

```
In [1]: # Autoreload changed python modules
%load_ext autoreload
```

```
In [2]: import os, glob
import h5py # for loading .h5 files
import numpy as np
import matplotlib.pyplot as plt
import random
%matplotlib inline
```

```
In [3]: plt.style.use('seaborn') # pretty matplotlib plots
plt.rcParams["axes.grid"] = False # don't show grid lines on plots by
plt.rcParams['figure.figsize'] = (12, 16) # increase size of subplots
```

```
In [4]: import cs230_project_utilities as utils
# make sure you have pywt: pip3 install PyWavelets --user
```

Loading the data

```
In [5]: # Location of directory H5Exports_AnimiX/ (downloaded from Olivier's 1
DATASET_DIRECTORY = '/home/ubuntu/cs230/data/H5Exports_AnimiX'
```

```
In [6]: # Find all the files in our dataset
h5_files = utils.automap.find_dataset_files(DATASET_DIRECTORY)
```

Found 134 .h5 files and 134 .txt files.

Visualizing the data

```

In [7]: ##### Finally, we can see the raw data
sample_filename = list(h5_files.keys())[20]
print('Taking a look at file: {}'.format(sample_filename))
h5 = h5_files[sample_filename]['h5']
h5_data = utils.automap.read_h5_file(h5)
print(h5_data.keys())

images = h5_data['images']
magnitude = h5_data['magnitude']
phase = h5_data['phase']
classification = h5_data['classification']

# (Note: shape of magnitude and phase are different from image)
print(images.shape, magnitude.shape, phase.shape)
print(np.ndarray.flatten(classification))

Taking a look at file: 943_10158
dict_keys(['classification', 'images', 'magnitude', 'phase'])
(15, 256, 256) (15, 256, 256) (15, 256, 256)
[1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1.]

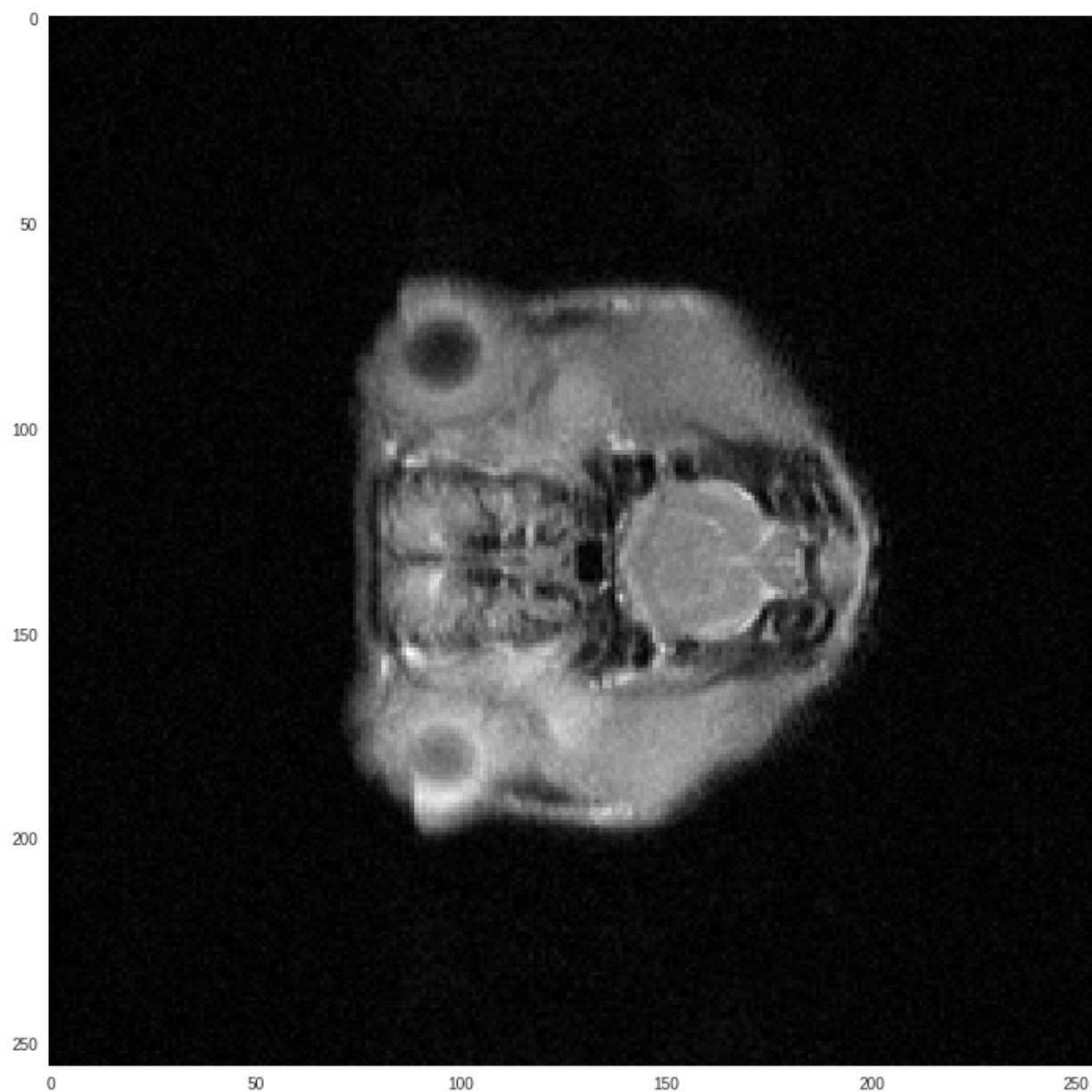
```

```

In [8]: sample_index = np.argmax(classification)

```

```
In [9]: # Uncomment to view example image in dataset  
utils.plot.imshowgray(images[sample_index])
```



```
In [10]: # Construct FFT (k-space data) from magnitude and phase
fft = magnitude[sample_index] * np.exp(1j * phase[sample_index])

# Take the inverse FFT
ifft = utils.signal_processing.ifft_2D_centered(fft)

# Note: shape of magnitude and phase are different from image.
# Because of this, the reconstruction shape is different from the
# image shape and so we can't compare the image and reconstruction di
# How will we solve this?

# This check to make sure we are correctly combining magnitude and pha
print('Error in FFT magnitude: {}'.format(utils.signal_processing.mean_squ
print('Error in FFT phase: {}'.format(utils.signal_processing.mean_squ
```

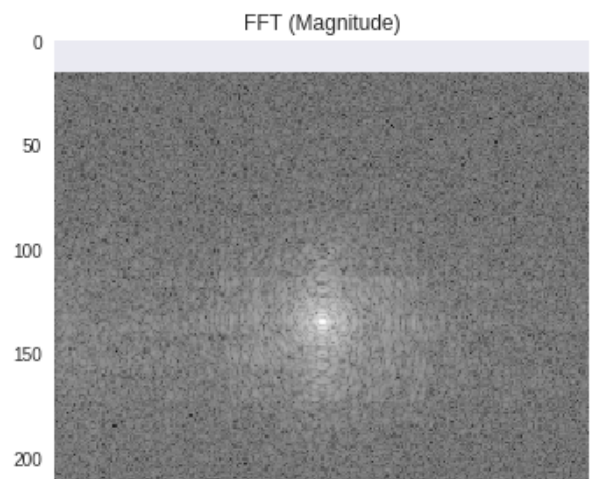
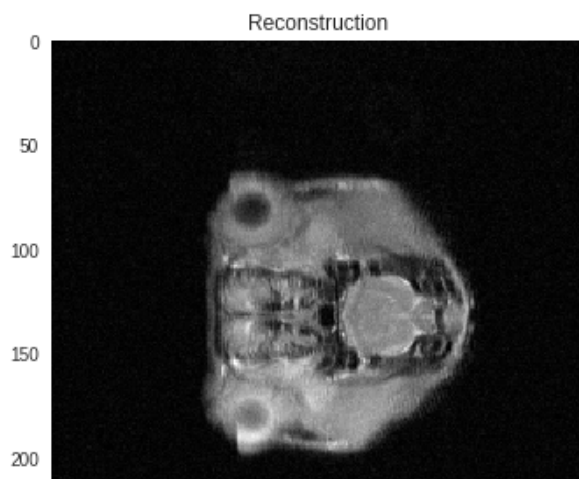
Error in FFT magnitude: 2.4687782802584184e-20
Error in FFT phase: 5.288901564141631e-16

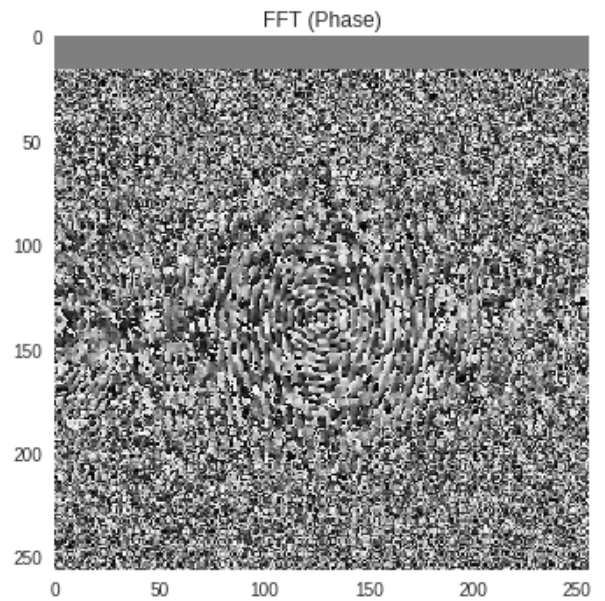
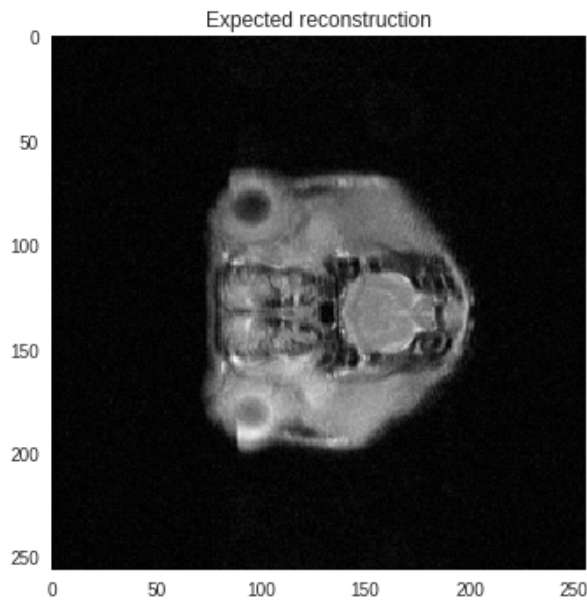
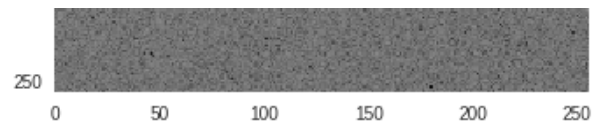
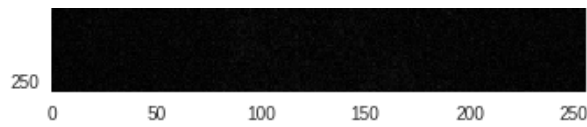
```
In [11]: ''' Uncomment to show plots.'''
plt.subplot(2, 2, 1)
plt.title('Reconstruction')
utils.plot.imshowgray(np.abs(ifft))
#
plt.subplot(2, 2, 2)
plt.title('FFT (Magnitude)')
utils.plot.imshowfft(np.abs(fft))

plt.subplot(2, 2, 3)
plt.title('Expected reconstruction')
image = images[sample_index]
utils.plot.imshowgray(image)

plt.subplot(2, 2, 4)
plt.title('FFT (Phase)')
utils.plot.imshowgray(np.angle(fft))
```

/home/ubuntu/cs230/code/MRI_reconstruction_example/cs230_project_util
ities/plot.py:13: RuntimeWarning: divide by zero encountered in log10
imshowgray(20 * np.log10(np.abs(fft)))





Automap Model

```
In [12]: import tensorflow as tf
```

```
In [13]: config = tf.ConfigProto()
config.gpu_options.allow_growth = True
```

```
In [14]: import keras
from keras.layers import Input, Conv2D, Conv2DTranspose, Dense, Reshape
from keras.models import Model
from keras.optimizers import RMSprop
from keras import losses
```

Using TensorFlow backend.

```
In [15]: tf.reset_default_graph()
```

```
In [16]: def load_model():
    n_H, n_W = 256, 256
    X = Input((n_H, n_W, 2))
    conv_downsample1 = Conv2D(16, (4, 4), strides=(2, 2), activation='tanh')
    conv_downsample2 = Conv2D(4, (4, 4), strides=(1, 1), activation='tanh')
    conv_downsample3 = Conv2D(2, (4, 4), strides=(2, 2), activation='tanh')
    X1 = Flatten()(conv_downsample3)
    current_H, current_W = (256 // 4, 256 // 4) # after downsampling by 4
    fc1 = Dense(current_H * current_W * 2, activation = 'tanh')(X1)
    fc2 = Dense(current_H * current_W, activation = 'tanh')(fc1)
    fc3 = Dense(current_H * current_W, activation = 'tanh')(fc2)
    X2 = Reshape((current_H, current_W, 1))(fc3)
    conv1_1 = Conv2D(64, 5, activation='relu', padding='same')(X2)
    conv1_2 = Conv2D(64, 5, activation='relu', padding='same')(conv1_1)
    conv1_3a = Conv2DTranspose(64, 9, activation='relu', padding='same')(conv1_2)
    conv1_3b = Conv2DTranspose(64, 9, strides=2, activation='relu', padding='same')(conv1_3a)
    conv1_3c = Conv2DTranspose(64, 9, strides=2, activation='relu', padding='same')(conv1_3b)
    out = Conv2D(1, 1, activation = 'linear',padding='same')(conv1_3c)
    model = Model(inputs=X, outputs=out)
    model.compile(optimizer=keras.optimizers.Adam(lr=1e-4, decay=1e-3))
    return model
```

```
In [17]: ## Original full model. Trainable params: 26,424,796,993.
## (The 64 x 64 version has 117,892,929 params. Baseline has 74,843,616)
def load_model():
    # n_H, n_W = 256, 240
    # X = Input((n_H, n_W, 2))
    # X1 = Flatten()(X)
    # fc1 = Dense(n_H * n_W * 2, activation = 'tanh')(X1)
    # fc2 = Dense(n_H * n_W, activation = 'tanh')(fc1)
    # fc3 = Dense(n_H * n_W, activation = 'tanh')(fc2)
    # X2 = Reshape((n_H, n_W, 1))(fc3)
    # conv1_1 = Conv2D(64, 5, activation='relu', padding='same')(X2)
    # conv1_2 = Conv2D(64, 5, activation='relu', padding='same')(conv1_1)
    # conv1_3 = Conv2DTranspose(64, 9, activation='relu', padding='same')(conv1_2)
    # out = Conv2D(1, 1, activation = 'linear',padding='same')(conv1_3)
    # model = Model(inputs=X, outputs=out)
    # model.compile(optimizer=RMSprop(lr=1e-5), loss='mean_squared_error')
    # return model
```

```
In [18]: model = load_model()
print(model.summary())
```

WARNING:tensorflow:From /home/ubuntu/anaconda3/envs/tensorflow_p36/lib/python3.6/site-packages/tensorflow/python/framework/op_def_library.py:263: colocate_with (from tensorflow.python.framework.ops) is deprecated and will be removed in a future version.

Instructions for updating:

Colocations handled automatically by placer.

Layer (type)	Output Shape	Param #
=====		
input_1 (InputLayer)	(None, 256, 256, 2)	0
conv2d_1 (Conv2D)	(None, 128, 128, 16)	528
conv2d_2 (Conv2D)	(None, 128, 128, 4)	1028
conv2d_3 (Conv2D)	(None, 64, 64, 2)	130
flatten_1 (Flatten)	(None, 8192)	0
dense_1 (Dense)	(None, 8192)	67117056
dense_2 (Dense)	(None, 4096)	33558528
dense_3 (Dense)	(None, 4096)	16781312
reshape_1 (Reshape)	(None, 64, 64, 1)	0
conv2d_4 (Conv2D)	(None, 64, 64, 64)	1664
conv2d_5 (Conv2D)	(None, 64, 64, 64)	102464
conv2d_transpose_1 (Conv2DTr	(None, 64, 64, 64)	331840
conv2d_transpose_2 (Conv2DTr	(None, 128, 128, 64)	331840
conv2d_transpose_3 (Conv2DTr	(None, 256, 256, 64)	331840
conv2d_6 (Conv2D)	(None, 256, 256, 1)	65
=====		
Total params: 118,558,295		
Trainable params: 118,558,295		
Non-trainable params: 0		
None		

```
In [19]: def batch_generator():
# Generate training batches by reading sequences from disk

randomize_file_order = True
```

```

# Find all the files in our dataset
h5_files = utils.automap.find_dataset_files(DATASET_DIRECTORY)

batch_size = 16
n_H, n_W = 256, 256

X_batch = np.zeros((batch_size, n_H, n_W, 2))
Y_batch = np.zeros((batch_size, n_H, n_W, 1))

current_batch_size = 0

h5_keys = list(h5_files.keys())

current_h5_key_index = 0

while True:

    if randomize_file_order:
        h5_key = random.choice(h5_keys)
    else:
        h5_key = h5_keys[current_h5_key_index % len(h5_keys)]
        current_h5_key_index += 1

    h5_file = h5_files[h5_key]

    h5_data = utils.automap.read_h5_file(h5_file['h5'])

    image_sequence = h5_data['images']

    assert len(image_sequence.shape) == 3, 'Input must be have 3 c

    image_sequence = np.expand_dims(image_sequence, axis=-1) # mod

    magnitude_sequence = h5_data['magnitude']
    phase_sequence = h5_data['phase']
    fft_sequence = np.concatenate((np.expand_dims(magnitude_sequer
                                                np.expand_dims(phase_sequence, axis=3)),
                                    axis=3)

    # Contains info on positive/negative samples
    class_sequence = h5_data['classification']

    for i in range(len(fft_sequence)):

        # Only keep good (class == 1?) samples and skip the rest

        try:

            if len(image_sequence) != len(class_sequence):
                # print("skipping, len(image_sequence) {} != len(c
                continue

            if class_sequence[i] == 1:

```



```

        try:
            X_batch[current_batch_size, ...] = fft_sequences[current_batch_size, ...]
            Y_batch[current_batch_size, ...] = image_sequences[current_batch_size, ...]
        except Exception as e:
            print('Error filling arrays of batch: {}'.format(current_batch_size))

        current_batch_size += 1

    if current_batch_size == batch_size:
        current_batch_size = 0
        yield X_batch, Y_batch

except Exception as e:
    print('Unexpected error making batch:', e, class_sequence)

```

In [20]: *# With batch generator:*

```

# Use first batch as validation data for now
X_development, Y_development = next(batch_generator())

sess = tf.Session(config=config)

```

Found 134 .h5 files and 134 .txt files.

In [21]: *# Uncomment to resume training from checkpoint*
model.load_weights('automap_baseline.h5')

In []: *# Start training*

```

with sess.as_default():
    fit_model = model.fit_generator(batch_generator(),
                                   validation_data=(X_development, Y_development),
                                   steps_per_epoch=2600 // 16,
                                   epochs=20,
                                   shuffle=True,
                                   verbose=1,
                                   use_multiprocessing=True)

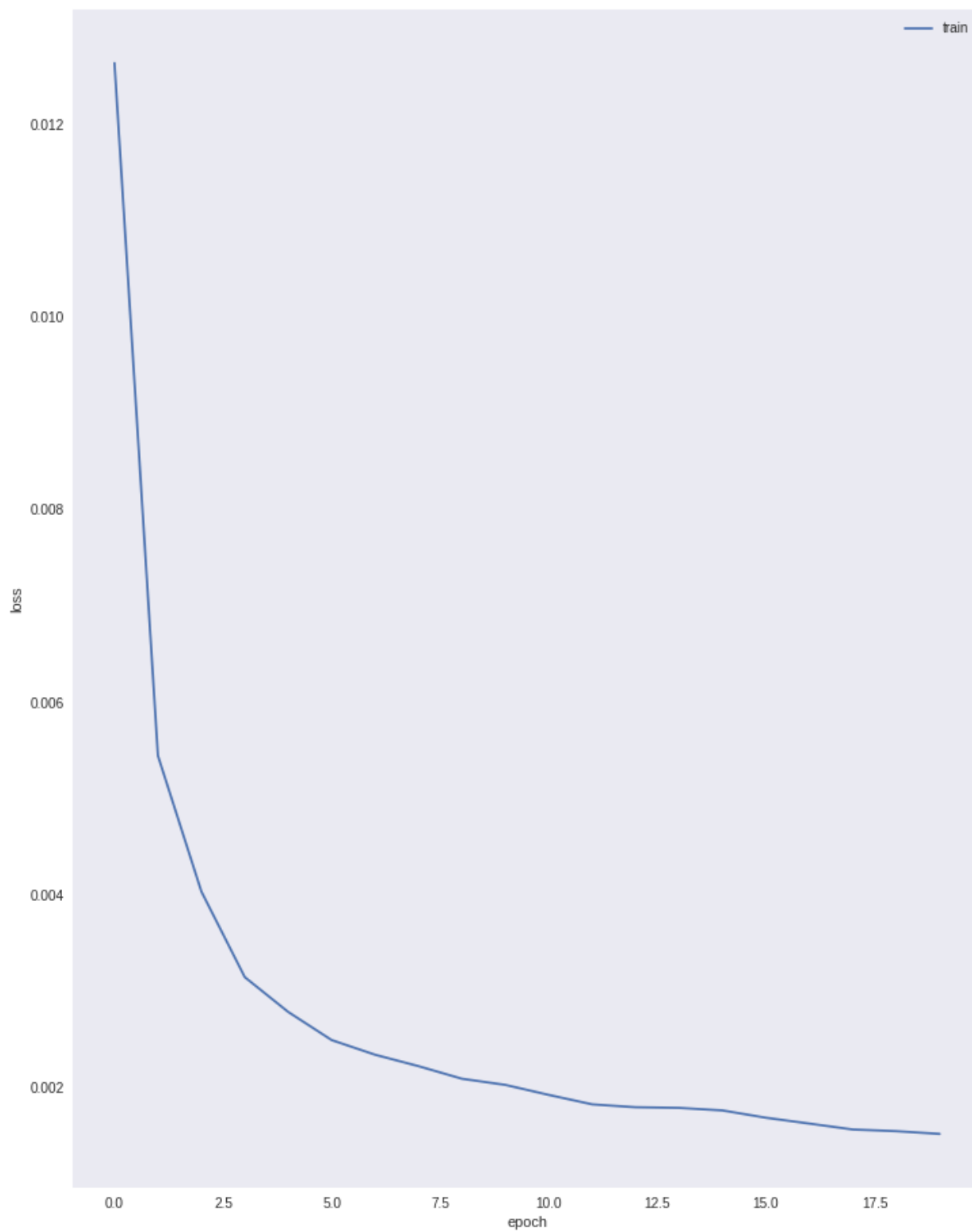
    model.save('automap_keras_good_classes.h5')

```

In [33]: *# Visualize predictions*

```
In [24]: plt.plot(fit_model.history['loss'])  
plt.ylabel('loss')  
plt.xlabel('epoch')  
plt.legend(['train'])
```

Out[24]: <matplotlib.legend.Legend at 0x7f62f04f95f8>



```
In [25]: # Run predictions on development set
with sess.as_default():

    prediction_batch = model.predict(X_development)
    prediction_batch = prediction_batch.squeeze()

    ground_truth_batch = Y_development.squeeze()
```

```
In [26]: plt.rcParams['image.cmap'] = 'gray' # b/w images

# Prediction 0

mag, phase = X_development[0][..., 0], X_development[0][..., 1]
fft = mag * np.exp(1j * phase)

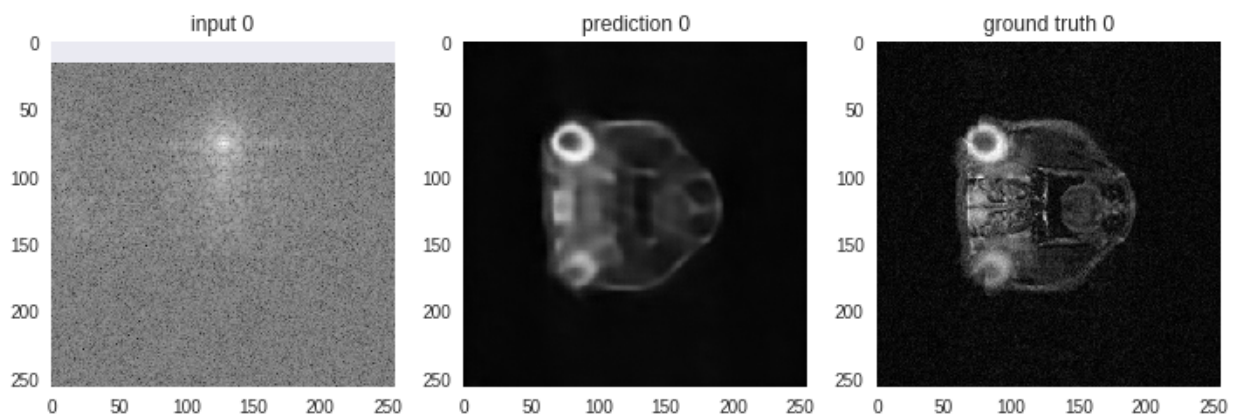
# Uncomment to see reconstruction:
# plt.title('Reconstruction')
# utils.plot.imshowgray(np.abs(iff))

plt.subplot(1, 3, 1)
utils.plot.imshowfft(np.abs(fft))
plt.title('input 0')

plt.subplot(1, 3, 2)
plt.imshow(prediction_batch[0])
plt.title('prediction 0')

plt.subplot(1, 3, 3)
plt.imshow(ground_truth_batch[0])
plt.title('ground truth 0');
```

/home/ubuntu/cs230/code/MRI_reconstruction_example/cs230_project_utilities/plot.py:13: RuntimeWarning: divide by zero encountered in log10
 imshowgray(20 * np.log10(np.abs(fft)))



In [27]: *# Prediction 1*

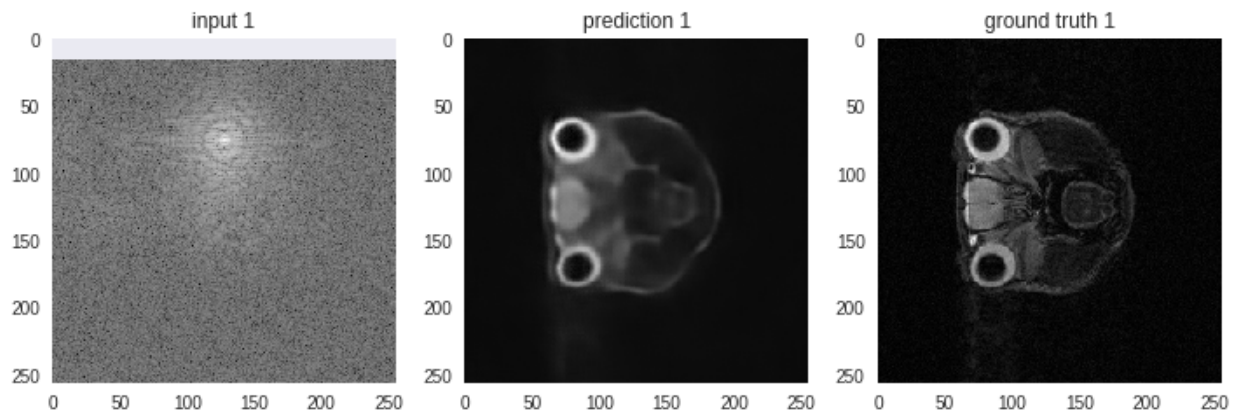
```
mag, phase = X_development[1][..., 0], X_development[1][..., 1]
fft = mag * np.exp(1j * phase)

plt.subplot(1, 3, 1)
utils.plot.imshowfft(np.abs(fft))
plt.title('input 1')

plt.subplot(1, 3, 2)
plt.imshow(prediction_batch[1])
plt.title('prediction 1')

plt.subplot(1, 3, 3)
plt.imshow(ground_truth_batch[1])
plt.title('ground truth 1');
```

/home/ubuntu/cs230/code/MRI_reconstruction_example/cs230_project_utilities/plot.py:13: RuntimeWarning: divide by zero encountered in log10
imshowgray(20 * np.log10(np.abs(fft)))



In [28]: *# Prediction 2*

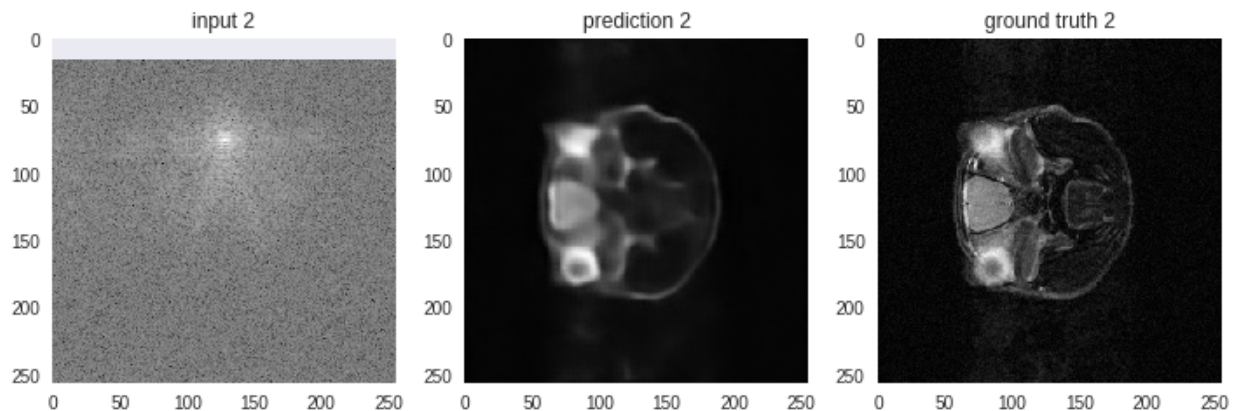
```
mag, phase = X_development[2][..., 0], X_development[2][..., 1]
fft = mag * np.exp(1j * phase)

plt.subplot(1, 3, 1)
utils.plot.imshowfft(np.abs(fft))
plt.title('input 2')

plt.subplot(1, 3, 2)
plt.imshow(prediction_batch[2])
plt.title('prediction 2')

plt.subplot(1, 3, 3)
plt.imshow(ground_truth_batch[2])
plt.title('ground truth 2');
```

/home/ubuntu/cs230/code/MRI_reconstruction_example/cs230_project_utilities/plot.py:13: RuntimeWarning: divide by zero encountered in log10
imshowgray(20 * np.log10(np.abs(fft)))



In [29]: *# Prediction 3*

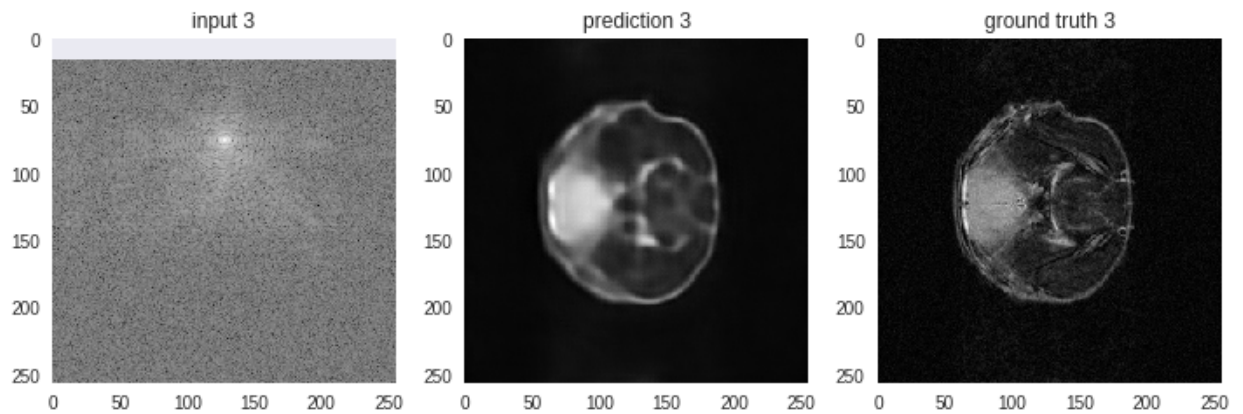
```
mag, phase = X_development[3][..., 0], X_development[3][..., 1]
fft = mag * np.exp(1j * phase)
```

```
plt.subplot(1, 3, 1)
utils.plot.imshowfft(np.abs(fft))
plt.title('input 3')
```

```
plt.subplot(1, 3, 2)
plt.imshow(prediction_batch[3])
plt.title('prediction 3')
```

```
plt.subplot(1, 3, 3)
plt.imshow(ground_truth_batch[3])
plt.title('ground truth 3');
```

/home/ubuntu/cs230/code/MRI_reconstruction_example/cs230_project_utilities/plot.py:13: RuntimeWarning: divide by zero encountered in log10
imshowgray(20 * np.log10(np.abs(fft)))



In []:

In []:

In []: