(-\frac{\hbar \omega}{k_B T}) - 1}$$

$$u(v,T) = \frac{\omega^2}{\pi^2 c^3} \frac{\hbar \omega}{\exp\left(\frac{\hbar \omega}{k_B T}\right) - 1} = \frac{4v^2}{c^3} \frac{hv}{\exp\left(\frac{hv}{k_B T}\right) - 1}$$
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Predicted:

Boltzmann const. and Avogadro #

Bohr's (planetary) model

Problem: continuous radiation and atom instability

$$E_m - E_n = \hbar \omega$$

Postulated: Stationary states

$$l = n\hbar, n \in N$$

Postulated: Angular momentum is quantized

$$\vec{l} = \vec{r} \times \vec{p}$$

$$l = mvr$$

$$mvr = n\hbar$$

$$\frac{mv^2}{r} = \frac{Ze^2}{r^2} \Rightarrow v = \sqrt{\frac{Ze^2}{mr}}$$





$$mr_n \sqrt{\frac{Ze^2}{mr_n}} = \sqrt{Ze^2 mr_n} = n\hbar \Rightarrow r_n = \frac{\hbar^2}{Zme^2} n^2$$

"orbital" radius

$$E = \frac{mv^{2}}{2} - \frac{Ze^{2}}{r} = \frac{Ze^{2}}{2r} - \frac{Ze^{2}}{r} = -\frac{Ze^{2}}{2r}$$

Total energy

$$E_n = -\frac{Ze^2}{2} \left(\frac{\hbar^2}{Zme^2} n^2 \right)^{-1} = -\frac{Ze^2}{2\hbar^2} Zme^2 \frac{1}{n^2} = -\frac{me^4}{2\hbar^2} \frac{1}{n^2} = -R \frac{Z^2}{n^2}$$

$$R = \frac{me^4}{2\hbar^2} = 0.5 \text{ a.u. (Ha)} \approx 13.6 \text{ eV}$$

Rydberg constant

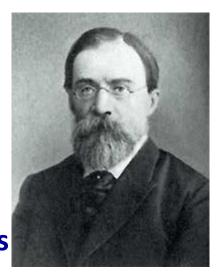
$$-\frac{1}{2}\frac{1}{1^2} = -0.5 \text{ a.u.} (\text{Ha}) = -\frac{1}{1^2} \text{Ry}$$

Energy of H atom in the ground state

$$\oint p_r dq_r = nh$$

Bohr - Zommerfeld (action-angle)

Photoeffect



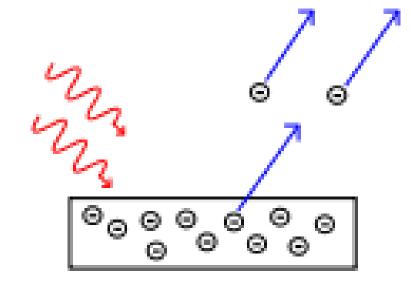
Stoletov laws

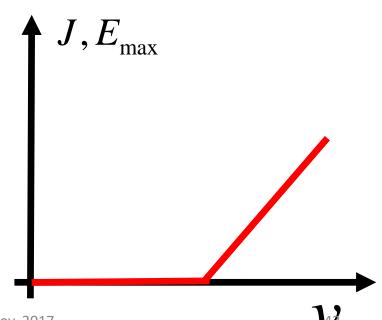
1-st law: $J \sim I$

2-nd law : $E_{\rm max} \sim v$

$$\frac{\partial E_{\max}}{\partial I} = 0$$

3-rd law: $\exists v_{crit} : \forall v < v_{crit}, J = 0$





Photoeffect

1905 Einstein

Nobel Prize

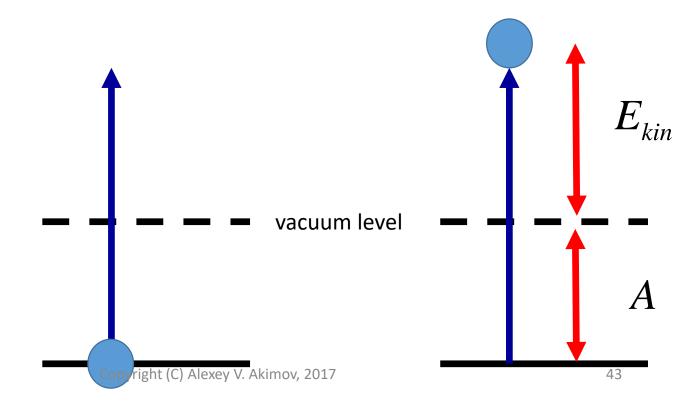
Light is composed of "particles" that concentrate energy

$$hv = A + E_{kin}$$

"particles" = photons

A – the **workfunction**

Modern explanation



De Broglie's waves

1924 **De Broglie**

Louis-Victor-Pierre-Raymond, 7ème duc de Broglie, Louis de Broglie

Wave-particle dualism established for photons is true for all other particles (Nobel Prize) so, same equations hold:

$$E = hv$$

$$c = \lambda v$$

$$E = hv$$
 $c = \lambda v$ so $E = \frac{hc}{\lambda} = pc$

$$\frac{h}{\lambda_B} = p \Leftrightarrow \lambda_B = \frac{h}{p}$$

Large m, v → small wavelength (wave-like properties can not be observed)

1927 – **Davisson & Thompson** – electron diffraction on crystals – found the interference pattern, so electrons have wavelike properties. (also got a Nobel Prize)

Wave-particle duality

All "particles" propagate as waves but interacts as a particles

Thesis + Anti-thesis = Synthesis

Need a theory that combines both

$$\psi(x,t) \sim \exp(i(xk - \omega t)) = \exp\left(i\frac{(xp_x - Et)}{\hbar}\right)$$

Ger Manches rechnet Erwin schon
Mit Seiner Wellenfunction
Nur Wissen Mocht'man wohl
Was man sich dabei vorstell'n soll?

Erwin with his psi can do
Calculations quite a few.
But one thing has not been seen:
Just what does psi really mean?



Erwin Rudolf Josef Alexander Schrödinger

"Derivation" of the Schrodinger's equation

$$\psi = \exp(i(xk - \omega t)) = \exp\left(i\frac{(xp_x - Et)}{\hbar}\right)$$

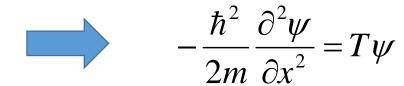
$$\frac{\partial \psi}{\partial t} = -i\frac{E}{\hbar}\psi \qquad \qquad i\hbar\frac{\partial \psi}{\partial t} = E\psi$$

$$i\hbar \frac{\partial \psi}{\partial t} = E\psi$$

$$\frac{\partial \psi}{\partial x} = i \frac{p_x}{\hbar} \psi$$

$$\frac{\partial^2 \psi}{\partial x^2} = -\left(\frac{p_x}{\hbar}\right)^2 \psi = -\frac{2m}{\hbar^2} \frac{p_x^2}{2m} \psi \qquad \qquad -\frac{\hbar^2}{2m} \frac{\partial^2 \psi}{\partial x^2} = T\psi$$

E = T



Free particle:

$$i\hbar \frac{\partial \psi}{\partial t} = -\frac{\hbar^2}{2m} \frac{\partial^2 \psi}{\partial x^2}$$

Generalize the SE

$$i\hbar\frac{\partial\psi}{\partial t} = -\frac{\hbar^2}{2m}\frac{\partial^2\psi}{\partial x^2} \Leftrightarrow i\hbar\frac{\partial\psi}{\partial t} = \hat{H}\psi$$

$$\hat{H} = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} = \frac{\hat{p}_x^2}{2m}$$

Hamiltonian

$$\hat{H} = -\frac{\hbar^2}{2m} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) = \left(\frac{\hat{p}_x^2}{2m} + \frac{\hat{p}_y^2}{2m} + \frac{\hat{p}_z^2}{2m} \right) = -\frac{\hbar^2}{2m} \nabla^2$$

$$\hat{H} = \sum_{i} -\frac{\hbar^2}{2m_i} \nabla_i^2$$

$$\hat{H} = \sum_{i} -\frac{\hbar^2}{2m_i} \nabla_i^2 + V(\{\vec{r}\})$$
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Postulates of QM

1. Existence of wavefunction

$$\exists \psi = \psi(x,t)$$

defines a state

2. Superposition principle

$$\psi = c_1 \psi_1 + c_2 \psi_2$$

3. Expectation values, operators, observables

$$A = \left\langle \hat{A} \right\rangle = \int_{-\infty}^{\infty} \psi^*(x,t) \hat{A} \psi(x,t) dx$$

4. TD-SE

$$i\hbar \frac{\partial \psi}{\partial t} = \hat{H}\psi$$

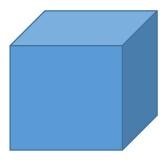
Postulate #1: Wavefunction

$$\psi(x,t)$$

- Contains all information about the system
- Doesn't have physical meaning on its own

$$dP = \left| \psi(x, t) \right|^2 dV$$

Probability to find in dV at time t



$$\int_{-\infty}^{\infty} dP = \int_{-\infty}^{\infty} |\psi(x,t)|^2 dV = 1$$

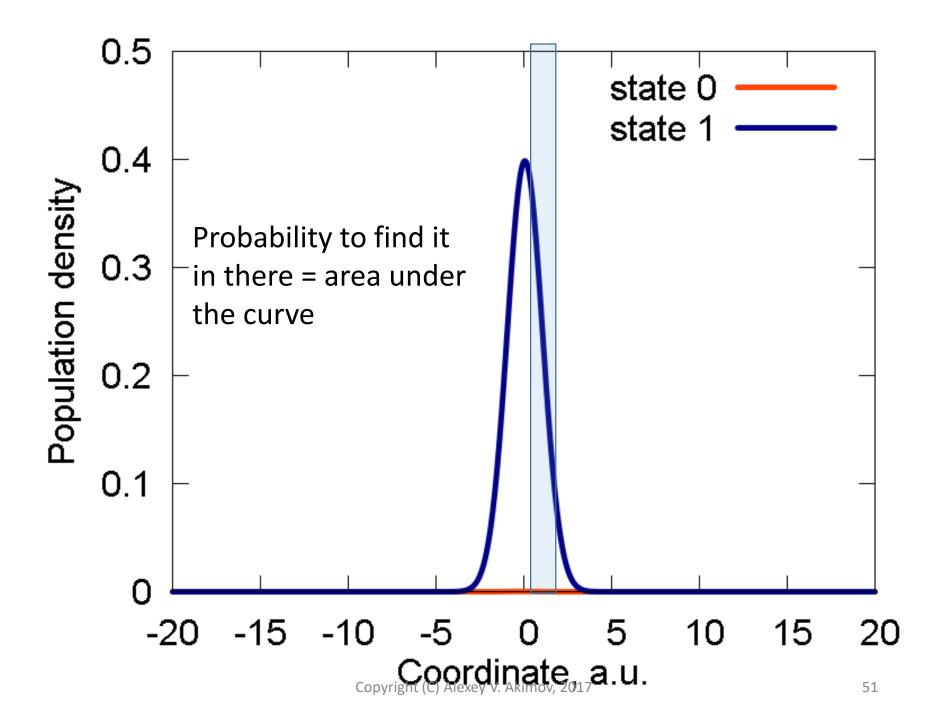
Probability to find anywhere at any time t

Normalization

$$|\psi(x,t)|^2$$

Probability density

Requirement of the form of WFC: $\int_{\text{Copyright (C) Alexev V. Akimov. 2017}}^{\infty} |\psi(x,t)|^2 dV < \infty \Leftrightarrow \psi \in L^2(-\infty,+\infty)$



Dirac bra-ket notation for states

$$\ket{i}$$
 Abstract state i (whatever it is) **KET**

$$|\psi
angle$$
 Misleading

$$|\psi_i\rangle$$
 Better = OK

$$\langle r | i \rangle = \psi_i(r)$$

This is what you really mean (coordinate/position representation)

$$\langle k | i \rangle = \widetilde{\psi}_i(k)$$

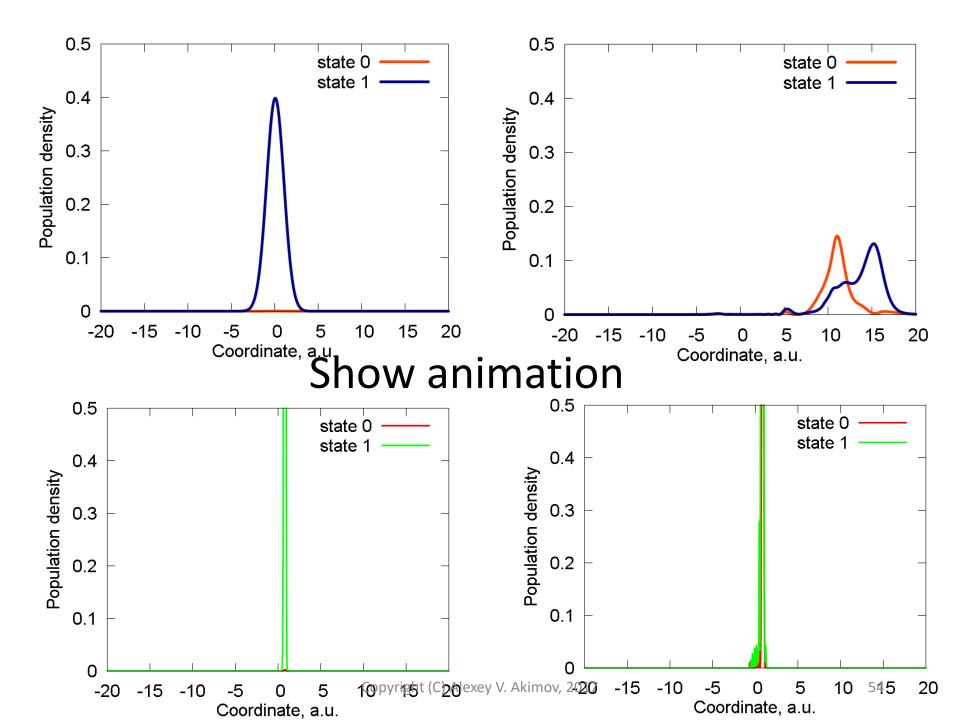
Momentum representation

Dirac bra-ket notation for states

 $\langle i |$ Abstract state i (whatever it is) **BRA**

Overlap = scalar product

$$\langle i | j \rangle = (\psi_i, \psi_j) = \int_{-\infty}^{+\infty} \psi_i^*(\vec{r}) \psi_j(\vec{r}) d\vec{r}$$



Dirac Delta-function and representations

$$\langle x | x' \rangle = \delta(x - x')$$

"grid states"

(Dirac) Delta-function Is a functional!

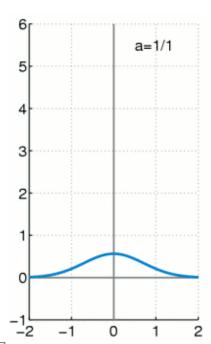
$$\delta(x) = \begin{cases} +\infty, x = 0 \\ 0, x \neq 0 \end{cases}$$

$$\int_{-\infty}^{+\infty} \delta(x) dx = 1$$

Representations of the delta-function

$$\delta_a(x) = \frac{1}{a\sqrt{\pi}} e^{-x^2/a^2}$$

$$\delta(x) = \lim_{a \to 0} \delta_a(x)$$



As a Fourier transform

$$\delta(x-a) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} e^{i(x-a)y} dy$$

$$\hat{I} = \int |y\rangle\langle y| dy$$

$$f(x) = \int_{-\infty}^{+\infty} \delta(x - a) f(a) da$$

$$\downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow$$

$$\psi(x) = \langle x | \psi \rangle$$

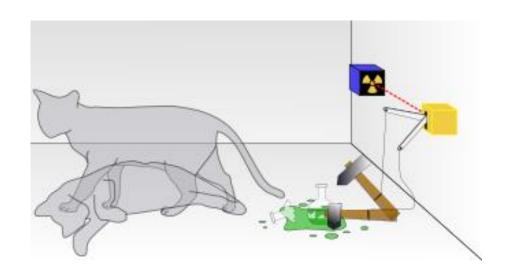
functional operator

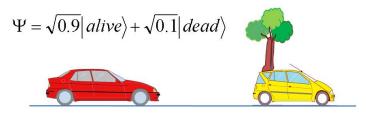


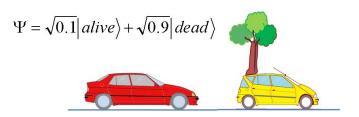


$$\langle x | x' \rangle = \int \langle x | x'' \rangle \langle x'' | x' \rangle dx'' = \int_{\text{Copyright (C) Alexey V. Akimov, 2017}} \mathcal{S}(x'' - x') dx'' = \mathcal{S}(x - x') = \hat{I}$$

2 Superposition principle

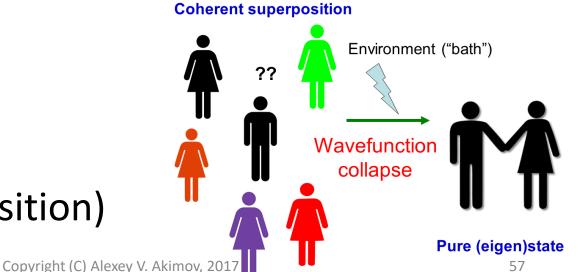




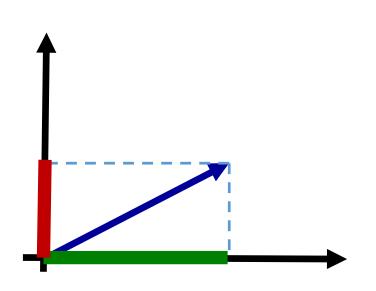


Pure

Mixed (coherent superposition)



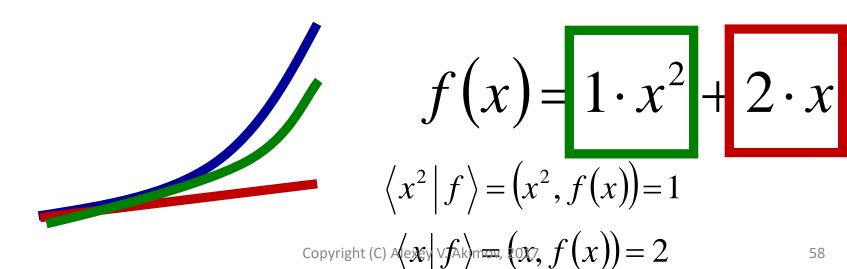
Projections (wfc collapse)



$$\vec{r} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} = 2 \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 1 \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\langle \vec{e}_1 | \vec{r} \rangle = (\vec{e}_1, \vec{r}) = 2$$

$$\langle \vec{e}_2 | \vec{r} \rangle = (\vec{e}_2, \vec{r}) = 1$$



3 Operators

$$x \to \hat{x} \equiv x$$

$$p_x \to \hat{p}_x \equiv -i\hbar \frac{\partial}{\partial x}$$

In position representation

that is:
$$\langle x | \psi \rangle = \psi(x)$$

$$\hat{x}\psi(x) = x\psi(x)$$

$$\hat{p}_{x}\psi(x) = -i\hbar\psi'(x)$$

$$x \to \hat{x} \equiv i\hbar \frac{\partial}{\partial p_x} \qquad p_x \to \hat{p}_x \equiv p_x$$

$$p_{x} \to \hat{p}_{x} \equiv p_{x}$$

In momentum representation

that is:
$$\langle p_x | \psi \rangle = \psi(p_x)$$

$$\hat{x}\psi(p_x) = i\hbar\psi'(p_x) \quad \hat{p}_x\psi(p_x) = p_x\psi(p_x)$$

$$\hat{p}_{x}\psi(p_{x}) = p_{x}\psi(p_{x})$$

#3 Operators

Overlap = scalar product

$$\langle i | j \rangle = (\psi_i, \psi_j) = \int_{-\infty}^{+\infty} \psi_i^*(\vec{r}) \psi_j(\vec{r}) d\vec{r}$$

Matrix element = "dress" the operator

$$A_{ij} = \langle i | \hat{A} | j \rangle = \langle i | \hat{A}j \rangle = \langle \psi_i, \hat{A} \psi_j \rangle = \int_{-\infty}^{+\infty} \psi_i^*(\vec{r}) \hat{A} \psi_j(\vec{r}) d\vec{r}$$

Operators acting backwards

Original = acts forward

$$A_{ij} = \langle i | \hat{A} | j \rangle = \langle i | \hat{A}j \rangle = (\psi_i, \hat{A} \psi_j) = \int_{-\infty}^{+\infty} \psi_i^*(\vec{r}) \hat{A} \psi_j(\vec{r}) d\vec{r}$$

Adjoint = acts backward

$$A_{ij}^{+} = \langle i | \hat{A}^{+} | j \rangle = (\hat{A} \psi_{i}, \psi_{j}) = \int_{-\infty}^{+\infty} (\hat{A} \psi_{i} (\vec{r}))^{*} \psi_{j} (\vec{r}) d\vec{r}$$

Hermitian = acts both ways the same

$$\hat{A}^+ = \hat{A}$$

Outer product of state vectors

$$|i\rangle\langle j|$$

What is this?

Lets "act by it" on $|k\rangle$ from the left

$$(|i\rangle\langle j|)k\rangle = |i\rangle\langle j|k\rangle = |i\rangle a_{jk} = a_{jk}|i\rangle$$

So this is an operator!!!

$$(|i\rangle\langle i|)k\rangle = a_{ik}|i\rangle = \delta_{ik}|i\rangle = \begin{cases} |i\rangle, k=i\\ 0, k\neq i \end{cases}$$

Projector

Resolution of identity and Hamiltonian

If
$$\langle i | j \rangle = \delta_{ij}$$

then

$$\sum_{i} |i\rangle\langle i| = \hat{1}$$

$$\langle a \left(\sum_{i} |i\rangle\langle i| \right) |b\rangle = \sum_{i} \langle a|i\rangle\langle i|b\rangle = \sum_{i} \delta_{ia}\delta_{ib} = \delta_{ab}$$

corresponds to the identity matrix

$$\hat{H} = \hat{I}\hat{H}\hat{I} = \sum_{i,i} |i\rangle\langle i|\hat{H}|j\rangle\langle j|$$

Compute the matrix element

Why p is Hermitian?

$$\begin{aligned} \left\langle i \left| \hat{p} \right| j \right\rangle &= -i\hbar \int \psi_i^* d\psi_j = -i\hbar \left[\psi_i^* \psi_j \right|_{-\infty}^{+\infty} - \int \psi_j d\psi_i^* \right] = \\ &= i\hbar \int \psi_j d\psi_i^* = \left(-i\hbar \int \psi_j^* d\psi_i \right)^* = \left(\left\langle j \left| \hat{p} \right| i \right\rangle \right)^* \end{aligned}$$

Eigenvalues and eigenfunctions

functional form

$$\hat{A}|i\rangle=a_i|i\rangle$$
 eigenstate eigenvalue

matrix representation

$$\langle i | \hat{A} | j \rangle = \langle i | a_j | j \rangle = a_j \langle i | j \rangle \Leftrightarrow A_{ij} = a_j S_{ij}$$

Example:

$$A_{00} = a_0 S_{00}$$

$$A_{01} = a_1 S_{01}$$

$$A_{10} = a_0 S_{10}$$

$$A_{01} = a_0 S_{10}$$

$$A_{11}=a_1S_{11 ext{Copyright (C) Alexey V. Akimov, 2017}}$$

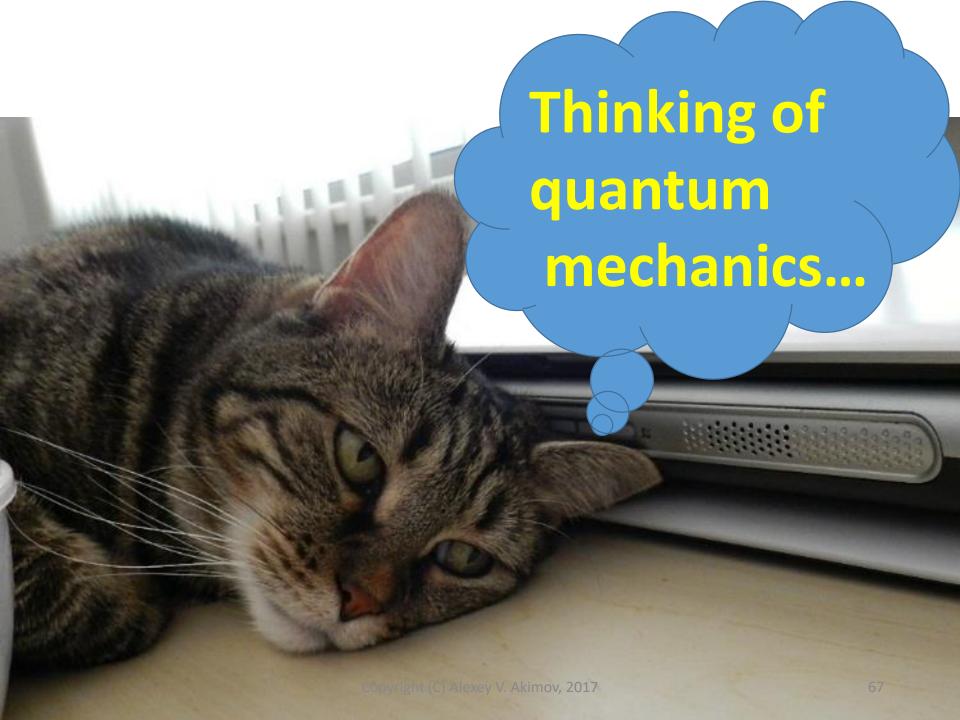
Finding the Eigenvalues and Eigenfunctions

$$\begin{pmatrix} A_{00} & A_{01} \\ A_{10} & A_{11} \end{pmatrix} = \begin{pmatrix} S_{00} & S_{01} \\ S_{10} & S_{11} \end{pmatrix} \begin{pmatrix} a_0 & 0 \\ 0 & a_1 \end{pmatrix}$$

if orthogonal basis
$$\begin{pmatrix} A_{00} & A_{01} \\ A_{10} & A_{11} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a_0 & 0 \\ 0 & a_1 \end{pmatrix} = \begin{pmatrix} a_0 & 0 \\ 0 & a_1 \end{pmatrix}$$

secular equation

$$\det \begin{pmatrix} A_{00} - a & A_{01} \\ A_{10} & A_{11} - a \end{pmatrix} = 0$$



Theorems about Hermitian operators

- 1. Eigenvalues of Hermitian op are real
- 2. Non-degenerate eigenstates of Hermitian op that correspond to different eigenvalues are **orthogonal**

Proof

Eigenvalues of Hermitian op are real

Theorems about commuting operators

- If two operators commute with each other, they have a common set of eigenvectors
- 2. If two operators have a common set of eigenvectors, they commute with each other

Proof

$$A|i\rangle = a_i|i\rangle, \forall i$$
 $B|i\rangle = b_i|i\rangle, \forall i$ $\{i\} - complete \Rightarrow |\psi\rangle = \sum_i c_i|i\rangle, \forall \psi$

then

$$\hat{A}\hat{B}|\psi\rangle = \hat{A}\hat{B}\left(\sum_{i}c_{i}|i\rangle\right) = \hat{A}\left(\sum_{i}c_{i}\hat{B}|i\rangle\right) = \hat{A}\left(\sum_{i}c_{i}b_{i}|i\rangle\right) = \sum_{i}c_{i}b_{i}\hat{A}|i\rangle = \sum_{i}c_{i}b_{i}a_{i}|i\rangle$$

$$\hat{B}\hat{A}|\psi\rangle = \hat{B}\hat{A}\left(\sum_{i}c_{i}|i\rangle\right) = \hat{B}\left(\sum_{i}c_{i}\hat{A}|i\rangle\right) = \hat{B}\left(\sum_{i}c_{i}a_{i}|i\rangle\right) = \sum_{i}c_{i}a_{i}\hat{B}|i\rangle = \sum_{i}c_{i}a_{i}b_{i}|i\rangle$$

$$\hat{A}\hat{B}|\psi\rangle = \hat{B}\hat{A}|\psi\rangle \Rightarrow \hat{A}\hat{B} - \hat{B}\hat{A} = [\hat{A}, \hat{B}] = 0$$

Proof

$$\left[\hat{A}, \hat{B}\right] = 0 \Rightarrow \hat{A}\hat{B}|\psi\rangle = \hat{B}\hat{A}|\psi\rangle$$

$$\hat{A}(\hat{B}|\psi\rangle) = \hat{B}\hat{A}|\psi\rangle = \hat{B}a|\psi\rangle = a(\hat{B}|\psi\rangle)$$

then
$$|\psi'\rangle = \hat{B}|\psi\rangle$$

is an eigenstate of the operator A corresponding to the eigenvalue a

that describes the same state as
$$|\varphi\rangle = const \cdot \hat{B}|\psi\rangle$$
 and is the eigenstate of A: $\hat{A}|\varphi\rangle = a|\varphi\rangle$

Thus
$$\hat{A}|\varphi\rangle = \hat{A}(const \cdot b|\psi\rangle) = const \cdot a|\psi\rangle \Rightarrow \hat{A}|\psi\rangle = \frac{a}{b}|\psi\rangle$$
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Time-dependent Schrodinger equation (TD-SE)

$$i\hbar \frac{\partial \Psi}{\partial t} = \hat{H}\Psi$$

Separation of variables

$$\Psi(t,R) = \varphi(t)\psi(R)$$

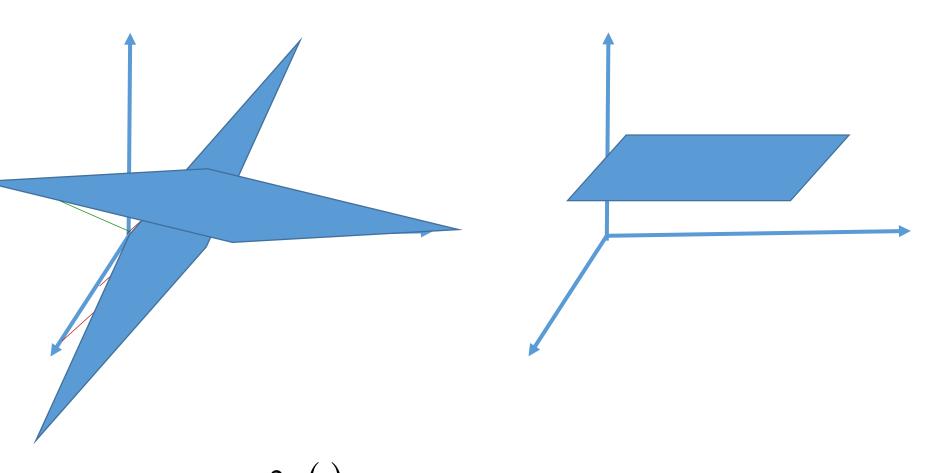
$$i\hbar \frac{\partial(\varphi(t)\psi(R))}{\partial t} = i\hbar \frac{\partial\varphi(t)}{\partial t}\psi(R) = \hat{H}(R)(\varphi(t)\psi(R)) = \varphi(t)(\hat{H}(R)\psi(R))$$



$$i\hbar \frac{\partial \varphi(t)}{\partial t} = \frac{(\hat{H}(R)\psi(R))}{\psi(R)}$$
 Depends only on \mathbb{R}



When is this possible?



$$i\hbar \frac{\partial \varphi(t)}{\partial t} = \frac{(\hat{H}(R)\psi(R))}{(\hat{H}(R)\psi(R))} = E = const$$
Copyright (\psi_A(R)). Akimov, 2017

Time-dependent part of TD-SE

$$i\hbar \frac{\partial \varphi(t)}{\partial t} = E \Rightarrow i\hbar \frac{d\varphi}{\varphi} = Edt \Rightarrow \int_{\varphi(0)}^{\varphi(t)} d\ln \varphi = -i\int_{0}^{t} \frac{E}{\hbar} dt'$$

$$\varphi(t) = \exp\left(-\frac{i}{\hbar} \int_{0}^{t} E dt'\right) \varphi(0) = \exp\left(-\frac{iE}{\hbar} t\right) \varphi(0)$$

Phase factor

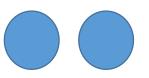
Stationary SE

$$\frac{(\hat{H}(R)\psi(R))}{\psi(R)} = E \Leftrightarrow \hat{H}(R)\psi(R) = E\psi(R)$$

Produces energy spectrum at **fixed** positions

Excited state

Ground state









Chemical Dynamics

$$\Psi(t,R) = \sum_{i} c_{i}(t) \psi_{i}(R) = \sum_{i} c_{i}(t) |i(R)\rangle$$

$$i\hbar \sum_{i} \frac{\partial c_{i}(t)}{\partial t} |i(R)\rangle = \sum_{i} c_{i}(t) \hat{H}(R) |i(R)\rangle$$

$$i\hbar\langle i(R)|\sum_{j}\frac{\partial c_{j}(t)}{\partial t}|j(R)\rangle = \sum_{j}c_{j}(t)\langle i(R)|\hat{H}(R)|j(R)\rangle$$

$$i\hbar \frac{\partial c_i(t)}{\partial t} = \sum_j H_{ij} c_j(t)$$

Solve for

$$\{C_i(t)\}$$
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Stationary SE: Particle in the Box

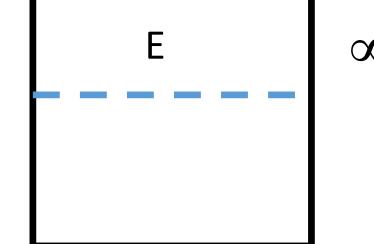
$$\hat{H}\psi = E\psi \qquad \hat{H} = \sum_{i} -\frac{\hbar^{2}}{2m_{i}} \nabla_{i}^{2} + V(\{\vec{r}\})$$

$$-\frac{\hbar^2}{2m}\psi''(x) + (V(x) - E)\psi(x) = 0$$

Model problem (Hamiltonian)



$$V(x) = \begin{cases} 0, x \in [0, L] \\ \infty, x < 0, x > L \end{cases}$$



Stationary SE: Particle in the Box

$$\psi(0) = 0$$

Because of the infinite potential

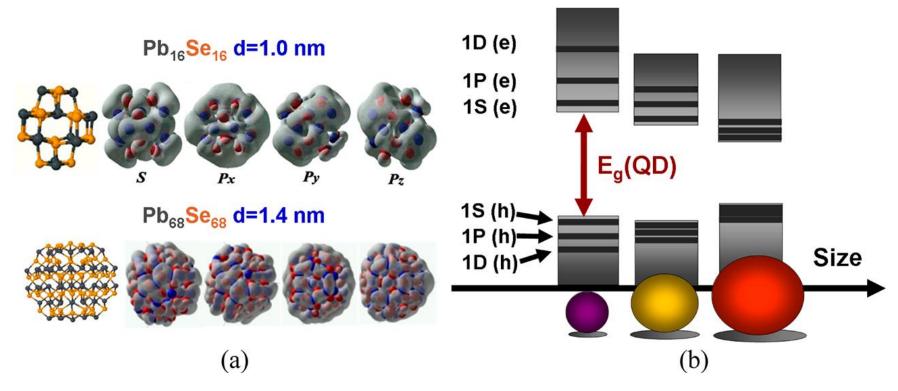
Particle confinement

quantization

Spectrum: energy spacing quadratic

Eigenstates: nodal structure

Applications: Quantum Dots and Linear Polyenes



$$E_{n,e} = E_{CBE} + \frac{\pi^2 \hbar^2}{2m_e^* L^2} n^2$$

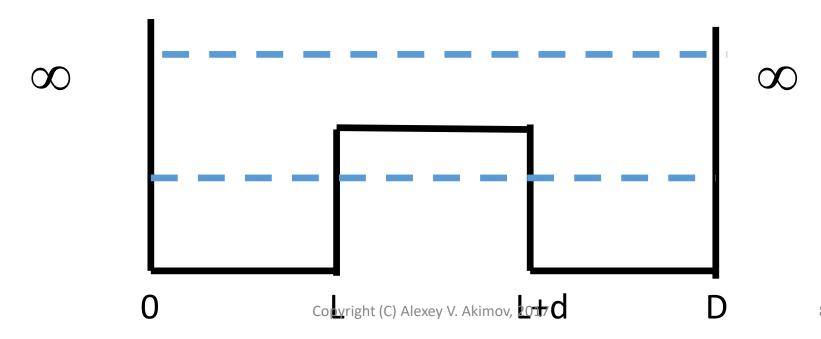
$$E_{n,h} = E_{VBE} - \frac{\pi^2 \hbar^2}{2m_*^* L^2} n^2$$

$$E_g = 3.30 + \frac{0.293}{d} + \frac{3.94}{d^2}$$

Tunneling

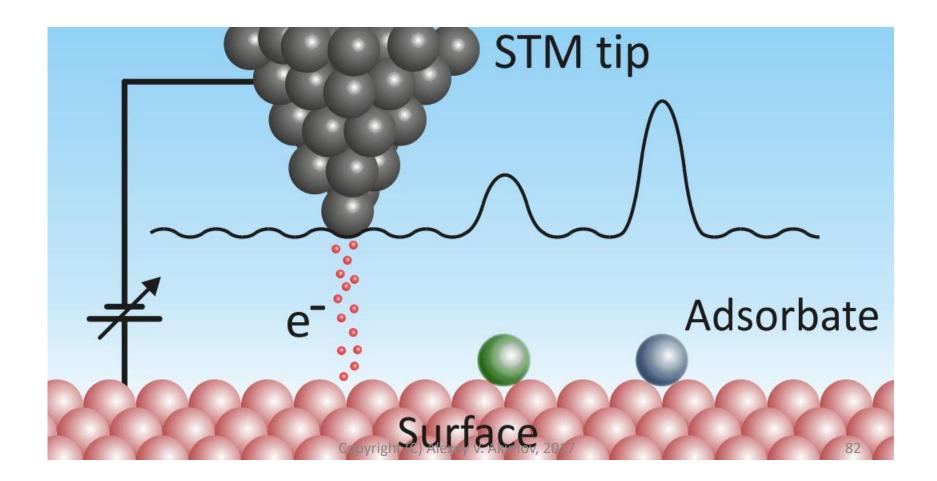
$$V(x) = \begin{cases} 0, x \in [0, L] \cup [L+d, D] \\ \infty, x \in (-\infty, 0) \cup (D, \infty) \end{cases}$$
 1) E < V

$$V(x) = \begin{cases} 0, x \in [0, L] \cup [L+d, D] \\ 0, x \in (-\infty, 0) \cup (D, \infty) \\ 0, x \in (L, L+d) \end{cases}$$
 2) E > V

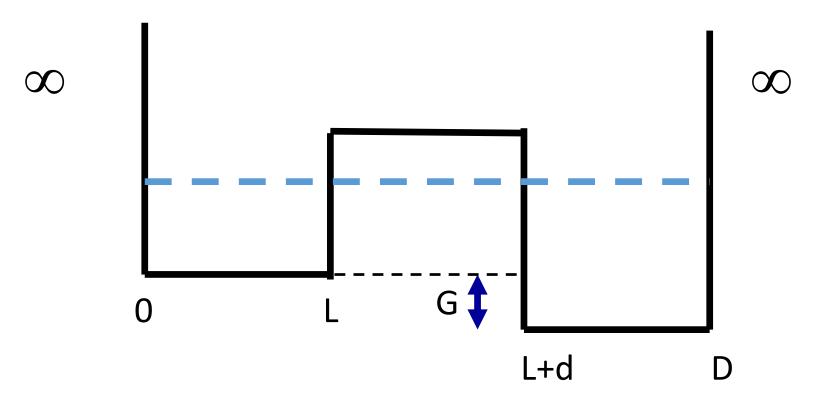


Solve. Applications: STM

$$\psi(z) \sim e^{-\alpha z}$$



The "WIN COURSE"



- 1) Get eigenstates of the problem above $\left\{oldsymbol{\psi}_i
 ight>
 ight\}$ adiabatic basis
- 2) Get eigenstates of the problem Donor and Acceptor boxes

$$\left\{ \left| \widetilde{oldsymbol{arphi}}_{i}^{A}
ight.
ight. \left. \left| \left| \widetilde{oldsymbol{arphi}}_{i}^{D}
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ight.
ight.
ight.$$

diabatic basis

3) Start in a given acceptor state, n, (with energy below the barrier)

$$\left\{\widetilde{\psi}_{n}^{A}\right\}$$

4) This initial state can be expressed in the adiabatic basis, initially:

$$|\psi(0)\rangle = |\widetilde{\psi}_{n}^{A}\rangle = \sum_{i} c_{in}(0)|\psi_{i}\rangle$$

5) ... or at any time t:

$$|\psi(t)\rangle = \sum_{i} c_{in}(t) |\psi_{i}\rangle$$

- 6) To find the evolution of the coefficients, solve the TD-SE (see before)
- 7) To find how the population of the acceptor state, m, at any time t:

$$P_{A,m} = \left| \left\langle \psi_m^D \left| \psi(t) \right\rangle \right|^2$$

Vibrational motion: Harmonic Oscillator

Reading assignment: Chapter 6 Prof. Autschbach Notes

Harmonic Oscillator: Another approach

$$\hat{H}\psi(x) = E\psi(x) \Leftrightarrow \left(\frac{\hat{p}^2}{2m} + \frac{1}{2}k\hat{x}^2\right)\psi(x) = E\psi(x)$$

Introduce:

$$a_{+} = \frac{1}{\sqrt{2\hbar m\omega}} \left(-i\hat{p} + m\omega\hat{x} \right) \qquad a_{-} = \frac{1}{\sqrt{2\hbar m\omega}} \left(i\hat{p} + m\omega\hat{x} \right)$$

$$a_{-}a_{+} = \frac{H}{\hbar\omega} + \frac{1}{2}$$
 $a_{+}a_{-} = \frac{H}{\hbar\omega} - \frac{1}{2}$ so: $[a_{-}, a_{+}] = \hat{1}$

and:

$$\hat{H} = \hbar \omega \left(a_{\scriptscriptstyle -} a_{\scriptscriptstyle +} - \frac{1}{2} \right) = \hbar \omega \left(a_{\scriptscriptstyle +} a_{\scriptscriptstyle -} + \frac{1}{2} \right)$$

Raising and lowering operations

If:
$$\hat{H}\psi(x) = E\psi(x)$$
 then:

$$\hat{H}(a_+\psi(x)) = (E + \hbar\omega)(a_+\psi(x)) \qquad \qquad \hat{H}(a_-\psi(x)) = (E - \hbar\omega)(a_-\psi(x))$$

Prove it?

Raising/Creation operator:

$$a_+: \psi(x) \to \widetilde{\psi}(x) = a_+ \psi(x)$$
 new state with energy $E + \hbar \omega$

Lowering/Annihilation operator:

$$a_{-}: \psi(x) \to \widetilde{\psi}(x) = a_{-}\psi(x)$$
 new state with energy $E - \hbar \omega$

The Ground state

There a state, for which the energy is minimal ψ_0

 a_- When acting on ψ_0 will try to lower its energy, but since there is no such state, the result is zero

$$a_{-}\psi_{0}(x) = 0$$

$$\hbar \psi'_0 + m \omega x \psi_0 = 0$$

Solve it?

Solution:
$$\psi_0(x) = A$$

$$\psi_0(x) = A \exp\left(-\frac{m\omega x^2}{2\hbar}\right)$$

$$A = \left(\frac{m\omega}{m\omega}\right)^{1/4}$$
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All other states

$$a_+: \psi(x) \to \widetilde{\psi}(x) = a_+ \psi(x)$$

$$\psi_n(x) = A_n(a_+)^n \psi_0(x)$$

The normalization of the operators (and switching to bra-ket)

$$a_{+}|n\rangle = \sqrt{n+1}|n+1\rangle$$

$$a_{-}|n\rangle = \sqrt{n}|n-1\rangle$$

Many variables: Factorization

$$\hat{A}\,\psi_A = \lambda_A \psi_A$$

$$\hat{B}\psi_B = \lambda_B \psi_B$$

$$\hat{C}\psi_C = \lambda_C \psi_C$$

And:

$$\left[\hat{A},\hat{B}\right] = 0$$

$$\left[\hat{A}, \hat{B}\right] = 0$$
 $\left[\hat{A}, \hat{C}\right] = 0$ $\left[\hat{B}, \hat{C}\right] = 0$

Then for the operator:

$$\hat{X} = \hat{A} + \hat{B} + \hat{C} + \dots$$

$$\psi_X = \psi_A \cdot \psi_B \cdot \psi_C$$

is the eigenfunction

$$\lambda_X = \lambda_A + \lambda_B + \lambda_C$$

is the eigenvalue

Example

$$\hat{H}(x,y) = \left(\frac{\hat{p}_x^2}{2m} + \frac{\hat{p}_y^2}{2m} + \frac{1}{2}k\hat{x}^2 + \frac{1}{2}k\hat{y}^2\right)$$

$$\hat{H}(x,y) = \hat{h}(x) + \hat{h}(y) = \left(\frac{\hat{p}_x^2}{2m} + \frac{1}{2}k\hat{x}^2\right) + \left(\frac{\hat{p}_y^2}{2m} + \frac{1}{2}k\hat{y}^2\right)$$

$$\psi_{n_1 n_2}(x, y) = \psi_{n_1}(x) \cdot \psi_{n_2}(y)$$

$$E_{n_1 n_2} = E_{n_1} + E_{n_2} = \hbar \omega \left(n_1 + \frac{1}{2} \right) + \hbar \omega \left(n_2 + \frac{1}{2} \right)$$

Room for degeneracies (symmetries!)

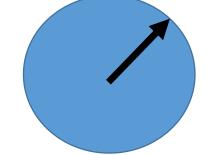
Particle in a spherically-symmetric potential

$$\hat{H} = -\frac{\hbar^2}{2m} \nabla^2 + V(|\vec{r}|)$$

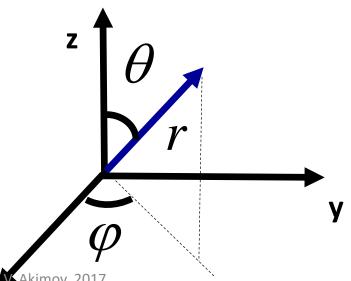
$$\left| \vec{r} \right| = \sqrt{\left(\vec{r}, \vec{r} \right)}$$

 $V(|\vec{r}|)$ Spheric symmetry

Forces are called central



Change of coordinate system: spherical polar coordinates



Coordinates Transformations

$$x = r \sin \theta \cos \varphi$$
$$y = r \sin \theta \sin \varphi$$
$$z = r \cos \theta$$

$$r = |\vec{r}| = \sqrt{(\vec{r}, \vec{r})} = \sqrt{x^2 + y^2 + z^2}$$

$$\varphi = \arctan\left(\frac{y}{x}\right) \qquad \theta = \arccos\left(\frac{z}{r}\right)$$

$$f(x, y, z) = f(x(r, \theta, \varphi), y(r, \theta, \varphi), z(r, \theta, \varphi))$$

so, using the chain rule

$$\frac{\partial}{\partial x}f = \frac{\partial}{\partial r}f \cdot \frac{\partial r}{\partial x} + \frac{\partial}{\partial \theta}f \cdot \frac{\partial \theta}{\partial x} + \frac{\partial}{\partial \varphi}f \cdot \frac{\partial \varphi}{\partial x} = \begin{pmatrix} \frac{\partial r}{\partial x} & \frac{\partial \theta}{\partial x} & \frac{\partial \varphi}{\partial x} \end{pmatrix} \begin{pmatrix} \frac{\partial}{\partial r} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \varphi} \end{pmatrix} f$$

Transformations and Jacobian

that is

$$\frac{\partial}{\partial x} = \begin{pmatrix} \frac{\partial r}{\partial x} & \frac{\partial \theta}{\partial x} & \frac{\partial \varphi}{\partial x} \end{pmatrix} \begin{pmatrix} \frac{\partial}{\partial r} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \varphi} \end{pmatrix}$$

For all components:

$$\vec{\nabla} = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} = \begin{pmatrix} \frac{\partial r}{\partial x} & \frac{\partial \theta}{\partial x} & \frac{\partial \varphi}{\partial x} \\ \frac{\partial r}{\partial y} & \frac{\partial \theta}{\partial y} & \frac{\partial \varphi}{\partial y} \\ \frac{\partial r}{\partial z} & \frac{\partial \theta}{\partial z} & \frac{\partial \varphi}{\partial z} \end{pmatrix} \begin{pmatrix} \frac{\partial}{\partial r} \\ \frac{\partial}{\partial r} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \varphi} \end{pmatrix}$$

Laplacian and Angular momentum

$$\Delta(x, y, z) = \nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

$$\Delta(r,\theta,\varphi) = \left(\frac{\partial^2}{\partial r^2} + \frac{2}{r}\frac{\partial}{\partial r}\right) + \frac{1}{r^2}\left(\frac{\partial^2}{\partial \theta^2} + \frac{1}{\tan\theta}\frac{\partial}{\partial \theta} + \frac{1}{\sin^2\theta}\frac{\partial^2}{\partial \varphi^2}\right)$$

$$\hat{L}_{x} = i\hbar \left(\frac{1}{\tan \theta} \cos \varphi \frac{\partial}{\partial \varphi} + \sin \varphi \frac{\partial}{\partial \theta} \right)$$

so:

$$\hat{L}_{y} = i\hbar \left(\frac{1}{\tan \theta} \sin \varphi \frac{\partial}{\partial \varphi} - \cos \varphi \frac{\partial}{\partial \theta} \right)$$

$$\hat{L}^2 = -\hbar^2 \left(\frac{\partial^2}{\partial \theta^2} + \frac{1}{\tan \theta} \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right)$$

$$\hat{L}_z = -i\hbar \frac{\partial}{\partial \varphi}$$

Then:

$$\Delta(r,\theta,\varphi) = \left(\frac{\partial^2}{\partial r} + \frac{2}{2}\frac{\partial}{\partial r}\right) - \frac{\hat{L}^2}{\hbar^2 r^2}$$
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Kinetic energy and Classification

$$\hat{T} = -\frac{\hbar^2}{2m} \Delta(r, \theta, \varphi) = -\frac{\hbar^2}{2m} \left(\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} \right) + \frac{\hat{L}^2}{2mr^2} = \hat{T}_R + \hat{T}_{ang}$$

Operator factorization: separation of radial and angular components

Particle in a Sphere

(a.k.a rigid rotor)

$$\hat{H} = \hat{T}_{ang}$$
 $r = const$



Hydrogen-like atoms

$$\hat{H} = \hat{T}_R + \hat{T}_{ang} + V(r)$$

with $V(r) = -\frac{1}{r}$

common form of solution

$$\Psi(r_{CO}\theta_{V}, \varphi_{C}) = R_{V}(r_{CO}Y_{I}^{m}(\theta, \varphi))$$

The difference in the Radial component

(a summary in advance)

Rigid rotor

Particle-in-a-sphere

Hydrogen-like atoms

$$R_{n,l}(r) = const$$

$$R_{n,l}(r) \sim j_l(k \cdot r)$$

Spherical **Bessel** functions of order l

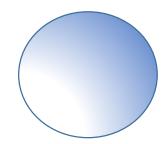
$$k = \frac{\sqrt{2mE}}{\hbar}$$

$$R_{n,l}(r) \sim L_{n-l-1}^{2l+1}(2\alpha \cdot r) \cdot e^{-\alpha r}$$

Laguerre polynomial and exponent

Angular kinetic energy

$$\hat{H} = \hat{T}_{ang} = \frac{\hat{L}^2}{2I}$$



Kinetic energy of rotational motion I – moment of inertia

More general case:



$$\hat{H} = \frac{\hat{L}_x^2}{2I_x} + \frac{\hat{L}_y^2}{2I_y} + \frac{\hat{L}_z^2}{2I_z}$$

Lets looks at the commutation relationships first

Commutation of angular momentum components

$$\hat{L} = \hat{r} \times \hat{p} = \begin{pmatrix} \hat{y} \cdot \hat{p}_z - \hat{z} \cdot \hat{p}_y \\ \hat{z} \cdot \hat{p}_x - \hat{x} \cdot \hat{p}_z \\ \hat{x} \cdot \hat{p}_y - \hat{y} \cdot \hat{p}_x \end{pmatrix}$$

Using:

$$[\hat{x}, \hat{p}] = i\hbar$$

$$[A,BC] = B[A,C] + [A,B]C$$

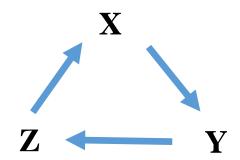
Show that

$$\left[\hat{L}_{x},\hat{L}_{y}\right]=i\hbar\hat{L}_{z}$$

$$\left[\hat{L}_{z},\hat{L}_{x}\right]=i\hbar\hat{L}_{y}$$

$$\left|\hat{L}_{_{\mathrm{V}}},\hat{L}_{_{z}}\right|=i\hbar\hat{L}_{_{x}}$$

Mnemonics: cyclic permutations



Commutation with the total angular momentum

$$\begin{split} & \left[\hat{L}_{x}, \hat{L}^{2} \right] = \left[\hat{L}_{x}, \hat{L}_{x}^{2} + \hat{L}_{y}^{2} + \hat{L}_{z}^{2} \right] = \left[\hat{L}_{x}, \hat{L}_{y}^{2} + \hat{L}_{z}^{2} \right] \\ & \left[\hat{L}_{x}, \hat{L}_{y}^{2} \right] = \hat{L}_{y} \left[\hat{L}_{x}, \hat{L}_{y} \right] + \left[\hat{L}_{x}, \hat{L}_{y} \right] \hat{L}_{y} = i\hbar \left(\hat{L}_{y} \hat{L}_{z} + \hat{L}_{z} \hat{L}_{y} \right) \\ & \left[\hat{L}_{x}, \hat{L}_{z}^{2} \right] = \hat{L}_{z} \left[\hat{L}_{x}, \hat{L}_{z} \right] + \left[\hat{L}_{x}, \hat{L}_{z} \right] \hat{L}_{z} = i\hbar \left(\hat{L}_{z} \left(-\hat{L}_{y} \right) + \left(-\hat{L}_{y} \right) \hat{L}_{z} \right) \end{split}$$

$$\left[\hat{L}_x,\hat{L}^2\right]=0$$

Same for other components

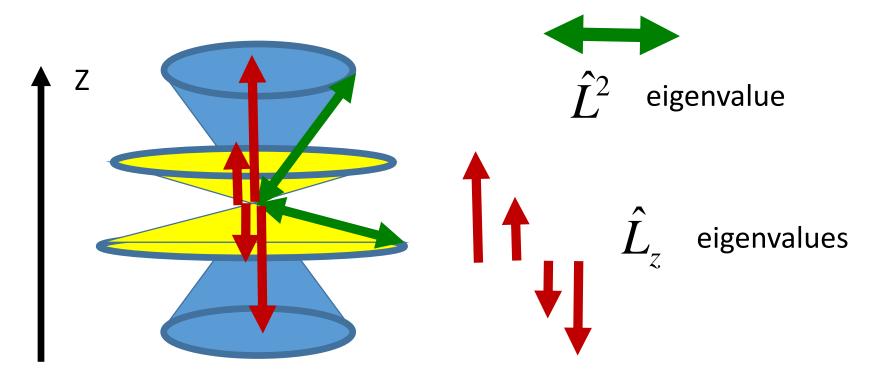
Summary: Quantization of Rotational DOF

$$\left[\hat{L}_{i},\hat{L}_{j}\right]=i\hbar\varepsilon_{ijk}\hat{L}_{k}$$

$$\left|\hat{L}_{i},\hat{L}^{2}\right|=0,\forall i$$

What does that mean?

What does that mean?



Back to the angular equation

$$\hat{H} = \frac{-\hbar^2}{2mr^2} \left(\frac{\partial^2}{\partial \theta^2} + \frac{1}{\tan \theta} \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right) = \hat{H}_{\theta} + \hat{H}_{\varphi}$$

We can separate variables then: $\Psi(\theta, \varphi) = f(\theta) \cdot g(\varphi)$

$$\Psi(\theta,\varphi) = f(\theta) \cdot g(\varphi)$$

Because
$$\left| \hat{L}_z, \hat{L}^2 \right| = 0$$

$$\Psi(\theta,\varphi) = f(\theta) \cdot g(\varphi)$$

is also an eigenfunction of

$$\hat{L}_z$$

which leads to

$$\hat{L}_{z}g(\varphi) = -i\hbar \frac{\partial}{\partial \varphi} g(\varphi) = \lambda g(\varphi) \Rightarrow g(\varphi) = Ne^{-i\frac{\lambda}{\hbar}\varphi}$$

Azimuthal part of wfc

Periodic boundary conditions:

$$e^{i\frac{\lambda}{\hbar}(\varphi+2\pi)} = e^{i\frac{\lambda}{\hbar}\varphi} \Longrightarrow e^{2\pi i\frac{\lambda}{\hbar}} = 1$$

$$\cos\left(2\pi\frac{\lambda}{\hbar}\right) = 1 \Leftrightarrow 2\pi\frac{\lambda}{\hbar} = 2\pi m, m \in \mathbb{Z}$$

$$\Rightarrow \lambda = m\hbar$$

$$g(\varphi) = Ne^{-im\varphi}$$

Normalize!

$$g_m(\varphi) = \sqrt{\frac{1}{2\pi}}e^{-im\varphi}$$
 $m = 0, \pm 1, \pm 2, etc$

Polar part of the wfc

$$\hat{H}f(\theta)e^{-im\varphi} = \frac{-\hbar^2}{2mr^2} \left(\frac{\partial^2}{\partial \theta^2} + \frac{1}{\tan \theta} \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right) f(\theta)e^{-im\varphi} = Ef(\theta)e^{-im\varphi}$$

$$\frac{-\hbar^2}{2mr^2} \left(\frac{\partial^2}{\partial \theta^2} + \frac{1}{\tan \theta} \frac{\partial}{\partial \theta} - \frac{m^2}{\sin^2 \theta} + \frac{2mr^2 E}{\hbar^2} \right) f(\theta) = 0$$

The solution is: associated Legendre polynomial

$$f_{l,m}(\theta) = P_l^{|m|}(\cos \theta) = \frac{1}{2^l l!} \sin^{|m|} \theta \frac{d^{l+|m|}}{d \cos(\theta)^{l+|m|}} (\cos^2 \theta - 1)^l \qquad l = 0,1,2,...$$

Overall solution: Spherical Harmonics

$$Y_l^m(\theta,\varphi) = (-1)^m \left(\frac{2l+1}{4\pi} \frac{(l-m)!}{(l+m)!}\right)^{1/2} P_l^{|m|}(\cos\theta) e^{im\varphi}$$

The functions are **complex-valued**, but one can use real-valued linear combinations

Symmetries:

$$\left(Y_l^m\right)^* = \left(-1\right)^m Y_l^{-m}$$

Orthonormalization:

$$\int_{0}^{2\pi} d\varphi \int_{0}^{\pi} (Y_{l}^{m})^{*} Y_{l'}^{m'} \sin \theta d\theta = \langle l, m | l', m' \rangle = \delta_{l,l'} \delta_{m,m'}$$

Note how the scalar product is defined (it contains an extra sin(theta))!

Eigenvalues:

$$\hat{L}^{2}Y_{l}^{m}(\theta,\varphi) = l(l+1)\hbar^{2}Y_{l}^{m}(\theta,\varphi)$$

$$\hat{L}_{7}Y_{l}^{m}(\theta,\varphi) = l(l+1)\hbar^{2}Y_{l}^{m}(\theta,\varphi)$$

$$\hat{L}_{7}Y_{l}^{m}(\theta,\varphi) = l(l+1)\hbar^{2}Y_{l}^{m}(\theta,\varphi)$$

Some important points

$$\hat{I}^2$$
 Defines the magnitude of the vector

$$\hat{L}_{_{\scriptscriptstyle 7}}$$
 Defines the projection of the vector

so:
$$m^2 \le l(l+1) \Longrightarrow -l \le m \le l$$
 there are 2l+1 degenerate states for a given l

Total magnitude is always a bit large than the max. projection (uncertainty principle in action!!!)

Linear combinations of spherical harmonics "pre-Atomic orbitals"

S-states (spherically-symmetric)

$$Y_0^0 = \frac{1}{2\sqrt{\pi}}$$

$$Y_1^{-1} = \frac{1}{2} \sqrt{\frac{3}{2\pi}} e^{-i\varphi} \sin \theta$$
 $Y_1^{1} = \frac{1}{2} \sqrt{\frac{3}{2\pi}} e^{i\varphi} \sin \theta$

$$Y_1^1 = \frac{1}{2} \sqrt{\frac{3}{2\pi}} e^{i\varphi} \sin \theta$$

$$Y_1^0 = \frac{1}{2} \sqrt{\frac{3}{\pi}} \cos \theta = \frac{1}{2} \frac{z}{r} \sqrt{\frac{3}{\pi}}$$

$$Y_1^{-1} + Y_1^{1} = \frac{1}{2} \sqrt{\frac{3}{2\pi}} \left(e^{-i\varphi} + e^{i\varphi} \right) \sin \theta = \sqrt{\frac{3}{2\pi}} \cos \varphi \sin \theta = \frac{x}{r} \sqrt{\frac{3}{2\pi}}$$

$$i(Y_1^{-1} - Y_1^{-1}) = \frac{i}{2} \sqrt{\frac{3}{2\pi}} (e^{-i\varphi} - e^{i\varphi}) \sin \theta = \sqrt{\frac{3}{2\pi}} \sin \varphi \sin \theta = \frac{y}{r} \sqrt{\frac{3}{2\pi}}$$

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Raising/Lowering operators

$$L_{+} = L_{x} + iL_{y}$$

$$\left[L_{\pm}, L^{2}\right] = 0$$

$$L_{-} = L_{x} - iL_{y}$$

$$\hat{L}^{2}Y_{l}^{m}(\theta, \varphi) = l(l+1)\hbar^{2}Y_{l}^{m}(\theta, \varphi)$$

$$\begin{split} & \left[\hat{L}_{z},\hat{L}_{x}\right] = i\hbar\hat{L}_{y} \\ & \left[\hat{L}_{y},\hat{L}_{z}\right] = i\hbar\hat{L}_{x} \\ & \left[\hat{L}_{z},\hat{L}_{+}\right] = \left[\hat{L}_{z},\hat{L}_{x}\right] + i\left[\hat{L}_{z},\hat{L}_{y}\right] = i\hbar\hat{L}_{y} + \hbar\hat{L}_{x} = \hbar\hat{L}_{+} \end{split}$$

$$\hat{L}^2\hat{L}_{\pm}Y_l^m(\theta,\varphi) = \hat{L}_{\pm}\hat{L}^2Y_l^m(\theta,\varphi) = \hat{L}_{\pm}l(l+1)\hbar^2Y_l^m(\theta,\varphi) = l(l+1)\hbar^2\left(\hat{L}_{\pm}Y_l^m(\theta,\varphi)\right)$$

same is for \hat{L}_z do not change L

$$\hat{L}_z\hat{L}_{\pm}Y_l^m = \hat{L}_{\pm}\hat{L}_zY_l^m + \left[\hat{L}_z,\hat{L}_{\pm}\right]Y_{\rm lot}^m \equiv \hat{L}_{\pm}m\hbar Y_{\rm lot}^m \pm \hbar\hat{L}_{\pm}Y_l^m = \hbar(m\pm1)(\hat{L}_{\pm}Y_{l-1}^m)$$

$$\hat{L}_{\pm}Y_l^m$$
 is an eigenstate of \hat{L}_z corresponding to m+/- 1 $\hat{L}_{\pm}Y_l^m=C_{l,m}^{\pm}Y_l^{m\pm 1}$

$$\hat{L}_{\scriptscriptstyle \perp}\hat{L}_{\scriptscriptstyle \perp}=\hat{L}^2-\hat{L}_{\scriptscriptstyle au}^2\pm\hbar\hat{L}_{\scriptscriptstyle au}$$

$$\left\langle \hat{L}_{\pm} Y_{l}^{m} \middle| \hat{L}_{\pm} Y_{l}^{m} \right\rangle = \left\langle Y_{l}^{m} \middle| \hat{L}_{\mp} \hat{L}_{\pm} \middle| Y_{l}^{m} \right\rangle = \left\langle Y_{l}^{m} \middle| \hat{L}^{2} - \hat{L}_{z}^{2} \mp \hbar \hat{L}_{z} \middle| Y_{l}^{m} \right\rangle \ge 0$$

$$l(l+1) \ge m^2 \pm m \Longrightarrow -l < m < l$$

$$\left|C_{l,m}^{\pm}\right|^{2} = l(l+1) - m^{2} \mp m \Rightarrow C_{l,m}^{\pm} = \sqrt{l(l+1) - m(m\pm 1)}$$

$$\hat{L}_{\pm}Y_{l}^{m} = \sqrt{l(l+1)-m(m\pm 1)}Y_{l}^{m\pm 1}$$

Spin

$$\hat{S}_x = \frac{1}{2}\hat{\sigma}_x = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\hat{S}_{y} = \frac{1}{2}\hat{\sigma}_{y} = \frac{1}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$\hat{S}_z = \frac{1}{2}\hat{\sigma}_x = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\alpha = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \qquad \beta = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\langle \alpha | \beta \rangle = \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 0$$

$$\hat{S}_x \alpha = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{2} \beta$$

$$\hat{S}_x \beta = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2} \alpha$$

$$\hat{S}_{y}\alpha = \frac{1}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 0 \\ i \end{pmatrix} = \frac{i}{2} \beta$$

$$\hat{S}_{x}\beta = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2}\alpha \qquad \hat{S}_{y}\beta = \frac{1}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -i \\ 0 \end{pmatrix} = -\frac{i}{2}\alpha$$

$$\hat{S}_z \alpha = \frac{1}{2} \alpha$$

$$\hat{S}_z \beta = -\frac{1}{2} \beta$$

Non-collinear

$$S^{2}\alpha = (\hat{S}_{x}^{2} + \hat{S}_{y}^{2} + \hat{S}_{z}^{2})\alpha = \frac{3}{4}\alpha$$

$$S^{2}\beta = (\hat{S}_{x}^{2} + \hat{S}_{y}^{2} + \hat{S}_{z}^{2})\beta = \frac{3}{4}\beta$$

$$\begin{aligned} & \left(\hat{S}_{1}^{2} + \hat{S}_{2}^{2} + 2\hat{S}_{1}\hat{S}_{2}\right) \beta(1)\alpha(2) = \\ & = \frac{3}{4}\beta(1)\alpha(2) + \beta(1)\frac{3}{4}\alpha(2) + 2\left(\frac{1}{2}\alpha(1)\frac{1}{2}\beta(2) + \frac{i}{2}\alpha(1)\frac{-i}{2}\beta(2) + \frac{-1}{2}\beta(1)\frac{1}{2}\alpha(2)\right) = \\ & = \frac{3}{2}\beta(1)\alpha(2) + \alpha(1)\beta(2) - \frac{1}{2}\beta(1)\alpha(2) = \beta(1)\alpha(2) + \alpha(1)\beta(2) \end{aligned}$$

$$(\hat{S}_{1}^{2} + \hat{S}_{2}^{2} + 2\hat{S}_{1}\hat{S}_{2})\alpha(1)\beta(2) = \alpha(1)\beta(2) + \beta(1)\alpha(2)$$

$$\left(\hat{S}_{1}^{2} + \hat{S}_{2}^{2} + 2\hat{S}_{1}\hat{S}_{2}\right)\left[\beta(1)\alpha(2) - \alpha(1)\beta(2)\right] = \left[\beta(1)\alpha(2) + \alpha(1)\beta(2)\right] - \left[\alpha(1)\beta(2) + \beta(1)\alpha(2)\right] = 0$$