Covariate Shift

David S. Rosenberg

NYU: CDS

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Supervised learning framework

- \bullet \mathfrak{X} : input space
- y: outcome space
- A: action space
- Prediction function $f: \mathcal{X} \to \mathcal{A}$ (takes input $x \in \mathcal{X}$ and produces action $a \in \mathcal{A}$)
- Loss function $\ell: \mathcal{A} \times \mathcal{Y} \to \mathbb{R}$ (evaluates action a in the context of outcome y).

Risk minimization

- Let $(X, Y) \sim p(x, y)$.
- The **risk** of a prediction function $f: \mathcal{X} \to \mathcal{A}$ is $R(f) = \mathbb{E}\ell(f(X), Y)$.
 - the expected loss of f on a new example $(X, Y) \sim p(x, y)$
- Ideally we'd find the Bayes prediction function $f^* \in \operatorname{arg\,min}_f R(f)$.

Empirical risk minimization

- Training data: $\mathcal{D}_n = ((X_1, Y_1), \dots, (X_n, Y_n))$ • drawn i.i.d. from p(x, y).
- Let \mathcal{F} be a **hypothesis space** of functions mapping $\mathfrak{X} \to \mathcal{A}$
- ullet A function \hat{f} is an **empirical risk minimizer** over \mathcal{F} if

$$\hat{f} \in \underset{f \in \mathcal{F}}{\operatorname{arg\,min}} \frac{1}{n} \sum_{i=1}^{n} \ell(f(X_i), Y_i).$$

- We're using sample \mathcal{D}_n from p(x,y) to estimate an expectation w.r.t. p(x,y).
- Most machine learning methods can be written in this form.
- What if we only have a sample from another distribution q(x, y)?

Covariate shift

• Goal: Find f minimizing risk $R(f) = \mathbb{E}\ell(f(X), Y)$ where

$$(X, Y) \sim p(x, y) = p(x)p(y \mid x).$$

- We'll refer to p(x, y) as the **test** or **target distribution** (following [CMM10]).
- Training data: $\mathfrak{D}_n = ((X_1, Y_1), \dots, (X_n, Y_n))$ is i.i.d. from

$$q(x,y) = q(x)p(y \mid x).$$

- We'll refer to q(x, y) as the training distribution.
- Covariate shift is when
 - the covariate distribution is different in training and test $(p(x) \neq q(x))$, but
 - the conditional distribution $p(y \mid x)$ is the same in both cases.

Covariate shift: the issue

Under covariate shift,

$$\mathbb{E}_{(X_i,Y_i)\sim q(x,y)}\left[\frac{1}{n}\sum_{i=1}^n\ell(f(X_i),Y_i)\right]\neq\mathbb{E}_{(X,Y)\sim p(x,y)}\ell(f(X),Y).$$

- The empirical risk is a biased estimator for risk.
- Naive empirical risk minimization is optimizing the wrong thing.
- Can we get an unbiased estimate of risk using $\mathcal{D}_n \sim q(x,y)$?
- Importance weighting is one approach to this problem.

Change of measure and importance sampling

(Precise formulation in the "importance-sampling" slide notes.)

Theorem (Change of measure)

Suppose that $p(x) > 0 \implies q(x) > 0$ for all $x \in \mathcal{X}$. Then for any $f : \mathcal{X} \to \mathbb{R}$,

$$\mathbb{E}_{X \sim p(x)} f(X) = \mathbb{E}_{X \sim q(x)} \left[f(X) \frac{p(X)}{q(X)} \right].$$

• If we have a sample $X_1, \ldots, X_n \sim q(x)$, then a Monte Carlo estimate of the RHS

$$\hat{\mu}_{\mathsf{IS}} = \frac{1}{n} \sum_{i=1}^{n} f(X_i) \frac{\rho(X_i)}{q(X_i)}$$

is called an **importance sampling** estimator for $\mathbb{E}_{X \sim p(x)} f(X)$.

• The ratios $p(X_i)/q(X_i)$ are called the **importance weights**.

Importance weighting for covariate shift

• $\mathfrak{D}_n = ((X_1, Y_1), \dots, (X_n, Y_n))$ is i.i.d. from

$$q(x,y) = q(x)p(y \mid x).$$

• The importance-weighted empirical risk is

$$\hat{R}_{IW}(f) = \frac{1}{n} \sum_{i=1}^{n} \frac{p(X_{i})p(Y_{i} | X_{i})}{q(X_{i})p(Y_{i} | X_{i})} \ell(f(X_{i}), Y_{i})$$

$$= \frac{1}{n} \sum_{i=1}^{n} \frac{p(X_{i})}{q(X_{i})} \ell(f(X_{i}), Y_{i}).$$

- Note that $\mathbb{E}_{\mathcal{D}_{\sigma} \sim g(X,Y)} \hat{R}_{\mathsf{IS}}(f) = \mathbb{E}_{(X,Y) \sim g(X,Y)} \ell(f(X),Y)$.
- So the importance-weighted empirical risk is unbiased for the target risk.
- Importance weighted ERM is finding $f \in \mathcal{F}$ that minimizes $\hat{R}_{IW}(f)$.

Importance weighting for covariate shift

importance weighting for covariate shift $= 2_0 - \{(X_1,Y_1), \dots, (X_N,Y_N) \text{ is i.i.d. } for = \sigma(s)\sigma(y) \neq s\}$ $= \text{The importance weighted empirical risk is } \\ \hat{\theta}_{00}(f) = \frac{1}{s} \sum_{i=1}^N \frac{\rho(X_i(H,Y)|X_i)}{\rho(X_i(H,Y)|X_i)} f(f(X_i,Y_i)) \\ = \frac{1}{s} \sum_{i=1}^N \frac{\rho(X_i(H,Y)|X_i)}{\rho(X_i(H,Y)|X_i)} \\ = \frac{1}{s} \sum_{i=1}^N \frac{\rho(X_i(H,Y)|X_i)}{\rho(X_i(H,Y)|X_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y_i)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y_i)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y_i)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y_i)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y_i)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y_i)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y_i)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y_i)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y_i)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y_i)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since that } \sum_{(X_i,Y_i) \in \mathcal{X}_i(H,Y_i)} \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)} \\ = \text{Since } \frac{\rho(X_i,Y_i)}{\rho(X_i,Y_i)}$

- Apologies for the confusing change between "importance sampling" and "importance weighting".
- Importance sampling is the term used when we're talking about Monte Carlo estimation of an expectation [Owe13, Ch 9.1].
- In the context of making an empirical risk function that we will optimize over, it's generally referred to as "importance weighting" [CMM10, BDL09]. The term "importance weighted empirical risk" is used in the book [SSK12, Ch 9.1]
- That said, one of the original papers on using importance sampling for covariate shift just says "weighted least squares" and "weighted log-likelihood", and refers to the underlying mathematical idea as the "importance sampling identity" [Shi00].

Potential variance issues

• Since the summands are independent, we have

$$\operatorname{Var}\left(\hat{R}_{\mathsf{IW}}(f)\right) = \operatorname{Var}\left(\frac{1}{n}\sum_{i=1}^{n}f(X_{i})\frac{p(X_{i})}{q(X_{i})}\right)$$
$$= \frac{1}{n}\operatorname{Var}\left(f(X)\frac{p(X)}{q(X)}\right)$$

- If q(x) is much smaller than p(x) in certain regions,
 - the importance weight can get very large,
 - variance can blow up.

Variance reduction for importance sampling

- Many ways to sacrifice some bias to reduce variance.
- Importance weight clipping: $\frac{1}{n} \sum_{i=1}^{n} \min \left(M, \frac{p(X_i)}{q(Y_i)} \right) \ell(f(X_i), Y_i)$
 - for hyperparameter M > 0.
- Shomodaira's exponentiation: $\frac{1}{n} \sum_{i=1}^{n} \left(\frac{p(X_i)}{q(X_i)} \right)^{\gamma} \ell(f(X_i), Y_i)$
 - where the "flattening" hyperparameter $\gamma \in [0,1]$ [Shi00].
- Self-normalization:

$$\frac{\sum_{i=1}^{n} \frac{p(X_i)}{q(X_i)} \ell(f(X_i), Y_i)}{\sum_{i=1}^{n} \frac{p(X_i)}{q(X_i)}}.$$

- Also useful when you only know p(x) and/or q(x) up to a scale factor.
- Self-normalization hopefully improves the variance of the risk estimate, but note that it has no effect on which f minimizes the expression.

References

Resources

- The most commonly cited article for using importance weighting with empirical risk minimization is [Shi00].
- Some statistical learning theory style bounds for this setting is given in [CMM10].
- There are plenty of resources on importance sampling more generally. Sections 9.1 and 9.2 in Art Owen's book [Owe13] is a good starting place.

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- [Owe13] Art B. Owen, Monte carlo theory, methods and examples, 2013.
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References II

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