Optimization and Computational Linear Algebra – Brett Bernstein

Recitation 11

It may be helpful if after recitation you try to re-solve these problems by yourself, and use them as additional study problems for the class.

1. Let $f(x) = -e^{-x^2/2}$. Is f convex?

Solution. No. $f'(x) = xe^{-x^2/2}$ and $f''(x) = (1-x^2)e^{-x^2/2}$ which is negative for x > 1.

2. Prove that $e^x \ge 1 + x$ and $e^x \ge ex$ for all $x \in \mathbb{R}$.

Solution. Note that e^x is convex since if $f(x) = e^x$ then $f''(x) = e^x > 0$. Also note that f'(0) = 1 and f'(1) = e. Thus the tangent lines given by 1 + x and e^x must globally underestimate the function.

3. Let $f: \mathbb{R}^n \to \mathbb{R}$ be defined by $f(x) = \log(1 + x^T A x)$ where $A \in \mathbb{R}^{n \times n}$ is symmetric and positive semidefinite. Compute $\nabla f(x)$.

Solution. We can apply the chain rule. Let $g(t) = \log(t)$ and $h(x) = 1 + x^T Ax$ so that f(x) = g(h(x)). Then we have

$$\nabla f(x) = g'(h(x))\nabla h(x) = \left(\frac{1}{1 + x^T A x}\right)(2Ax).$$

To see that $\nabla h(x) = 2Ax$ we can either apply the homework result or use the following calculation:

$$h(x+v) = 1 + (x+v)^{T} A(x+v) = 1 + x^{T} A x + 2x^{T} A v + v^{T} A v = h(x) + 2x^{T} A v + v^{T} A v.$$

Thus $\nabla h(x)^T = 2x^T A$ since

$$\left| \frac{h(x+v) - h(x) - 2x^T A v}{\|v\|} \right| = \frac{|v^T A v|}{\|v\|} \le \frac{\|A\| \|v\|^2}{\|v\|} \to 0.$$

4. Let $f: \mathbb{R} \to \mathbb{R}$ be convex and differentiable. Prove that for all $x, h \in \mathbb{R}$ that

$$f(x+h) \ge f(x) + f'(x)h.$$

Solution.

Proof. Suppose, for contradiction, there is an x, h with

$$f(x+h) < f(x) + f'(x)h.$$

We assume h > 0 (a similar proof holds for h < 0, or we could just apply the result proven below to g(x) = f(-x), which is also convex). Define $\alpha > 0$ such that

$$f(x+h) = f(x) + (f'(x) - \alpha)h.$$

In other words

$$\alpha := -\frac{f(x+h) - f(x) - f'(x)h}{h} > 0.$$

By convexity we have, for all $t \in (0, 1)$,

$$f(x+th) = f((1-t)x + t(x+h))$$

$$\leq (1-t)f(x) + tf(x+h)$$

$$= (1-t)f(x) + tf(x) + t(f'(x) - \alpha)h$$

$$= f(x) + t(f'(x) - \alpha)h.$$

Rearranging we have

$$\frac{f(x+th) - f(x)}{th} < f'(x) - \alpha$$

for all t. Letting $t \to 0$ shows

$$f'(x) < f'(x) - \alpha$$

a contradiction.

5. Let $f: \mathbb{R}^n \to \mathbb{R}$ be convex and differentiable. Prove that for all $x, h \in \mathbb{R}^n$ that

$$f(x+h) \ge f(x) + \nabla f(x)^T h.$$

Solution.

Proof. Suppose, for contradiction, there is an $x, h \in \mathbb{R}^n$ with

$$f(x+h) < f(x) + \nabla f(x)^T h.$$

Define $g: \mathbb{R} \to \mathbb{R}$ by g(t) = f(x+th). Then g is convex and the above statement says that

$$g(1) < g(0) + g'(0).$$

But this is impossible by the previous problem.

6. Suppose $A \in \mathbb{R}^{2\times 2}$ is symmetric with positive eigenvalues. Describe geometrically the contour lines of $f: \mathbb{R}^2 \to \mathbb{R}$ given by $f(x) = x^T A x$. Recall that the contour line for value γ is given by

$$\{x \in \mathbb{R}^2 : f(x) = \gamma\}.$$

Solution. First suppose A is diagonal:

$$A = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}.$$

Then $x^T A x = \lambda_1 x_1^2 + \lambda_2 x_2^2$. Thus solving $f(x) = \gamma$ is the equation for an elippse. By the spectral theorem, any symmetric matrix is diagonal up to a rotation. Thus generally we obtain a rotated ellipse.

7. Suppose $f: \mathbb{R}^2 \to \mathbb{R}$ is defined by $f(x) = x_1^2 + 100x_2^2$. Explain what issues this may pose for gradient descent.

Solution. The contour lines of f are very eccentric ellipses. Gradient descent started at (-1,0.1) will take many steps to converge.

- 8. (a) Give a quadratic approximation q(h) to f(x+h) at x.
 - (b) What is the minimizer of the quadratic approximation assuming the Hessian is positive definite (has positive eigenvalues)?

Solution.

(a)

$$f(x+h) \approx f(x) + \nabla f(x)^T h + \frac{1}{2} h^T \nabla^2 f(x) h$$

$$= f(x) + \sum_{i=1}^n \frac{\partial f(x)}{\partial x_i} h_i + \frac{1}{2} \sum_{i,j=1}^n \frac{\partial^2 f(x)}{\partial x_i \partial x_j} h_i h_j$$

$$=: g(h).$$

To get the result from class, we let h = y - x to obtain

$$f_x^2(y) = f(x) + \nabla f(x)^T (y - x) + \frac{1}{2} (y - x)^T \nabla^2 f(x) (y - x).$$

(b) As q(h) is quadratic, we can apply the homework to see that

$$\nabla q(h) = \nabla f(x) + \nabla^2 f(x)h,$$

which is zero when

$$h = -(\nabla^2 f(x))^{-1} \nabla f(x).$$

9. What is the third order approximation to f at x?

Solution.

$$f(x+h) \approx f(x) + \sum_{i=1}^{n} \frac{\partial f(x)}{\partial x_i} h_i + \frac{1}{2} \sum_{i,j=1}^{n} \frac{\partial^2 f(x)}{\partial x_i \partial x_j} h_i h_j + \frac{1}{6} \sum_{i,j,k=1}^{n} \frac{\partial^3 f(x)}{\partial x_i \partial x_j \partial x_k} h_i h_j h_k.$$

As above we obtain $f_x^3(y)$ letting h = y - x.

- 10. (\star) Let $f: \mathbb{R} \to \mathbb{R}$ be convex and let X be a random variable.
 - (a) Assuming X only takes finitely many values x_1, \ldots, x_n with probabilities p_1, \ldots, p_n that sum to 1. Prove that $E[f(X)] \ge f(E[X])$.
 - (b) Prove $E[f(X)] \ge f(E[X])$ for an arbitrary random variable X.

Solution.

(a) Consider the random vector (X, f(X)) taking values in \mathbb{R}^2 on the graph of f. Then we have

$$E[(X, f(X))] = \sum_{i=1}^{n} p_i(x_i, f(x_i)) = (E[X], E[f(X)])$$

which is a convex combination of points on the graph of f, and thus must lie in the epigraph of f. This immediately gives

$$E[f(X)] \ge f(E[X]).$$

(b) Although we only prove this for differentiable functions in class, for any convex function $f: \mathbb{R} \to \mathbb{R}$ and any $v \in \mathbb{R}$ there is a tangent line g(x) = f(v) + a(x - v) (for some $a \in \mathbb{R}$) that lies below f (i.e., $g(x) \leq f(x)$ for all $x \in \mathbb{R}$). Letting v = E[X] we obtain

$$f(E[X]) + a(x - E[X]) \le f(x)$$

for all $x \in \mathbb{R}$, so we plug in X for x and take expectations to obtain

$$E[f(X)] \ge E[f(E[X]) + a(X - E[X])] = f(E[X]).$$

- 11. Let $f: \mathbb{R}^2 \to \mathbb{R}$ be smooth (at least twice continuously differentiable) and assume that $x \in \mathbb{R}$ has $\nabla f(x) = 0$. What do each of the following conditions on the Hessian $\nabla^2 f(x)$ imply?
 - (a) $\nabla^2 f(x)$ has two positive eigenvalues.
 - (b) $\nabla^2 f(x)$ has two negative eigenvalues.
 - (c) $\nabla^2 f(x)$ has one positive and one negative eigenvalue.

Solution.

- (a) Local minimum.
- (b) Local maximum.
- (c) Saddle point.

We will prove the first of these statements to show how these types of results are justified.

Lemma 1 (Multivariate Taylor's Theorem). Let $f : \mathbb{R}^n \to \mathbb{R}$ with $f \in C^2$. Then for all $x, h \in \mathbb{R}^n$ we have

$$f(x+h) = f(x) + \nabla f(x)^T h + \frac{1}{2} h^T \nabla^2 f(x+sh)h,$$

for some $s \in (0,1)$.

Proof. Fix $x, h \in \mathbb{R}^n$ and define $g : \mathbb{R} \to \mathbb{R}$ by

$$g(t) = f(x + th).$$

Then by the one-dimensional version of Taylor's theorem we have

$$g(1) = g(0) + g'(0) + \frac{1}{2}g''(s),$$

for some $s \in (0,1)$. Using the definition of g and applying the chain rule we have

$$g'(t) = \nabla f(x+th)^T h$$
 and $g''(t) = h^T \nabla^2 f(x+th) h$.

Plugging in we obtain

$$f(x+h) = f(x) + \nabla f(x)^{T} h + \frac{1}{2} h^{T} \nabla^{2} f(x+sh) h.$$

Lemma 2. Let $A, B \in \mathbb{R}^{n \times n}$ be symmetric. Let λ_n^A and λ_n^B denote the smallest eigenvalues of A and B, respectively. Then $|\lambda_n^A - \lambda_n^B| \leq ||A - B||$.

Proof. For any $x \in \mathbb{R}^n$ with ||x|| = 1 we have

$$|x^T B x - x^T A x| = |x^T (B - A) x| \le ||B - A||.$$

Since

$$\lambda_n^A = \min_{\|x\|=1} x^T A x$$

we have that

$$\lambda_n^B = \min_{\|x\|=1} x^T B x \le \min_{\|x\|=1} x^T A x + x^T (B - A) x \le \lambda_n^A + \|B - A\|.$$

Reversing the roles of A, B completes the proof.

Lemma 3. Let $f: \mathbb{R}^n \to \mathbb{R}$ with $f \in C^2$. If $\nabla^2 f(x) \succ 0$ for some $x \in \mathbb{R}^n$ then there is a $\delta > 0$ such that $\nabla^2 f(y) \succ 0$ for all y with $||x - y|| < \delta$.

Proof. Fix $x \in \mathbb{R}^n$. Since $f \in \mathbb{C}^2$, each of the second partial derivatives

$$\frac{\partial^2 f}{\partial x_i \partial x_i}$$

are continuous. Thus for any $\epsilon > 0$ there is a $\delta > 0$ such that

$$\|\nabla^2 f(y) - \nabla^2 f(x)\|_F^2 < \epsilon$$

whenever $||x-y|| < \delta$. [To see this note that for each $\frac{\partial^2 f}{\partial x_i \partial x_j}$ there is a δ_{ij} such that $|\frac{\partial^2 f(y)}{\partial x_i \partial x_j} - \frac{\partial^2 f(x)}{\partial x_i \partial x_j}|^2 < \epsilon/n^2$. Thus the bound holds for $||x-y||_{\infty} < \min_{i,j} \delta_{ij}$. But $||x-y||_{\infty} \le ||x-y||_2$, so we can let $\delta = \min_{i,j} \delta_{ij}$.] Let $\epsilon = \lambda_n^{\nabla^2 f(x)}/2$, where $\lambda_n^{\nabla^2 f(x)}$ is the smallest eigenvalue of $\nabla^2 f(x)$. Since the Frobenius norm upper bounds the spectral norm, the previous lemma applies proving that

$$\lambda_n^{\nabla^2 f(y)} \geq \lambda_n^{\nabla^2 f(x)} - \epsilon = \lambda_n^{\nabla^2 f(x)}/2 > 0.$$

Theorem 4 (Second Derivative Test for a Local Minimum). Let $f : \mathbb{R}^n \to \mathbb{R}$ with $f \in C^2$ and suppose there is an $x \in \mathbb{R}^n$ with $\nabla f(x) = 0$ and $\nabla^2 f(x) \succ 0$. Then x is a local minimizer of f.

Proof. By the previous lemma, there is a $\delta > 0$ such that $\nabla^2 f(y) \succ 0$ for all y with $||y - x|| < \delta$. For any such y we can apply Taylor's theorem (letting h = y - x) to obtain

$$f(y) = f(x) + \nabla f(x)^{T} (y - x) + \frac{1}{2} (y - x)^{T} \nabla^{2} f(x + t(y - x)) (y - x)$$

$$= f(x) + \frac{1}{2} (y - x)^{T} \nabla^{2} f(x + t(y - x)) (y - x)$$

$$\geq f(x),$$

for some $t \in (0,1)$. The final inequality follows since $||x-(x+t(y-x))|| = ||t(y-x)|| < \delta$ so the Hessian is positive definite and

$$\frac{1}{2}(y-x)^T \nabla^2 f(x + t(y-x))(y-x) \ge 0.$$

12. If f, g are convex, is h(x) = f(g(x)) convex?

Solution. No. Let $f, g : \mathbb{R} \to \mathbb{R}$ with f(x) = -x and $g(x) = x^2$. The statement is true if f is also increasing.

13. What is the relationship between $b \in \mathbb{R}^n$ and $S = \{x \in \mathbb{R}^n : b^T x \ge a\}$?

Solution. S is a half-space on one side of a hyperplane. b is orthogonal to the hyperplane pointing into the half-space.

14. Let $S = \{x \in \mathbb{R}^2 : (Ax)_i \ge 0 \text{ for } i = 1, \dots, m\}$ where $A \in \mathbb{R}^{m \times n}$. Give a geometric description of S.

Solution. It is an intersection of half planes, also called a polyhedral set. If the resulting set is bounded we call it a convex polygon in \mathbb{R}^2 , or a convex polytope in higher dimensions.